

Zeitschrift: Elemente der Mathematik
Herausgeber: Schweizerische Mathematische Gesellschaft
Band: 68 (2013)

Artikel: Tetrahedron classes based on edge lengths
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DOI: <https://doi.org/10.5169/seals-515896>

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Tetrahedron classes based on edge lengths

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1 Tetrahedron e-classes

Among triangles (the simplexes in 2-space) there are 3 kinds, the equilateral, the isosceles and the scalene. Which analogous kinds of tetrahedrons (the simplexes in 3-space) can be distinguished? Obviously, a regular tetrahedron (all edge lengths equal), at one extreme, corresponds to the equilateral triangle and a completely irregular tetrahedron (all edge lengths mutually different), at the other extreme, corresponds to the scalene. However, while there is only 1 kind, the isosceles, between the 2 extreme triangle kinds, there are 23 kinds between the 2 extreme tetrahedron kinds, thus 25 in total.

How do we arrive at these 25 tetrahedron kinds? To explain, we replace the more colloquial ‘tetrahedron kind’ by the concept of ‘tetrahedron e-class’ based on vertex maps: If T and

Es gibt gleichseitige, gleichschenklige und ungleichseitige Dreiecke. Wie sieht die entsprechende Klassifizierung bei Tetraedern aus? Am einen Ende der Skala befindet sich das gleichseitige Tetraeder, am andern Ende Tetraeder mit lauter unterschiedlich langen Kanten. Die Autoren der vorliegenden Arbeit finden dazwischen 23 Klassen von Tetraedern. Dabei sind nebst der Symmetriegruppe \mathcal{S} auch die sogenannte Permetriegruppe \mathcal{P} und die resultierende Longometriegruppe $\mathcal{L} := \mathcal{P}/\mathcal{S}$ Klasseninvarianten. Exemplarisch wird dargelegt, wie diese Gruppen, die für beliebige Polytope definierbar sind, algorithmisch ermittelt werden können. Aus der Ordnung der Kantenlängen ergibt sich sodann eine verfeinerte Klassifizierung von Tetraedern, deren Klassen sich mit Hilfe von \mathcal{L} abzählen lassen. Diese Klassen werden innerhalb von einfachen grösseren Klassen hinsichtlich Repräsentierbarkeit mit kleinsten ganzzahligen Kantenlängen untersucht. Schliesslich geht es noch um die Anzahl entsprechender Simplexklassen in höheren Dimensionen.

T' are two tetrahedrons we call a bijection f which maps the vertexes of T onto the vertexes of T' a *vertex map* from T to T' .

Definition 1.1. Let T be a tetrahedron. A tetrahedron T' belongs to the *e-class* represented by T and denoted by $[T]_e$ if there exists a vertex map f from T to T' , so that f induces a bijection between equal edge lengths of T and those of T' or, in other words, so that both edge maps induced by f and by f^{-1} preserve the lengths equality. We call such a vertex map f an *e-metry* from T to T' .

If f is an e-metry, the induced bijection of edge lengths is denoted by $\lambda(f)$. Fig. 1 shows an example of an e-metry f from T to T' and we have $\lambda(f) : 6 \mapsto 9, 8 \mapsto 5, 7 \mapsto 4$.

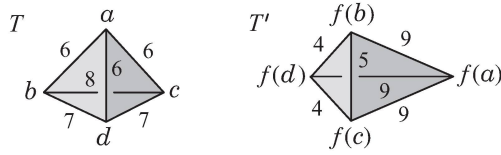


Fig. 1

In the special case of an e-metry f where $\lambda(f)$ is the identity, we speak of an *isometry* (this uniquely determines an 'isometry' in its ordinary sense, i.e., a length preserving map of the whole space onto itself).


























Of course, the e-classes form a (set) partition of all tetrahedrons. By constructive combinatorics we now generate the e-classes in showing how Tab. 1 is obtained: In the first column, the number n of different edge lengths, called *lengths number*, varies from 1 to 6. In the second column, the distributions of the edge lengths correspond to the 11 (number) partitions of 6, i.e., $6, 5+1, \dots, 1+1+1+1+1+1$, for short written as $6, 51, \dots, 111111$, denoted by m and named *lengths partition*. In each row with a given lengths partition m , the different arrangements of the edges are elaborated. This leads to a total of 25 cells where each cell contains a drawing of a tetrahedron (edge lengths differentiated by line formats) representing one of the 25 e-classes: $[T_1]_e, [T_2]_e, \dots, [T_{25}]_e$; this classification is also found in [2]. The further information within the cells will be explained in the following Section 2.

Remark. So far, we have tacitly assumed that the tetrahedrons under consideration actually exist. But if one admits any six lengths there are those that are not the edge lengths of a tetrahedron, a circumstance which was originally treated by Menger, Blumenthal, Herzog and others and was elaborated in a survey article [5]. In this paper, given edge lengths will always define a tetrahedron.

2 Symmetry and permetry groups

Based on e-metries, we consider what we call permetries as a conceptual extension of the well known symmetries of a tetrahedron:

Definition 2.1. An e-metry of a tetrahedron T onto itself is called a *permetry*. If p is a permetry of T , the induced bijection $\lambda(p)$ is said to be a *longometry* of T .

n	m	
1	6	T_1  $S_1 \equiv T_d$ $\mathcal{P}_1 \equiv T_d$
2	51	T_2  $S_2 \equiv C_{2v}$ $\mathcal{P}_2 \equiv C_{2v}$
	42	T_3  $S_3 \equiv C_s$ $\mathcal{P}_3 \equiv C_s$ T_4  $S_4 \equiv D_{2d}$ $\mathcal{P}_4 \equiv D_{2d}$
	33	T_5  $S_5 \equiv C_{3v}$ $\mathcal{P}_5 \equiv C_{3v}$ T_6  $S_6 \equiv C_2$ $\mathcal{P}_6 \equiv S_4$
3	411	T_7  $S_7 \equiv I$ $\mathcal{P}_7 \equiv C_s$ T_8  $S_8 \equiv C_{2v}$ $\mathcal{P}_8 \equiv D_{2d}$
	321	T_9  $S_9 \equiv C_s$ $\mathcal{P}_9 \equiv C_s$ T_{10}  $S_{10} \equiv I$ $\mathcal{P}_{10} \equiv I$ T_{11}  $S_{11} \equiv C_2$ $\mathcal{P}_{11} \equiv C_2$ T_{12}  $S_{12} \equiv C_s$ $\mathcal{P}_{12} \equiv C_s$
	222	T_{13}  $S_{13} \equiv I$ $\mathcal{P}_{13} \equiv C_3$ T_{14}  $S_{14} \equiv C_s$ $\mathcal{P}_{14} \equiv C_{2v}$ T_{15}  $S_{15} \equiv D_2$ $\mathcal{P}_{15} \equiv T_d$
4	3111	T_{16}  $S_{16} \equiv I$ $\mathcal{P}_{16} \equiv C_{3v}$ T_{17}  $S_{17} \equiv I$ $\mathcal{P}_{17} \equiv C_2$ T_{18}  $S_{18} \equiv I$ $\mathcal{P}_{18} \equiv C_{3v}$
	2211	T_{19}  $S_{19} \equiv I$ $\mathcal{P}_{19} \equiv I$ T_{20}  $S_{20} \equiv I$ $\mathcal{P}_{20} \equiv C_s$ T_{21}  $S_{21} \equiv C_s$ $\mathcal{P}_{21} \equiv C_{2v}$ T_{22}  $S_{22} \equiv C_2$ $\mathcal{P}_{22} \equiv D_{2d}$
5	21111	T_{23}  $S_{23} \equiv I$ $\mathcal{P}_{23} \equiv C_s$ T_{24}  $S_{24} \equiv I$ $\mathcal{P}_{24} \equiv D_{2d}$
6	111111	T_{25}  $S_{25} \equiv I$ $\mathcal{P}_{25} \equiv T_d$




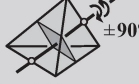
Tab. 1

The expression ‘permetry’ p is used, because p permutes the edge lengths of a tetrahedron T , i.e., the longometry $\lambda(p)$ is an edge lengths permutation. A permetry p where $\lambda(p)$ is the identity, is called a *symmetry* (again, this uniquely determines a ‘symmetry’ in its ordinary sense).

Just as the symmetries of a tetrahedron T form a group, so do the permetries and the longometries of T . The groups are called *symmetry*, *permetry* and *longometry group* and denoted by \mathcal{S} , \mathcal{P} and \mathcal{L} , respectively. The map λ which assigns to each permetry p of T the longometry $\lambda(p)$ is a group homomorphism from \mathcal{P} to \mathcal{L} with the kernel \mathcal{S} and, as is well known from group theory, \mathcal{L} and the factor group \mathcal{P}/\mathcal{S} are isomorphic.

We use *Schoenflies symbols* (common for symmetry groups in chemistry) to designate both groups \mathcal{S} and \mathcal{P} of a tetrahedron T . They are explained in Tab. 2 as subgroups of the full symmetry group of a regular tetrahedron T_{reg} : Consider a vertex map from T to T_{reg} , where the edges of T_{reg} have been colored in such a way that there is induced a bijection between equal edge lengths of T and equal edge color of T_{reg} . The groups \mathcal{S} and \mathcal{P} of T are then isomorphic with the ‘color preserving’ and with the ‘color equality preserving’ symmetry group of T_{reg} , respectively.

The Schoenflies symbols of the symmetry groups \mathcal{S}_i and permetry groups \mathcal{P}_i of the e-class representatives T_i ($1 \leq i \leq 25$) are shown in the previous Tab. 1. Clearly, all tetrahedrons of $[T_i]_e$ have isomorphic symmetry and isomorphic permetry groups, so that \mathcal{S}_i and \mathcal{P}_i can be considered to be e-class properties. The elements of this groups are derivable by

			
two-fold rotation	three-fold rotation	mirror reflection	four-fold rotation reflection

Subgroups of T_{reg} (group orders in parentheses, ε denotes the identity element):

I	(1)	ε (the group is also named C_1)
C₂	(2)	ε and 1 two-fold rotation
C₃	(3)	ε and 2 three-fold rotations (around the same axis)
D₂	(4)	ε and 3 two-fold rotations (around different axes)
C_s	(2)	ε and 1 mirror reflection
C_{2v}	(4)	ε and 1 two-fold rotation and 2 mirror reflections (in planes intersecting at the rotation axis)
C_{3v}	(6)	ε and 2 three-fold rotations (around the same axis) and 3 mirror reflections (in planes intersecting at the rotation axis)
S₄	(4)	ε and 1 two-fold rotation and 2 four-fold rotation reflections (all around the same axis)
D_{2d}	(8)	ε and 3 two-fold rotations (around different axes) and 2 mirror reflections (in planes intersecting at one of the rotation axes) and 2 four-fold rotation reflections (around this axis)
T_d	(24)	all 24 symmetries

Tab. 2

‘visual coincidence operations’ with their representatives T_i , but can also be generated by a *canonizing procedure*, which will be summarized here briefly.

The canonizing procedure is based on relational descriptions, or for short *descriptions*, of the given tetrahedron and an appropriate canonizing algorithm. Since the one we use operates with a minimizing process it will be called *minimizing algorithm* (see [3], [4], [6]). We explain with an example, namely with the tetrahedron T of the e-class $[T_{22}]_e$ as shown in Fig. 2 having lengths number $n = 4$ and lengths partition $m = 2211$; T exists according to Tab. 4 (see Section 4).

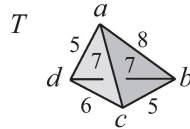


Fig. 2

A first description of T , denoted by $\text{Desc}_1(T)$, looks as follows:

$$\text{Desc}_1(T) = (\underbrace{\{a, b, c, d\}}_{= X}, \underbrace{\{ad, da, bc, cb\}}_{= R_1}, \underbrace{\{cd, dc\}}_{= R_2}, \underbrace{\{ac, ca, bd, db\}}_{= R_3}, \underbrace{\{ab, ba\}}_{= R_4}).$$

This description comprises the *vertex set* X followed by $n = 4$ so-called *metric relations* R_1, R_2, R_3 , and R_4 , each of which contains symmetric pairs of vertexes (written without

brackets and commas) representing equal edge lengths; the metric relations are ordered according to increasing lengths (identified by the indices). The minimizing algorithm now searches for those numberings $\mu : X \rightarrow \{1, 2, 3, 4\}$ which, after lexicographic ordering within each of the numbered X , R_1 , R_2 , R_3 , and R_4 , lead to a lexicographically smallest sequence, called the *minimal canonization* of T and denoted by $\text{Min}(T)$. In this way, $\text{Min}(T)$ results from each of the two numberings μ_1 and μ_2 ; they are named *minimal numberings*:

$$\begin{aligned} \text{Min}(T) &= ((1, 2, 3, 4), (12, 21, 34, 43)_5, (13, 31)_6, (14, 23, 32, 41)_7, (24, 42)_8)^1 \\ \text{from } \mu_1 : a \mapsto 2, b \mapsto 4, c \mapsto 3, d \mapsto 1 \text{ or } \mu_2 : a \mapsto 4, b \mapsto 2, c \mapsto 1, d \mapsto 3. \end{aligned}$$

The two symmetries of $\mathcal{S}_{22} \cong C_2$ are $\mu_1^{-1}\mu_1$ and $\mu_2^{-1}\mu_1$. How does one arrive at the eight permetries of $\mathcal{P}_{22} \cong D_{2d}$? The answer is given by the fact that, in addition to $\text{Desc}_1(T) = (X, R_1, R_2, R_3, R_4)$, one can create further descriptions of T , all transformable by the minimizing algorithm to the same $\text{Min}(T)$ as already achieved from $\text{Desc}_1(T)$. They are obtained by certain permutations of the metric relations R_1 , R_2 , R_3 , and R_4 . We find three of them, $\text{Desc}_2(T)$, $\text{Desc}_3(T)$, and $\text{Desc}_4(T)$, each leading to $\text{Min}(T)$ by two minimal numberings (not shown explicitly):

$$\begin{aligned} \text{Desc}_2(T) &= (X, R_1, R_4, R_3, R_2) \Rightarrow \text{Min}(T) \text{ from } \mu_3 \text{ or } \mu_4, \\ \text{Desc}_3(T) &= (X, R_3, R_2, R_1, R_4) \Rightarrow \text{Min}(T) \text{ from } \mu_5 \text{ or } \mu_6, \\ \text{Desc}_4(T) &= (X, R_3, R_4, R_1, R_2) \Rightarrow \text{Min}(T) \text{ from } \mu_7 \text{ or } \mu_8. \end{aligned}$$

Thus we have eight permetries: the already mentioned $\mu_1^{-1}\mu_1$ and $\mu_2^{-1}\mu_1$ (symmetries) together with $\mu_3^{-1}\mu_1$ and $\mu_4^{-1}\mu_1$ (coset permetries), $\mu_5^{-1}\mu_1$ and $\mu_6^{-1}\mu_1$ (coset permetries), $\mu_7^{-1}\mu_1$ and $\mu_8^{-1}\mu_1$ (coset permetries). The involved permutations of the metric relations, namely $(R_1)(R_2)(R_3)(R_4)$, $(R_1)(R_3)(R_2R_4)$, $(R_2)(R_4)(R_1R_3)$, and $(R_1R_3)(R_2R_4)$, form a group of order 4 which is isomorphic with the longometry group of T .

Remarks.

- (1) It is possible to extend the concepts symmetry, permetry and longometry group to polyhedrons or even to polytopes. These groups may be achieved by the canonizing procedure just illustrated. Such a symmetry group of a d -dimensional polytope was in [4] named *automorphism group* (the elements, being vertex permutations, are the automorphisms of the description). The automorphism group is isomorphic with the ‘ordinary symmetry group’ (where the elements are the isometries of the whole d -dimensional embedding space which map the polytope onto itself). But note that for polytopes, being different from simplexes, the automorphism group alone does not, in general, uniquely determine the kind of the isometries assigned by the isomorphism (for details see [4]).
- (2) It should also be mentioned that the canonizing procedure has been applied to generate the symmetry groups of non-rigid figures, which are not easily obtainable by ‘visual coincidence operations’, but which are of prime importance as models, for instance, of molecular structures (see [1]).

1. It would be sufficient to write only the lexicographically smaller of each symmetric pair.

3 Tetrahedron o-classes

We start again with triangles (the simplexes in 2-space): Isosceles triangles can be subdivided into two classes, the one where the laterals are larger than the base and the one in which they are smaller. By analogy, we consider subdivisions of the e-classes of tetrahedrons:

Definition 3.1. A tetrahedron T' belongs to the *o-class* represented by the tetrahedron T and denoted by $[T]_o$ if there exists an e-metry f from T to T' , so that $\lambda(f)$ preserves the order. We call such an e-metry f an *o-metry* from T to T' .

Clearly, the o-classes form a partition of all tetrahedrons and make up a refinement of the e-classes. What is the number of o-classes within an e-class $[T]_e$?

Theorem 3.1. Let T be a tetrahedron with lengths number n and longometry group \mathcal{L} . Then the number ω of o-classes within the e-class $[T]_e$ is given by $\omega = n!/|\mathcal{L}|$.

Proof. We use a finite completely tetrahedral set W (see [5]) with $|W| = n$. This assures that all o-classes within $[T]_e$ can be represented by tetrahedrons with edge lengths from W which is achieved as follows: Consider e-metries f_k with $1 \leq k \leq n!$ from a tetrahedron $\mathcal{T}_1 \in [T]_e$ to tetrahedrons \mathcal{T}_k such that (a) all \mathcal{T}_k have edge lengths from W and (b) all $\lambda(f_k)$ are mutually different. Clearly, to a fixed \mathcal{T}_k and to each e-metry g from \mathcal{T}_1 to \mathcal{T}_k there is assigned a permety p of \mathcal{T}_1 , such that $p = g^{-1}f_k$ and thus (c): $\lambda(p) = \lambda(g^{-1}f_k) = \lambda(g^{-1})\lambda(f_k)$. Now, when does \mathcal{T}_k belong to the o-class $[\mathcal{T}_1]_o$? By Definition 3.1, there must exist an o-metry g from \mathcal{T}_1 to \mathcal{T}_k which, according to (a) and since $\lambda(g)$ preserves the order, is exactly the case if g will be an isometry. But such an isometry g is given if and only if $\lambda(g^{-1})$ is the identity which, because of (c), is equivalent to $\lambda(f_k) = \lambda(p)$ or, in other words, to $\lambda(f_k)$ being equal to a longometry of \mathcal{T}_1 . From (b) and since the longometry group \mathcal{L} is an e-class property follows that the o-class $[\mathcal{T}_1]_o$ contains $|\mathcal{L}|$ tetrahedrons \mathcal{T}_k and this, of course, is true for each other o-class within $[T]_e$. Hence, $\omega = n!/|\mathcal{L}|$. \square

Tab. 3 shows the numbers ω_i of o-classes within the e-classes $[T_i]_e$. By summation over all ω_i one obtains the total number of o-classes, which is 225.

i	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25
ω_i	1	2	2	2	2	1	3	3	6	6	6	6	2	3	1	4	12	4	24	12	12	6	60	15	30

Tab. 3

There are, for instance, $\omega_{22} = 6$ o-classes within $[T_{22}]_e$ represented by the tetrahedrons as shown in Fig. 3, all of which exist according to Tab. 4 (see next Section 4). Note that the 2nd tetrahedron from the right is the tetrahedron T of Fig. 2.

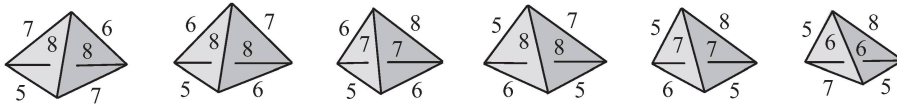


Fig. 3

Remarks.

- (1) The minimum value is $\omega_1 = \omega_6 = \omega_{15} = 1$ and, in these cases, the e-classes and o-classes coincide: $[T_1]_e = [T_1]_o$ (regular tetrahedrons), $[T_6]_e = [T_6]_o$ (golden tetrahedrons) and $[T_{15}]_e = [T_{15}]_o$ (isosceles tetrahedrons).
- (2) The maximum value is $\omega_{23} = 60$ which is bigger than $\omega_{25} = 30$, even though the tetrahedrons of $[T_{25}]_e$ have mutually different edge lengths (scalene tetrahedrons).

4 Smallest p- and q-sets

In this section we consider o-classes within two simple further classifications which can immediately be recognized by inspecting the first and second column of Tab. 1:

Definition 4.1. A *p-class* $[T]_p$ or a *q-class* $[T]_q$, where T is a representative, consists of all tetrahedrons with the same lengths *partition* m as T or the same lengths number (*quantity*) n as T , respectively.

There are 11 p-classes and 6 q-classes, both forming a partition of all tetrahedrons. Of course, the p-classes make up a refinement of the q-classes. Including the e-classes and o-classes we have: $[T]_q \supseteq [T]_p \supseteq [T]_e \supseteq [T]_o$ for any tetrahedron T .

First, let us consider the p-class $[T]_p$ where T has lengths partition m and lengths number n . We define a *smallest p-set* P_m as the set of the n smallest successive integers, such that for each o-class within $[T]_p$ there exists a representative with edge lengths from P_m . How can P_m be determined?

For this purpose we make use of spawning tetrahedrons and digress for a short summary of their features (see also [5]). By definition, a spawning tetrahedron is given according to Fig. 4 with $a \geq b \geq c \geq d \geq e \geq f$.

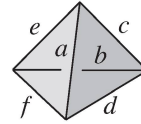


Fig. 4

The attribute ‘spawning’ is justified by the following remarkable property: All (anisometric) tetrahedrons conceivable by rearranging the edges of a spawning tetrahedron exist. But when do given edge lengths with the order $a \geq b \geq c \geq d \geq e \geq f$ determine a spawning tetrahedron? A necessary and sufficient condition is given by $D > 0$ where

$$D = \begin{vmatrix} 0 & a^2 & e^2 & c^2 & 1 \\ a^2 & 0 & f^2 & d^2 & 1 \\ e^2 & f^2 & 0 & b^2 & 1 \\ c^2 & d^2 & b^2 & 0 & 1 \\ 1 & 1 & 1 & 1 & 0 \end{vmatrix} \quad (\text{Cayley-Menger determinant}).$$

Of course, the attribute ‘spawning’, being based on the order of edge lengths, describes an o-class property. There are 32 spawning o-classes since $a \geq b \geq c \geq d \geq e \geq f$ is fulfilled exactly if one of the $2^5 = 32$ possible conditions, resulting from the replacement of ‘ \geq ’ by ‘ $>$ ’ or by ‘ $=$ ’, is fulfilled; in the following we speak of the 32 *spawning conditions*. Returning to the problem of detecting the smallest p-set P_m , we explain by means of an example: Let $[T]_p$ be the p-class represented by a tetrahedron T with lengths partition $m =$

2211. The determination of P_{2211} is now based on the $4!/(2!2!) = 6$ spawning o-classes within $[T]_p$ corresponding to the 6 arrangements of the partition numbers, namely 2211, 2121, 2112, 1221, 1212, and 1122, or to the following 6 spawning conditions, respectively:

$$\begin{aligned} a = b > c = d > e > f, \quad a = b > c > d = e > f, \quad a = b > c > d > e = f, \\ a > b = c > d = e > f, \quad a > b = c > d > e = f, \quad a > b > c = d > e = f. \end{aligned}$$

In each of these spawning conditions we replace the 4 unequal variables with $u, u + 1, u + 2$, and $u + 3$ (while adhering to the order) and form the respective Cayley-Menger determinants, being denoted by D_1, D_2, D_3, D_4, D_5 , and D_6 . We then calculate the smallest positive solution u_s of the following system of diophantine inequalities:

$$D_1 > 0 \wedge D_2 > 0 \wedge D_3 > 0 \wedge D_4 > 0 \wedge D_5 > 0 \wedge D_6 > 0.$$

The result $u_s = 5$ leads to the smallest p-set $P_{2211} = \{5, 6, 7, 8\}$ as shown in Tab. 4a.

Clearly, each of the $\omega_{19} + \omega_{20} + \omega_{21} + \omega_{22} = 54$ o-classes within $[T]_p$ can be represented by exactly one tetrahedron with edge lengths from P_{2211} . The 54 tetrahedrons include all anisometric tetrahedrons of $[T]_p$ conceivable with edge lengths from P_{2211} . Among these 54 tetrahedrons, 6 are spawning each generating 9 tetrahedrons by rearranging the edges. In general: Within a p-class, the number of spawning o-classes is a divisor of the number of o-classes because the quotient stands for the number of possible anisometric tetrahedrons with given edge lengths (see third column of Tab. 4a and also [5]).

Tab. 4a			Tab. 4b		
lengths partition m	smallest p-set P_m	number of o-classes: all (spawning)	lengths number n	smallest q-set Q_n	number of o-classes: all (spawning)
6	{1}	1 (1)	1	{1}	1 (1)
51	{2,3}	2 (2)	2	{3,4}	9 (5)
42	{3,4}	4 (2)			
33	{2,3}	3 (1)			
411	{4,5,6}	6 (3)	3	{5,6,7}	36 (10)
321	{5,6,7}	24 (6)			
222	{4,5,6}	6 (1)			
3111	{6,7,8,9}	20 (4)	4	{6,7,8,9}	74 (10)
2211	{5,6,7,8}	54 (6)			
21111	{7,8,9,10,11}	75 (5)	5	{7,8,9,10,11}	75 (5)
111111	{7,8,9,10,11,12}	30 (1)	6	{7,8,9,10,11,12}	30 (1)
total of o-classes: all (spawning)		225 (32)	total of o-classes: all (spawning)		225 (32)

Tab. 4

We now turn to Tab. 4b. Let $[T]_q$ be the q-class where T has lengths number n . By analogy to a smallest p-set P_m , we define a *smallest q-set* Q_n as the set of the n smallest successive integers such that for each o-class within $[T]_q$ there exists a representative with edge lengths from Q_n . There are $\binom{5}{n-1}$ spawning o-classes within $[T]_q$ corresponding to the spawning conditions with $n - 1$ signs ' $>$ ' and $6 - n$ signs ' $=$ '. A smallest q-set Q_n in Tab. 4b is obtained by determining the smallest positive solution of the system of the $\binom{5}{n-1}$

respective diophantine inequalities. The number of o-classes within $[T]_q$ results from summation over the appropriate ω_i . For $n = 4$, for instance, we have 74 o-classes and each of them can be represented by exactly one tetrahedron with the property that only the 4 edge lengths of Q_4 occur. And again, these 74 tetrahedrons make up all conceivable anisometric tetrahedrons with this property.

Remark. The reader may see that the calculation of the smallest p- and q-sets could be simplified should the following conjecture be true: *If in a tetrahedron all 6 edges are extended by the same length t (in our case by $t = 1$), then the resulting edges, being arranged in the same way, again determine a tetrahedron.*

5 Higher dimensions

A generalization in d -dimensional spaces may be considered. We counted the numbers of the simplex q-, p-, e- and o-classes denoted by $q(d)$, $p(d)$, $e(d)$, and $o(d)$, respectively. These numbers can be calculated as follows: $q(d) = \binom{d+1}{2}$ and $p(d)$ (partitions of a natural number) is obtained from a generating function well-known in combinatorics; for the determination of $e(d)$ we used DeBruijn's generalization of Polya's theory of counting and for $o(d)$ Polya's theory itself. In Tab. 5 these numbers are given for $1 \leq d \leq 7$.

d	$q(d)$	$p(d)$	$e(d)$	$o(d)$
1	1	1	1	1
2	3	3	3	4
3	6	11	25	225
4	10	42	1'299	856'608
5	15	176	1'974'452	319'872'163'585
6	21	792	94'345'468'975	16'096'217'596'356'372'660
7	28	3718	152'799'292'695'935'115	156'189'537'129'127'582'748'089'210'443

Tab. 5

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