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Autor: Schmidt, Wolfgang M.

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SIMULTANEOUS APPROXIMATION TO ALGEBRAIC NUMBERS

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define a parallelepiped $\Pi^{(p)}$ in E^l which we shall call the p-th pseudocompound of the parallelepiped Π defined by (8.4).

Remarks. Mahler (1955) defined the p-th compound of any symmetric convex set, and the pseudocompound of a parallelepiped is closely related to its compound. But the compound of a parallelepiped is not necessarily a parallelepiped. Except for the notation, the (n-1)-st pseudocompound is the same as the dual of a parallelepiped, and hence the results of the last subsection may be interpreted as special cases of the results of the present subsection.

Theorem 8D (Mahler 1955). Let $\lambda_1, ..., \lambda_n$ and $v_1, ..., v_l$ be the successive minima of a parallelepiped Π and of its p-th pseudocompound $\Pi^{(p)}$, respectively. For $\sigma \in C(n, p)$ put $\lambda_{\sigma} = \prod_{i \in \sigma} \lambda_i$ and order the elements of C(n, p) as $\sigma_1, ..., \sigma_l$ such that $\lambda_{\sigma_1} \leq ... \leq \lambda_{\sigma_l}$. Then

$$v_j \gg \ll \lambda_{\sigma_j} \qquad (j=1,...,l)$$
.

Moreover, if $\mathbf{x}_1, ..., \mathbf{x}_n$ are linearly independent integer points with (8.1), i.e. with $|L_i(\mathbf{x}_j)| \leq \lambda_j R_i$ (i, j = 1, ..., n), and if for $\tau = \{j_1, ..., j_p\}$ in C(n, p) we put $\mathbf{X}_{\tau} = \mathbf{x}_{j_1} \wedge ... \wedge \mathbf{x}_{j_p}$, then

$$|L_{\sigma}^{(p)}(\mathbf{X}_{\tau})| \ll \lambda_{\tau}R_{\sigma} \qquad (\sigma, \tau \in C(n, p)).$$

- 9. Outline of the proof of the theorems on simultaneous approximation to algebraic numbers
- 9.1. Let us see what happens if we try to generalize Roth's proof to prove, say, Corollary 7B. In Roth's proof we constructed a polynomial $P(x_1, ..., x_m)$ in m variables $x_1, ..., x_m$ which had a zero of high order at $(\alpha, ..., \alpha)$. Hence the natural thing to try would be
- (a) to construct a polynomial $P(x_{11}, ..., x_{1l}; ...; x_{m1}, ..., x_{ml})$ in ml variables of total degree $\leq r_h$ in each block of variables $x_{h1}, ..., x_{hl}$ (h = 1, ..., m) with a zero of high order at $(\alpha_1, ..., \alpha_l; ...; \alpha_1, ..., \alpha_l)$. Then
- (b) one would have to show that if each of m given rational l-tuples $\left(\frac{p_{h1}}{q_h}, ..., \frac{p_{hl}}{q_h}\right) (h = 1, ..., m)$ satisfies (7.2), then P also has a zero of high order at

$$\left(\frac{p_{11}}{q_1},...,\frac{p_{1l}}{q_1};...;\frac{p_{m1}}{q_m},...,\frac{p_{ml}}{q_m}\right).$$

Finally

(c) one would have to show that under suitable conditions P cannot have a high zero at such a rational point.

If we proceed in this fashion, we encounter difficulties in (c). In Roth's Lemma 3C it was essential that P had rather different degrees in its variables and that the denominators in $\frac{p_1}{q_1}$, ..., $\frac{p_m}{q_m}$ increased very fast. In our present situation the first l denominators are equal, so that Roth's Lemma does not apply. The example m = 1, l = 2, $P(x_1, x_2) = (x_1 - x_2)^r$ shows that we cannot expect to have a lemma similar to Roth's in our present context, since P has a zero of order as high as r at every point (ξ, ξ) .

The polynomial P is defined on $E^l \times ... \times E^l$ (m copies). While it is difficult to say much about the order of vanishing of P at rational points $\mathbf{r}_1 \times ... \times \mathbf{r}_m$, it is easier to show that P cannot have a zero of high order on certain linear manifolds $\mathcal{M}_1 \times ... \times \mathcal{M}_m$ where each \mathcal{M}_h is a rational (i.e. defined by a linear equation with rational coefficients) hyperplane in E^l . We can illustrate this when m = 1. Namely, \mathcal{M}_1 is defined by an equation $a_0 + a_1x_1 + ... + a_lx_l = 0$ which can be normalized such that $a_0, a_1, ..., a_l$ are coprime rational integers. If $P(x_1, ..., x_l)$ has a zero of order $\geq i$ on \mathcal{M}_1 (i.e. P has a zero of order $\geq i$ at every point of \mathcal{M}_1), then $P(x_1, ..., x_l) = (a_0 + a_1x_1 + ... + a_lx_l)^i R(x_1, ..., x_l)$, where R has integer coefficients by Gauss' Lemma. It follows that

$$(9.1) (H(M))^i \le H(P)$$

where H(M) is the height of $M(\mathbf{x}) = a_0 + a_1 x_1 + ... + a_l x_l$. This inequality provides a good upper bound for i if H(M) is large.

9.2. It will be more convenient to deal with hyperplanes through the origin in E^{l+1} than with hyperplanes in E^{l} . Hence we shall put

$$(9.2) n = l + 1$$

and we shall consider polynomials $P(x_{11}, ..., x_{1n}; ...; x_{m1}, ..., x_{mn})$ which are homogeneous of degree r_h in each block of variables $x_{h1}, ..., x_{hn}$ (h=1, ..., m). The manifold $\mathcal{M}_1 \times ... \times \mathcal{M}_m$ now becomes a subspace defined by $L_1(x_{11}, ..., x_{1n}) = ... = L_m(x_{m1}, ..., x_{mn}) = 0$, where each L_h is a not

identically vanishing linear form in $x_{h1}, ..., x_{hn}$ (h=1, ..., m). The polynomial P vanishes on $\mathcal{M}_1 \times ... \times \mathcal{M}_m$ precisely if it lies in the ideal generated by $L_1, ..., L_m$. A suitable definition of the index is now as follows.

Let $L_h = L_h(x_{h1}, ..., x_{hn})$ (h=1, ..., m) be not identically vanishing linear forms. For positive integers $r_1, ..., r_m$ and for $c \ge 0$ let $\mathcal{T}(c)$ be the ideal generated by the products $L_1^{i_1} ... L_m^{i_m}$ with

$$\frac{i_1}{r_1} + \ldots + \frac{i_m}{r_m} \ge c .$$

The index of P with respect to $(L_1, ..., L_m; r_1, ..., r_m)$ is the largest value of c such that $P \in \mathcal{F}(c)$ if P is not identically zero, and it is $+\infty$ if P is identically zero.

9.3. Now suppose that $L(\mathbf{x}) = \alpha_1 x_1 + ... + \alpha_n x_n$ has real algebraic coefficients. In analogy with Lemma 3A in step (a) in the proof of Roth's Theorem, one can construct a polynomial P as above which is not identically zero and which has not too large rational integer coefficients, such that P has index at least

$$\left(\frac{1}{n}-\varepsilon\right)m$$
,

with respect to $(L, ..., L; r_1, ..., r_m)$. Here L really occurs with m different meanings; namely, the h-th copy of L means $\alpha_1 x_{h1} + ... + \alpha_n x_{hn}$ (h=1, ..., m). Perhaps it should be explained why the factor $\frac{1}{2} - \varepsilon$ in Lemma 3A is now replaced by $\frac{1}{n} - \varepsilon$. A form P in mn variables $x_{11}, ..., x_{1n}; ...; x_{m1}, ..., x_{mn}$ is also a form in $L, x_{12}, ..., x_{1n}; ...; L, x_{m2}, ..., x_{mn}$ provided $\alpha_1 \neq 0$ (and where L occurs with different meanings again). Now for "most" monomials in $L, x_{12}, ..., x_{1n}; ...; L, x_{m2}, ..., x_{mn}$ the degree in L will be about $\frac{1}{n}$ times the total degree of the monomial, and hence will be greater than $\left(\frac{1}{n} - \varepsilon\right)$ times the total degree of the monomial.

But a result with only one linear form L is not enough. In general, say when dealing with General Roth Systems, one has n linear forms $L_1, ..., L_n$ to start with, and one can deal with them simultaneously. The following result now replaces Lemma 3A.

LEMMA 9A. Let $L_1, ..., L_n$ be not identically vanishing linear forms with real algebraic coefficients. Suppose $\varepsilon > 0$. Then if $m > m_0 (L_1, ..., L_n; \varepsilon)$ and if $r_1, ..., r_m$ are positive integers, there is a polynomial $P(x_{11}, ..., x_{1n}; ...; x_{m1}, ..., x_{mn}) \not\equiv 0$ with rational integer coefficients such that

- (i) P is homogeneous in $x_{h1}, ..., x_{hn}$ of degree r_h (h=1, ..., m).
- (ii) P has index $\geq \left(\frac{1}{n} \varepsilon\right) m$ with respect to $(L_i, ..., L_i; r_1, ..., r_m)$ (i=1, ..., n).
- (iii) $H(P) \leq B^{r_1 + ... + r_m}$ where $B = B(L_1, ..., L_m)$.

This takes care of generalizing part (a) of Roth's proof. We have chosen our definition of the index such that (c) has a chance of going through, and in fact one can derive from Roth's Lemma 3C a more general lemma that applies in our situation. Namely, if $M_1(\mathbf{x}), ..., M_m(\mathbf{x})$ are linear forms with rational integer coefficients, then under suitable conditions the index of P with respect to $(M_1, ..., M_m; r_1, ..., r_m)$ is $\leq \varepsilon$.

9.4. If thus remains to deal with part (b). Suppose, say, that we want to derive a criterion for General Roth Systems as defined in §7.3. Suppose $L_1, ..., L_n$ are linear forms with real algebraic coefficients and suppose $\gamma_1 + ... + \gamma_n = 0$. Suppose there is a $\delta > 0$ and there are arbitrarily large values of Q for which there is an integer point $\mathbf{x} \neq \mathbf{0}$ with $|L_i(\mathbf{x})| < Q^{\gamma_i - \delta}$ (i = 1, ..., n). Assume in particular that this is true for $Q = Q_1, ..., Q_m$ and with integer points $\mathbf{x}_1, ..., \mathbf{x}_m$, respectively. An argument like the one used in the proof of Lemma 3B shows that if suitable auxiliary conditions are satisfied, then the polynomial P of Lemma 9A does in fact have

$$P(\mathbf{x}_1, \dots, \mathbf{x}_m) = 0.$$

But this is not what we really need. Namely, we need a rational subspace of the type $\mathcal{M}_1 \times ... \times \mathcal{M}_m$ where each \mathcal{M}_h is a hyperplane of E^n , such that P vanishes on this subspace.

There is a way out of this difficulty, although it is a rather costly one. Namely, we have to assume that for each Q_h (h=1, ..., m) there is not just one but there are

$$l = n - 1$$

linearly independent integer points $\mathbf{x}_h^{(1)}$, ..., $\mathbf{x}_h^{(l)}$ with

$$(9.3) |L_i(\mathbf{x}_h^{(j)})| \leq Q_h^{\gamma_i - \delta} \ (i = 1, ..., n; j = 1, ..., l; h = 1, ..., m).$$

Now if \mathcal{M}_h is the hyperplane through $\mathbf{0}$ spanned by $\mathbf{x}_h^{(1)}, ..., \mathbf{x}_h^{(l)}$ (h = 1, ..., m), then one can show that P vanishes on $\mathcal{M}_1 \times ... \times \mathcal{M}_m$. In fact one can show that if M_h is the linear form defining \mathcal{M}_h (h = 1, ..., m), then the index of P with respect to $(M_1, ..., M_m; r_1, ..., r_m)$ is $\geq m\varepsilon$, which in conjunction with (c) gives the desired contradiction.

9.5. But what have we really shown now? The inequalities

(9.4)
$$|L_i(\mathbf{x})| \leq Q^{\gamma_i} \qquad (i = 1, ..., n)$$

define a parallelepiped. The presence of l=n-1 linearly independent integer points $\mathbf{x}^{(1)},...,\mathbf{x}^{(l)}$ with $\left|L_i(\mathbf{x}^{(j)})\right| \leq Q^{\gamma_i-\delta}$ (i=1,...,n;j=1,...,l) means that the (n-1) st minimum $\lambda_{n-1}=\lambda_{n-1}(Q)$ satisfies $\lambda_{n-1}\leq Q^{-\delta}$. The inequalities (9.3) mean precisely that $\lambda_{n-1}(Q)\leq Q^{-\delta}$ for $Q=Q_1,Q_2,...,Q_m$. Thus we obtain a theorem about λ_{n-1} :

Theorem 9B. (Theorem on the next to last minimum). Suppose $n \ge 2$ and $L_1, ..., L_n$ are linearly independent linear forms with real algebraic coefficients, and suppose $L_1^*, ..., L_n^*$ are their duals. Suppose $\delta > 0$, suppose $\gamma_1 + ... + \gamma_n = 0$, and let Σ be the set of integers i in $1 \le i \le n$ for which

$$\gamma_i + \delta \ge 0$$
.

There is a $Q_0 = Q_0(L_1, ..., L_n; \gamma_1, ..., \gamma_n; \delta)$ with the following property: Let $\lambda_1 = \lambda_1(Q), ..., \lambda_n = \lambda_n(Q)$ be the successive minima of the parallelepiped $\Pi(Q)$ given by (9.4). Then for $Q > Q_0$ either

$$(9.5) \lambda_{n-1} > Q^{-\delta}$$

or

$$(9.6) L_i^*(\mathbf{x}_n^*) = 0 \text{ for every } i \in \Sigma,$$

where \mathbf{x}_1^* , ..., \mathbf{x}_n^* are the duals ¹) to linearly independent integer points \mathbf{x}_1 , ..., \mathbf{x}_n with $\mathbf{x}_j \in \lambda_j \prod (j=1,...,n)$.

It was clear from the discussion above that some inequality such as (9.5) would result. The hyperplanes \mathcal{M} of the discussion above were spanned by $\mathbf{x}_1, ..., \mathbf{x}_{n-1}$ (but with the notation $\mathbf{x}^{(1)}, ..., \mathbf{x}^{(l)}$), and hence the coefficients

¹⁾ I.e. they satisfy $\mathbf{x}_i \mathbf{x}_j^* = \delta_{ij}$ (i, j=1, ..., n).

in the defining equation for \mathcal{M} are proportional to \mathbf{x}_n^* . The alternative (9.6) had to be put in to allow for the possibility that \mathcal{M} behaves in a somewhat degenerate fashion. In most cases, e.g., if the coefficients of some L_i^* with $i \in \Sigma$ are linearly independent over the rationals, then no integer point $\mathbf{x} \neq \mathbf{0}$ can satisfy (9.6), and then (9.5) must hold.

Theorem 9B gives information on λ_{n-1} rather than on λ_1 . In what follows, transference theorems will be used to gain information on λ_1 .

9.6. Theorem 9B says that if Q is large and $\lambda_{n-1} < Q^{-\delta}$, then \mathbf{x}_n^* must lie in a certain subspace. The inequality (8.7) of Mahler's Theorem 8C further restricts the possibilities for \mathbf{x}_n^* . A combination of these results yields

COROLLARY 9C. Suppose $L_1, ..., L_n, \gamma_1, ..., \gamma_n, \delta, \mathbf{x}_1 = \mathbf{x}_1(Q), ..., \mathbf{x}_n = \mathbf{x}_n(Q), \mathbf{x}_1^* = \mathbf{x}_1^*(Q), ..., \mathbf{x}_n^* = \mathbf{x}_n^*(Q)$ are as above. Suppose there are arbitrarily large values of Q with

Then there is a fixed vector \mathbf{c} and there are arbitrarily large values of Q with (9.7) and with $\mathbf{x}_n^*(Q) = \mathbf{c}$.

Next, the condition (9.7) will be replaced by

$$(9.8) \lambda_{n-1} < Q^{-\delta} \lambda_n.$$

The latter condition usually is milder, since $\lambda_n \gg 1$ by (8.5).

THEOREM 9D. (Theorem on the last two minima). Suppose $L_1, ..., L_n, \gamma_1, ..., \gamma_n, \delta, \mathbf{x}_1, ..., \mathbf{x}_n^*$ are as above. Suppose there are arbitrarily large values of Q with (9.8). Then there are arbitrarily large values of Q with (9.8) and with $\mathbf{x}_n^*(Q) = \mathbf{c}$, where \mathbf{c} is a fixed vector.

To prove this theorem one needs Davenport's Lemma (Theorem 8B). Namely, put $\rho_0 = (\lambda_1 \dots \lambda_{n-2} \lambda_{n-1}^2)^{1/n}$ and

$$\rho_1 = \rho_0/\lambda_1, ..., \rho_{n-1} = \rho_0/\lambda_{n-1}, but \rho_n = \rho_0/\lambda_{n-1}.$$

By Davenport's Lemma we can compare the successive minima $\lambda_1, ..., \lambda_n$ of Π with the successive minima $\lambda_1', ..., \lambda_n'$ of another parallelepiped Π' . We have $\lambda_j' \gg \ll \rho_j \lambda_j$ (j=1, ..., n) and $\rho_0 \ll \lambda_1' \ll ... \ll \lambda_{n-1}' \ll \rho_0 \ll (\lambda_{n-1}/\lambda_n)^{1/n} \ll Q^{-\delta/n}$ by (8.5) and (9.8). Hence $\lambda_{n-1}' < Q^{-\delta/(2n)}$ if Q is large, and applying Corollary 9C to Π' we see that $\mathbf{x}_n^{*}(Q)$ is the same

for arbitrarily large values of Q, which in turn (by the last assertion of Davenport's Lemma) implies that $\mathbf{x}_n^*(Q)$ is the same for certain arbitrarily large values of Q.

9.7. Theorem 9E. (Subspace Theorem). Suppose $L_1, ..., L_n, \gamma_1, ..., \gamma_n, \delta, \mathbf{x}_1(Q), ..., \mathbf{x}_n(Q)$ are as above. Suppose there is a d in $1 \leq d \leq n-1$ such that

$$(9.9) \lambda_d < \lambda_{d+1} Q^{-\delta}$$

for certain arbitrarily large values of Q. Then there is a fixed rational subspace S^d of dimension d such that for some arbitrarily large values of Q with (9.9), the points

$$\mathbf{x}_1(Q), ..., \mathbf{x}_d(Q)$$
 lie in S^d .

For the proof put p = n - d and construct the linear forms $L_{\sigma}^{(p)}$ as in §8.4. Also put $\Gamma_{\sigma} = \sum_{i \in \sigma} \gamma_i$. The inequalities

$$|L_{\sigma}^{(p)}(\mathbf{X})| \leq Q^{\Gamma_{\sigma}} \qquad (\sigma \in C(n, p))$$

define the p-th pseudocompound $\Pi^{(p)}$ of Π . By Mahler's Theorem 8D the last two minima v_{l-1} , v_l of this pseudocompound have

$$v_{l-1} \gg \ll \lambda_d \lambda_{d+2} \lambda_{d+3} \dots \lambda_n, \quad v_l \gg \ll \lambda_{d+1} \lambda_{d+2} \lambda_{d+3} \dots \lambda_n,$$

whence $v_{l-1} < v_l \, Q^{-\delta/2}$ for large Q by (9.9). An application of Theorem 9D shows that \mathbf{X}_l^{*-1}) is the same for some arbitrarily large values of Q. Some algebra combined with the last assertion of Theorem 8D shows that (because of (9.9)) \mathbf{X}_l^{*} is proportional to $\mathbf{x}_{d+1}^{*} \wedge ... \wedge \mathbf{x}_n^{*}$. It follows that the subspace S^{*} spanned by $\mathbf{x}_{d+1}^{*}, ..., \mathbf{x}_n^{*}$ is the same for some arbitrarily large values of Q. But for these values of Q the vectors $\mathbf{x}_1, ..., \mathbf{x}_d$ lie in the orthogonal complement S^d of S^{*} .

9.8. We shall illustrate the power of the Subspace Theorem by deducing Theorem 7E. Suppose we have $\delta > 0$, $1 \le m < n$, m linearly independent linear forms $L_1, ..., L_m$ with real algebraic coefficients, and infinitely many integer solutions $\mathbf{x} \ne \mathbf{0}$ of

¹⁾ X_l^* in E^l is defined in terms of $\Pi^{(p)}(Q)$ just as x_n^* in E^n was defined in terms of $\Pi(Q)$.

$$|L_i(\mathbf{x})| \leq |\mathbf{x}|^{-((n-m)/m)-\delta} \qquad (i=1,...,m).$$

We may assume without loss of generality that $L_1, ..., L_m, x_1, ..., x_{n-m}$ are linearly independent. Put $L_{m+1}(\mathbf{x}) = x_1, ..., L_n(\mathbf{x}) = x_{n-m}$. It is easy to see that there is a $\delta' > 0$ and there are arbitrarily large values of Q for which there are solutions $\mathbf{x} \neq \mathbf{0}$ of

$$|L_i(\mathbf{x})| \leq Q^{\gamma_i - \delta'}$$
 $(i = 1, ..., n)$

where $\gamma_1 = \ldots = \gamma_m = -(n-m)/m$ and $\gamma_{m+1} = \ldots = \gamma_n = 1$. For these values of Q one has $\lambda_1 = \lambda_1(Q) < Q^{-\delta'}$. Since $\lambda_1 \leq \ldots \leq \lambda_n$ and $1 \leq \lambda_1 \ldots \lambda_n \leq 1$, there is a d with $1 \leq d \leq n-1$ and a $\delta'' > 0$ such that

$$(9.10) \lambda_d < \lambda_{d+1} Q^{-\delta''}$$

for arbitrarily large values of Q. Let S^d be the subspace in the conclusion of Theorem 9E.

Let $\Pi^*(Q)$ be the intersection of $\Pi(Q)$ and S^d ; this is a symmetric convex set in S^d . Let $\lambda_1^*, ..., \lambda_d^*$ be the successive minima of $\Pi^*(Q)$ with respect to the lattice Λ of integer points in S^d , and let $V^* = V^*(Q)$ be the (d-dimensional) volume of $\Pi^*(Q)$. By applying (8.3) to the lattice Λ we obtain

$$(9.11) 1 \leqslant \lambda_1^* \dots \lambda_d^* V^* \leqslant 1,$$

where the constants in \leq may depend on S^d . There are arbitrarily large values of Q for which $\mathbf{x}_1(Q), ..., \mathbf{x}_d(Q)$ lie in S^d , and for these values we have $\lambda_1 = \lambda_1^*, ..., \lambda_d = \lambda_d^*$, whence by (8.5) and (9.10),

$$\begin{split} \lambda_1^* \dots \lambda_d^* &= \lambda_1 \dots \lambda_d = (\lambda_1 \dots \lambda_d)^{d/n} (\lambda_1 \dots \lambda_d)^{(n-d)/n} \\ &< (\lambda_1 \dots \lambda_d)^{d/n} (\lambda_{d+1} \dots \lambda_n)^{d/n} Q^{-\delta'' d(n-d)/n} \leqslant Q^{-\delta'' d(n-d)/n} = Q^{-\eta}, \end{split}$$

say. In conjunction with (9.11) this yields $V^* \gg Q^{\eta}$.

Now if $L_1, ..., L_m$ have rank r on S^d , then

$$V^* \ll Q^{-(r(n-m)/m)+d-r} = Q^{d-(rn/m)}$$
.

It follows that $d - (rn/m) \ge \eta > 0$ and that

$$r < dm/n$$
.

This cannot happen if (7.6) holds, and hence $L_1, ..., L_m$ is a Roth System in this case. Since the case of linearly dependent forms $L_1, ..., L_m$ is trivial and since the other half of the theorem was proved in §7.3, Theorem 7E is established.