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On a measure of axiality for triangular domains

Abstract. A measure of axial symmetry for triangles T in E_2 is studied, with the function $f(T) = \max_{T^*} \{[T^*]/[T]: T^* \text{ is axial and } T^* \subset T\}$ chosen as a measure of axiality, where [T] and $[T^*]$ denote the area of the triangle and of the axially symmetric oval, respectively. The greatest lower bound, $g_A = \inf_T \{f(T): T \text{ is a triangle in } E_2\} = 2(\sqrt{2}-1)$, is approached as a limit. The least axial triangle is a triangle whose altitude h is arbitrarily close to zero and whose sides are in the ratio $(\sqrt{2}-1):1:\sqrt{2}$ in the limit of h=0.

1. Introduction

Ovals in the euclidean plane E_2 are compact convex sets with interior points. An oval can be symmetric with respect to a point (centrally symmetric or *centric*) or a line (axially symmetric or *axial*). Measures of centrality for convex sets have been critically reviewed by Grünbaum [7]. Measures of axiality for ovals have been investigated by Nohl [9], Krakowski [8], Chakerian and Stein [2], and de Valcourt [3-5]. In this paper we describe a measure of axiality for triangles – the simplexes in E_2 .

Let K' denote the mirror image (enantiomorph) of an oval K obtained by reflection about a line k through an interior point. Let $K^* = K \cap K'$, a convex set, and $P = K \cup K'$. Then $K^* \subset K$ and $P \supset K$ are both necessarily axial, whereas K and K' are axial if and only if there exists a k (symmetry axis or mirror line) for which $K^* = P = K = K'$. In what follows, the chosen measure of axiality is the continuous real-valued function f(K)defined on the class \mathbf{K}_2 of all ovals K in E_2 by

$$f(K) = \max_{K^*} \{ [K^*] / [K] : K^* \text{ is axial and } K^* \subset K \},$$

where [K] and $[K^*]$ denote the areas of the corresponding ovals [3, 4]. This function has the following properties:

- (1) $0 \le f(K) \le 1$ for every oval $K \in \mathbf{K}_2$;
- (2) f(K)=1 if and only if K is axial;
- (3) f(K) is similarity-invariant.

2. Maximal overlap ratios for enantiomorphous triangles

Let T denote a triangular oval, T' its enantiomorph, and T* the intersection $T \cap T'$ of the enantiomorphous triangles. When T' is generated by reflection about a line k through an interior point of T, then T* is an axial polygon inscribed in T and T', and k is its symmetry axis.

Alternatively, T^* may be generated simply by overlapping T and T'; in that case T^* is not necessarily axially symmetric. However, Giering [6] has shown that maximal overlap of enantiomorphous triangles obtains only if T^* is axial and the sides of T^* are segments of all six sides of the two overlapped triangles. Triangular intersections are ipso facto excluded for non-axial triangles, and it remains to discuss quadrilateral, pentagonal, and hexagonal intersections that satisfy Giering's conditions.

(a) Quadrilateral intersections. If the intersection of T(ABC) and T'(A'B'C') is quadrilateral, maximal overlap under Giering's conditions requires k to be the bisector of the shared angle. We choose the shared angle α opposite side a (Figure 1), and b, c as the two sides of T whose ratio is closest to unity, with $b \le c$. It is then easily seen that

$$f_1(T) = \max_{T^*} \{ [T^*]/[T] : T^* \text{ is an axial quadrilateral and } T^* \subset T \}$$



(b) Pentagonal intersections. For a pentagonal intersection of T and T', maximal overlap under Giering's conditions requires k to be perpendicular to the shared side, c (Figure 2). With reference to Figure 2, for $1 \le \frac{2b \cos \alpha}{c} \le 2$ (acute angle at B) P is the projection of vertex C onto side c, and t is a segment of c, with $0 \le \frac{t}{c} \le \frac{1}{2}$. For $2 < \frac{2b \cos \alpha}{c}$ (obtuse angle at B), P is the projection of vertex C onto an extension of c, and t is negative. Let x, with $0 \le x \le c - 2t$, denote the segment of c that is not coextensive with c', the side

opposite C'. The intersection T^* is the pentagon BDED'B', and the overlap ratio is

$$\frac{[T^*]}{[T]} = \frac{(c+x)^2}{2c(c-t)} - \frac{2x^2}{c(c-2t)}.$$

This ratio is maximal for $x = \frac{c(c-2t)}{3c-2t}$, and it follows that



$$f_2(T) = \max_{T^*} \{ [T^*]/[T] : T^* \text{ is an axial pentagon and } T^* \subset T \}$$

$$=\frac{2c}{3c-2t}$$
, with $\frac{t}{c} \le \frac{1}{2}$, (2.2)

with (2.2) equivalently expressed as

$$=\frac{2}{1+\frac{2b\cos\alpha}{c}}, \quad \text{with} \quad 1 \le \frac{2b\cos\alpha}{c}, \tag{2.3}$$

where $b \equiv AC$ and $\alpha \equiv CAB$ as shown in Figure 2.

It is obvious that $f_2(T)$ is achieved when c is chosen as the side for which $\frac{t}{c}$ is closest to $\frac{1}{2}$ (or $\frac{2b \cos \alpha}{c}$ is closest to 1).

(c) Hexagonal intersections. Two alternatives are distinguished [6] if T^* is hexagonal: the six sides of T^* belong alternately to T and T', i.e., no two adjacent sides of T^* belong to one triangle (alternant hexagonal intersection), or one pair of adjacent sides in T^* belongs to T and another pair belongs to T' (nonalternant hexagonal intersection). We consider the latter case first.

In Figure 3, T_h^* is the hexagon *CEFGC'D*, and k is a bisector of the inscribed square *EFGD* [6]. Without loss of generality, let us assign unit dimensions to the square. Then c = 1 + x + y, where c is the side of T that is collinear with a side of the square, and x and



y are variables. In terms of these variables the overlap ratio is given by

$$\frac{[T_h^*]}{[T]} = \frac{2}{1+x+y}, \text{ with } 1 < y \text{ and } 0 < x \le y.$$

Â,

With reference to Figure 3, $BC \equiv a < c$ for every 1 < y and $0 < x \le y$. Hence

$$x+y > \frac{x+y}{\sqrt{1+x^2}} = \frac{c}{a}$$
, and $\frac{2}{1+x+y} < \frac{2}{1+\frac{c}{a}} \le \frac{2}{1+\frac{c''}{b''}}$,

where c'' and b'' are sides of the triangle such that $\frac{c''}{b''}$ is closest to 1 and $b'' \le c''$.

By comparison with (2.1) it follows that nonalternant hexagonal intersections are incapable of yielding f(T).

We next consider the case of alternant hexagonal intersections. To achieve maximal overlap, two additional conditions have to be satisfied [6]: (i) two enantiomorphous triangles abc and a'b'c' in the interior of T^* (Figure 4), which are similar to and share one side with T and T', respectively, have a vertex in common that lies on k; (ii) the three lines m_a , m_b , and m_c , which are perpendicular to and pass through the midpoints of alternating sides of T^* , meet at a common point in the interior of T^* . We define

$$f_3(T) = \max_{T^*} \{ [T^*]/[T] : T^* \text{ is an axial alternant hexagon and } T^* \subset T \}.$$

It can be shown that $f_3(T) = 2/\mu$, where μ is the ratio of magnification (or scaling factor) that relates similar triangles: $AB = \mu c$, $AC = \mu b$, $BC = \mu a$. In terms of the quantities in Figure 4:



For axial (isosceles or equilateral) triangles, T^* is axial and centric, $\mu = 3$, and $f_3(T) = 2/3$. This result accords with a finding by Besicovitch [1] that the largest value of the area of a centric oval inscribed in a triangle of area a is 2a/3. However, for non-axial triangles T^* cannot be centric.

We shall now prove that for all triangles $f_3(T) \le 2/3$, i.e., that $\mu \ge 3$. After appropriate substitutions in (2.4) this assertion takes the form

$$a^{2}\sin\theta + b^{2}\sin\phi \ge 2ab\sin\left(\frac{\theta+\phi}{2}\right).$$
 (2.5)

It is obvious that if $\gamma = \frac{\pi}{2}$, m_a , m_b , and m_c meet at the midpoint of c and $\theta = \phi = \frac{\pi}{2}$. Therefore (2.5) is always satisfied. The condition that the three lines m_a , m_b , m_c meet at a common point in the interior of T^* is fulfilled if and only if

$$\frac{a^2}{b^2} = \frac{\cos\phi}{\cos\theta} \,. \tag{2.6}$$

Combining (2.5) and (2.6) we obtain

$$\frac{\cos\phi\,\sin\theta}{\cos\theta} + \sin\phi - 2\left(\frac{\cos\phi}{\cos\theta}\right)^{\frac{1}{2}} \cdot \sin\left(\frac{\theta+\phi}{2}\right) \ge 0\,.$$

That this relationship is true for any θ and ϕ in the domains $\frac{\pi}{2} < \theta < \pi$ and $\frac{\pi}{2} < \phi < \pi$ defined by the constraints of the problem can be shown by elementary means. This completes the proof of the assertion. Accordingly

$$f_3(T) \le \tfrac{2}{3}$$

for all alternant hexagonal intersections of enantiomorphous triangles. Furthermore, since, for every T, $f_1(T)$ and $f_2(T)$ are both equal to or greater than 2/3 for quadrilateral and pentagonal intersections, respectively, it follows that alternant hexagonal intersections are also incapable of yielding f(T).

3. Greatest lower bound of f(T) for triangles

We have seen that only quadrilateral and pentagonal intersections, with shared angles and shared sides, respectively, need be considered as candidates for f(T). Moreover, in order to achieve the greatest lower bound of f(T) we seek the condition under which $f_1(T) = f_2(T)$.

Let us take c and b as the sides of a triangle, with $b \le c$, such that $\frac{c}{b}$ is closest to 1. Then, according to (2a), only one quadrilateral intersection has to be considered:

$$f_1(T) = \frac{2}{1 + \frac{c}{b}}.$$

However, three alternatives need to be considered for pentagonal intersections (2b):

$$f_2(T) = \frac{2}{1 + \frac{2b'' \cos \alpha''}{c''}}, \quad \text{with} \quad 1 \le \frac{2b'' \cos \alpha''}{c''} \le 2,$$

where c'' is the shared side and α'' is the angle subtended by b'' and c''.

(a) Pentagonal intersection with shared side a. For this intersection, $f_1(T) = f_2(T)$ takes the form

$$\frac{2}{1+\frac{c}{b}} = \frac{2}{1+\frac{2c\cos\beta}{a}}, \quad \text{with} \quad 1 \le \frac{2c\cos\beta}{a} \le 2.$$

This equation is satisfied for either an isosceles triangle (b=c) or for a scalene triangle with

$$b = \frac{c}{4\cos^2 \beta - 1}, \qquad a = \frac{2c\cos\beta}{4\cos^2\beta - 1}, \qquad \frac{\sqrt{2}}{2} \le \cos\beta \le \frac{\sqrt{3}}{2}.$$

Further, since $\frac{c}{b}$ is closest to 1, it follows that

$$\frac{c}{b} \leq \sqrt{2\cos\beta}$$

and, in addition, that

$$\frac{\sqrt{2}}{2} \le \cos\beta < \frac{\sqrt{5}+1}{4}.$$

Therefore

$$f(T) = \frac{2}{1 + \frac{c}{b}} \ge \frac{2}{1 + \sqrt{2\cos\beta}} > \frac{2}{1 + \sqrt{\frac{\sqrt{5} + 1}{2}}}.$$

(b) Pentagonal intersection with shared side b. For this intersection, $f_1(T) = f_2(T)$ takes the form

$$\frac{2}{1+\frac{c}{b}} = \frac{2}{1+\frac{2a\cos\gamma}{b}}, \quad \text{with} \quad 1 \le \frac{2a\cos\gamma}{b} \le 2.$$

This equation is satisfied for any triangle with $c = 2a \cos \gamma$ and $\cos \gamma \le \frac{1}{2}$. However, no such triangle, with the exception of the equilateral triangle, satisfies the condition that $\frac{c}{b}$ is closest to 1.

Therefore f(T) = 1.

(c) Pentagonal intersection with shared side c. For this intersection, $f_1(T) = f_2(T)$ takes the form

$$\frac{2}{1+\frac{c}{b}} = \frac{2}{1+\frac{2b\cos\alpha}{c}}, \quad \text{with} \quad 1 \le \frac{2b\cos\alpha}{c} \le 2,$$

which can be expressed as

$$\frac{c}{b} = \sqrt{2\cos\alpha}, \quad \text{with} \quad \frac{1}{2} \le \cos\alpha < 1.$$
(3.1)

Therefore

$$f(T) = \frac{2}{1 + \frac{c}{b}} = \frac{2}{1 + \sqrt{2\cos\alpha}} > \frac{2}{1 + \sqrt{2}} = 2(\sqrt{2} - 1).$$
(3.2)

Since

$$2(\sqrt{2}-1) < \frac{2}{1+\sqrt{\frac{\sqrt{5}+1}{2}}} < 1$$
,

it follows that the greatest lower bound of f(T) is $2(\sqrt{2}-1)$.

Equation (3.1) gives the unique geometry of a triangle T, with a given $\frac{c}{b}$ or a given α , that corresponds to the lowest value of f(T) for all possible intersections of T and its enantiomorph under conditions of maximal overlap. Let g_{Δ} denote the greatest lower bound of f(T). Then

 $g_{\Delta} = \inf_{T} \{ f(T) \colon T \text{ is a triangle in } E_2 \}.$

As seen from (3.2), for the general triangle the infimum of f(T) corresponds to $\alpha = 0$. Therefore the greatest lower bound is approached as a limit. Indeed, the similarity-invariance of f(T) implies [7] that \mathbf{K}_2 is not a compact space and that an extremal triangle for which f(T) assumes a minimal value may not exist. Accordingly, for the general triangle we have

$$f(T) > 2(1/2-1) \approx 0.828$$

The least axial triangle is therefore a triangle whose altitude ($h \equiv CP$, Figure 2) is arbitrarily close to zero and for which $\frac{c}{b} = \sqrt{2}$ and $\frac{a}{b} = \sqrt{2} - 1$ in the limit of h = 0. The same lower bound was found by Nohl [9] for centric ovals K_c , with equality for a special class of parallelograms:

$$f(K_c) \geq 2(\sqrt{2}-1).$$

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Klassische Beleuchtungsgeometrie im $E^d (d \ge 2)$ I. Bekannte Kurvenklassen in der Beleuchtungsgeometrie des $E^d (d \ge 2)$

Untersuchungen zur Beleuchtung von Flächen sind naturgemäss mit der Physik und Geometrie des dreidimensionalen euklidischen Raumes E^3 verknüpft. Gerade in jüngster Zeit hat die *Beleuchtungsgeometrie* eine merkliche Wiederbelebung erfahren, so dass auch Betrachtungen, die über eigentliche Anregungen hinausgehen, nahegelegt werden. Dazu gehört eine Übertragung klassischer Ergebnisse auf den beliebigdimensionalen Raum E^d ($d \ge 2$).

1. Begriffswelt mit d-dimensionalem Abstandsgesetz

Grundbegriffe der auf den E^3 bezogenen Beleuchtungstechnik und -geometrie werden sinngemäss aus [8] bzw. [3] übernommen. Der geometrische Raum E^d ($d \ge 2$) sei bezüglich eines kartesischen Normalkoordinatensystems durch den Raum der Koordinatenvektoren \mathbb{R}^d beschrieben, wobei Punkte durch ihre Koordinatenvektoren bezeichnet sind (z. B. x). Weiterhin steht $\langle \cdots \rangle$ für das *innere Produkt*, $\|\cdot\|$ für die *euklidische Norm*, $S^{d-1} := \{u \in \mathbb{R}^d | \langle u, u \rangle = 1\}$ für die *Einheitssphäre* und *o* für den Koordinatennullpunkt des E^d .

Ein orientiertes Flächenelement sei mit (x, u) bezeichnet, wobei $x \in \mathbb{R}^d$ den Träger und $u \in S^{d-1}$ den Stellung und Orientierung des Elements angebenden Normaleneinheitsvektor bedeuten. Ist (x, u) von t Parametern v_1, \ldots, v_t abhängig, dann liegt (im Anschluss an [6], S. 528 ff. und S. 33 ff., sowie [4], S. 102 ff.) eine Element-t-Schar vor.

Für $\{x(v_1, \ldots, v_t), u(v_1, \ldots, v_t)\}$ seien alle wünschenswerten analytischen Eigenschaften vorausgesetzt und uninteressante Ausartungen ausgeschlossen. Eine Elementschar ist ein *Element-t-Verein*, wenn in jedem Punkt der Trägermannigfaltigkeit $\{x(v_1, \ldots, v_t)\}$ die durch u beschriebenen (d - 1)-Ebenen den Tangentialraum enthalten. Insbesondere sind hier jene Elementvereine $\{x(v_1), u(v_1)\}$ interessant, die im differentialgeometrischen Sinne *Streifen* bilden (Streifenbedingung: $\langle \dot{x}, u \rangle = 0$). Eine geometrische Zentralbeleuchtung des E^d wird durch das Paar (q, I(n)) beschrieben, wobei $q \in \mathbb{R}^d$ die punktförmige Lichtquelle