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Autor(en): Steinig, J.<br>Objekttyp: Article<br>Zeitschrift: Commentarii Mathematici Helvetici

Band (Jahr): 44 (1969)

PDF erstellt am: 25.04.2024

Persistenter Link: https://doi.org/10.5169/seals-33783

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# The Changes of Sign of Certain Arithmetical Error-Terms 

J. Steinig

## 1. Introduction

If $\pi(x)$ denotes the number of primes not exceeding $x$, and $\operatorname{li} x=\int_{2}^{x}(\log t)^{-1} d t(x \geqslant 2)$, then the prime number theorem states that $\pi(x) \sim \operatorname{li} x$, as $x \rightarrow \infty$. The error-term in this asymptotic relation is $\pi(x)-\mathrm{li} x$, and it was for long conjectured that $\pi(x)-\operatorname{li} x<0$ for all large $x$. J. E. Littlewood proved this conjecture false by showing [8] that $\pi(x)-\operatorname{li} x=\Omega_{ \pm}\left(x^{1 / 2} \log \log \log x / \log x\right)$. The prime number theorem is equivalent to the assertion that $\psi(x) \sim x$, where $\psi$ is the well-known Chebyshev function. The error-term here is $\psi(x)-x$, and it changes sign an infinity of times, as shown by Phragmén [9]. Phragmén's result is a corollary of a general theorem of Landau's [7] on Dirichlet integrals. Pólya [11] refined Landau's theorem, and considered, as a particular case, the problem of estimating the number of changes of sign of $\psi(x)-x$ in the interval $1<x \leqslant t$. If $N(t)$ denotes that number, then Pólya's result implies that

$$
\begin{equation*}
\varlimsup_{t \rightarrow \infty} \frac{N(t)}{\log t}>0 . \tag{1.1}
\end{equation*}
$$

The original proof of Pólya's theorem contains a gap, first recognized by Pólya himself, which is filled in § 2. Pólya's theorem can be applied, as we shall show in $\S 2.3$, to the error-term associated with the arithmetical function $r_{k}(n)$, which is the number of representations of an integer $n$ as a sum of $k$ squares $(k \geqslant 2)$. This application is made possible by the fact that the Dirichlet series $\sum_{n=1}^{\infty} r_{k}(n) \cdot n^{-s}$ represents the Epstein zeta-function $\zeta_{k}(s)$, which satisfies Hecke's functional equation, namely

$$
\begin{equation*}
\pi^{-s} \Gamma(s) \zeta_{k}(s)=\pi^{s-k / 2} \Gamma\left(\frac{k}{2}-s\right) \zeta_{k}\left(\frac{k}{2}-s\right) \tag{1.2}
\end{equation*}
$$

and this equation implies a fundamental identity given by K . Chandrasekharan and Raghavan Narasimhan [2].

More generally, we consider in $\S 3$ the functional equation of Chandrasekharan and Narasimhan, which includes (1.2), and study the problem of change of sign of the "error-term" associated with the coefficients of Dirichlet series which satisfy such an equation. Thus, given an equation such as

$$
\begin{equation*}
\Delta(s) \varphi(s)=\Delta(\delta-s) \varphi(\delta-s) \tag{1.3}
\end{equation*}
$$

where $\delta$ is a real number, $\Delta(s)$ is a product of a finite number of gamma functions, say $\Delta(s)=\prod_{v=1}^{N} \Gamma\left(\alpha_{v} s+\beta_{v}\right)$, and $\varphi(s)=\sum_{n=1}^{\infty} a_{n} \lambda_{n}^{-s}$, we define for $\varrho \geqslant 0$,

$$
A_{\lambda}^{e}(x)=\frac{1}{\Gamma(\varrho+1)} \sum_{\lambda_{n} \leqslant x}^{\prime} a_{n}\left(x-\lambda_{n}\right)^{\varrho}
$$

which is the fractional integral of order $\varrho$ of the summatory function $A_{\lambda}^{0}(x) \equiv A(x)=$ $\sum_{\lambda_{n} \leqslant x}^{\prime} a_{n}$. Chandrasekharan and Narasimhan have shown [3] that corresponding to the equation (1.3), there exists a "residual function" $S_{e}(x)$, such that

$$
\begin{equation*}
\operatorname{Re}\left\{A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)\right\}=\Omega_{ \pm}\left(x^{\theta}\right) \tag{1.4}
\end{equation*}
$$

where $\Theta=\left\{A \delta+(2 A-1) \varrho-\frac{1}{2}\right\} / 2 A$, with $A=\sum_{v=1}^{N} \alpha_{v}$. (A similar result holds for the imaginary part of $A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)$.) The proof of this general $\Omega$-theorem rests on the fact that equation (1.3) implies, for sufficiently large $\varrho$, the formula

$$
\begin{equation*}
x^{c}\left\{A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)\right\}=\sum_{n=1}^{\infty} c_{n} \cdot \cos \left(\gamma_{n} x^{1 / 2 A}+D\right)+g(x) \tag{1.5}
\end{equation*}
$$

where $c$ is a real constant, $\sum_{n=1}^{\infty}\left|c_{n}\right|<\infty, 0<\gamma_{1}<\gamma_{2}<\cdots<\gamma_{n} \rightarrow \infty, A$ is as in (1.4), $D$ is a real constant, and $g(x)=o(1)$, as $x \rightarrow \infty$.

Clearly, (1.4) implies that the real part of the "error-term" $A_{\lambda}^{e}(x)-S_{0}(x)$ has an infinity of changes of sign in the interval $0<x<\infty$. In this paper, we obtain a lower bound for the number of changes of sign of $\operatorname{Re}\left\{A_{\lambda}^{\varrho}(x)-S_{e}(x)\right\}$, and of $\operatorname{Im}\left\{A_{\lambda}^{\varrho}(x)-\right.$ $\left.S_{\varrho}(x)\right\}$, in a given interval (Theorem 4.1). This is achieved by combining asymptotic formula (1.5) with an argument introduced by Liouville, and later applied by Pólya [12] to the study of the changes of sign of certain trigonometrical series. In the case $\varrho=0$, Theorem 4.1 gives a lower bound for the number of changes of sign, in any interval, of the error-term associated with such arithmetical functions as $d(n)$, the number of positive divisors of the positive integer $n$, or $r_{k}(n)$, or Ramanujan's function $\tau(n)$.

It may be remarked that the results obtained by appealing to Pólya's theorem are weaker than those obtained in § 4 from asymptotic formula (1.5), since Pólya's theorem gives only a "lim sup result", as in (1.1), for an interval $0<x \leqslant t$, whereas Theorem 4.1 gives a lower bound for the number of changes of sign of the error-term under consideration in any given interval.

The problems discussed in this paper were suggested to me by Professor K. Chandrasekharan; I take pleasure in recording here my gratitude for his advice and constant encouragement.

## 2. Pólya's Theorem

2.1. If $\omega$ is a function of the real variable $u$, bounded and integrable over every finite interval $1 \leqslant u \leqslant U$, and $s$ is a complex number, written $s=\sigma+i t$, where $\sigma$ and $t$ are real, and $i^{2}=-1$, then the integral $\int_{1}^{\infty} \omega(u) u^{-s} d u$ is called a Dirichlet integral.

A theorem of Landau's ([7]; [6], p. 88) states that if $\omega(u)$ is real-valued, and is of constant sign for all sufficiently large $u$, and if the integral $f(s)=\int_{1}^{\infty} \omega(u) u^{-s} d u$ has a finite abscissa of convergence $\sigma=\sigma_{0}$, then the real point $s=\sigma_{0}$ of its line of convergence is a singularity of the function $f(s)$ which it represents.

In order to state this theorem in a more convenient form, we introduce a function $W(x)$ associated with the sign of $\omega(u)$. We assume that $\omega(u)$ is either of constant sign for $u>1$, or that there exists a sequence $\left(u_{n}\right), 1=u_{0}<u_{1}<u_{2}<\cdots$, with no finite point of accumulation, such that

$$
\begin{equation*}
(-1)^{n} \omega(u) \geqslant 0 \quad \text { for } \quad u_{n-1}<u<u_{n} \tag{2.1}
\end{equation*}
$$

and such that $\omega(u)$ is not identically zero in any of the intervals $u_{n-1}<u<u_{n}$. If $\omega(u)$ is of constant sign for $u>1$, then $W(x)=0$; otherwise we define $W(x)=n$ for $u_{n-1} \leqslant x<u_{n}$. Thus $W(x)$ is simply the number of changes of sign of $\omega(u)$ in the interval $1<u \leqslant x$. LANDAU's theorem then takes the following form.

Theorem A (Landau). Let $\int_{1}^{\infty} \omega(u) u^{-s} d u$ have a finite abscissa of convergence $\sigma_{0}$. Let $\Phi(s)=\int_{1}^{\infty} \omega(u) u^{-s} d u$ be regular in the half-plane $\sigma>\theta$, but in no larger half-plane $\sigma>\theta-\varepsilon(\varepsilon>0)$. If $\Phi(s)$ is regular at $s=\theta$, then $\lim _{x \rightarrow \infty} W(x)=+\infty$.

Pólya's extension [11] of Landau's theorem is as follows.
Theorem B (Pólya). Let the integral $\int_{1}^{\infty} \omega(u) u^{-s} d u$ have a finite abscissa of con-
vergence $\sigma_{0}$. Let

$$
\begin{equation*}
\Phi(s)=\int_{1}^{\infty} \omega(u) u^{-s} d u \tag{2.2}
\end{equation*}
$$

be regular in the half-plane $\sigma>\theta$, but in no larger half-plane $\sigma>\theta-\varepsilon(\varepsilon>0)$. Further, let $\Phi(s)$ be meromorphic in $\sigma \geqslant \theta-b$, for some $b>0$. Then,

$$
\begin{equation*}
\varlimsup_{x \rightarrow \infty} \frac{W(x)}{\log x} \geqslant \frac{\gamma}{\pi} \tag{2.3}
\end{equation*}
$$

where $\gamma$ is defined as follows: If $\Phi(s)$ has poles on the line $\sigma=\theta$, then $s=\theta+i \gamma$ is the pole with the smallest non-negative imaginary part; otherwise, $\gamma=+\infty$.
2.2. We shall now indicate how the gap in Pólya's original proof of Theorem B can be filled. Pólya's proof applies previous results of his on entire functions of exponential type [10]. Use is also made of certain properties of plane convex sets. The argument runs as follows.

If $\omega(u)$ is of constant sign for $u>u_{0}$, Theorem A implies that $\gamma=0$, and then (2.3) is trivial. We therefore suppose that $\omega(u)$ has an infinity of changes of sign. Let $\left(u_{n}\right)$ be the points of change of sign of $\omega(u)$, and let $W(x)$ be the number of its changes of sign in the interval $1<u \leqslant x$, as defined earlier. Set

$$
d=\varlimsup_{x \rightarrow \infty} \frac{W(x)}{\log x}
$$

and suppose at first that $d<\infty$; then Pólya shows that the infinite product

$$
\prod_{n=1}^{\infty}\left\{1-\frac{z^{2}}{\left(\log u_{n}\right)^{2}}\right\}=F(z)
$$

is absolutely convergent, and that $F$ is an entire function of exponential type ([11], p. 22). He sets

$$
F(z)=a_{0}+\frac{a_{2} z^{2}}{2!}+\frac{a_{4} z^{4}}{4!}+\cdots
$$

defines

$$
\begin{equation*}
f(z)=\frac{a_{0}}{z}+\frac{a_{2}}{z^{3}}+\frac{a_{4}}{z^{5}}+\cdots, \tag{2.4}
\end{equation*}
$$

and shows that series (2.4) converges (at least) for $|z|>\pi d$ ([10], p. 578). Let $J$ be the convex hull of the singularities of $f$. Since $f$ is an odd function, and the coefficients $\left(a_{n}\right)$ are real, $J$ is symmetric with respect to both real and imaginary axes. Let $s=\kappa$ be the point at which the positive real axis intersects the boundary of $J$.

Theorem B is established by applying Landau's Theorem A to the function

$$
\begin{equation*}
\Phi^{*}(s)=\int_{1}^{\infty} \omega(u) F(\log u) u^{-s} d u \tag{2.5}
\end{equation*}
$$

Because of the definition of $F$, combined with inequality (2.1), the integrand in (2.5) satisfies the inequality

$$
\begin{equation*}
\omega(u) F(\log u) \leqslant 0 \quad(u>1) \tag{2.6}
\end{equation*}
$$

A theorem proved by Pólya in [10] (Satz V, p. 598) implies that $\Phi^{*}(s)$ is regular in the half-plane $\sigma>\theta+\kappa$ ([11], p. 25). The behaviour of $\Phi^{*}(s)$ for $\sigma \leqslant \theta+\kappa$ depends on the behaviour of $\Phi(s)$, defined by (2.2), on the line $\sigma=\theta$. Accordingly, PólyA distinguishes two cases:
(a) $\Phi$ has poles on $\sigma=\theta$;
(b) $\Phi$ is regular on $\sigma=\theta$.

In Case (a), he shows that if $\pi d<\gamma$, then $\Phi^{*}$ is regular at $s=\theta+\kappa$, but has a singularity at another point of the line $\sigma=\theta+\kappa$. But this is impossible, because of (2.6) and Theorem A. Therefore $\pi d \geqslant \gamma$.

The gap in Pólya's proof occurs in Case (b). The argument here is that if $d<\infty$, then $\Phi^{*}$ is regular at $s=\theta+\kappa$, but has singularities arbitrarily near the line $\sigma=\theta+\kappa$, in the half-plane $\sigma<\theta+\kappa$. Again, this is impossible because of (2.6) and Theorem A. Hence $d=+\infty$.

In order to establish this part of Theorem B, we require the following result on plane convex sets:

Lemma 2.1. Let $\mathfrak{A}$ be a closed, bounded, plane convex set, whose boundary consists only of extreme points ${ }^{1}$ ). Let $l$ be a supporting line ${ }^{2}$ ) of $\mathfrak{A}$ through $\xi \in \mathfrak{H}$. If $\mathfrak{B}$ is a translate of $\mathfrak{A}$, such that $\xi \in \mathfrak{B}$ and $\mathfrak{B}$ lies on the same side of $l$ as $\mathfrak{A}$, then $\mathfrak{A}$ and $\mathfrak{B}$ coincide.

Proof. Let $\tau$ be the translation $\tau: \mathfrak{A} \rightarrow \mathfrak{B}$. Since $\xi \in \mathfrak{B}, \xi \in l$, and $\mathfrak{B}$ is entirely on one side of $l, l$ is a supporting line of $\mathfrak{B}$ through $\xi$. Since the boundary of $\mathfrak{A}$ consists only of extreme points, there are exactly two points on the boundary such that the supporting lines through these points are parallel to a given direction ${ }^{3}$ ). Now $\xi^{\prime}=$ $\tau(\xi)$ is a point on the boundary of $\mathfrak{B}$ such that there is a supporting line $l^{\prime}$ of $\mathfrak{B}$ through $\xi^{\prime}$ which is parallel to $l$. Since $\mathfrak{B}$ is on the same side of $l$ as $\mathfrak{A}, l^{\prime}$ must be that one of the two supporting lines of $\mathfrak{B}$ parallel to $l$ which is closest to $l$. Therefore $l=l^{\prime}$ and $\xi=\xi^{\prime}$, so that $\mathfrak{A}$ and $\mathfrak{B}$ coincide.

The problem which must be solved in order to establish Case (b) of Theorem B may be stated geometrically as follows ${ }^{4}$ ).

Let $\left(c_{v}\right)$ be a sequence of points in the complex $s$-plane, with the following properties:
$\left.\begin{array}{l}\text { The points } c_{v} \text { lie pairwise symmetric to the real axis. They have no } \\ \text { point of accumulation in the finite part of the plane. }\end{array}\right\}$

$$
\begin{equation*}
\operatorname{Re}\left(c_{v}\right)<\theta \text { for all } v, \text { and } \varlimsup_{v \rightarrow \infty} \operatorname{Re}\left(c_{v}\right)=\theta \tag{2.7}
\end{equation*}
$$

[^0]Further, let $J$ be a bounded, closed, plane convex set, which is symmetric with respect to both the real and the imaginary axis, and is contained in the disc $|s| \leqslant \pi d$. Let $\sigma=\kappa$ be the supporting line of $J$ which is perpendicular to the positive real axis. Consider the sets $\left.c_{v}+J^{5}\right)(v=1,2, \ldots)$. We have to prove that for each $\varepsilon>0$, there exists a point $\zeta=\zeta(\varepsilon)$, which satisfies the following conditions:

$$
\begin{equation*}
\theta+\kappa-\varepsilon \leqslant \operatorname{Re}(\zeta)<\theta+\kappa \tag{2.9}
\end{equation*}
$$

$\zeta$ is an extreme point of some set $c_{n}+J$,
and

$$
\begin{equation*}
\zeta \notin c_{v}+J \quad \text { for } \quad v \neq n \tag{2.10}
\end{equation*}
$$

For that purpose, we consider the convex hull $\mathfrak{G}$ of all the sets $c_{v}+J$ with $\operatorname{Im}\left(c_{v}\right)>0$. Let $h$ be (one of) the extreme point(s) of $\mathfrak{G}$ on its supporting line parallel to the real axis; and let $H$ be that part of the boundary of $\mathfrak{H}$ which is in the half-plane $\sigma>\operatorname{Re}(h)$. Then, $\mathfrak{V}$ and $H$ have the following properties:

Each extreme point of $\mathfrak{S}$ belongs to the boundary of one of the sets $c_{v}+J$.
Indeed, suppose, if possible, that $p$ is an extreme point of $\mathfrak{G}$ such that $p \notin c_{v}+J$, for all $\nu$. Then, since the sets $c_{v}+J$ are closed, we can find a circle $\mathfrak{C}$ with $p$ as centre, such that $\mathbb{C} \cap\left(c_{v}+J\right)=\emptyset$, for all $v$. If $\mathfrak{C}$ is small enough, the set obtained by removing $\mathfrak{C} \cap \mathfrak{S}$ from $\mathfrak{H}$ is contained in a proper convex subset $\mathfrak{S}^{*}$ of $\mathfrak{H}$, since $p$ is an extreme point of $\mathfrak{S}^{6}$ ). But since $(\mathfrak{C} \cap \mathfrak{H}) \cap\left(c_{v}+J\right)$ is empty for all $v$, we would have $\mathfrak{G} \subset \mathfrak{S}^{*}$, which is absurd.

## $H$ contains no half-line.

Indeed, because of (2.8), $H$ could contain a half-line only if this line were on the vertical $\sigma=\theta+\kappa$. Now there cannot be a point $q=(\theta+\kappa)+i \tau$ on the line $\sigma=\theta+\kappa$ such that all points of $H$ with imaginary part greater than $\tau$ lie on this line, while those with imaginary part smaller than $\tau$ lie to the left of it (Fig. 1). For if this were the case, $q$ would be an extreme point of $\mathfrak{H}$ and would therefore, by (2.12), belong to one of the $c_{v}+J$. But this is impossible, since $\operatorname{Re}\left(c_{v}\right)<\theta$.

There are extreme points of $\mathfrak{G}$ with arbitrarily large imaginary part.
Indeed, let $t_{0}>0$ be given. Because of (2.7) and (2.8), we can find a point $p_{1} \in H$ such that $\operatorname{Im}\left(p_{1}\right) \geqslant t_{0}$. Because of (2.13), $p_{1}$ does not lie on any half-line belonging to $H$. Therefore, if $p_{1}$ is not itself an extreme point of $\mathfrak{H}$, the supporting line of $\mathfrak{H}$ through $p_{1}$ contains two extreme points of $\mathfrak{G}$. One of these, say $p_{2}$, is such that $\operatorname{Im}\left(p_{2}\right)>$ $\operatorname{Im}\left(p_{1}\right) \geqslant t_{0}$.

[^1]Now it follows from the conditions on the $\left(c_{v}\right)$ and from the convexity of $\mathfrak{G}$ that if $h_{1} \in H$ and $\theta+\kappa-\varepsilon \leqslant \operatorname{Re}\left(h_{1}\right)<\theta+\kappa$, all points $h_{2} \in H$ for which $\operatorname{Im}\left(h_{2}\right)>\operatorname{Im}\left(h_{1}\right)$ also lie in the strip $\theta+\kappa-\varepsilon \leqslant \sigma<\theta+\kappa$. From this remark, and from (2.8) and (2.14), it easily follows that there is a point $\zeta^{*}$, such that

$$
\begin{gather*}
\zeta^{*} \in H  \tag{2.15}\\
\theta+\kappa-\varepsilon \leqslant \operatorname{Re}\left(\zeta^{*}\right)<\theta+\kappa  \tag{2.16}\\
\zeta^{*} \text { lies on the boundary of a set } c_{n}+J \text { with } \operatorname{Im}\left(c_{n}\right)>2 \pi d . \tag{2.17}
\end{gather*}
$$

In order to locate a point $\zeta$ with properties (2.9), (2.10) and (2.11), we shall consider two cases, according as the boundary of $J$ consists only of extreme points, or not.
A. If the boundary of $J$ consists only of extreme points, we may choose $\zeta=\zeta^{*}$. Indeed, $\zeta^{*}$ is an extreme point of $c_{n}+J$. Since $J$ is contained in the disc $|s| \leqslant \pi d$, it follows from (2.17) that $\zeta^{*} \notin c_{v}+J$ if $\operatorname{Im}\left(c_{v}\right) \leqslant 0$. By applying Lemma 2.1 with $\mathfrak{A}=c_{n}+J$ and $\xi=\zeta^{*}$, we see that $\zeta^{*} \notin c_{v}+J$ if $\operatorname{Im}\left(c_{v}\right)>0$ and $\nu \neq n$.
B. If the boundary of $J$ does not consist entirely of extreme points, $\zeta^{*}$ need not be an extreme point of $c_{n}+J$. Also, $\zeta^{*}$ may belong to the boundary of some other translate of $J$, say of $c_{n_{1}}+J$ (Fig. 2). But if $\zeta^{*}$ is not an extreme point of $c_{n}+J$, the


Fig. 1.


Fig. 2.
supporting line $g$ of $c_{n}+J$ through $\zeta^{*}$ contains two extreme points of $c_{n}+J$, say $\zeta_{0}^{*}$ and $\zeta_{1}^{*}$. One of these has a real part greater than that of $\zeta^{*}$; suppose that $\operatorname{Re}\left(\zeta_{1}^{*}\right)>$ $\operatorname{Re}\left(\zeta^{*}\right)$. Then, $\theta+\kappa-\varepsilon<\operatorname{Re}\left(\zeta_{1}^{*}\right) \leqslant \operatorname{Re}\left(c_{n}\right)+\kappa<\theta+\kappa$, so that $\zeta_{1}^{*}$ lies in the strip $\theta+\kappa-\varepsilon \leqslant \sigma<\theta+\kappa$. If $\zeta_{1}^{*}$ lies on the boundary of $c_{n_{1}}+J$ (as in Fig. 2), consider its translate $\zeta_{2}^{*} ; \zeta_{2}^{*}$ lies on $g$, is an extreme point of $c_{n_{1}}+J$, and is in the strip $\theta+\kappa-\varepsilon \leqslant$ $\sigma<\theta+\kappa$.

Should $\zeta_{2}^{*}$ lie on the boundary of some other translate $c_{n_{2}}+J$ of $J$, we can find in the same manner an extreme point $\zeta_{3}^{*}$ of $c_{n_{2}}+J$ on $g$ and in the strip $\theta+\kappa-\varepsilon \leqslant \sigma<$
$\theta+\kappa$. Proceeding in this manner, we must finally obtain a set $c_{n_{r}}+J$ and an extreme point $\zeta_{r+1}^{*}$ of this set which is exterior to all the other sets $c_{v}+J$, for otherwise the points $c_{n}, c_{n_{1}}, c_{n_{2}}, \ldots$, which lie on a parallel to $g$, would have a point of accumulation in the finite part of the plane, in contradiction with condition (2.7). Then, we may take $\zeta=\zeta_{r+1}^{*}$.

This concludes the proof of Case (b), and hence of Pólya's theorem.

### 2.3. A new application of Pólya's theorem

Let $r_{k}(n)$ denote the number of representations of the positive integer $n$ as a sum of $k$ integral squares ( $k \geqslant 2$ ), representations which differ only in sign, or order, being counted as distinct.

The generating function of $r_{k}(n)$ is $\zeta_{k}(s)$, Epstein's zeta-function of order $k$ [5], which has the representation

$$
\zeta_{k}(s)=\sum_{n=1}^{\infty} \frac{r_{k}(n)}{n^{s}}
$$

in the half-plane $\operatorname{Re}(s)>k / 2$, and satisfies the functional equation

$$
\begin{equation*}
\pi^{-s} \Gamma(s) \zeta_{k}(s)=\pi^{s-k / 2} \Gamma\left(\frac{k}{2}-s\right) \zeta_{k}\left(\frac{k}{2}-s\right) \tag{2.18}
\end{equation*}
$$

Let

$$
P_{k}^{g}(x)=\frac{1}{\Gamma(\varrho+1)} \sum_{n \leqslant x}^{\prime} r_{k}(n)(x-n)^{\varrho}-\frac{\pi^{k / 2} x^{\varrho+k / 2}}{\Gamma(\varrho+k / 2+1)}+\frac{x^{\varrho}}{\Gamma(\varrho+1)} \quad(\varrho \geqslant 0),
$$

the dash meaning that if $\varrho=0$ and $x$ is an integer, the last term in the sum must be multiplied by $\frac{1}{2}$. If $\varrho=0, P_{k}^{0}(x)$ is the error-term in the lattice-point problem for the sphere in $k$-dimensional space. Indeed, if we define $r_{k}(0)=1$, we have

$$
\begin{equation*}
P_{k}^{0}(x)=\sum_{0 \leqslant n \leqslant x}^{\prime} r_{k}(n)-\frac{(\pi x)^{k / 2}}{\Gamma(k / 2+1)} \tag{2.19}
\end{equation*}
$$

if $x$ is not an integer, $\sum_{0 \leqslant n \leqslant x}^{\prime} r_{k}(n)$ is equal to the number of lattice-points in a sphere of radius ${ }^{x}$, whose centre is a lattice-point, and $(\pi x)^{k / 2} / \Gamma(k / 2+1)$ is the volume of this sphere.
K. Chandrasekharan and Raghavan Narasimhan have shown [2] that functional equation (2.18) implies the identity

$$
\begin{equation*}
\sqrt{\pi} 2^{2 r+1} \int_{0}^{\infty} F_{k}^{e}\left(x^{2}\right) x^{2 r} e^{-s x} d x=(2 \pi)^{k / 2} \sum_{n=1}^{\infty} r_{k}(n) g_{n}(s) \tag{2.20}
\end{equation*}
$$

where $F_{k}^{e}(x)=P_{k}^{e}(2 x), \operatorname{Re}(s)>0, r$ is a sufficiently large integer, and

$$
g_{n}(s)=\sum_{v=0}^{r}(-1)^{v+r} e_{v} \frac{s^{2 v} \Gamma(\gamma+v+r)}{2^{2 v}\left(s^{2}+8 \pi^{2} n^{2}\right)^{\gamma+v+r}}
$$

where $\gamma=\varrho+\frac{1}{2} k+\frac{1}{2}$, and the $e_{v}$ are constants.
If $k$ is odd, this identity allows the application of Pólya's theorem to $P_{k}^{0}(x)$.
Indeed, if we make the change of variable $x \rightarrow \log x$ in the integral on the left-hand side of (2.20), we obtain an identity which shows that the function of $s$ defined by the integral

$$
\int_{1}^{\infty} \log ^{2 r} x \cdot F_{k}^{Q}\left(\log ^{2} x\right) x^{-1-s} d x
$$

is regular in the half-plane $\sigma>0$, and has singularities on the imaginary axis, at the points $s= \pm \pi n \sqrt{-8}(n=1,2, \ldots)$.

If $k$ is odd, these singularities are poles. Pólya's theorem can then be applied to obtain the following result, announced in [13]:

If $k$ is odd, and if $W_{k}(t)$ denotes the number of changes of sign of $P_{k}^{0}(x)$ in the interval $0<x \leqslant t$, then

$$
\begin{equation*}
\varlimsup_{t \rightarrow \infty} \frac{W_{k}(t)}{\sqrt{t}} \geqslant 2 \tag{2.21}
\end{equation*}
$$

If $k$ is even, identity (2.20) cannot be used to estimate the number of changes of sign of $P_{k}^{0}(x)$; in this case, Pólya's theorem gives information only on the changes of sign of those $P_{k}^{\varrho}(x)$ for which $\varrho \equiv \frac{1}{2}(\bmod 1)$. This is curious, since results on representations of an integer as a sum of an odd number of squares are usually more difficult to obtain than results on representations as a sum of an even number of squares.

Identities analogous to (2.20), which involve the error-terms arising from other solutions of the functional equation $\Gamma(s) \varphi(s)=\Gamma(\delta-s) \psi(\delta-s)$, can be deduced from a general identity given in [2] (Lemma 3, p. 491), of which (2.20) is a particular case. However, these identities permit the application of Pólya's theorem only when $\delta+\varrho+\frac{1}{2}$ is an integer, and this condition often precludes the possibility of obtaining a result in the case $\varrho=0$.

Identities of this type in the case of functional equations with more than one gamma factor are not known. In the following sections, we shall apply a different method, and obtain a lower bound for the number of changes of sign, in a given interval, of the error-terms arising from any given instance of functional equation (1.3).

## 3. The Functional Equation

3.1. We begin by defining, after Chandrasekharan and Narasimhan [3], the general functional equation with which we shall be concerned.

Definition 3.1. Let $\left(\lambda_{n}\right)$ and $\left(\mu_{n}\right)$ be two sequences of real numbers such that

$$
\begin{aligned}
& 0<\lambda_{1}<\lambda_{2}<\cdots<\lambda_{n} \rightarrow \infty \\
& 0<\mu_{1}<\mu_{2}<\cdots<\mu_{n} \rightarrow \infty
\end{aligned}
$$

and let $\left(a_{n}\right),\left(b_{n}\right)$ be two sequences of complex numbers, not all zero. Let $\delta$ be a real number, and $s$ a complex variable with real part $\sigma$ and imaginary part $t$. Let

$$
\begin{equation*}
\Delta(s)=\prod_{v=1}^{N} \Gamma\left(\alpha_{v} s+\beta_{v}\right) \tag{3.1}
\end{equation*}
$$

where $N \geqslant 1, \alpha_{v}>0$ and $\beta_{v}$ is complex, and let $A=\sum_{v=1}^{N} \alpha_{v}$. We say that the functional equation

$$
\begin{equation*}
\Delta(s) \varphi(s)=\Delta(\delta-s) \psi(\delta-s) \tag{3.2}
\end{equation*}
$$

holds, if the functions $\varphi$ and $\psi$ are representable by the Dirichlet series

$$
\begin{equation*}
\varphi(s)=\sum_{n=1}^{\infty} \frac{a_{n}}{\hat{\lambda}_{n}^{s}}, \quad \psi(s)=\sum_{n=1}^{\infty} \frac{b_{n}}{\mu_{n}^{s}}, \tag{3.3}
\end{equation*}
$$

each of which is absolutely convergent in some half-plane, and if there is a domain $D$ in the $s$-plane, which is the exterior of a bounded, closed set $S$, and in which there exists a holomorphic function $\chi$ with the properties

$$
\lim _{|t| \rightarrow \infty} \chi(\sigma+i t)=0
$$

uniformly in every interval $-\infty<\sigma_{1} \leqslant \sigma \leqslant \sigma_{2}<+\infty$, and

$$
\begin{aligned}
& \chi(s)=\Delta(s) \varphi(s), \text { for } \sigma>c_{1} \\
& \chi(s)=\Delta(\delta-s) \psi(\delta-s), \text { for } \sigma<c_{2}
\end{aligned}
$$

where $c_{1}$ and $c_{2}$ are some constants.
3.2. For $\varrho \geqslant 0$, we define

$$
\begin{equation*}
A_{\lambda}^{\varrho}(x)=\frac{1}{\Gamma(\varrho+1)} \sum_{\lambda_{n} \leqslant x}^{\prime} a_{n}\left(x-\lambda_{n}\right)^{e} \tag{3.4}
\end{equation*}
$$

the accent indicating that the last term of the sum is to be multiplied by $\frac{1}{2}$ if $\varrho=0$ and $x=\lambda_{n}$. We shall restrict our considerations to the case where $\varrho$ is an integer.

Let

$$
\begin{equation*}
S_{\varrho}(x)=\frac{1}{2 \pi i} \int_{\mathscr{Q}} \frac{\Gamma(s) \varphi(s)}{\Gamma(s+\varrho+1)} x^{s+e} d s, \quad \varrho \geqslant 0 \tag{3.5}
\end{equation*}
$$

where $\varphi(s)=\sum_{n=1}^{\infty} a_{n} \lambda_{n}^{-s}$, as in (3.3), and where $\mathscr{C}$ is a curve enclosing all the singularities of the integrand.

Further, let

$$
c_{\varrho}=\frac{A \delta+\varrho}{2 A}-\varepsilon, \quad 0<\varepsilon<\frac{1}{4 A}
$$

and let

$$
\begin{equation*}
I_{\varrho}(x)=\frac{1}{2 \pi i} \int_{\mathscr{G}^{\prime}} \frac{\Gamma(\delta-s) \Delta(s)}{\Gamma(\delta+\varrho+1-s) \Delta(\delta-s)} x^{\delta+e-s} d s \tag{3.6}
\end{equation*}
$$

where $\mathscr{C}^{\prime}$ is a curve formed by the lines $\sigma=c_{e}+i t$, with $|t|>R$, together with three sides of the rectangle whose vertices are $c_{\varrho}-i R, c_{e}+r-i R, c_{\varrho}+r+i R$ and $c_{e}+i R$. We assume that

$$
c_{e}>\max \left(-\operatorname{Re} \frac{\beta_{v}}{\alpha_{v}}\right), \quad v=1,2, \ldots, N
$$

and choose $r$ and $R$ in such a manner that all the poles of the integrand in (3.6) are to the left of $\mathscr{C}^{\prime}$.

It is shown in $[3, \S 4]$ that the identity

$$
\begin{equation*}
A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)=\sum_{n=1}^{\infty} \frac{b_{n}}{\mu_{n}^{\delta+e}} I_{\varrho}\left(\mu_{n} x\right) \tag{3.7}
\end{equation*}
$$

holds for $\varrho \geqslant 2 A \beta-A \delta-\frac{1}{2}$, where $\beta$ is such that $\sum_{n=1}^{\infty}\left|b_{n}\right| \mu_{n}^{-\beta}<\infty$.
For $I_{\varrho}(x)$ we have, as in [3, §4], the asymptotic formula

$$
\begin{equation*}
I_{\varrho}(x)=c \cdot x^{(\omega-1 / 2) / 2 A} \cos \left(h x^{1 / 2 A}+D\right)+o\left(x^{(\omega-1 / 2) / 2 A}\right) \tag{3.8}
\end{equation*}
$$

as $x \rightarrow \infty$, where $c$ and $D$ are real constants, $\omega=A \delta+(2 A-1) \varrho$ and $h=2 e^{-\theta / 2 A}$ with $\theta=2\left\{\sum_{v=1}^{N} \alpha_{v} \log \alpha_{v}-A \log A\right\}$, and $\delta, \alpha_{v}$ and $A$ are as in Definition 3.1. A more precise asymptotic formula for $I_{e}(x)$ is given in [4, Lemma 1], but (3.8) is sufficient for our purposes.

By combining (3.7) and (3.8) we obtain, for integral $\varrho \geqslant 2 A \beta-A \delta-\frac{1}{2}$, the asymptotic formula
$A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)=c \sum_{n=1}^{\infty} \frac{b_{n}}{\mu_{n}^{\delta+e}}\left(\mu_{n} x\right)^{(\omega-1 / 2) / 2 A} \cos \left(h\left(\mu_{n} x\right)^{1 / 2 A}+D\right)+o\left(x^{(\omega-1 / 2) / 2 A}\right)$,
as $x \rightarrow \infty$.

In order to obtain a lower bound for the number of changes of sign of the real and imaginary parts of $A_{\lambda}^{e}(x)-S_{e}(x)$ in a given interval, for a given non-negative integer $\varrho$, we shall require, beside (3.9), the following trivial extension of Rolle's theorem, which we state without proof.

Lemma 3.1. Let $f$ be continuous in the closed interval $[a, b]$ and differentiable in the open interval $(a, b)$, except perhaps at $c \in(a, b)$ at which, however, the left and right hand derivatives $f^{\prime-}(c)$ and $f^{\prime+}(c)$ exist. Let $f(a)=f(b)$. Then, $f^{\prime-}, f^{\prime+}$ and $\frac{1}{2}\left(f^{\prime-}+f^{\prime+}\right)$ all change sign at least once in $(a, b)$.

We also state as a lemma some properties of $A_{\lambda}^{e}(x)$ and $S_{\varrho}(x)$ which are easily verified with the definitions (3.4) and (3.5) of these functions.

Lemma 3.2. For $\varrho \geqslant 0$,

$$
S_{\varrho}(x)=\frac{d}{d x} S_{\varrho+1}(x)
$$

For $\varrho>0$,

$$
A_{\lambda}^{e}(x)=\frac{d}{d x} A_{\lambda}^{\varrho+1}(x)
$$

For $\varrho=0$ and $x \neq \lambda_{n}$,

$$
A_{\lambda}^{0}(x)=\frac{d_{\lambda}}{d x} A_{\lambda]}^{1}(x)
$$

whereas if $x=\lambda_{n}$,

$$
A_{\lambda}^{0}(x)=\frac{1}{2}\left(\frac{d^{+}}{d x}+\frac{d^{-}}{d x}\right) A_{\lambda}^{1}(x)
$$

since

$$
\frac{d^{+}}{d x} A_{\lambda}^{1}(x)=\sum_{\lambda_{n} \leqslant x} a_{n} \quad \text { and } \quad \frac{d^{-}}{d x} A_{\lambda}^{1}(x)=\sum_{\lambda_{n}<x} a_{n}
$$

## 4. A Lower Bound for the Change of Sign Function

4.1. We are now in a position to prove the following result on the changes of sign of the real and imaginary parts of $A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)$.

Theorem 4.1. Suppose that the functional equation

$$
\Delta(s) \varphi(s)=\Delta(\delta-s) \psi(\delta-s)
$$

is satisfied as in Definition 3.1. Let $\varrho$ be a non-negative integer. Let $W_{\lambda}^{\varrho}(t)$ denote the number of changes of sign of the function $\operatorname{Re}\left\{A_{\lambda}^{\varrho}(x)-S_{e}(x)\right\}$ in the interval $0<x \leqslant t$. If $\operatorname{Re}\left(b_{n}\right) \neq 0$ for at least one value of $n$, then ${ }^{7}$ )

$$
\begin{equation*}
W_{\lambda}^{\varrho}(t) \geqslant\left[\frac{h\left(\mu_{1} t\right)^{1 / 2 A}}{\pi}\right]-C \tag{4.1}
\end{equation*}
$$

[^2]where $C$ is a number independent of $t$, and $h=2 e^{-\theta / 2 A}$, with
$$
\theta=2\left\{\sum_{v=1}^{N} \alpha_{v} \log \alpha_{v}-A \log A\right\}
$$

Let $V_{\lambda}^{\varrho}(t)$ denote the number of changes of sign of $\operatorname{Im}\left\{A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)\right\}$ in the interval $0<x \leqslant t$. If $\operatorname{Im}\left(b_{n}\right) \neq 0$ for at least one value of $n$, then

$$
V_{\lambda}^{e}(t) \geqslant\left[\frac{h\left(\mu_{1} t\right)^{1 / 2 A}}{\pi}\right]-C^{\prime}
$$

where $C^{\prime}$ is independent of $t$.
Proof. We shall assume that $\operatorname{Re}\left(b_{1}\right) \neq 0$, as we may. The idea of the proof is to obtain first a lower bound for the number of changes of sign of $\operatorname{Re}\left\{A_{\lambda}^{\varrho+m}(x)-S_{\varrho+m}(x)\right\}$ in $0<x \leqslant t$, where $m$ is a sufficiently large non-negative integer. This is achieved by applying relation (3.9). Then, by differentiating $m$ times, and applying Lemmas 3.1 and 3.2, we get (4.1).

Given $\varrho \geqslant 0$, we choose an integer $m \geqslant 0$ which is so large, that

$$
\begin{equation*}
\varrho+m \geqslant 2 A \beta-A \delta-\frac{1}{2}, \tag{4.2}
\end{equation*}
$$

and that also

$$
\begin{equation*}
\frac{\left|\operatorname{Re}\left(b_{1}\right)\right|}{\mu_{1}^{\vartheta}}>\sum_{n=2}^{\infty} \frac{\left|\operatorname{Re}\left(b_{n}\right)\right|}{\mu_{n}^{9}} \tag{4.3}
\end{equation*}
$$

where

$$
\begin{equation*}
\vartheta=\left(A \delta+\varrho+m+\frac{1}{2}\right) / 2 A . \tag{4.4}
\end{equation*}
$$

Then, because of (4.2), (3.9) holds, with $\varrho+m$ in place of $\varrho$, and we have the relation $c^{\prime} \cdot x^{\vartheta-\delta-\varrho-m} \operatorname{Re}\left\{A_{\lambda}^{\varrho+m}(x)-S^{\varrho+m}(x)\right\}=\sum_{n=1}^{\infty} \frac{\operatorname{Re}\left(b_{n}\right)}{\mu_{n}^{\vartheta}} \cos \left(h\left(\mu_{n} x\right)^{1 / 2 A}+D\right)+g(x)$,
where $c^{\prime}$ is a real constant, $\vartheta$ is defined by (4.4), and

$$
\begin{equation*}
g(x)=o(1) \tag{4.6}
\end{equation*}
$$

as $x \rightarrow \infty$.
Because of (4.3) and (4.6), we can find an $X$ such that

$$
\begin{equation*}
|g(x)|<\frac{\left|\operatorname{Re}\left(b_{1}\right)\right|}{\mu_{1}^{s}}-\sum_{n=2}^{\infty} \frac{\left|\operatorname{Re}\left(b_{n}\right)\right|}{\mu_{n}^{s}}, \text { for } x \geqslant X \tag{4.7}
\end{equation*}
$$

Now let the sequence $x_{0}<x_{1}<x_{2}<\cdots$ be such that $x_{0} \geqslant X$, and

$$
\begin{equation*}
\cos \left(h\left(\mu_{1} x_{v}\right)^{1 / 2 A}+D\right)=(-1)^{v}, \quad v=0,1,2, \ldots \tag{4.8}
\end{equation*}
$$

Then, we have

$$
\begin{equation*}
\operatorname{sgn} \operatorname{Re}\left\{A_{\lambda}^{\varrho+m}\left(x_{v}\right)-S_{e^{+m}}\left(x_{v}\right)\right\}=(-1)^{v} \operatorname{sgn} \operatorname{Re}\left(b_{1}\right) \tag{4.9}
\end{equation*}
$$

for $v=0,1,2, \ldots$.
Indeed, on setting $x=x_{v}$, the right-hand side of (4.5) becomes

$$
(-1)^{v} \frac{\operatorname{Re}\left(b_{1}\right)}{\mu_{1}^{g}}+\sum_{n=2}^{\infty} \frac{\operatorname{Re}\left(b_{n}\right)}{\mu_{n}^{g}} c_{n}\left(x_{v}\right)+g\left(x_{v}\right)=G\left(x_{v}\right)
$$

say, where $c_{n}(x)=\cos \left(h\left(\mu_{n} x\right)^{1 / 2 A}+D\right)$. We have

$$
\begin{equation*}
-\left|\operatorname{Re}\left(b_{n}\right)\right| \leqslant \operatorname{Re}\left(b_{n}\right) \cdot c_{n}\left(x_{v}\right) \leqslant\left|\operatorname{Re}\left(b_{n}\right)\right| \tag{4.10}
\end{equation*}
$$

and it is easily seen that inequalities (4.7) and (4.10) imply that

$$
\begin{equation*}
(-1)^{v} \frac{\operatorname{Re}\left(b_{1}\right)}{\mu_{1}^{9}}-\frac{\left|\operatorname{Re}\left(b_{1}\right)\right|}{\mu_{1}^{9}}<G\left(x_{v}\right)<(-1)^{v} \frac{\operatorname{Re}\left(b_{1}\right)}{\mu_{1}^{9}}+\frac{\left|\operatorname{Re}\left(b_{1}\right)\right|}{\mu_{1}^{9}} \tag{4.11}
\end{equation*}
$$

whence (4.9) follows immediately.
Therefore, $\operatorname{Re}\left\{A_{\lambda}^{\varrho+m}(x)-S_{\varrho^{+m}}(x)\right\}$ changes sign at least once in each of the open intervals $\left(x_{v}, x_{v+1}\right), v=0,1,2, \ldots$. Consequently, its number of changes of sign in the interval $0<x \leqslant t$ is not less than

$$
\left[\frac{h\left(\mu_{1} t\right)^{1 / 2 A}}{\pi}\right]-k
$$

where $k$ is a number independent of $t$. By applying Lemma 3.2 and Rolle's theorem (or Lemma 3.1, if $\varrho=0$ ), we conclude that $\operatorname{Re}\left\{A_{\lambda}^{\varrho}(x)-S_{e}(x)\right\}$ has at least

$$
\left[\frac{h\left(\mu_{1} t\right)^{1 / 2 A}}{\pi}\right]-k-m
$$

changes of sign, as $x$ varies from 0 to $t$; this proves our theorem.
4.2. We have actually proved slightly more in the case $\varrho=0$. Because of Lemma 3.1, it follows from our proof that besides $\operatorname{Re}\left\{A_{\lambda}^{0}(x)-S_{0}(x)\right\}$, the functions

$$
\operatorname{Re}\left\{\sum_{\lambda_{n}<x} a_{n}-S_{0}(x)\right\} \text { and } \operatorname{Re}\left\{\sum_{\lambda_{n} \leqslant x} a_{n}-S_{0}(x)\right\}
$$

also change sign at least $\left[h\left(\mu_{1} t\right)^{1 / 2 A} / \pi\right]-C$ times in $(0, t]$.
4.3. It is clear that the method used to prove Theorem 4.1 can be applied to prove

Theorem 4.1'. Under the same assumptions as in Theorem 4.1, there exists a positive constant $X$ such that if $a \geqslant X$, then $\operatorname{Re}\left\{A_{\lambda}^{e}(x)-S_{\mathbf{e}}(x)\right\}$ changes sign at least
$\left[h \mu_{1}^{1 / 2 A}\left(b^{1 / 2 A}-a^{1 / 2 A}\right) / \pi\right]-C^{\prime \prime}$ times in the interval $a \leqslant x \leqslant b$, where $C^{\prime \prime}$ depends neither on a nor on $b$.
[In fact, $X$ is the real number which appears in inequality (4.7), and $C^{\prime \prime}=m$, the integer which satisfies inequalities (4.2) and (4.3).]

It may be of interest to remark that a result of this sort, for an arbitrary interval $[a, b]$, does not follow from Pólya's theorem.
4.4. In the same manner as above, results analogous to Theorems 4.1 and $4.1^{\prime}$ can be proved for the changes of sign of the real and imaginary parts of $B_{\mu}^{e}(x)-S_{e}(x)$.
4.5. We shall now apply Theorem 4.1 to the error-terms connected with the arithmetical functions $r_{k}(n)$ and $d(n)$.

The lattice-point function $r_{k}(n)$. As we have already seen in $\S 2$, the generating function of $r_{k}(n)$ is the Epstein zeta-function $\zeta_{k}(s)$. It is regular in the finite part of the plane, except for a simple pole with residue $\pi^{k / 2} / \Gamma(k / 2)$ at $s=k / 2$. It vanishes at $s=-1,-2, \ldots$, and has the value -1 at $s=0$. Functional equation (3.2) is satisfied by $\varphi(s)=\psi(s)=\pi^{-s} \zeta_{k}(s)$, with $a_{n}=b_{n}=r_{k}(n), \lambda_{n}=\mu_{n}=\pi n$ and $\delta=k / 2$. We have $A=1$ and $h=1$. It follows that

$$
A_{\lambda}^{\varrho}(x)-S_{\varrho}(x)=\sum_{\pi n \leqslant x}^{\prime} r_{k}(n)(x-\pi n)^{\varrho}-\frac{x^{k / 2+\varrho}}{\Gamma(\varrho+k / 2+1)}+\frac{x^{\varrho}}{\Gamma(\varrho+1)}
$$

In the case $\varrho=0$, if we make the substitution $x \rightarrow \pi x$, and set $r_{k}(0)=1$, Theorem 4.1 implies that as $x$ varies from 0 to $t$, the error-term

$$
P_{k}^{0}(x)=\sum_{0 \leqslant n \leqslant x}^{\prime} r_{k}(n)-\frac{(\pi x)^{k / 2}}{\Gamma(k / 2+1)}
$$

changes sign at least $2 \sqrt{t}-A_{1}$ times, where $A_{1}$ is independent of $t$. This result is obviously stronger than inequality (2.21), which we deduced from Pólya's theorem, and which holds only for odd $k$.

The divisor function $d(n)$. Let $d(n)$ denote the number of positive divisors of $n$. Its generating function is $\zeta^{2}(s)$, the square of Riemann's zeta-function, and functional equation (3.2) is satisfied by $\varphi(s)=\psi(s)=\pi^{-s} \zeta^{2}(s), a_{n}=b_{n}=d(n), \lambda_{n}=\mu_{n}=\pi n$, and $\delta=1$. We have $N=2, \alpha_{1}=\alpha_{2}=\frac{1}{2}$, whence $A=1$ and $h=2$. Further,

$$
\begin{aligned}
& S_{\varrho}(x)=\frac{\pi^{\varrho} \zeta^{2}(0)}{\Gamma(\varrho+1)}\left(\frac{x}{\pi}\right)^{\varrho}-\pi^{\varrho} \sum_{1 \leq 2 v+1 \leqslant \varrho}\left(\frac{x}{\pi}\right)^{e-2 v-1} \frac{\zeta^{2}(-2 v-1)}{\Gamma(2 v-1) \Gamma(2 v+2)} \\
&+\frac{\pi^{e}}{\Gamma(\varrho+2)}\left(\frac{x}{\pi}\right)^{\varrho+1}\left(\gamma-\frac{\Gamma^{\prime}}{\Gamma}(2+\varrho)+\log \frac{x}{\pi}\right)
\end{aligned}
$$

where $\gamma$ is Euler's constant (see [3], p. 130). If we consider the case $\varrho=0$, and make the substitution $x \rightarrow \pi x$, it follows from Theorem 4.1 that the error-term

$$
\sum_{n \leqslant x}^{\prime} d(n)-\left\{x \log x+(2 \gamma-1) x+\frac{1}{4}\right\}
$$

has at least $4 \sqrt{ } \bar{t}-A_{2}$ changes of sign in the interval $0<x \leqslant t$, where $A_{2}$ is independent of $t$.

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[^0]:    ${ }^{1}$ ) An extreme point of a closed plane convex set $K$ is a boundary point which is not an interior point of any line segment belonging to $K$ (for example, $\mathfrak{A}$ can be a circle, or an ellipse, but not a rectangle).
    ${ }^{2}$ ) A supporting line of a closed plane convex set $K$ is a line which contains at least one point of $K$, and such that $K$ lies entirely on one side of this line. A supporting line contains at most two extreme points. There are exactly two supporting lines parallel to a given direction.
    ${ }^{3}$ ) This follows from the remarks in Footnote (2): there are two supporting lines of $\mathfrak{A}$ in each direction, and since all boundary points of $\mathfrak{A}$ are extreme points, each supporting line contains exactly one boundary point.
    ${ }^{4}$ ) The $\left(c_{v}\right)$ are the poles of $\Phi(s)$ in the strip $\theta-b \leqslant \sigma \leqslant \theta ; J$ is the convex hull of the singularities of $f$ [c.f. (2.4)]. With the notation introduced in [11], and according to the Hilfssatz on p. 24 of [11], $\zeta$ is a singularity of $X^{*}(s)$. Because of $\operatorname{Satz} \mathrm{V}$ of [10], $\zeta$ is a regular point of $\Psi^{*}(s)$. Hence, $\zeta$ is a singularity of $\Phi^{*}=\Psi^{*}+X^{*}([11]$, pp. 24-25).

[^1]:    ${ }^{5}$ ) By $c_{v}+J$, we understand the translate of $J$ through the vector $c_{v}$.
    ${ }^{6}$ ) For a proof of this property of extreme points, see for instance [10], pp. 577-578.

[^2]:    ${ }^{7}$ ) Here, $[\xi]$ denotes the largest integer $\leqslant \xi$.

