## 4. Deviation of a domain from a disc

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$1^{\circ}$ Any two points of the set $E \cap \operatorname{cl} U(z, r)$ can be joined by an arc lying in $E \cap \operatorname{cl} U(z, b r)$.
$2^{\circ}$ Any two points of the set $E-U(z, r)$ can be joined by an arc lying in $E-U(z, r / b)$.

The following result has recently been proved by Gehring [2]:
Lemma 3.2. Let the set $C$ contain at least two points and bound a simply connected domain $A$. If $A$ is b-locally connected, then $C$ is a $c$ (b)-quasicircle, where $c(b)$ depends only on $b$.
3.3 Quasiconformal reflection. Let $C$ be a Jordan curve bounding the domains $A$ and $B$. A sense-reversing $K$-quasiconformal mapping $\varphi: A \rightarrow B$ is a $K$-quasiconformal reflection in $C$ if $\varphi$ leaves every point of $C$ invariant.

It is not difficult to prove that $C$ admits a quasiconformal reflection if and only if $C$ is a quasicircle. It follows that a quasiconformal mapping $f: A \rightarrow B$ between domains $A$ and $B$ bounded by quasicircles can be extended to a quasiconformal mapping of the plane. In fact, if $\varphi$ and $\psi$ are quasiconformal reflections in the boundaries $\partial A$ and $\partial B$, such that $\varphi$ is defined outside $A$ and $\psi$ in $B$, then $\psi \circ f \circ \varphi$ extends $f$ quasiconformally.

A quasicircle always admits quasiconformal reflections which are continuously differentiable or even real-analytic. For a $K$-quasicircle passing through $\infty$, a reflection $\varphi$ exists such that $|d \varphi(z)| /|d z|$ is bounded by a constant depending only on $K$.

For more details of the properties of quasicircles we refer to [10].

## 4. Deviation of a domain from a disc

4.1 Schwarzian derivative. Let $f$ be a locally injective meromorphic function in a simply connected domain $A$. At finite points of $A$ which are not poles of $f$, the Schwarzian derivative $S_{f}$ of $f$ is defined by

$$
S_{f}=\left(f^{\prime \prime} \mid f^{\prime}\right)^{\prime}-\frac{1}{2}\left(f^{\prime \prime} \mid f^{\prime}\right)^{2},
$$

and the definition is extended to $\infty$ and to the poles of $f$ by means of inversion.

The Schwarzian derivative is holomorphic in $A$. Conversely, every function which is holomorphic in $A$ is the Schwarzian of some $f$. The Schwarzian vanishes identically if and only if $f$ is a Möbius transformation.

More generally, the Schwarzian determines a function up to a Möbius transformation.

Suppose the boundary of $A$ consists of more than one point; then a conformal mapping $h$ of $A$ onto the unit disc exists. Through $h$ a conformally invariant metric $\rho(z)|d z|$ is defined in $A$, by the rule $\rho(z)|d z|$ $=\left(1-|w|^{2}\right)^{-1}|d w|, w=h(z)$. For functions $\varphi$ holomorphic in $A$ we introduce the norm

$$
\|\varphi\|_{A}=\sup _{z \in A}|\varphi(z)| \rho(z)^{-2}
$$

The Schwarzian obeys the composition rule $S_{f \circ g}=\left(S_{f} \circ g\right) f^{\prime 2}+S_{g}$. We note certain of its immediate consequences. First, let $f$ be meromorphic in $A$ and $h: A \rightarrow B$ a conformal mapping. Then

$$
\begin{equation*}
\left|S_{f}(z)-S_{h}(z)\right| \rho_{A}(z)^{-2}=\left|S_{f^{\circ} h^{-1}}(\zeta)\right| \rho_{B}(\zeta)^{-2}, \quad \zeta=h(z) \tag{4.1}
\end{equation*}
$$

It follows that $\left\|S_{f}-S_{h}\right\|_{A}=\left\|S_{f \circ h^{-1}}\right\|_{B}$. In particular,

$$
\begin{equation*}
\left\|S_{h}\right\|_{A}=\left\|S_{h^{-1}}\right\|_{B} . \tag{4.2}
\end{equation*}
$$

Secondly, let $f$ and $g$ be meromorphic in $A$ and $h: G \rightarrow A$ a conformal mapping. Then

$$
\begin{equation*}
\left\|S_{f \circ h}-S_{g \circ h}\right\|_{G}=\left\|S_{f}-S_{g}\right\|_{A} \tag{4.3}
\end{equation*}
$$

Finally, we remark that the norm of the Schwarzian is completely invariant under Möbius transformations: If $f$ is meromorphic in $A$ and $g$ and $h$ are Möbius transformations, then $\left\|S_{h \circ f \circ g}\right\|_{g-1(A)}=\left\|S_{f}\right\|_{A}$.
4.2 Constant $\sigma_{1}$. We associate with the domain $A$ the constant $\sigma_{1}$ $=\left\|S_{f}\right\|_{A}$, where $f$ is a conformal map of $A$ onto a disc. Here a disc means an ordinary disc or a half-plane. The number $\sigma_{1}$ is well defined, and equal to 0 if and only if $A$ itself is a disc. It can be regarded as a measure of how much the domain $A$ differs from a disc.

It is well known that $\sigma_{1} \leqslant 6$ (Theorem of Kraus [6]). For the domain $A=\{z \mid 0<\arg z<k \pi\}, 1 \leqslant k \leqslant 2$, we have $\sigma_{1}=2\left(k^{2}-1\right)$. If follows that $\sigma_{1}$ can take any value in the closed interval $[0,6]$.
4.3 Domains bounded by a quasicircle. In some cases, information about the boundary of $A$ makes it possible to improve the estimate $\sigma_{1} \leqslant 6$.

Theorem 4.1. For a domain $A$ bounded by a K-quasicircle,

$$
\begin{equation*}
\sigma_{1} \leqslant 6 \frac{K^{2}-1}{K^{2}+1} \tag{4.4}
\end{equation*}
$$

Proof: By Lemma 3.1, there exists a $K^{2}$-quasiconformal mapping $w$ of the plane whose restriction to the upper half-plane $H$ maps $H$ conformally onto $A$. For the function $w \mid H$ the Krauss estimate can be improved:

$$
\left\|S_{w \mid I}\right\|_{H} \leqslant 6 \frac{K^{2}-1}{K^{2}+1}
$$

for the proof we refer to Kühnau [7], or to [8]. Hence (4.4) follows from (4.2).
4.4 Domains with bounded boundary rotation. Let $A$ be a domain bounded by a continuously differentiable Jordan curve. The total variation of the direction angle of the boundary tangent under a complete circuit is called the boundary rotation of $A$. If the boundary is not so regular, boundary rotation is defined by means of approximations from inside.

Let $f$ be a conformal mapping of the unit disc $D$ onto a domain $A$ with boundary rotation $k \pi, 2 \leqslant k<\infty$. A real-valued function $\psi$ with the properties

$$
\int_{0}^{2 \pi} d \psi(\theta)=2, \int_{0}^{2 \pi}|d \psi(\theta)|=k
$$

can be associated with $f$, such that

$$
\begin{equation*}
f^{\prime}(z)=f^{\prime}(0) \exp \left(-\int_{0}^{2 \pi} \log \left(1-z e^{-i \theta}\right) d \psi(\theta)\right) \tag{4.5}
\end{equation*}
$$

The domain $A$ is convex if and only if $k=2$. This is equivalent to $\psi$ being an increasing function. A function $f$ whose derivative admits the representation (4.5) is always univalent if the total variation of $\psi$ is $\leqslant 4$.

Domains with bounded boundary rotation were introduced by Löwner and their basic properties established by Paatero [14].

Theorem 4.2. For a domain $A$ with boundary rotation $\leqslant k \pi, 2 \leqslant k \leqslant 4$,

$$
\begin{equation*}
\sigma_{1} \leqslant \frac{2 k+4}{6-k} . \tag{4.6}
\end{equation*}
$$

The bound is sharp.
Proof: Let $f: D \rightarrow A$ be a conformal mapping, $z_{0}$ an arbitrary point of $D$, and $h$ a conformal self-mapping of $D$, such that $h(0)=z_{0}$. Since $\rho_{D}(0)=1$, it follows from (4.1) that

$$
\begin{equation*}
\left|S_{f}\left(z_{0}\right)\right| \rho_{D}\left(z_{0}\right)^{-2}=\left|S_{f 0 h}(0)\right| \tag{4.7}
\end{equation*}
$$

Hence, (4.6) follows if we prove that $\left|S_{f}(0)\right| \leqslant(2 k+4) /(6-k)$. Since we may replace $f$ by the function $z \rightarrow c f\left(z e^{i \varphi}\right), c$ complex, $\varphi$ real, there is no loss of generality in assuming that $S_{f}(0) \geqslant 0$ and that $f^{\prime}(0)_{s}=1$. From the representation formula (4.5) we then deduce that

$$
\begin{align*}
S_{f}(0)= & \int_{0}^{2 \pi} \cos 2 \theta d \psi(\theta)-\frac{1}{2}\left(\int_{0}^{2 \pi} \cos \theta d \psi(\theta)\right)^{2}  \tag{4.8}\\
& +\frac{1}{2}\left(\int_{0}^{2 \pi} \sin \theta d \psi(\theta)\right)^{2}
\end{align*}
$$

If $k=2$, we have $d \psi(\theta) \geqslant 0$. In this case we get the inequality $\sigma_{1} \leqslant 2$ for convex domains from (4.8) quite easily, just by use of Schwarz's inequality. Extremal functions can also be determined. These computations have been carried out in [9]. Nehari [13] proved the result $\sigma_{1} \leqslant 2$ by means of variational methods.

If $2<k \leqslant 4$, establishing (4.6) requires a more careful handling of formula (4.8). These computations will be published in a joint paper with O. Tammi.

Matti Lehtinen has let me know that for functions $f$ whose derivative satisfies (4.5) with a $\psi$ whose total variation is $\leqslant k, k \geqslant 4$, the sharp upper bound for $\left\|S_{f}\right\|$ is equal to $\left(k^{2}-4\right) / 2$. The extremal functions are not univalent.
4.5 Constant $\sigma_{2}$. The domain constant

$$
\sigma_{2}=\sup \left\{\left\|S_{f}\right\|_{A} \mid f \text { univalent in } A\right\}
$$

is in simple relation with $\sigma_{1}$ ([9]):

Theorem 4.3. In every domain $A, \sigma_{2}=\sigma_{1}+6$.
Proof: Let $f$ be univalent in $A$ and $h: D \rightarrow A$ conformal. By (4.3),

$$
\left\|S_{f}\right\|_{A}=\left\|S_{f \circ h}-S_{f}\right\|_{D} \leqslant 6+\left\|S_{h}\right\|_{D}=6+\sigma_{1}
$$

In order to derive an estimate in the opposite direction, let an $\varepsilon>0$ be given. In view of formula (4.7), we can choose $h: D \rightarrow A$ so that $\left|S_{h}(0)\right|$
$>\sigma_{1}-\varepsilon$. If $w$ is defined by $w(z)=z+e^{i \theta} / z$ and $f=w \circ h^{-1}$, then $f$ is univalent in $A$ and

$$
\left\|S_{f}\right\|_{A}=\left\|S_{w}-S_{h}\right\|_{D} \geqslant\left|S_{w}(0)-S_{h}(0)\right|=\left|6 e^{i \theta}+S_{h}(0)\right| .
$$

By choosing $\varphi$ suitably we obtain $\left\|S_{f}\right\|_{A}>6+\sigma_{1}-\varepsilon$.

## 5. Schwarzian derivative and univalence

5.1 Constant $\sigma_{3}$. Let $A$ again be a simply connected domain with more than one boundary point. As a kind of opposite to the constant $\sigma_{2}$ we define

$$
\sigma_{3}=\sup \left\{a \mid\left\|S_{f}\right\| \leqslant a \text { implies } f \text { univalent in } A\right\}
$$

Note that the number $a=0$ is always in the above set. In this definition, sup can be replaced by max, as can be shown by a standard normal family argument.

Nehari [12] proved that in a disc, the condition $\left\|S_{f}\right\| \leqslant 2$ implies the univalence of $f$, and Hille [5] showed that the bound 2 is best possible. In other words, $\sigma_{3}=2$ for a disc.

A closer study of $\sigma_{3}$ leads to the universal Teichmüller space and reveals an intrinsic significance of quasiconformal mappings in the theory of univalent functions. The gist is the following result.

Theorem 5.1. The constant $\sigma_{3}$ is positive if and only if $A$ is bounded by a quasicircle.

Proof: The sufficiency of the condition was established by Ahlfors [1] who actually proved more: If $A$ is bounded by a $K$-quasicircle, there is an $\varepsilon>0$ depending only on $K$, such that whenever $\left\|S_{f}\right\|_{A}<\varepsilon$, then $f$ is univalent and can be continued to a quasiconformal mapping of the plane. In the proof, the extension of the given meromorphic $f$ is explicitly constructed by means of a continuously differentiable quasiconformal reflection $\varphi$ in $\partial A$ with bounded $|d \varphi| /|d z|$ (cf. 3.3).

The necessity was proved by Gehring [2]. His proof was in two steps. It was first shown, by aid of an example, that if $A$ is not $b$-locally connected for any $b$, then $\sigma_{3}=0$. After this, the desired conclusion was drawn from the result we stated above as Lemma 3.2.
5.2 Universal Teichmüller space. Henceforth, we assume that the domain $A$ is bounded by a quasicircle. Let $Q(A)$ be the Banach space

