## 4. SOME APPLICATIONS AND REMARKS

## Objekttyp: Chapter

Zeitschrift: L'Enseignement Mathématique

Band (Jahr): 49 (2003)
Heft 1-2: L'ENSEIGNEMENT MATHÉMATIQUE

PDF erstellt am:
29.04.2024

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which is always positive since the matrix $(H \bar{H}+\bar{H} H)$ is positive semi-definite, so its trace is $\geq 0$. Hence the maps $\alpha$ and $\Phi$ are well defined. It is clear that the image of $\Phi$ is contained in $S^{4} \subset \mathcal{S}$, because the linearity of the trace implies that

$$
[\operatorname{trace}(\Phi(H))]^{2}=\alpha^{2}(H)[\operatorname{trace} \psi(H)]^{2}=1
$$

It is also clear that $\Phi$ is $\operatorname{SO}(3, \mathbf{R})$-equivariant, since the trace is invariant under conjugation and $\psi$ is equivariant by Lemma 3.7. These considerations imply both Lemma 3.8 and the following

Lemma 3.9. The map $\Phi$ is an equivariant surjection from $P(2)$ over $S^{4} \subset \mathcal{S}$, and it is two-to-one, except over the image of the real matrices in $P(2)$ where it is one-to-one.

This gives the map in Theorem 3.4 that determines an equivariant diffeomorphism between $S^{4}$ and $P_{\mathbf{C}}^{2}$ modulo the involution given by conjugation. To complete the proof of Theorem 3.4 we need to show that $\Phi$ is invariant under the involution of $P(2)$ that corresponds to complex conjugation in $P_{\mathbf{C}}^{2}$. For this we notice that if $L_{H}$ is the complex line in $\mathbf{C}^{3}$ which is the image of $H \in P(2)$, and if $0 \neq\left(z_{1}, z_{2}, z_{3}\right) \in L_{H}$, we can associate to $H$ the point in $P_{\mathbf{C}}^{2}$ with projective coordinates $\left[z_{1}, z_{2}, z_{3}\right]$. To the matrix $\bar{H}$ there corresponds the line with projective coordinates $\left[\bar{z}_{1}, \bar{z}_{2}, \bar{z}_{3}\right]$. Therefore we have

Lemma 3.10. The involution $j *$ of $P(2)$ defined by $j *(H)=\bar{H}$ coincides with the involution $j$ of $P_{\mathbf{C}}^{2}$ given by complex conjugation, $\left[z_{1}, z_{2}, z_{3}\right] \stackrel{j}{\mapsto}$ $\left[\bar{z}_{1}, \bar{z}_{2}, \bar{z}_{3}\right]$.

Then $\Phi$ is invariant under this involution, since $\Re(H)=\Re(\bar{H})$, proving Theorem 3.4.

## 4. Some applications and REMARKS

It is interesting to describe explicitly the orbits of the $\Gamma$ action of $\mathrm{SO}(3, \mathbf{R})$ on $S^{4}$, regarded ${ }^{2}$ ) as the set of matrices with norm 1 in $\mathcal{S}$. In fact, the orbits of this action are conjugacy classes (or congruency classes) of traceless symmetric matrices whose square has trace 1 . This is the connection between our construction and the spherical Tits buildings. Every $S \in \mathcal{S}$ can

[^0]be diagonalized by an element in $\operatorname{SO}(3, \mathbf{R})$, hence every orbit has a unique representative which is diagonal. So let us assume that $S$ is diagonal with eigenvalues $\lambda_{1}, \lambda_{2}, \lambda_{3}$. The two special orbits correspond to the cases when two eigenvalues coincide. Since $\lambda_{1}+\lambda_{2}+\lambda_{3}=0$ and $\lambda_{1}^{2}+\lambda_{2}^{2}+\lambda_{3}^{2}=1$, if two eigenvalues coincide we must have, up to conjugation, $\lambda_{1}=\lambda_{2}=\frac{1}{\sqrt{6}}$ and $\lambda_{3}=-\frac{2}{\sqrt{6}}$, or $\lambda_{1}=\lambda_{2}=-\frac{1}{\sqrt{6}}$ and $\lambda_{3}=\frac{2}{\sqrt{6}}$. In both cases the corresponding matrix is determined by the plane $P$ given by the two equal eigenvalues, say $\lambda_{1}$ and $\lambda_{2}$. Equivalently, this matrix is determined by the line orthogonal to $P$, in which we act by the multiplier $\lambda_{3}= \pm \frac{2}{\sqrt{6}}$; the sign here distinguishes the two orbits. Since $\operatorname{SO}(3, \mathbf{R})$ acts transitively on the lines in $\mathbf{R}^{3}$, it follows that each of these special orbits is a copy of $P_{\mathbf{R}}^{2}$, as we know from [HL]. The general orbits occur when the three eigenvalues are distinct and the corresponding eigenspaces are orthogonal lines. Since the trace is 0 , two eigenvalues determine the third. Hence in each case the transformation is determined by the plane $P$ given by two eigenvalues and the line $l$ in $P$ given by one of them, together with the corresponding multipliers on $l$, on the line orthogonal to $l$ in $P$ and on the line orthogonal to $P$ in $\mathbf{R}^{3}$. That is, we have a flag $(P, l)$ in $\mathbf{R}^{3}$, together with the multipliers $\lambda_{1}, \lambda_{2}$ and $\lambda_{3}$. Since the action of $\operatorname{SO}(3, \mathbf{R})$ is transitive on the planes in $\mathbf{R}^{3}$ and on the lines in each such plane, it follows that each principal orbit, a copy of the flag manifold $F^{3}(2,1)$, is the orbit of the flag $(P, l)$. The different orbits correspond to the different multipliers.

We also notice that there is a double fibration, similar to the one considered in (1.4) above:

where $\pi_{1}(P, l)=l$ and $\pi_{2}(P, l)=P$. We can form the corresponding double mapping cylinder $\left(F^{3}(2,1) \times[0,1]\right) / \sim$, where $\sim$ identifies a point $\left(\left(P_{0}, l_{0}\right), 0\right) \in\left(F^{3}(2,1) \times\{0\}\right)$ with the point $\pi_{1}\left(P_{0}, l_{0}\right)=l_{0} \in P_{\mathbf{R}}^{2}$, and a point $\left(\left(P_{1}, l_{1}\right), 1\right) \in\left(F^{3}(2,1) \times\{1\}\right)$ with the point $\pi_{2}\left(P_{1}, l_{1}\right)=P_{1} \in P_{\mathbf{R}}^{2}$. We obtain $S^{4}$.

The double fibration given by (1.4) in this dimension descends to (4.1) by conjugation. By the previous discussion, the image of $Q$ in $S^{4}$ is the copy of $P_{\mathbf{R}}^{2}$ which is the orbit of the diagonal matrix with eigenvalues $\left\{-\frac{1}{\sqrt{6}},-\frac{1}{\sqrt{6}}, \frac{2}{\sqrt{6}}\right\}$, while $\Pi$ is taken diffeomorphically into the orbit
of $\left\{\frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}},-\frac{2}{\sqrt{6}}\right\}$.
Since the action of $\operatorname{SO}(3, \mathbf{R})$ in $S^{4}$ is by isometries and is transitive on each orbit, the principal orbits are at constant distance from each of these exceptional orbits $M_{1} \cong P_{\mathbf{R}}^{2}$ and $M_{2} \cong P_{\mathbf{R}}^{2}$, i.e. they are "parallel". In other words, as in Section 2, the principal orbits are the level sets of the function $f: S^{4} \rightarrow \mathbf{R}$ given by $f(x)=\left(d\left(x, M_{1}\right)\right)^{2}$ (or the level sets of the function $\left.g(x)=\left(d\left(x, M_{2}\right)\right)^{2}\right)$. Both $f$ and $g$ are smooth Bott-Morse functions (cf. [DR]).

The fixed-point free involution on $S^{4}$ given by $\iota: A \in \mathcal{S} \mapsto-A \in \mathcal{S}$ commutes with our $\mathrm{SO}(3, \mathbf{R})$ action and therefore it takes $\mathrm{SO}(3, \mathbf{R})$-orbits into orbits. The quotient $S^{4} / \iota$ is the real projective space $P_{\mathbf{R}}^{4}$, equipped with an isometric $\operatorname{SO}(3, \mathbf{R})$-action. The two exceptional orbits $M_{1}$ and $M_{2}$ on $S^{4}$ are identified by $\iota$. Thus we have only one exceptional orbit for the action of $\operatorname{SO}(3, \mathbf{R})$ on $P_{\mathbf{R}}^{4}$. The orbit $N$ of the matrix in $S^{4}$ which corresponds to the matrix in $\mathcal{S}$ whose eigenvalues are $\left\{-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right\}$ is the manifold consisting of points such that $d\left(x, M_{1}\right)=d\left(x, M_{2}\right)$. Then, $N$ is invariant under $\iota$ and separates $S^{4}$ into two regions which are interchanged by $\iota$ (i.e. $N$ is an "equator" for the orientation-reversing involution $\iota$ ). The orientable 3-manifold $N$ is the flag manifold described earlier, but it can also be described as the set of ordered pairs $\left(l_{1}, l_{2}\right)$ of non-oriented lines of $\mathbf{R}^{3}$ which are mutually orthogonal. These lines are the eigenspaces corresponding to the eigenvalues $-\frac{1}{\sqrt{2}}$ and $\frac{1}{\sqrt{2}}$, respectively.

The restriction of $\iota$ to $N$ is the orientation-preserving and fixed-point free involution given by $\left(l_{1}, l_{2}\right) \mapsto\left(l_{2}, l_{1}\right)$. Let $\pi$ denote the double covering map from $S^{4}$ to $P_{\mathbf{R}}^{4}=S^{4} / \iota$. Let $\pi\left(M_{1}\right)=\pi\left(M_{2}\right):=M \cong P_{\mathbf{R}}^{2}$ and $\pi(N):=\widehat{N}$. The manifold $\widehat{N}$ is diffeomorphic to $\operatorname{SO}(3, \mathbf{R}) / D_{4}$, where $D_{4}$ is the group of order 8 of isometries of the square. This is because $\operatorname{SO}(3, \mathbf{R})$ acts transitively on the set of non-oriented pairs $\left\{l_{1}, l_{2}\right\}$ of lines in $\mathbf{R}^{3}$ which are mutually orthogonal and the isotropy group is precisely $D_{4}$. Therefore $\widehat{N}$ is diffeomorphic to $\mathrm{SU}(2) / \widetilde{D}_{4} \cong S^{3} / \widetilde{D}_{4}$, where $\widetilde{D}_{4}$ is the binary dihedral group of order 16 , i.e. $\widetilde{D}_{4}=\phi^{-1}\left(D_{4}\right)$ where $\phi: S^{3} \cong \mathrm{SU}(2) \rightarrow \mathrm{SO}(3, \mathbf{R})$ is the canonical epimorphism.

The embedding $P_{\mathbf{R}}^{2} \cong M \subset P_{\mathbf{R}}^{4}$ is exactly the embedding given by the Veronese embedding $P_{\mathbf{R}}^{2} \rightarrow S^{4}$, followed by the canonical projection from $S^{4}$ into $P_{\mathbf{R}}^{4}$ (see [HL]). We know that $S^{4} \backslash\left(M_{1} \cup M_{2}\right)$ is diffeomorphic to $N \times \mathbf{R}$, and the restriction of the involution $\iota$ to $S^{4} \backslash\left(M_{1} \cup M_{2}\right)$ is conjugate to the involution $\mathfrak{I}$ of $N \times \mathbf{R}$ given by $\left(\left(l_{1}, l_{2}\right), t\right) \mapsto\left(\left(l_{2}, l_{1}\right),-t\right)$. Therefore the quotient $(N \times \mathbf{R}) / \mathfrak{I}$ is diffeomorphic to the total space of the non-orientable
line bundle over $\widehat{N}$. Summarizing, we have the following
COROLLARY 4.2. Let $P_{\mathbf{R}}^{2} \cong M \subset P_{\mathbf{R}}^{4}$ be the embedding induced by the classical Veronese embedding $P_{\mathbf{R}}^{2} \hookrightarrow S^{4}$. Then $P_{\mathbf{R}}^{4} \backslash M$ is diffeomorphic to the total space of the non-orientable real line bundle over $\mathrm{SU}(2) / \widetilde{D}_{4}=S^{3} / \widetilde{D}_{4}$. In particular the fundamental group of $P_{\mathbf{R}}^{4} \backslash M$ is the binary dihedral group of order 16 .

Let us now recall that there is a remarkable fibre bundle $\pi: P_{\mathrm{C}}^{3} \rightarrow S^{4}$ with fibre $P_{\mathbf{C}}^{1}$, called the twistor fibration, or also the Calabi-Penrose fibration (we refer to [Sa, SV] for details). The fibres are called the twistor lines. There are several equivalent ways to construct this fibration. The standard way is to think of $P_{\mathbf{C}}^{3}$ as being the homogeneous space $\operatorname{SO}(5, \mathbf{R}) / U(2)$, which fibres over $\operatorname{SO}(5, \mathbf{R}) / \mathrm{SO}(4, \mathbf{R}) \cong S^{4}$ with fibre $\operatorname{SO}(4, \mathbf{R}) / U(2) \cong S^{4} \cong P_{\mathbf{C}}^{1}$. A more geometric way of describing this twistor fibration is to consider $S^{4}$ as being the quaternionic projective line $P_{\mathcal{H}}^{1}$, of right quaternionic lines in the quaternionic plane $\mathcal{H}^{2}$ (regarded as a 2 -dimensional right $\mathcal{H}$-module). That is, for $q:=\left(q_{1}, q_{2}\right) \in \mathcal{H}^{2}(q \neq(0,0))$, the right quaternionic line passing through $q$ is the linear space

$$
R_{q}:=\left\{\left(q_{1} \lambda, q_{2} \lambda\right) \mid \lambda \in \mathcal{H}\right\} .
$$

We can identify $\mathcal{H}^{2}$ with $\mathbf{C}^{4}$ via the $\mathbf{R}$-linear map given by $\left(q_{1}, q_{2}\right) \mapsto$ $\left(z_{1}, z_{2}, z_{3}, z_{4}\right)$, where $q_{1}=z_{1}+z_{2} \mathbf{j}=x_{1}+x_{2} \mathbf{i}+x_{3} \mathbf{j}+x_{4} \mathbf{k}$ and $q_{2}=z_{3}+z_{4} \mathbf{j}=$ $y_{1}+y_{2} \mathbf{i}+y_{3} \mathbf{j}+y_{4} \mathbf{k}$. In this notation $\mathbf{i}, \mathbf{j}, \mathbf{k}$ denote the standard quaternionic units, $z_{1}=x_{1}+x_{2} \mathbf{i}, z_{2}=x_{3}+x_{4} \mathbf{i}, z_{3}=y_{1}+y_{2} \mathbf{i}$ and $z_{4}=y_{3}+y_{4} \mathbf{i}$.

Under this identification each right quaternionic line is invariant under right multiplication by $\mathbf{i}$. Hence such a line is canonically isomorphic to $\mathbf{C}^{2}$. If we think of $P_{\mathbf{C}}^{3}$ as being the space of complex lines in $\mathbf{C}^{4}$, then there is an obvious map $\pi: P_{\mathbf{C}}^{3} \rightarrow S^{4}$, whose fibre over a point $H \in P_{\mathcal{H}}^{1}$ is the space of complex lines in the given right quaternionic line $H \cong \mathbf{C}^{2}$; thus the fibre is $P_{\mathrm{C}}^{1}$.

The group Conf $_{+}\left(S^{4}\right)$ of orientation preserving conformal automorphisms of $S^{4}$ is isomorphic to $\operatorname{PL}(2, \mathcal{H})$, the projectivization of the group of $2 \times 2$, invertible, quaternionic matrices. This is naturally a subgroup of $P \mathrm{SL}(4, \mathbf{C})$, since every quaternion corresponds to a couple of complex numbers. Hence $\operatorname{Conf}_{+}\left(S^{4}\right)$ has a canonical lifting to a group of holomorphic transformations of $P_{\mathrm{C}}^{3}$, carrying twistor lines into twistor lines.

Let us split (differentiably) the tangent bundle of $P_{\mathbf{C}}^{3}$ into a horizontal subbundle and a "vertical" sub-bundle (the bundle tangent to the twistor fibres),
via the Levi-Civita connexion of the metric. Since the lifting of $\operatorname{Conf}_{+}\left(S^{4}\right)$ permutes the twistor lines, this action on $T P_{\mathbf{C}}^{3}$ preserves the decomposition into horizontal and vertical sub-bundles. By [SV], the action on the vertical subbundle is by isometries with respect to the Fubini-Study metric (which is just the standard metric on $S^{2}$ ). We remark that the horizontal bundle is a holomorphic complex sub-bundle of rank two of the complex tangent bundle of $P_{\mathbf{C}}^{3}$. On this sub-bundle, the action is conformal. However, the group $\operatorname{SO}(5, \mathbf{R})$ is a subgroup of $\operatorname{Conf}_{+}\left(S^{4}\right)$ and, by construction, its induced action on the horizontal sub-bundle is by isometries. Thus we have an isometric action of $\operatorname{SO}(5, \mathbf{R})$ on $P_{\mathbf{C}}^{3}$, with respect to the Fubini-Study metric, which restricts to an isometric action of $\operatorname{SO}(3, \mathbf{R})$ on $P_{\mathbf{C}}^{3}$, via the representation $\Gamma$ of this group in $\operatorname{SO}(5, \mathbf{R})$ discussed earlier. We denote this latter action of $\operatorname{SO}(3, \mathbf{R})$ on $P_{\mathbf{C}}^{3}$ by $\check{\Gamma}$.

We notice that the special orbits of the $\operatorname{SO}(3, \mathbf{R})$-action on $S^{4}$ give rise to the special orbits in $P_{\mathbf{C}}^{3}$, each being diffeomorphic to $P_{\mathbf{R}}^{2}$. There is one such orbit for each point in the twistor line over a point in the corresponding special orbit in $S^{4}$. Since the twistor bundle is trivial when restricted to any proper subset of $S^{4}$, it follows that the set of all special orbits of each type is diffeomorphic to $P_{\mathbf{R}}^{2} \times P_{\mathbf{C}}^{1}$. Similar remarks apply to the principal orbits. Moreover, by [HL], each special orbit is a minimal submanifold of $P_{\mathrm{C}}^{3}$, and so is their product $P_{\mathbf{R}}^{2} \times P_{\mathbf{C}}^{1}$ since the projection $P_{\mathbf{C}}^{3} \rightarrow S^{4}$ is a harmonic map which is a Riemannian fibration (i.e. it is transversally isometric), by [EL] and [EV; 7.9]. Thus we have

Theorem 4.3. The action $\check{\Gamma}$ of $\operatorname{SO}(3, \mathbf{R})$ on $P_{\mathbf{C}}^{3}$ is such that:
(1) The action is by elements of $P \mathrm{SU}(4)$, i.e. by isometries of $P_{\mathbf{C}}^{3}$ that permute the twistor lines, sending each twistor line isometrically onto its image.
(2) There are two exceptional types of orbits, each of which is diffeomorphic to $P_{\mathbf{R}}^{2}$. If we denote by $K_{1}$ and $K_{2}$ the union of orbits of each of these two types, then both $K_{1}$ and $K_{2}$ are diffeomorphic to $P_{\mathbf{R}}^{2} \times P_{\mathbf{C}}^{1}$. Furthermore, $K_{1}$ and $K_{2}$ are minimally embedded in $P_{\mathbf{C}}^{3}$.
(3) The principal orbits are diffeomorphic to $F^{3}(2,1)$. Hence the action has cohomogeneity 3.
(4) The functions $h_{1}: P_{\mathbf{C}}^{3} \rightarrow \mathbf{R}$ and $h_{2}: P_{\mathbf{C}}^{3} \rightarrow \mathbf{R}$, given by $h_{1}(Z)=$ $\left(d\left(Z, K_{1}\right)\right)^{2}$ and $h_{2}(Z)=\left(d\left(Z, K_{2}\right)\right)^{2}$, are both Bott-Morse functions with critical set $K_{1} \cup K_{2}$.
(5) The space of orbits is $S^{2} \times[0,1]$.

We may now consider the Hopf fibration $\tilde{\pi}: S^{7} \rightarrow S^{4}$ and we identify $\mathbf{R}^{8} \cong \mathcal{H}^{2}$ in the obvious way.

The group $\mathrm{SU}(2)$ consists of all $2 \times 2$ complex matrices of the form $\left(\begin{array}{cc}z_{1} & z_{2} \\ -\bar{z}_{2} & \bar{z}_{1}\end{array}\right)$ with determinant 1 . This group can be identified with the group $\mathrm{Sp}(1)$ of unit quaternions by mapping each such matrix to the unit quaternion $u=z_{1}+z_{2} \mathbf{j}$. Hence $\operatorname{SU}(2)$ acts by the right on $\mathcal{H}^{2} \cong \mathbf{R}^{8}$ by the map $\left(\left(q_{1}, q_{2}\right), u\right) \mapsto\left(q_{1} u, q_{2} u\right)$, for each $u \in \operatorname{Sp}(1)$ and $\left(q_{1}, q_{2}\right) \in \mathcal{H}^{2}$. This action leaves invariant each right line $R_{q}\left(q=\left(q_{1}, q_{2}\right)\right)$ and it acts as an isometry on this line.

On the other hand, each complex number is a quaternion, so each matrix in $\mathrm{SU}(2)$ can be regarded as a $2 \times 2$ quaternionic matrix in $\operatorname{GL}(2, \mathcal{H})$, the group of all invertible $2 \times 2$ quaternionic matrices $A=\left(\begin{array}{ll}a & b \\ c & d\end{array}\right)$. This group acts on $\mathcal{H}^{2}$ by the left according to the formula

$$
q=\left(q_{1}, q_{2}\right) \mapsto\left(a q_{1}+b q_{2}, c q_{1}+d q_{2}\right)=A(q),
$$

and induces the aforementioned action of $P \operatorname{SL}(2, \mathcal{H})$ on $P_{\mathcal{H}}^{1} \cong S^{4}$.
We thus have an action of $\operatorname{SU}(2) \times \operatorname{Sp}(1)$ on $\mathbf{R}^{8} \cong \mathcal{H}^{2}$ by the formula

$$
\left((g, u),\left(q_{1}, q_{2}\right)\right) \mapsto\left(a_{g} q_{1} u+b_{g} q_{2} u, c_{g} q_{1} u+d_{g} q_{2} u\right)
$$

for each $g=\left(\begin{array}{ll}a_{g} & b_{g} \\ c_{g} & d_{g}\end{array}\right)$ in $\mathrm{SU}(2)$. This action induces a natural action

$$
\widehat{\Gamma}:(\mathrm{SU}(2) \times \mathrm{SU}(2)) \times S^{7} \rightarrow S^{7}
$$

on the sphere $S^{7}$, and this action is a lifting of the action $\Gamma$ considered in Section 3, i.e. the following diagram is commutative:

$$
\begin{array}{ccc}
(\mathrm{SU}(2) \times \mathrm{SU}(2)) \times S^{7} & \stackrel{\widehat{\Gamma}}{ } S^{7} \\
f \times \tilde{\pi} \downarrow & & \tilde{\pi} \downarrow \\
\mathrm{SO}(3, \mathbf{R}) \times S^{4} & \xrightarrow{\Gamma} & S^{4},
\end{array}
$$

where $f(g, u)=\phi(g), \phi$ being the canonical epimorphism from $\mathrm{SU}(2)$ to $\mathrm{SO}(3, \mathbf{R}))$. It is clear that $\widehat{\Gamma}((-I d,-1), x)=x$ for all $x \in S^{7}$, so $\widehat{\Gamma}$ actually descends to an action of

$$
\mathrm{SO}(4) \cong \mathrm{SU}(2) \times \mathrm{Sp}(1) /(\mathbf{Z} / 2 \mathbf{Z})
$$

on $S^{7}$. We have

THEOREM 4.4. This $\mathrm{SO}(4)$ action on $S^{7}$ satisfies:
(1) It is a hyperpolar isometric action of cohomogeneity 1, with space of orbits the interval $\left[0, \frac{\pi}{2}\right]$.
(2) The two exceptional orbits are both diffeomorphic to $P_{\mathbf{R}}^{2} \times S^{3}$. and both are minimally embedded in $S^{7}$.
(3) The principal orbits are diffeomorphic to $F^{3}(2,1) \times S^{3}$.
(4) The square of the distance functions to the exceptional orbits are both Bott-Morse functions.
(5) The union of the two exceptional orbits, both copies of $P_{\mathbf{R}}^{2} \times S^{3}$, is the Spanier-Whitehead dual of one principal orbit $F^{3}(2,1) \times S^{3}$.

We notice that the action of $\mathrm{SO}(n+1)$ on $\mathbf{C}^{n+1}$ considered in Section 2 also provides, when $n=3$, an isometric action of cohomogeneity 1 of $\mathrm{SO}(4)$ on $S^{7}$. However, in this case the two special orbits are the inverse images of the quadric $Q$ and the real projective space $\Pi \cong P_{\mathbf{R}}^{3}$ under the projection $S^{7} \rightarrow P_{\mathrm{C}}^{3}$. So this action is not equivalent to the "twistorial" one given by Theorem 4.4.

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[^0]:    ${ }^{2}$ ) This orbit description of $S^{4}$ is also given in [Ma2].

