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of C belongs to the interior of the polynomial hull of  $\overline{W}$ , then C is entirely included in the interior of the polynomial hull of  $\overline{W}$ .

By holomorphic curve we will mean a connected 1-dimensional holomorphic manifold.

**Proof.** Let O be the interior of the polynomial hull of W. It has to be shown that the set of points  $p \in C$  which belong to O is closed in C. It is obviously open. Things being so localized one has to face the following situation: a "small" analytic disk given by a holomorphic parametrization  $\varphi: \overline{\Delta} \to C$  ( $\Delta$  the unit disk in C) so that  $\varphi(1) \in O$ ,  $U^+$  a side of M included in W (at least one of the two sides is such) hence in O, in some neighborhood of  $\varphi(\overline{\Delta})$ ; and one has to show that  $\varphi(0) \in O$ . Fix  $\psi$  a holomorphic map from C into C<sup>n</sup> so that:  $\psi(e^{i\theta}) \approx -\overline{N}$  for  $\theta$  outside some small neighborhood of 0 (mod  $2\pi$ ), where  $\overline{N}$  is the unit outer normal to M (with respect to  $U^+$ ), at say the point  $\varphi(0)$ , and  $\psi(0)$  is arbitrarily chosen.

For  $\eta > 0$ ,  $\eta$  small enough  $\varphi(e^{i\theta}) + \eta \psi(e^{i\theta}) \in O$  for all  $\theta$ , hence  $\varphi(0) + \eta \psi(0) \in O$ . Taking into account some uniformity with respect to  $\psi(0)$ , this gives Lemma 2.

# III. LIFTING TO $C^3$

We are simply going to consider sets K in  $\mathbb{C}^3$  rotationally invariant in the first variable, that we describe as follows. For each  $t \in [0, t_0]$  we are given a compact set  $K_t \in \mathbb{C}^2$ . We consider the set  $K \in \mathbb{C}^3$  which is the closure of the set  $\{(w, z_1, z_2) \in \mathbb{C}^3; (z_1, z_2) \in K_{|w|}, |w| \leq t_0\}$ . i.e.

$$K = \bigcup_{|w| \leq t_0} \{w\} \times K_{|w|}.$$

 $\hat{K}$  denotes the polynomial hull of K in  $\mathbb{C}^3$ , while  $\bigcup K_t$  denotes the polynomial hull in  $\mathbb{C}^2$  of the closure of the set  $\bigcup_{t \leq t_0} K_t$ .

LEMMA 3. Let  $(0, \zeta_1, \zeta_2) \in \mathbb{C}^3$ , the following are equivalent:

$$\begin{cases} (i) \quad (0,\zeta_1,\zeta_2) \in \hat{K} \\ (ii) \quad (\zeta_1,\zeta_2) \in \stackrel{\frown}{\cup} K_t . \end{cases}$$

*Proof.* (i)  $\Rightarrow$  (ii) is trivial. We are interested in (ii)  $\Rightarrow$  (i). Let  $P(w, z_1, z_2)$  be a polynomial in 3 variables. To P we associate the polynomial  $\tilde{P}$  defined by

$$\tilde{P}(w, z_1, z_2) = P(0, z_1, z_2) = \frac{1}{2\pi} \int_0^{2\pi} P(e^{i\theta} w, z_1, z_2) d\theta .$$

Since K is invariant under rotation in the w variable:

$$\sup_{K} |\tilde{P}| \leq \sup_{K} |P|.$$

Set  $Q(z_1, z_2) = P(0, z_1, z_2)$ . Using (ii) one gets  $|P(0, \zeta_1, \zeta_2)| = |Q(\zeta_1, \zeta_2)| \leq \sup_{\bigcup K_t} |Q| = \sup_K |\tilde{P}| \leq \sup_K |P|.$ 

So (i) is established.

*Remark.* There is another approach to Lemma 3, which may better "explain" the situation, and that we just sketch. If  $\varphi: \Delta \to \mathbb{C}^2$  is a holomorphic disk ( $\varphi$  continuous on  $\overline{\Delta}$ , holomorphic on  $\Delta$ ) and T is a continuous map from  $\mathbb{R}/2\pi\mathbb{Z}$  into  $[0, t_0]$  so that  $\varphi(e^{i\theta}) \in K_{T(\theta)}(\theta \in [0, 2\pi))$ , then  $\varphi(0) \in \widehat{\bigcup} K_t$ . One sees that  $(0, \varphi(0)) \in \widehat{K}$  by considering holomorphic disks  $(Q, \varphi): \Delta \to \mathbb{C} \times \mathbb{C}^2$ , with Q(0) = 0 and  $|Q(e^{i\theta})| \simeq T(\theta)$ . Carrying this out in general may require the use of the fundamental theorem by Poletsky [6], which says that, in an appropriate sense, polynomial hulls are always explained by holomorphic disks.

# IV. TREPEAU'S EXAMPLE

Here we describe a class of examples. Let  $\chi$  be a smooth real valued function defined on [0, 1], constant in no neighborhood of 0, and so that  $\chi(0) = 0$ ,  $|\chi| < 1$ . In one of the versions of Trepreau's original example  $\chi(t) = t$ . Let  $\mathcal{M}$  be the generic 4-dimensional manifold in  $\mathbb{C}^3$ , given by:

$$\mathcal{M} = \{ (w, z_1, z_2) \in \mathbb{C}^3, |w| < 1, z_1 = s_1 + i\chi(|w|^2)s_2, z_2 = s_2 - i\chi(|w|^2)s_1; (s_1, s_2) \in \mathbb{R}^2 \}.$$

Notice that on  $\mathcal{M}$ ,  $z_1^2 + z_2^2$  is a real valued function, (on  $\mathcal{M}$ ,  $z_1^2 + z_2^2 \ge 0$ ), hence:

(\*) Any function which depends only on  $(z_1^2 + z_2^2)$  is a CR function on  $\mathcal{M}$ .

This already gives example of CR functions which cannot be holomorphically extended to any wedge. The existence of such functions is related to the fact that  $\mathcal{M}$  is not "minimal" (in the sense of Tumanov), it contains  $\mathbb{C} \times \{0\} \times \{0\}$  as a (nongeneric) CR manifold of same CR dimension (see [9], [2]).