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where the coefficients of the  $(n - 1)$ -form  $v$  as well as  $(w_i)_i$  are Lipschitz functions. Clearly, the usual Stokes formula on  $[0, 1]^n$  holds for  $v$  whereas, for  $1 \leq i \leq n - 1$ ,

$$\begin{aligned} & \int_{[0, 1]^{n-1}} (w_i(x', 1) - w_i(x', 0)) \partial_i \varphi(x') dx' \\ &= (-1)^{n-1} \int_0^1 \int_{[0, 1]^{n-1}} \frac{\partial w_i(x', x_n)}{\partial x_n} \partial_i \varphi(x') dx' \wedge dx_n. \end{aligned}$$

Consequently, the Stokes formula holds for  $h^*u$  on  $[0, 1]^n$ , so that

$$\begin{aligned} \int_{\partial K} u &= \int_{\partial [0, 1]^n} h^*u = \iint_{[0, 1]^n} d(h^*u) = \iint_{[0, 1]^n} h^*(du) \\ &= \iint_{[0, 1]^n} h^*f = \iint_K f \end{aligned}$$

and the proof is complete.  $\square$

**DEFINITION 1.5.** *Let  $\Omega$  be a Lipschitz domain in  $\mathbf{R}^n$ . An integrally continuous  $(n - 1)$ -form  $u$  on  $\Omega$  is called absolutely continuous on  $\Omega$  if  $d(u|_{\Omega})$ , taken in the distribution sense, is integrable on  $\overset{\circ}{K}$  for any compact subset  $K$  of  $\Omega$ .*

Note that if  $u = \sum_{i=1}^n (-1)^{i-1} u_i dx_1 \wedge \cdots \wedge \widehat{dx_i} \wedge \cdots \wedge dx_n$  and  $u_i$  are, for instance, locally Lipschitz on  $\Omega$ , then  $u$  is absolutely continuous on  $\Omega$ .

A simple consequence of Theorem 1.3 and of the above definition is the next.

**THEOREM 1.6.** *If  $K$  is a compact Lipschitz domain in  $\mathbf{R}^n$  and  $u$  is an absolutely continuous  $(n - 1)$ -form on  $K$ , then*

$$\int_{\partial K} u = \iint_{\overset{\circ}{K}} du.$$

## 2. CHARACTERIZATIONS OF THE PLURIDIMENSIONAL ABSOLUTE CONTINUITY

Theorem 1.3 suggests the possibility of characterizing pluridimensional absolute continuity of  $(n - 1)$ -forms in a way similar to Lebesgue's definition of absolute continuity of functions on the real line (i.e. without involving the exterior derivative operator). This is made precise in the following theorem.

**THEOREM 2.1.** *Let  $\Omega$  be an open subset of  $\mathbf{R}^n$  and let  $u$  be a  $(n - 1)$ -form which is locally  $(n - 1)$ -integrable on  $\Omega$ . The following are equivalent.*

- (1) *There exists a locally integrable  $n$ -form  $f$  on  $\Omega$  such that  $du = f$  in the distribution sense on  $\Omega$ .*
- (2) *There exists a locally integrable  $n$ -form  $f$  on  $\Omega$  such that  $\int_{\partial Q} u = \iint_Q f$ , for any  $Q \in \mathcal{R}(\Omega)$ .*
- (3) *There exists a locally integrable  $n$ -form  $g$  on  $\Omega$  such that  $|\int_{\partial Q} u| \leq \iint_Q g$ , for any  $Q \in \mathcal{R}(\Omega)$ .*
- (4) *For any  $Q \in \mathcal{R}(\Omega)$  and any  $\varepsilon > 0$ , there exists  $\delta > 0$  such that*

$$\sum_{i \in J} \left| \int_{\partial Q_i} u \right| \leq \varepsilon,$$

*for any subdivision  $(Q_i)_{i \in I}$  of  $Q$  and any  $J \subseteq I$  for which  $\sum_{i \in J} \lambda_n(Q_i) \leq \delta$ .*

In particular, Theorem 1.3 and the above result show that an integrally continuous  $(n - 1)$ -form  $u$  on  $\Omega$  is absolutely continuous on  $\Omega$  if it satisfies one of the above equivalent conditions. However, let us note that, without the integral continuity condition,  $u$  with (1)-(4) above is not necessarily absolutely continuous, except for  $n = 1$ .

Here is a simple counterexample in  $\mathbf{R}^2$ . If  $\chi$  is the characteristic function of  $\{(1 - t, t); 0 \leq t \leq 1\} \subset \mathbf{R}^2$ , then  $u := \chi dx_2$  is locally 1-integrable and satisfies (1) – (4) in the above theorem, without being absolutely continuous on  $\Omega := \mathbf{R}^2$ .

*Proof of Theorem 2.1.* Clearly, all we need to show is that (4) implies (1). For each rectangle  $Q$  contained in  $\Omega$  we set

$$(2.1) \quad \rho(Q) := \sup \left\{ \sum_{i \in I} \left| \int_{\partial Q_i} u \right| ; (Q_i)_{i \in I} \text{ an elementary subdivision of } Q \right\}.$$

Note that  $|\int_{\partial Q} u| \leq \rho(Q) < +\infty$  for any rectangle  $Q$ . Also, since  $Q \mapsto \int_{\partial Q} u$  is *rectangle-additive*, i.e.  $\int_{\partial Q} u = \sum_{i \in I} \int_{\partial Q_i} u$  for any rectangle  $Q$  and any subdivision  $(Q_i)_{i \in I}$  of  $Q$ , so is  $\rho$ . Therefore, it makes sense to extend  $\rho$  by setting

$$(2.2) \quad \rho(P) := \sum_{i \in I} \rho(Q_i),$$

for any paved set  $P$  contained in  $\Omega$  and any subdivision  $(Q_i)_{i \in I}$  of  $P$ . The rectangle-additivity of  $\rho$  ensures that this extension is consistent with (2.1) and that (2.2) is independent of the particular choice of the subdivision  $(Q_i)_{i \in I}$  of  $P$ . Going further, we extend  $\rho$  to  $\text{comp}(\Omega)$  by setting

$$\rho(K) := \inf \{\rho(P); P \text{ paved set}, K \subseteq P\}, \quad K \in \text{comp}(\Omega).$$

By (4), this extension is continuous in the sense that  $\rho(K_v) \rightarrow \rho(K)$  whenever  $(K_v)_v$  is a nested sequence of compact sets in  $\Omega$  such that  $\cap_v K_v = K$ .

Now, for each multi-index  $\alpha \in \mathbf{N}^n$  and for each  $k \in \mathbf{N}$  we consider the cube  $Q_{k,\alpha} := [0, 2^{-k}]^n + 2^{-k}\alpha$ , and the set of multi-indices  $I_k := \{\alpha \in \mathbf{N}^n; Q_{k,\alpha} \subseteq \Omega\}$ . Moreover, for any complex-valued, continuous and compactly supported function  $\psi$  on  $\Omega$ , we set

$$I_k(\psi) := \{\alpha \in I_k; \text{supp } \psi \cap Q_{k,\alpha} \neq \emptyset\}$$

and

$$P_k(\psi) := \bigcup_{\alpha \in I_k(\psi)} Q_{k,\alpha}.$$

It follows that  $P_{k+1}(\psi) \subseteq P_k(\psi)$  for any  $k \in \mathbf{N}$  and that  $\cap_k P_k(\psi) = \text{supp } \psi$ .

Next, we define

$$s_k(\psi) := \sum_{\alpha \in I_k(\psi)} \psi(2^{-k}\alpha) \int_{\partial Q_{k,\alpha}} u.$$

Clearly,  $s_k$  is a  $\mathbf{C}$ -linear functional on  $C_0(\Omega)$  which satisfies

$$|s_k(\psi)| \leq \rho(P_k(\psi)) \sup_{\Omega} |\psi|, \quad \psi \in C_0(\Omega).$$

Finally, we introduce  $\mu: C_0(\Omega) \rightarrow \mathbf{C}$  by setting

$$\mu(\psi) := \lim_k s_k(\psi), \quad \psi \in C_0(\Omega),$$

where the existence of the limit easily follows from the uniform continuity of  $\psi$ . As  $\mu$  is  $\mathbf{C}$ -linear and satisfies  $|\mu(\psi)| \leq \rho(\text{supp } \psi) \|\psi\|_{L^\infty}$ , we infer that  $\mu$  is a complex-valued Radon measure on  $\Omega$ .

Fix  $Q \in \mathcal{R}(\Omega)$  and take  $\psi_v \in C_0(\Omega)$  a sequence of real-valued functions such that  $0 \leq \psi_v \leq 1$  on  $\Omega$ ,  $\psi_v = 1$  on a neighborhood of  $Q$ ,  $\text{supp } \psi_{v+1} \subseteq \text{supp } \psi_v$  and  $\cap_v \text{supp } \psi_v = Q$ . From the definition of  $\mu$  it is not difficult to see that

$$\left| \mu(\psi_v) - \int_Q u \right| \leq \rho(\text{supp } \psi_v) - \rho(Q).$$

Hence, on account of the continuity of  $\rho$ , we see that  $\int_Q d\mu = \int_{\partial Q} u$ , for any  $Q$ . With this at hand and by once again using the hypothesis (4), we conclude that  $\mu$  is absolutely continuous with respect to the  $n$ -dimensional Lebesgue measure  $\lambda_n$ . Therefore, if  $f \in L^1(\Omega, \text{loc})$  denotes the Radon-Nikodym-Lebesgue density of  $\mu$  with respect to  $\lambda_n$ , we have that

$$\int_{\partial Q} u = \int_Q d\mu = \iint_Q f$$

for any  $Q \in \mathcal{R}(\Omega)$ . Using this, Theorem 1.3 finally implies that  $du = f$  in the distribution sense on  $\Omega$ , and this concludes the proof of the theorem.  $\square$

**REMARK 2.2.** Inspection of the proof also shows that  $\rho(K) = \int_K |f| d\lambda_n$  for any compact subset  $K$  of  $\Omega$ , and that  $|f| \leq g$  a.e. on  $\Omega$ .

An *integrally Lipschitz*  $(n - 1)$ -form in  $\Omega$  is a locally  $(n - 1)$ -integrable form  $u$  for which there exists  $M > 0$  so that

$$\left| \int_{\partial Q} u \right| \leq M \lambda_n(Q)$$

for each  $Q \in \mathcal{R}(\Omega)$ . Note that any integrally Lipschitz  $(n - 1)$ -form  $u$  in  $\Omega$  satisfies the equivalent conditions in Theorem 1.3.

### 3. A MAXIMUM PRINCIPLE

The purpose of this section is to prove a localization theorem which plays a significant role in the sequel. Here, our approach is of an abstract nature.

Let  $\mathcal{X}$  be a fixed metric space. In general, for an arbitrary set  $E$ , we shall denote by  $\mathcal{F}(E)$  the collection of all finite families of subsets of  $E$ , and by  $\mathcal{S}(E)$  the collection of all subsets of  $\mathcal{F}(E)$ .

**DEFINITION 3.1.** A rectangular system on  $\mathcal{X}$  is a subset  $\mathcal{R}$  of  $\text{comp}(\mathcal{X})$  together with an application  $\text{div}: \mathcal{R} \rightarrow \mathcal{S}(\mathcal{R})$  satisfying the following:

- (1) If  $Q \in \mathcal{R}$  and  $(Q_i)_{i \in I} \in \text{div}(Q)$ , then  $Q_i \subseteq Q$  for any  $i \in I$ ;
- (2) For any  $Q \in \mathcal{R}$  and any  $\varepsilon > 0$ , there exists  $(Q_i)_{i \in I} \in \text{div}(Q)$  so that  $\text{diam}(Q_i) < \varepsilon$  for every  $i \in I$ .