

# 4. HIGHER SPHERE GEOMETRY

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and the  $n0$ -entry is

$$\omega = dx_n - p_1 dx_1 - \dots - p_{n-1} dx_{n-1}.$$

This identifies the contact structure with the classical one as in 2.12.

3.5 The real contact structure on the  $(2n-1)$ -dimensional space of co-directions in real projective space  $P^n$  is described by viewing all quantities in the foregoing discussion as being real. Especially,  $G_0$  of 2.11 is the connected centerless group  $PSL(n+1; \mathbf{R})$  consisting of real contact automorphisms.

#### 4. HIGHER SPHERE GEOMETRY

4.1 In complex Euclidean space  $E^n$ , the equation

$$x_1'^2 + \dots + x_n'^2 - 2a_1 x_1' - \dots - 2a_n x_n' + C = 0$$

describes a sphere with center  $(a_1, \dots, a_n)$  and complex radius  $r$  given by

$$r^2 = a_1^2 + \dots + a_n^2 - C.$$

When  $r \neq 0$ , the two choices of sign for  $r$  is said to give two "orientations" to the sphere. Thus, the  $n+2$  coordinates  $a_1, \dots, a_n, r, C$ , which are related by

$$a_1^2 + \dots + a_n^2 - r^2 - C = 0,$$

describe the space of oriented spheres in  $E^n$  [6, §25].

Introduce homogeneous coordinates by

$$a_i = \frac{\alpha_i}{v}, \quad r = \frac{\lambda}{v}, \quad C = \frac{\mu}{v},$$

$i = 1, 2, \dots, n$ . Then the oriented spheres of  $E^n$  correspond to certain points of the quadric  $\Psi^{n+1}$  in  $P^{n+2}$  described by

$$\alpha_1^2 + \dots + \alpha_n^2 - \lambda^2 - \mu v = 0.$$

The sphere corresponding to the point  $(\alpha_1, \dots, \alpha_n, \lambda, \mu, v)$  of  $\Psi^{n+1}$  is

$$v(x_1'^2 + \dots + x_n'^2) - 2\alpha_1 x_1' - \dots - 2\alpha_n x_n' + \mu = 0.$$

Ordinary spheres have finite nonzero radius  $r$ , so  $v \neq 0$ . For  $v = 0$ , we obtain oriented hyperplanes. For  $\lambda = 0$ , we obtain point spheres or hyperplanes with isotropic hyperplane coordinate vector; these carry no

orientation. If we include these special cases as spheres of  $E^n$ , then  $\Psi^{n+1}$  is the space of all oriented spheres in  $E^n$ .

Two spheres in  $E^n$  with centers  $(a_1, \dots, a_n)$ ,  $(a'_1, \dots, a'_n)$  and radii  $r, r'$  respectively are tangent, orientations taken into account, if

$$(a_1 - a'_1)^2 + \dots + (a_n - a'_n)^2 = (r - r')^2.$$

Use  $a_1^2 + \dots + a_n^2 = r^2 + C$  for both spheres to obtain the condition for tangency as

$$2a_1 a'_1 + \dots + 2a_n a'_n - 2rr' - C - C' = 0$$

or, in homogeneous coordinates,

$$2\alpha_1 \alpha'_1 + \dots + 2\alpha_n \alpha'_n - 2\lambda \lambda' - \mu \nu' - \nu \mu' = 0.$$

Hence, two spheres of  $E^n$  are tangent when their corresponding points in  $\Psi^{n+1}$  are conjugate, that is, the line joining these points lies entirely in  $\Psi^{n+1}$  [6, §25].

4.2. A pencil of mutually tangent spheres in  $E^n$  corresponds to a line in  $\Psi^{n+1}$ . This pencil of spheres determines an "oriented complex co-direction" in  $E^n$  since it contains a point sphere and an incident oriented hyperplane. Corresponding to the hyperplane

$$x'_n - x_n = p_1 (x'_1 - x_1) + \dots + p_{n-1} (x'_{n-1} - x_{n-1})$$

at the point  $(x_1, \dots, x_n)$  is the line

$$\begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_{n-1} \\ \alpha_n \\ \hline \lambda \\ \mu \\ \nu \end{bmatrix} = \begin{bmatrix} x_1 \\ \vdots \\ x_{n-1} \\ x_n \\ \hline 0 \\ xx \\ 1 \end{bmatrix} + t \begin{bmatrix} -p_1 \\ \vdots \\ -p_{n-1} \\ 1 \\ \hline -\sqrt{pp+1} \\ 2(x_n - px) \\ 0 \end{bmatrix}$$

of  $\Psi^{n+1}$ , where

$$xx = \sum_{i=1}^n x_i^2, \quad px = \sum_{i=1}^{n-1} p_i x_i, \quad pp = \sum_{i=1}^{n-1} p_i^2;$$

this is the pencil of spheres

$$\sum_{i=1}^{n-1} (x'_i - x_i + t p_i)^2 + (x'_n - x_n - t)^2 = t^2 \left( \sum_{i=1}^{n-1} p_i^2 + 1 \right)$$

passing through  $(x_1, \dots, x_n)$  and having their centers on the line normal to the hyperplane at this point.

For later calculations it will be convenient to replace  $-p, \dots, -p_{n-1}, 1$  by homogeneous  $u_1, \dots, u_{n-1}, u_n$ . The line in  $\Psi^{n+1}$  corresponding to the hyperplane

$$u_1(x'_1 - x_1) + \dots + u_n(x'_n - x_n) = 0$$

at the point  $(x_1, \dots, x_n)$  is then

$$\begin{array}{|c|} \hline \alpha_1 \\ \hline \vdots \\ \hline \alpha_{n-1} \\ \hline \alpha_n \\ \hline \lambda \\ \hline \mu \\ \hline \nu \\ \hline \end{array} = \begin{array}{|c|} \hline x_1 \\ \hline \vdots \\ \hline x_{n-1} \\ \hline x_n \\ \hline 0 \\ \hline xx \\ \hline 1 \\ \hline \end{array} + t \begin{array}{|c|} \hline u_1 \\ \hline \vdots \\ \hline u_{n-1} \\ \hline u_n \\ \hline -\sqrt{uu} \\ \hline 2ux \\ \hline 0 \\ \hline \end{array},$$

where

$$xx = \sum_{i=1}^n x_i^2, \quad ux = \sum_{i=1}^n u_i x_i, \quad uu = \sum_{i=1}^n u_i^2.$$

Any convenient condition may be imposed on  $uu$ .

4.3. The contact structure on the  $(2n-1)$ -dimensional space of lines in  $\Psi^{n+1}$ , that is, the space of oriented co-directions in complex Euclidean space  $E^n$ , is obtained when the construction of 2.10. is carried out for the simple complex Lie algebra of type  $B_l$  or  $D_l$ ,  $l \geq 2$  and  $l \geq 3$  respectively. However, it will be simpler to identify quantities geometrically if

we proceed by using the description of 2.7, since now the groups are determined first.

Let

$$A = \left[ \begin{array}{c|ccc} 2 \cdot 1_n & & & 0 \\ \hline & & & \\ & & -2 & 0 & 0 \\ & 0 & 0 & 0 & -1 \\ & & & 0 & -1 & 0 \end{array} \right]$$

be the matrix of the quadratic form defining  $\Psi^{n+1}$  in  $P^{n+1}$ .  $SO(A; \mathbb{C})$ , the special orthogonal group of this form, consists of matrices  $g$  in  $SL(n+3; \mathbb{C})$  for which  ${}^t g A g = A$ . The connected centerless simple group  $G = PSO(A; \mathbb{C}) = SO(A; \mathbb{C})/\{\text{center}\}$  is transitive on the lines of  $\Psi^{n+1}$  by Witt's theorem. Let  $l_0$  be the line

$$\begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_{n-1} \\ \alpha_n \\ \hline \lambda \\ \mu \\ \nu \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 0 \\ \hline 0 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ \hline -1 \\ 0 \\ 0 \end{bmatrix}$$

of  $\Psi^{n+1}$ , joining

$${}^t(0, \dots, 0, 0 \mid 0, 0, 1) \quad \text{and} \quad {}^t(0, \dots, 0, 1 \mid -1, 0, 0);$$

this corresponds to the pencil of spheres

$$\sum_{i=1}^{n-1} x_i'^2 + (x_n' - t)^2 = t^2$$

tangent to the hyperplane  $x_n = 0$  at the origin of  $E^n$ , suitably oriented, as in 4.2. Let  $P$  denote the isotropy subgroup of  $l_0$ . Then

- $G/P$  = space of lines in  $\Psi^{n+1}$
- = space of pencils of mutually tangent oriented spheres in  $E^n$
- = space of oriented co-directions in complex  $E^n$ .

The Lie algebra  $\mathfrak{g}$  of  $G$  consists of  $(n+3)$  by  $(n+3)$  matrices  $X$  for which  ${}^tXA + AX = 0$ . The matrices of  $\mathfrak{g}$  are of the form

$$\left[ \begin{array}{ccc|ccc} & & & b_1 & c_1 & d_1 \\ & & & \vdots & \vdots & \vdots \\ n \text{ by } n \text{ skew-} & & & b_{n-1} & c_{n-1} & d_{n-1} \\ \text{symmetric} & & & b_n & c_n & d_n \\ \hline b_1 \dots b_{n-1} & b_n & & 0 & c & d \\ 2d_1 \dots 2d_{n-1} & 2d_n & & -2d & e & 0 \\ 2c_1 \dots 2c_{n-1} & 2c_n & & -2c & 0 & -e \end{array} \right].$$

$P$  consists of those elements of  $G$  which send the subspace of  $\mathbb{C}^{n+3}$  spanned by  ${}^t(0, \dots, 0, 0 \mid 0, 0, 1)$  and  ${}^t(0, \dots, 0, 1 \mid -1, 0, 0)$

into itself; the Lie algebra  $\mathfrak{p}$  of  $P$  consists of those elements of  $\mathfrak{g}$  which do the same. Hence, the matrices of  $\mathfrak{p}$  are of the form

$$\left[ \begin{array}{ccc|ccc} & & & b_1 & b_1 & c_1 & 0 \\ & & & \vdots & \vdots & \vdots & \vdots \\ (n-1) \text{ by } (n-1) & & & b_{n-1} & b_{n-1} & c_{n-1} & 0 \\ \text{skew-symmetric} & & & & & & \\ \hline -b_1 \dots -b_{n-1} & 0 & & b_n & c_n & -d \\ b_1 \dots b_{n-1} & b_n & & 0 & c & d \\ 0 \dots 0 & -2d & & -2d & e & 0 \\ 2c_1 \dots 2c_{n-1} & 2c_n & & -2c & 0 & -e \end{array} \right].$$

Note that  $\mathfrak{g}$  and  $\mathfrak{p}$  have dimensions  $\frac{1}{2}(n+3)(n+2)$  and  $\frac{1}{2}(n-1)(n-2) + 2n + 3 = \frac{1}{2}(n+3)(n+2) - 2n + 1$ , respectively, in agreement with  $G/P$  having dimension  $2n-1$ .

4.4. For  $n \geq 2$ , set  $n+3 = 2l+1$  or  $2l$  according as  $n$  is even or odd.  $\mathfrak{g}$  is of type  $B_l$  or  $D_l$ ,  $l \geq 2$  and  $l \geq 3$  respectively.

For Cartan subalgebra  $\mathfrak{h}$  of  $\mathfrak{g}$  take matrices of the form

$$H = \text{diag} \left[ \begin{array}{c} 0 \\ \left[ \begin{array}{cc} 0 & h_1 \\ -h_1 & 0 \end{array} \right], \dots, \left[ \begin{array}{cc} 0 & h_{l-2} \\ -h_{l-2} & 0 \end{array} \right], \left[ \begin{array}{cccc} 0 & h_{l-1} & 0 & 0 \\ h_{l-1} & 0 & 0 & 0 \\ 0 & 0 & h_l & 0 \\ 0 & 0 & 0 & -h_l \end{array} \right] \end{array} \right];$$

the first row and column occur only in case  $B_l$ , it is suppressed for case  $D_l$ . The Killing form of  $\mathfrak{g}$  is  $\langle X, Y \rangle = (n+1) \text{tr}(XY)$ , but we replace this with  $\langle X, Y \rangle = \frac{1}{2} \text{tr}(XY)$  for convenience.

Let  $W$  in  $\mathfrak{p}$  be

$$W = \left[ \begin{array}{ccc|ccc} 0 & 0 & 0 & & & \\ \hline 0 & 0 & 0 & & & \\ & & 0 & 0 & -\frac{1}{2} & 0 \\ \hline 0 & 0 & 0 & 0 & \frac{1}{2} & 0 \\ & & 0 & 0 & 0 & 0 \\ \hline & & -1 & -1 & 0 & 0 \end{array} \right]$$

For  $H$  in  $\mathfrak{h}$  we have  $[H, W] = -(h_{l-1} + h_l)W$ , so  $\rho(H) = -(h_{l-1} + h_l)$  is a root of  $\mathfrak{g}$  with respect to  $\mathfrak{h}$  and  $W = E_\rho$  is the corresponding root vector.

For  $X$  in  $\mathfrak{g}$  as described in 4.3, direct calculation shows  $[X, W] = 0$  implies  $X$  is in  $\mathfrak{p}$  and  $b_n + e = 0$ ; thus the centralizer of  $W$  in  $\mathfrak{g}$  consists of those elements of  $\mathfrak{p}$  with  $b_n + e = 0$ . For  $X$  in  $\mathfrak{p}$  now, the same calculation gives  $[X, W] = -(b_n + e)W$ , so  $[X, W] = \rho(X)W$  with  $\rho$  extended to  $\mathfrak{p}$  by  $\rho(X) = -(b_n + e)$ . Finally,  $W$  is orthogonal to  $\mathfrak{p}$  with respect to the Killing form. Hence,  $(a', c', b')$  of 2.7 are satisfied, and  $W$  is the element of  $\mathfrak{g}$  giving the contact structure on  $G/P$ .

The origin of the element  $W$  is not immediately evident. It was obtained by determining the maximal root and corresponding root vector for Lie algebras of type  $B_l$  and  $D_l$  when the quadratic form is

$$\xi_0^2 + 2\xi_1\xi_{l+1} + \dots + 2\xi_l\xi_{2l}$$

and then passing to the form

$$\alpha_1^2 + \dots + \alpha_n^2 - \lambda^2 - \mu\nu$$

by conjugating by the element of  $PSL(n+3; \mathbf{C})$  which corresponds to the "line-sphere transformation". This will be described further in the next section.

4.5. Let  $\mathfrak{m}$  be the  $(2n-1)$ -dimensional supplement to  $\mathfrak{p}$  in  $\mathfrak{g}$  consisting of matrices of the form

$$\left[ \begin{array}{cccc|ccc} & & & -b_1 & b_1 & 0 & d_1 \\ & & & \vdots & \vdots & \vdots & \vdots \\ & 0 & & -b_{n-1} & b_{n-1} & 0 & d_{n-1} \\ & & & \vdots & \vdots & \vdots & \vdots \\ b_1 & \dots & b_{n-1} & 0 & 0 & 0 & d_n \\ \hline b_1 & \dots & b_{n-1} & 0 & 0 & 0 & d_n \\ 2d_1 & \dots & 2d_{n-1} & 2d_n & -2d_n & 0 & 0 \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 \end{array} \right],$$



cf. 2.12. For  $X$  in  $\mathfrak{m}$  we have

$$X^2 = \begin{bmatrix} 0 & & & & 0 \\ & -bb & & bb & 0 & bd \\ & & & & & \\ \hline & -bb & & bb & 0 & bd \\ & & & & & \\ 0 & -2bd & & 2bd & 0 & 2dd \\ & & & & & \\ & 0 & & 0 & 0 & 0 \end{bmatrix}$$

where

$$bb = \sum_{i=1}^{n-1} b_i^2, \quad bd = \sum_{i=1}^{n-1} b_i d_i, \quad dd = \sum_{i=1}^{n-1} d_i^2.$$

The product of any three matrices of  $\mathfrak{m}$  is zero. Especially,

$$\exp X = 1_{n+3} + X + \frac{1}{2} X^2.$$

In order to establish classically identifiable coordinates on  $G/P$  as in 2.12, we must determine  $X$  in  $\mathfrak{m}$  so that  $(\exp X) \cdot l_0$  is the line of  $\Psi^{n+1}$  described in 4.2. With  $X$  in  $\mathfrak{m}$  as above,  $(\exp X) \cdot l_0$  is the line joining the points

$$(\exp X) \cdot \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 0 \\ \hline 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} d_1 \\ \vdots \\ d_{n-1} \\ d_n + \frac{1}{2} bd \\ \hline d_n + \frac{1}{2} bd \\ dd \\ 1 \end{bmatrix}$$

and

$$(\exp X) \cdot \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ \hline -1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -2b_1 \\ \vdots \\ -2b_{n-1} \\ 1 - bb \\ \hline -1 - bb \\ 4d_n - 2bd \\ 0 \end{bmatrix}$$

On this line we can identify the point sphere when  $\lambda = 0$ , giving

$$\begin{bmatrix} d_1 \\ \vdots \\ d_{n-1} \\ d_n + \frac{1}{2} bd \\ \hline d_n + \frac{1}{2} bd \\ dd \\ 1 \end{bmatrix} + \frac{d_n + \frac{1}{2} bd}{1 + bb} \begin{bmatrix} -2b_1 \\ \vdots \\ -2b_{n-1} \\ 1 - bb \\ \hline -1 - bb \\ 4d_n - 2bd \\ 0 \end{bmatrix} = \begin{bmatrix} x_1 \\ \vdots \\ x_{n-1} \\ x_n \\ \hline 0 \\ xx \\ 1 \end{bmatrix},$$

and the incident oriented hyperplane when  $v = 0$ , giving

$$\begin{bmatrix} -2b_1 \\ \vdots \\ -2b_{n-1} \\ 1 - bb \\ \hline -1 - bb \\ 4d_n - 2bd \\ 0 \end{bmatrix} = \begin{bmatrix} u_1 \\ \vdots \\ u_{n-1} \\ u_n \\ \hline -\sqrt{uu} \\ 2ux \\ 0 \end{bmatrix} .$$

These equations will be satisfied if we impose the condition  $\sqrt{uu} = 1 + bb$  on  $uu$ , or

$$u_i = -2b_i, \quad u_n = 1 - bb,$$

$i = 1, 2, \dots, n-1$ , and then set

$$b_i = -\frac{1}{2} u_i,$$

$$d_i = x_i - \frac{1}{2} u_i x_n, \quad i = 1, 2, \dots, n-1$$

$$d_n = \frac{1}{4} \sum_{i=1}^{n-1} u_i x_i + \frac{1}{2} x_n .$$

Thus, this choice of  $X$  establishes the classically identifiable coordinates  $x_1, \dots, x_n, u_1, \dots, u_n$  on  $G/P$  as in 2.12 and 4.2.

4.6. From 2.12, the form  $\omega$  on  $G/P$  is obtained as

$$\omega = \langle W, (\exp X)^{-1} d(\exp X) \rangle$$

with  $(\exp X)^{-1} d(\exp X) = dX - \frac{1}{2} [X, dX] .$

Take  $X$  as in 4.5 and let the entries of  $dX$  be denoted as those of  $X$  with primes affixed. Then

$$(\exp X)^{-1} d (\exp X) = \left[ \begin{array}{cccc|cccc} & & -b_1' & & b_1' & 0 & & d_1' \\ & 0 & \vdots & & \vdots & \vdots & & \vdots \\ & & -b_{n-1}' & & b_{n-1}' & 0 & & d_{n-1}' \\ b_1' \dots b_{n-1}' & & 0 & & 0 & 0 & d_n' - \frac{1}{2}c & \\ \hline b_1' \dots b_{n-1}' & & 0 & & 0 & 0 & d_n' - \frac{1}{2}c & \\ 2d_1' \dots 2d_{n-1}' & 2d_n' - c & & -2d_n' + c & 0 & & & 0 \\ 0 \dots 0 & 0 & & 0 & 0 & 0 & & 0 \end{array} \right]$$

where

$$c = \sum_{i=1}^{n-1} (b_i d_i' - d_i b_i'),$$

and consequently, from the definition of  $W$  in 4.4,  $\omega = c - 2d_n'$ . Using the expressions in 4.5 for  $b_1, \dots, b_{n-1}, d_1, \dots, d_n$  in terms of  $x_1, \dots, x_n, u_1, \dots, u_n$ , we obtain

$$\omega = - \sum_{i=1}^{n-1} u_i dx_i - \left[ 1 - \frac{1}{4} \sum_{i=1}^{n-1} u_i^2 \right] dx_n$$

or, since  $1 - \frac{1}{4} \sum_{i=1}^{n-1} u_i^2 = u_n$ ,

$$\omega = - (u_1 dx_1 + \dots + u_n dx_n).$$

This identifies the contact structure with the classical one as in 2.12 and 4.2.

4.7. The real contact structure on the  $(2n-1)$ -dimensional space of oriented co-direction in real Euclidean space  $E^n$  is described by viewing all quantities in the foregoing discussion as being real. Especially,  $G_0$  of 2.11 is the two-component centerless group  $PSO(A; \mathbf{R})$  consisting of real contact automorphisms.