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$$(2.9) \quad c' |(f(\phi_t(x)) - b)^{1-\alpha} - (f(\phi_t(y)) - b)^{1-\alpha}| < \varepsilon/4.$$

This can be done because both maps $z \mapsto \phi_t(z)$ and $z \mapsto (f(\phi_t(z)) - b)^{1-\alpha}$ are continuous. Equations (2.6) and (2.9) imply that

$$(2.10) \quad c'(f(\phi_t(y)) - b)^{1-\alpha} < \varepsilon/2,$$

and so, by (2.5),

$$(2.11) \quad d(\phi_\infty(y), \phi_t(y)) < \varepsilon/2.$$

Putting (2.7), (2.8) and (2.10) together, we get that for $y \in S_C$, $d(x, y) < \delta$ implies

$$\begin{aligned} d(\phi_\infty(x), \phi_\infty(y)) &\leq d(\phi_\infty(x), \phi_t(x)) + d(\phi_t(x), \phi_t(y)) + d(\phi_t(y), \phi_\infty(y)) \\ &< \varepsilon/4 + \varepsilon/4 + \varepsilon/2 = \varepsilon. \end{aligned}$$

This proves that $\phi_\infty: S_C \rightarrow C$ is continuous.

Finally it follows from the argument above that for any $y_0 \in S_C$ and any $\varepsilon > 0$ there are $\delta > 0$ and $\tau > 0$ so that

$$t > \tau \text{ and } d(y, y_0) < \delta \Rightarrow d(\phi_t(y), \phi_\infty(y_0)) < \varepsilon$$

for all $y \in S_C$. Consequently

$$\phi: [0, \infty] \times S_C \rightarrow S_C, \quad (t, y) \mapsto \phi_t(y)$$

is continuous. That is, S_C deformation retracts onto C . This concludes the proof of Theorem 1.1. \square

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