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Fenchel type theorems for submanifolds of S^n

REMI LANGEVIN and HAROLD ROSENBERG

We dedicate this paper to the memory of Nicolaas Kuiper

The total curvature of compact hypersurfaces M of \mathbb{R}^n ($\int_M |K|$) is related to the topology of M and to the manner in which M is embedded in \mathbb{R}^n . K is the Gauss-Kronecker curvature of M, i.e., the determinant of the second fundamental form.

For curves C in \mathbb{R}^3 , the theorems of Fenchel and Fary-Milnor, state the total curvature of C is at least 2π (with equality precisely for convex planar curves) and if C is knotted in \mathbb{R}^3 then $\int_C |k| > 4\pi$, [Fe], [Fa], [M₁], [M₂].

Chern and Lashof observed the total curvature of $M^k \subset \mathbb{R}^n$ is

$$c\int_{P^{n-1}}|\mu|(M,l),$$

where c is a constant depending only on n and k, P^{n-1} is the projective space of lines l through the origin in \mathbb{R}^n and $|\mu|(M, l)$ is the number of critical points of the projection of M to l. Since this projection is a Morse function for almost all l, they obtained $c\beta$ as a minoration of the total curvature, β the sum of the betti numbers of M[C-L].

In particular for surfaces in \mathbb{R}^3 one has

$$\int_{M} |K| \ge 2\pi (2g+2),$$

g the genus of M. If a torus is knotted in \mathbb{R}^3 , then the total curvature is at least twice as large, i.e., 16π [L-R]. Results of this type for knotted surfaces of higher genus in \mathbb{R}^3 have been obtained by Kuiper and Meeks [K-M].

In this paper we establish results of this nature for submanifolds of S^n . For surfaces in S^3 , it is not sufficient to consider $\int_M |K|$, where K is the extrinsic curvature of M (consider the boundary of a small tubular neighborhood of a geodesic. Any two points of M differ by an isometry of S^3 so the intrinsic curvature of M is constant; it is zero by Gauss-Bonnet. So |K| = 1 and $\int_M |K|$ is the area of M). In fact,

for curves C in S^2 , it's easy to see that $\int_C (|k_g|+1) \ge 2\pi$, and equality holds precisely when C is a geodesic; k_g the geodesic curvature of C. However for surfaces M in S^3 , it is still not enough to consider $\int_M (|K|+1)$. One must add to |K|+1, a function $h_1(x)$ = the average of the absolute values of the normal curvatures to M at x. Then one has the desired results:

$$C(M) = \int_{M} (c_2|K| + c_1h_1(x) + c_0) \ge 2\pi(2g+2),$$

for certain constants c_0 , c_1 , c_2 , and g the genus of M. Moreover, if M is knotted in S^3 , then $C(M) \ge 2\pi(2g+4)$.

The function $\int_M h_1$ has an interesting geometric interpretation. It is the total number of folds of M. We call this the 1-length of M. It is a one dimensional measure of M; for M in \mathbb{R}^3 and tM the homothety of M by t, one has $L_1(tM) = tL_1(M)$. In general, for M a p dimensional submanifold of \mathbb{R}^n or S^n , we introduce i-length of M for every $i \le p$. We then study the behaviour of i-length through projections and intersections obtaining local and cinematic-type formulae.

Notice that $h_1(x)$ is not (except if M is convex) the first symmetric function of curvature σ_1 of M at x. Chern and Slavsky have studied $\int_M \sigma_1$, for M in \mathbb{R}^n and proved cinematic formulae for these functions [Ch], [Sl].

The 2-length of $M \subset S^3$, $L_2(M)$, is the area of M, $L_0(M)$ is the total curvature of M. We define $L_1(M)$ as follows. Let Σ be a geodesic 2-sphere of S^3 with X a conjugate point of Σ (i.e., $\operatorname{dist}(x, \Sigma) = \pi/2$). Let $p: S^3 - \{x, -x\} \to \Sigma$ be the projection along the geodesics starting at x. Denote by γ_{Σ} the critical values of p/M. Define

$$L_1(M) = \frac{1}{\pi^2} \int_{G(4,3)} |\gamma_{\Sigma}| d\Sigma,$$

where G(4, 3) is the Grassmann manifold of 3-planes through the origin of \mathbb{R}^4 , identified with the space of geodesic 2-spheres of S^3 .

We prove $L_1(M) = \pi^2 \int_M h_1$. Also we establish

$$L_0(M) = \frac{1}{2\text{Vol } G(4, 2)} \int_{G(4, 2)} |\gamma_l| \, dl,$$

where $l \in G(4, 2)$ is a geodesic of S^3 , and $|\gamma_l|$ is the number of critical points of the projection of M to l (along the geodesic spheres orthogonal to l).

Now one uses the cinematic formulae to relate $L_0(M) + L_1(M) + L_2(M)$ to the critical points of a Morse function on M. For this, we construct an "adapted" singular foliation of S^3 .

The theory is much simpler for curves on S^2 ; we indicate the argument here. Let $l \in G(3, 2)$ denote a geodesic of S^2 and for each $y \in P^2$ $(y = a \text{ pair of antipodal points of } S^2)$, let $\mathcal{F}(y)$ be the foliation of S^2 (singular at y) by geodesics passing through y.

We have

$$\int_C |k_g| = \frac{1}{2} \int_{P^2} |\mu|(C, \mathscr{F}(y)) dy,$$

where $|\mu|(C, \mathcal{F}(y))$ denotes the number of contact points of C and $\mathcal{F}(y)$. Also

$$|C| = \frac{1}{2} \int_{l \in G(3,2)} \#(C \cap l) dl = \frac{1}{2\pi} \int_{V} \left(\int_{l \in \mathscr{F}(V)} \#(C \cap l) \right) dy,$$

where |C| denotes the length of C. Hence

$$\int_C (|k_g|+1) = \frac{1}{2} \int_{\mathcal{Y}} \left[|\mu|(C, \mathscr{F}(y)) + \frac{1}{\pi} \int_{l \in \mathscr{F}(y)} \#(C \cap l) \, dl \right] dy.$$

Now for $y \in P^2$, if C intersects every $l \in \mathcal{F}(y)$, then C intersects every such l in at least two points and

$$\int_{l \in \mathscr{F}(y)} \# (C \cap l) \ge 2\pi$$

If C is disjoint from $l \in \mathcal{F}(y)$, then a moments thought shows there are at least two points of contact of C with $\mathcal{F}(y)$. Thus $|\mu|(C, \mathcal{F}(y)) \ge 2$; so $\int_C (|k_g| + 1) \ge 2\pi$. This illustrates the integral geometric technique but for curves the result is not interesting since the last inequality is just an application of Fenchel's theorem for curves in $\mathbb{R}^3 = (k = \sqrt{k_g^2 + 1})$ is the curvature of C in \mathbb{R}^3 .

For surfaces in S^3 the argument requires the introduction of a foliation adapted to a flag of geodesic spheres.

We remark that this notion of length has been applied in oceanography [J-L].

I. The length functions for submanifolds of R" and their cinematic formulae

Let M be a p-dimensional submanifold of \mathbb{R}^n and let h be a i+1 dimensional linear subspace of \mathbb{R}^n (we will denote by G(n, i+1) the Grassmann manifold of all such h). The critical points of the orthogonal projection p_h of M to h will be denoted

by $\Gamma_h(M)$ (or Γ_h if there is no ambiguity) and we denote the set of critical values of p_h by γ_h , or $\gamma(M, h)$.

When $p \ge i$, for almost every $h \in G(n, i+1)$, Γ_h is almost everywhere an *i*-dimensional submanifold of M and for almost every $x \in \Gamma_h$, $T_x(\Gamma_h)$ and h^{\perp} are transverse in $T_x(M)$, so γ_h is a hypersurface of h in a neighborhood of $p_h(x)$.

We define the *i*-length functional as:

$$L_i(M) = c \int_{G(n,i+1)} |\gamma_h| dh,$$

where $|\gamma_h|$ denotes the volume of γ_h (when i=0, γ_h is a finite set and $|\gamma_h|$ is the number of points in γ_h), and the constant c is chosen so that if M is the boundary of an ε -tubular neighborhood of an i-dimensional submanifold C of an affine p+1 dimensional subspace of \mathbb{R}^n , then $\lim_{\varepsilon \to 0} L_i(M) = |C|$.

If tM denotes a homothety of M by t > 0, then clearly

$$L_i(tM) = t^i L_i(M).$$

The constant c occurring in the definition of L_0 is $1/2|\mathbf{P}_{n-1}|$, since a sphere of any dimension ≥ 1 satisfies $|\gamma_l| = 2$ for every line $l \in G(n, 1)$. We will see shortly that $L_0(M)$ is the total curvature of M.

Here are some examples of 1-lengths of surfaces in \mathbb{R}^3 :

$$L_1(M) = \frac{1}{\pi^2} \int_{G(3,2)} |\gamma_h| dh.$$

If M is a round cylinder of height λ , then γ_h is (for almost all h) two parallel segments of length $\lambda |\cos \theta|$ where θ is the angle between the axis of M and the plane h. Hence $L_1(M) = \lambda$. If M is a sphere of radius R, γ_h is a circle of radius R and $L_1(M) = 4R$.

I.1. The local formulae

We define extrinsic curvature functions h_i on $M^p \subset \mathbb{R}^n$, and we prove $L_i(M) = c \int_M h_i(x) dx$, where c = c(n, p, i).

Let us begin by L_0 and L_1 of a surface M in \mathbb{R}^3 . We know that

$$L_0(M) = \frac{1}{4\pi} \int_{\mathbb{P}_2} |\gamma_l| \, dl,$$

where $|\gamma_l|$ is the number of critical points of the projection of M to l.

Let $\phi: M \to E$ be the map $\phi(x) = (l(x), p_{l(x)}(x))$, where l(x) is the line through the origin parallel to the normal line to M at $x, p_{l(x)}(x)$ is the orthogonal projection of x to l(x), and E is the tautological line bundle over P_2 . Let $N = \phi(M)$ and H be the horizontal plane field of the Riemannian fibration $\pi: E \to P_2$.

Clearly $\pi \phi$ is the Gauss map of M with $|\operatorname{Jac}(\pi \phi)| = |K(x)|$, K the Gauss curvature of M at x; so

$$|K(x)| = |\operatorname{Jac} \phi(x)| |\operatorname{Jac} p_{H(x)}|,$$

where $\operatorname{Jac} p_{H(x)}$ is the Jacobian of the orthogonal projection (in E) of $T_{\phi(x)}N$ to $H_{\phi(x)}=H(x)$.

Hence

$$\int_{\mathbf{P}_2} |\gamma_l| \, dl = \int_N |\operatorname{Jac}(p_H)| = \int_M |\operatorname{Jac}(\phi)| \, |\operatorname{Jac}(p_H)| \, dx = \int_M |K(x)| \, dx.$$

The first equality is a special case of the coarea formula and the second is a change of variables. Hence

$$L_0(M) = \frac{1}{4\pi} \int_M |K(x)| dx.$$

This formula for the total curvature of M is the basis of the Chern-Lashof theorem and easily generalises to \mathbb{R}^n [C-L].

For future calculations it is useful to introduce the following notation. Let $p: E \to B$ be a Riemannian fibration and $N \subset E$ a submanifold transverse to the fibers $F(y) = p^{-1}(y)$, $y \in B$. Let H be the horizontal plane field of the fibration. At $x \in N$, $T_x(N)$ is the orthogonal sum $T_x(N \cap F_x) + V(x)$ where V(x) is a subspace transverse to the fibers of dimension that of H(x). Denote by $\operatorname{Jac} p_{H(x)}$ the Jacobian of the orthogonal projection of V(x) to H(x). Then the coarea formula yields:

$$\int_{N} \left| \operatorname{Jac} p_{H(x)} \right| \, dx = \int_{B} \left| F(y) \cap N \right| \, dy,$$

and more generally, if $\phi: M \to E$ is an immersion transverse to the fibers, $N = \phi(M)$, then

$$\int_{M} \left| \operatorname{Jac} \phi \right| \left| \operatorname{Jac} p_{H(x)} \right| = \int_{N} \left| \operatorname{Jac} p_{H(x)} \right| dx = \int_{B} \left| F(y) \cap N \right| dy.$$

Now we derive the local formula for a surface M in \mathbb{R}^3 . Let l be a line in the tangent space to $x \in M$, and let |k(x, l)| be the module of the normal curvature of M at x in the direction l; i.e., k(x, l) is the curvature of the plane curve $M \cap (v_x \oplus l)$, v_x the normal line to M at x.

We define

$$h_1(x) = \frac{1}{\text{Vol}(\mathbf{P}_1)} \int_{\mathbf{P}_1(T_1(M))} |k(x, l)| dl.$$

When M is convex at x, $h_1(x)$ is the mean curvature of M at x.

PROPOSITION I.2. For M a surface in \mathbb{R}^3 ,

$$L_1(M) = \frac{1}{\pi} \int_M h_1(x) dx.$$

Proof. Let $\pi: E = E(3, 2) \rightarrow G(3, 2) = G$ be the tautological line bundle, $E = \{h \in G, x \in h\}.$

Let $\phi: P_1(M) \to E$ be the map

$$\phi(x, l) = (h = l^{\perp}, p_h(x)),$$

and let $\phi(P_1(M)) = N$. We know that

$$\int_{G} |\gamma_{h}| dh = \int_{P_{1}(M)} |\operatorname{Jac} \phi| |\operatorname{Jac} p_{H}|,$$

so we compute the Jacobians.

Let l be a line through x in $T_x(M)$, v_x denote the line normal to M at x, $h = l^{\perp}$ the subspace of \mathbb{R}^3 orthogonal to l and W the orthogonal to v_x in h; cf. Figure 1.

We choose a basis of $T_{(x,l)}(P_1(M))$ as follows:

- U_f is a unit vector tangent to the circle fiber of $P_1(M)$ at x,
- U_{Γ} is a horizontal lift of a unit vector tangent to Γ_h at x,
- U_l is a horizontal lift of a unit vector tangent to $(l \oplus v_x) \cap M$ at x.

Also, let U_{ν} be a horizontal lift (in E) of a unit vector tangent to γ_h at γ_h .

The volume of the parallelepiped generated by the first three vectors is $|\cos \theta|$ where θ is the angle between $T_x \Gamma_h$ and h.

The image $d\phi(U_{\Gamma})$ is the vector $\pm \cos(\theta)U_{\gamma}$. The vector $d\phi(U_{f})$ and $d\phi(U_{l})$ are projected by the differential $d\pi$ of the projection $\pi: E(3,2) \to G(3,2)$ on two orthogonal vectors of $T_{\pi\phi(x)}G(3,2)$; the first unitary and the second of norm |k(x,l)|.

Hence

$$|\operatorname{Jac} \phi(x)| |\operatorname{Jac} p_H| = |k(x, l)|,$$

and I.2 follows by integrating over the fibers of $P_1(M)$.

Remark. A different proof of this can be found in [L-S] based on a Meusnier formula.

Now we define the functions $h_i(x)$ when $M \subset \mathbb{R}^n$ is a hypersurface. Let $l = l^i$ be an *i*-dimensional subspace of $T_x(M)$, and let v(x) be the normal line to M at x. Denote by |K|(x, l) the absolute value of the Gauss-Kronecker curvature at x of the hypersurface $M \cap (l \oplus v(x))$ of $l \oplus v(x)$. Then we define

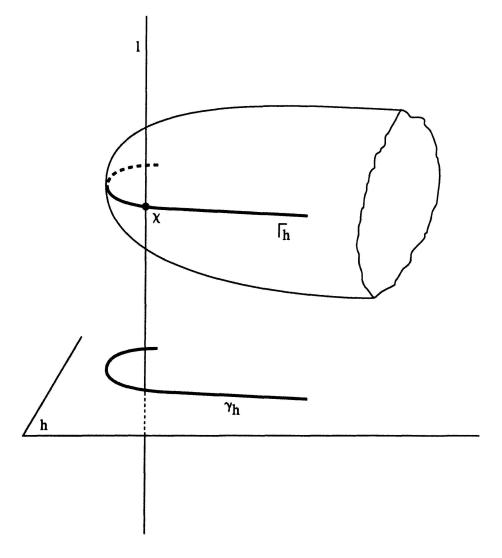


Figure 1

$$h_i(x) = \frac{1}{\operatorname{Vol} G(n-1, i)} \int_{G(T_i, M_i)} |K|(x, l) \, dl,$$

where $G(T_xM, i)$ is the *i*-dimensional subspaces of $T_x(M)$.

Now I.2 generalizes to \mathbb{R}^n .

PROPOSITION I.3. The functions $h_{n-i}(x)$ localize the functions $L_i(M)$; more precisely,

$$\int_{M} h_{n-i}(x) = cL_{i}(M),$$

where the constant c depends only on the dimensions.

Proof. Let G be the bundle over M whose fibers are the spaces $G(T_xM, l)$, l an n-1-i dimensional subspace of T_xM , and let $E=E(n, i+1) \rightarrow G(n, i+1)$ be the tautological bundle.

Define $\phi: G \rightarrow E$ by

$$\phi(x, l) = (h = l^{\perp}, p_h(x)).$$

Notice that the dimension of G(M, n-1-i) is equal to the dimension of $N = \bigcup_{h \in G(n,i+1)} \gamma_h$, which is $in + n + i^2 - i - 1$.

Now the proof proceeds as in I.2; we leave the details to the reader.

I.4. The cinematic formulae

We will show that the p-length of a submanifold $M \subset \mathbb{R}^n$ is equal to the (p-i)-length of the sections of M by affine subspaces of codimension i (up to a constant only depending on dimensions; we will denote such constants by c here).

The idea is to use the Cauchy formula and a projection in cascade.

Let D denote the flag of all pairs (h, L) where $g \in G_{n,p+1}$ and L is an affine subspace of h of codimension i.

When L is transverse to γ_h , the points of $\gamma_h \cap L$ are the critical points of the projection of $M \cap (L \oplus h^{\perp})$ to the vector subspace l determined by L. Let $H = L \oplus h^{\perp}$; H is an affine subspace of codimension i in \mathbb{R}^n .

Since $\gamma(M \cap H, l) = \gamma_h \cap L$, we have

$$|\gamma_h| = c \int_{L \in A(h,p+1-l)} |\gamma(M \cap H, l)|.$$

Hence

$$L_p(M) = c \int_{G(n,p+1)} \left(\int_{A(h,p+1-i)} |\gamma(M \cap H, l)| \right).$$

Notice that D can be thought of as $\{H \in A(n, n-i), l \in G(H, p+1-i)\}$, hence D is a Riemannian fibration over A(n, n-i) with fiber G(H, p+1-i).

Now

$$c \cdot L_{p-i}(M \cap H) = \int_{G(H,p+1-i)} |\gamma(M \cap H, l)|,$$

hence one has the cinematic formula:

$$L_p(M) = c \int_{A(n,n-i)} L_{p-i}(M \cap H).$$

II. Surfaces in S^3

In this section we will define the length functionals of surfaces in S^3 and establish the local and cinematic-type formulae. There are technical difficulties that arise here (in contrast to \mathbb{R}^3) due to the fact that the distortion of the projection in S^3 to a geodesic sphere depends on the point.

We begin with $L_2(M)$ (= the area of M) and the spherical Cauchy-Crofton formula [Sa].

THEOREM II.1. For M a compact surface in S^3 ,

$$L_2(M) = \frac{1}{\pi} \int_{G(4,2)} |M \cap l| dl,$$

where l is a great circle of S^3 (which we can think of as a 2-plane through the origin of \mathbb{R}^4), $|M \cap l|$ is the number of points of $M \cap l$.

Proof. Consider the map $\phi: P(TS^3/M) \to G(4, 2)$, $\phi(x, L) = l$ where l is the great circle whose tangent at x is L

Write the tangent space to G(4, 2) at l_0 as an orthogonal sum:

$$T_{l_0}G(4,2) = T_{l_0}\{l/x \in l\} \oplus T_{l_0}\{l \perp \Sigma_{l_0,x}\},$$

where $\Sigma_{l,x}$ is the geodesic 2-sphere at x orthogonal to l.

Write $T_{(x,L)}(PTS^3/M) = V \oplus H$ where V is the tangent space to the fiber and $H = V^{\perp}$. Then

$$d\phi = \begin{pmatrix} Id & * \\ \bigcirc & p_{L^{\perp}} \end{pmatrix},$$

where $p_{L^{\perp}}$ is the orthogonal projection of $T_x M$ to $T_x(\Sigma_{l,x}) = L^{\perp}$. Then

$$\int_{L \in P_x(TS^3/M)} \left| \operatorname{Jac} d\phi \right| = \int_{P_2} \left| \cos \not< (L^{\perp}, T_x M) \right| = \pi.$$

Since

$$\int_{G(4,2)} |\phi^{-1}(l)| = \int_{G(4,2)} |l \cap M|,$$

we have

$$\int_{G(4,2)} |l \cap M| = \pi |M|.$$

Now we discuss $L_1(M)$. Let $a = (x, -x) \in G(4, 1)$, be a pair of antipodal points of S^3 which are not on M. This point a determines a projection $p_{\Sigma} : M \to \Sigma$ where Σ is the geodesic 2-sphere of S^3 conjugate to a (i.e. dist $(x, \Sigma) = \pi/2$). By definition $p_{\Sigma}(y)$ is the point of Σ which is the intersection with Σ of the geodesic of S^3 through a and y. Let Γ_{Σ} be the critical points of p_{Σ} and γ_{Σ} the critical values.

DEFINITION.
$$L_1(M) = (1/2\pi^2) \int_{G(4,3)} |\gamma_{\Sigma}| d\Sigma$$
.

The constant is chosen so that the 1-length of an ε tubular neighborhood of a curve C tends to the length of C as $\varepsilon \to 0$. This choice will be justified once we have established the cinematic formulae for L_1 .

Now just as in \mathbb{R}^3 we define an extrinsic function h_1 on M. Let k(x, l) be the geodesic curvature at x of the curve $\Sigma_l \cap M$ in Σ_l , where Σ_l is the geodesic 2-sphere at x tangent to l and $v_x = T_x(M)^{\perp}$. Then define

$$h_1(x) = \frac{1}{\pi} \int_{P_1(T_x,M)} |k(x, l)| dl.$$

THEOREM II.2. For M a compact surface in S^3 ,

$$L_1(M) = \frac{1}{\pi} \int_M h_1.$$

Proof. For $x \in M$, let Σ_x be the geodesic 2-sphere tangent to M at x. Let P be the bundle over M with fiber the projective space P_2 :

$$P = \{(x, a)/a = (y, -y), y \in \Sigma_x\}.$$

Denote by Σ_a^* the geodesic 2-sphere conjugate to the pair a = (y, -y), and let $E = E(4, 3) \rightarrow G(4, 3) = G$ be the tautological bundle:

$$E = \{(\Sigma, y)/\Sigma \text{ a geodesic 2-sphere, } y \in \Sigma\}.$$

Then define $\phi: P \to E$ by:

$$\phi(x,a) = (\Sigma_a^*, p_{\Sigma_a^*}(x)).$$

By construction $N = \phi(P)$ is the union of the critical values γ_{Σ} ; $N = \bigcup_{\Sigma} \gamma_{\Sigma}$ (cf. Figure 2; the polar curve Γ_{Σ} is the set of critical points of the orthogonal projection on Σ , and the critical values Γ_{Σ} is in $p_{\Sigma}(\Gamma_{\Sigma})$).

Then

$$\int_{G_{4,3}} |\gamma_{\Sigma}| \, d\Sigma = \int_{P} |\operatorname{Jac} \phi| \, |\operatorname{Jac} p_{H}|,$$

so we must calculate the Jacobians.

To do this we decompose $T_{(x,a)}P$ and TN.

As y varies on Σ , Σ_y^* spans a sphere $S(\Sigma)$ contained in G.

Let F be the 3-dimensional orthogonal complement of $T\gamma_{\Sigma}$ in TN, at the point $u=(\Sigma_a^*, p_{\Sigma_a^*(x)})$. Write $F=F_1\oplus F_2$ (at x), where F_1 is the lift of $T_{\Sigma_a^*}(S(\Sigma))$ to F and F_2 is the orthogonal complement of F_1 in F. So $TN=F_1\oplus F_2\oplus T\gamma_{\Sigma}$, at x. Let H_1 be the horizontal lift to H(E) of $T_{\Sigma_a^*}(S(\Sigma))$, and let H_2 be H_1^{\perp} in H(E).

Now define a splitting of $T_{(x,y)}P$, non orthogonal in general, as follows. Write $T_xM = T_x\Gamma_{\Sigma_y^*} + L$, where L is the line tangent to the circle l joining x to y (this is not orthogonal in general). Let h_1 and h_2 be the horizontal lifts to P of $T_x\Gamma_{\Sigma_y^*}$ and L respectively.

We shall see that the matrix of $p_H \circ d\phi$ is then:

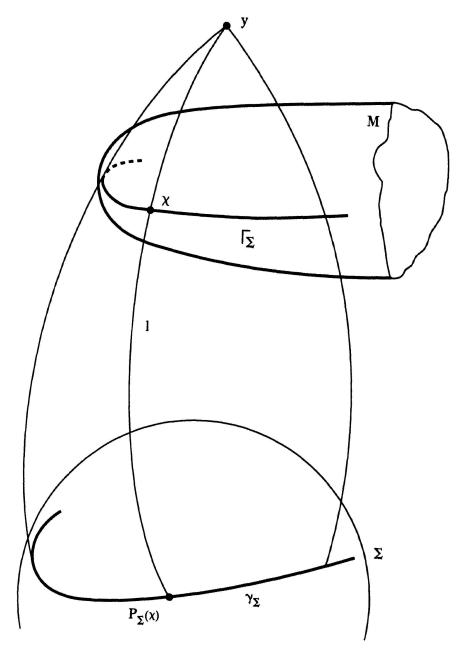


Figure 2

$$\begin{pmatrix} \alpha & * & * \\ 0 & Id & * \\ 0 & 0 & k(x, L)|\sin \theta| \end{pmatrix}$$

here α is the Jacobian of the projection of Γ_{Σ} on γ_{Σ} and θ is the arclength on l between x and y. This matrix is computed with respect to the basis vectors $\{h_1, T_{(x,y)}\Sigma_x, h_2\}$ of the domain and the basis vectors $\{T\gamma_{\Sigma}, H_1, H_2\}$ of the range. We calculate the matrix of $p_H \circ d\phi$ on $H_1 \oplus H_2$; identifying $H_1 \oplus H_2$ with TG.

By definition of Γ_{Σ} , $d\phi(h_1) \subset T\gamma_{\Sigma}$.

The coefficient α satisfies: $\alpha |\sin \theta| = \alpha_0$, where α_0 is the Jacobian of the projection of Γ_{Σ_0} on γ_{Σ_0} , when the geodesic sphere Σ_0 is orthogonal to l at x. This follows from lemma II.3, which we prove shortly.

By definition of $T_{\Sigma_d^*}(S(\Sigma))$, $d\phi(T_{(x,y)}\Sigma_x)$ is of the form:

$$\begin{pmatrix} * \\ Id \\ 0 \end{pmatrix}$$

It remains to determine the component of $d(p \circ \phi)(h_2)$ on H_2 . For that, we follow a point on the circle tangent at ξ , where ξ is a point moving on the curve C of intersection of M with the geodesic sphere at x containing l and the normal geodesic circle to M at x (cf. Figure 3). Figure 3 shows the analogous map for a curve on S^2 : the length of the arc of the evolute (image of the arc dl between x and

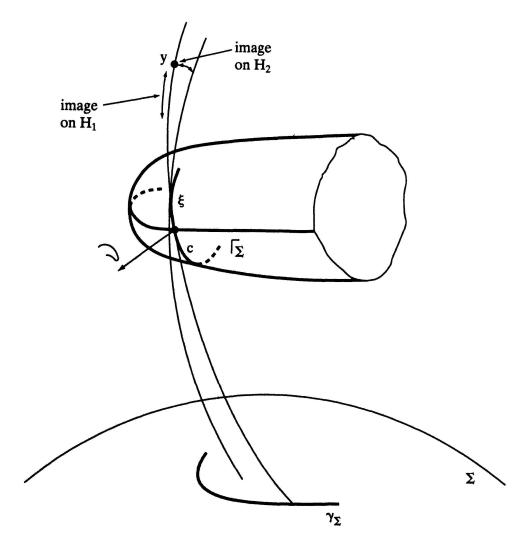


Figure 3

 ξ) is $k(x)|\sin\theta|$, up to first order, where θ is the arc length along l between x and y (since $k(x) = d\varphi/ds$).

The same analysis applies in S^3 ; one gets $k(x, l) |\sin \theta|$.

The decomposition of TP is not orthogonal; the volume of the parallelepiped generated by h_1 , $T_{(x,y)}\Sigma_x$ and h_2 is α_0 .

The volume density on $P(\Sigma_x)$ is $|\sin \theta \, d\theta \wedge d\varphi|$ where (θ, φ) are polar coordinates at x on the space $P(\Sigma_x)$ of pairs of antipodal points on Σ_x .

Hence

$$\int_{P} \left| \operatorname{Jac} \phi \right| \left| \operatorname{Jac} p_{H} \right| = \int_{M} \int_{P(\Sigma_{x})} \frac{\alpha_{0} |k(x, l)| \left| \sin \theta \right| \left| d\theta \wedge d\phi \right|}{\alpha_{0}}$$

$$= 2\pi \int_{M} h_{1}(x) dx.$$

To complete the proof of theorem II.2 we now prove Lemma II.3.

LEMMA II.3. Let C(t) be a curve on a surface M embedded in \mathbb{R}^3 . Assume $\dot{C}(t)$ is not in the kernel of γ at C(t), γ the Gauss map of M. Then the characteristic line of the envelope of the family of tangent planes to M along C(t) is $d\gamma(\dot{C})^{\perp}$.

Proof. The equations of the envelope are:

$$\langle X - x, \gamma(x) \rangle = 0,$$

$$\langle X - x, d\gamma(\dot{C}) \rangle = 0.$$

As an immediate corollary of this lemma we have: if $K(x) \neq 0$ (so $d\gamma(x)$ is non singular), all the curves C through x (C on M), such that the characteristic line through x of the envelope of the family of planes $T_{C(t)}M$ is a given line D, are tangent at x to the line Δ such that $d\gamma(\Delta) = D$.

The analogous result in S^3 , using envelopes of geodesic spheres tangent to M along a curve, follows from the following remark concerning cones in \mathbb{R}^4 , over $M \subset S^3$ and C(t) a curve on M. Then the envelope of the family $T_{C(t)}(Z)$, contains the 2-plane $(d\gamma(\dot{C}(t)))^{\perp}$, (orthogonal in $T_{C(t)}Z$ to $d\gamma(\dot{C}(t))$) whenever $\dot{C}(t)$ is not contained in $Ker d\varphi$. This remark is clear since the equations of the 2-plane are as before:

$$\langle X - C(t), \gamma(C(t)) \rangle = 0$$

$$\langle X - C(t), d\gamma(\dot{C}(t)) \rangle = 0.$$

We finish this section with a discussion of $L_0(M)$. By definition:

$$L_0(M) = \frac{1}{2 \text{ Vol}(G(4,2))} \int_{G(4,2)} |\gamma_l| \, dl,$$

where $|\gamma_l|$ is the number of critical points of the projection of M to the geodesic l; the projection along the (singular) foliation $\mathcal{F}(l)$ of geodesic 2-spheres orthogonal to l. Notice that $|\gamma_l|$ is the number of points of contact of M and $\mathcal{F}(l)$, for almost all l. The constant is chosen so that $L_0(\partial B(x, \varepsilon)) = 1$, for $\varepsilon \to 0$.

THEOREM II.4. Let M be a surface in S^3 and K(x) be the extrinsic Gauss curvature of M at x. Then

$$L_0(M) = \frac{1}{4\pi} \int_M |K(x)|.$$

Proof. Let $E = E(4, 2) \rightarrow G(4, 2) = G$ be the tautological fibration and let P(M) be the bundle over M of the geodesic 2-spheres tangent to M. Define $\phi: P \rightarrow E$ by:

$$\phi(x, y) = (y, l \text{ is orthogonal to } \Sigma_x \text{ at } y).$$

Here Σ_x is the geodesic sphere tangent to M at x. Let $N = \phi(P)$ and H be the horizontal field of the bundle $E \to G$.

Take a basis of $T_{(x,y)}P$ composed of a unitary frame tangent to Σ_x at y and two horizontal unit vectors that project to two unitary vectors tangent to the principal directions to M at x. Then it is clear that the proof of II.4 follows from Lemma II.5 below.

First we define the 0-length of a curve C on S^2 :

$$L_0(C) = \frac{1}{4\pi} \int_{G(3,2)} \left| \gamma_l \right| dl.$$

Then we have:

LEMMA II.5. Let k_g be the geodesic curvature of a curve $C \subset S^2$. Then

$$L_0(C) = \frac{1}{2\pi} \int_C |k_g|.$$

Proof. Let $E = E(3, 2) \rightarrow G(3, 2) = G$ be the tautological fibration and P(C) the bundle over C with fibers the geodesic circles of S^2 tangent to C. Define $\phi: P(C) \rightarrow E$ by

$$\phi(x, y) = (y, l \text{ is orthogonal to } \Sigma_x \text{ at } y).$$

Here Σ_x is the geodesic circle tangent to C at x. We have

$$\left| \operatorname{Jac} p_H \right| = \left| \cos d(x, y) \right| \left| k_g \right|,$$

so integrating on the fibers of P(C) we have

$$\int_C |k_g| = C_0 \cdot L_0(C).$$

Since

$$\lim_{\varepsilon \to 0} \int_{\partial B(x,y)} |k_g| = 2\pi,$$

we see that $C_0 = 2\pi$.

Now we derive a cinematic-type formula satisfied by $L_1(M)$.

THEOREM II.6. Let M be a surface in S^3 . Then

$$L_1(M) = \frac{1}{\pi} \int_{G(4,3)} L_0(M \cap \Sigma).$$

The constant is obtained by considering small spheres S_t . Then $L_1(S_t) \sim 4t$ and $\int_{G(4,2)} L_0(S_t \cap \Sigma) \sim 4\pi t$.

Proof. By definition,

$$L_1(M) = \frac{1}{2\pi^2} \int_{G(4.3)} |\gamma_{\Sigma}|.$$

The Cauchy-Crofton formula in S^2 says:

$$|\gamma_{\Sigma}| = \frac{1}{2} \int_{G(3,2)} |\gamma_{\Sigma} \cap l|.$$

The inverse image of the orthogonal projection onto Σ of the great circle l is a sphere Σ_l . The points of $\gamma_{\Sigma} \cap l$ are the critical points of the orthogonal projection of $\Sigma_l \cap M$ onto l. Hence

$$L_1(M) = \frac{1}{4\pi^2} \int_{G(4,3)} \int_{G(3,2)} |\gamma_{\Sigma} \cap l| = \frac{1}{4\pi^2} \int_{D(4,3,2)} |\mu| (\Sigma_l \cap M, P_l),$$

where P_l is the (singular) foliation of Σ_l by geodesics orthogonal to l. Here D = D(4, 3, 2) is the space of flags (Σ, l) , $\Sigma \supset l$. The map $D \mapsto D$, $(\Sigma \supset l) \mapsto (l \subset \Sigma)$, is an isometry of D. Hence

$$L_1(M) = \frac{1}{4\pi^2} \int_{G(4,3)} 4\pi L_0(\Sigma \cap M) = \frac{1}{\pi} \int_{G(4,3)} L_0(\Sigma \cap M),$$

which completes the proof of II.6.

III. The Fenchel theorem for surfaces in S^3

Let D = D(4, 3, 2, 1) be the space of flags $\Delta = (y \subset l \subset \Sigma)$ where y is a pair of antipodal points of a geodesic l contained in a geodesic sphere Σ of S^3 . Given Δ , let $\mathcal{F}(y)$ be the foliation (singular) of Σ by the geodesics of Σ passing through y and let $\mathcal{F}(l)$ be the foliation of S^3 by the geodesic spheres of S^3 containing l.

For M a compact surface in S^3 we define the geometry of M with respect to Δ , by

Geom
$$(M, \Delta) = \#(l \cap M) + |\mu|(M \cap \Sigma, \mathscr{F}(y)) + |\mu|(M, \mathscr{F}(l)),$$

where $|\mu|(M \cap \Sigma, \mathscr{F}(y))$ is the number of points of contact of $M \cap \Sigma$ and $\mathscr{F}(y)$, and $|\mu|(M, \mathscr{F}(l))$ the number of contact points of M and $\mathscr{F}(l)$. If M is transvere to Δ (i.e. $y \notin M$ and l and Σ are transverse to M) and if $M \cap \Sigma$ is in general position with respect to $\mathscr{F}(y)$, M in general position with respect to Δ , then Geom (M, Δ) is well defined. This holds for almost every $\Delta \in D$.

Hence we can define the geometry of M:

Geom
$$(M) = \frac{1}{\operatorname{Vol}(D)} \int_{D} \operatorname{Geom}(M, \Delta).$$

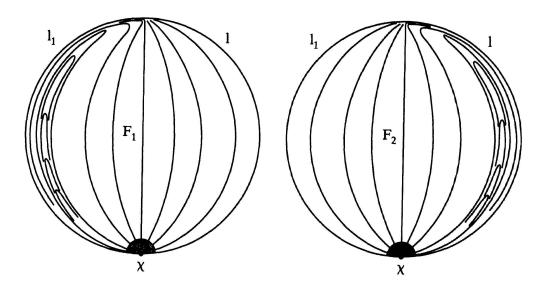


Figure 4

THEOREM III.1. Geom $(M) \ge 2g + 2$, g the genus of M, and if M is knotted in S^3 Geom $(M) \ge 2g + 4$. (M oriented).

Proof. It suffices to prove the inequalities for $Geom(M, \Delta)$ whenever M is transverse to Δ and in general position with respect to $\mathcal{F}(y)$ and $\mathcal{F}(l)$. To do this we shall construct a foliation $\mathcal{F} = \mathcal{F}(t)$ of $S^3 - B(x, t)$ for t > 0 small, $x \in y$, B(x, t) the t-ball of S^3 centered at x, satisfying:

- Geom $(M, \Delta) = |\mu|(M, \mathcal{F})$
- \mathcal{F} is smoothly equivalent to a foliation of \mathbb{R}^3 by parallel planes,
- M is in general position with respect to \mathcal{F} .

Then the standard Morse theory applies and the theorem follows.

Let t>0 be chosen so that B(x,t) is disjoint from M. Let Σ_1 be one of the hemispheres of Σ bounded by l, $\Sigma=\Sigma_1\cup\Sigma_2$, $\Sigma_1\cap\Sigma_2=l$. Let \mathscr{F}_1 be a one-dimensional foliation of $\Sigma_1-B(x,t)$ as in Figure 4). Notice that l is a leaf of \mathscr{F}_1 (actually l-B(x,t)). We require the leaves of \mathscr{F}_1 to be geodesics of Σ_1 through y, outisde of a small tubular neighborhood of l in Σ_1 .

This foliation of Σ_1 has a "Reeb-type" component near an arc $x = l_1$ of l going from -x to $\partial B(x, t)$ (the left side of l in Figure 4). Notice that if C is a curve on Σ , transverse to l_1 , then the foliation \mathcal{F}_1 can be constructed so that $\#(C \cap l_1) =$ the number of contact points of C and the Reeb-type component of \mathcal{F}_1 . It suffices to construct \mathcal{F}_1 so the Reeb-type component is close enough to l_1 .

Similarly, define a foliation \mathcal{F}_2 of $\Sigma_2 - B(x, t)$, with the Reeb type component of \mathcal{F}_2 close to the other arc of l, i.e. $l - l_1$; cf. Figure 4.

Now define $\mathscr{F}(\varepsilon)$; the trace of $\mathscr{F}(\varepsilon)$ on Σ will be $\mathscr{F}_1 \cup \mathscr{F}_2$; $\varepsilon = t$.

Each leaf α of \mathscr{F}_1 bounds a 2-disk in Σ_1 (more precisely, each leaf of \mathscr{F}_1 , together with an arc on $B(x, \varepsilon) \cap \Sigma_1$ joining the extremities of α , bounds a disk in Σ_1). Let

 α_1 be a leaf of \mathscr{F}_1 as indicated in Figure 4, and consider the leaves of α of \mathscr{F}_1 inside the disk of Σ_1 bounded by α_1 . Let $D(\alpha)$ be the disk of Σ_1 bounded by α . Let $F(\alpha)$ be a 2-disk in S^3 which is a thickened $D(\alpha)$; imagine $F(\alpha)$ as a thin pancake over $D(\alpha)$. $F(\alpha)$ is orthogonal to Σ_1 and $F(\alpha) \cap \Sigma_1 = \alpha$. In S^3 , Σ separates S^3 into two balls B_1 and B_2 , and $F(\alpha)$ intersects each ball in a 2-disk close to $D(\alpha)$.

Choose the $D(\alpha)$, α inside $D(\alpha_1)$, so that the $\bigcup_{\alpha} F(\alpha)$ foliate a part of S^3 , and all the $F(\alpha)$ are sufficiently flat so the foliated set is close to $D(\alpha)$. (One can do this by pushing one's thumb into $S^3 - B(x, \varepsilon)$, starting at $a \in \partial B(x, \varepsilon)$ to create the Reeb component. One keeps on pushing almost until x. The thumb starts out as a very thin thumb and then spreads out as a thin pancake till α_1 .)

Let $\Sigma(l)$ be the geodesic 2-sphere of S^3 containing l, which is orthogonal to Σ along l (in the ball B_1 for example, if one imagines Σ_1 as the upper hemisphere, then $\Sigma(l) \cap B_1$ is the equatorial plane). Now foliate the region of $S^3 - B(x, \varepsilon)$ between $F(\alpha_1)$ and $\Sigma(l) - B(x, l)$ by "blowing out" $F(\alpha_1)$ to $\Sigma(l)$. More precisely, the region in question is topologically $F(\alpha_1) \times [0, 1]$. One puts the product foliation in the region. However one does this so all the leaves outside a small tubular neighborhood of Σ , are leaves of $\mathcal{F}(l)$, i.e. they coincide with geodesic spheres containing l, outside of a tubular neighborhood of Σ .

This defines $\mathscr{F}(\varepsilon)$ on half of $S^3 - B(x, \varepsilon)$. To extend to the other half, one does the same thing we just did, blowing down to the foliation by thin pancakes close to the foliation \mathscr{F}_2 of Σ_2 . In fact, if β is the geodesic of S^3 through y and orthogonal to Σ , then one extends $\mathscr{F}(\varepsilon)$ by rotating $\mathscr{F}(\varepsilon)$ by π around β .

By construction, all the leaves of $\mathscr{F}(\varepsilon)$, outside a tubular neighborhood of Σ , are parts of the geodesic spheres of $\mathscr{F}(l)$. Now if M is a surface in S^3 , transverse to Σ , $y \notin M$ (i.e. $x \notin M$ and $-x \notin M$) and M in general position with respect to $\mathscr{F}(y)$ and $\mathscr{F}(l)$, then constructing $\mathscr{F}(\varepsilon)$ so that the tubular neighborhoods of l (to define \mathscr{F}_1) and of Σ , are small, one sees that $\operatorname{Geom}(M, \Delta) = |\mu|(M, \mathscr{F}(\varepsilon))$. A moments inspection shows $\mathscr{F}(\varepsilon)$ is equivalent to a parallel foliation of \mathbb{R}^3 . This completes the proof of Theorem III.1.

THEOREM III.2. Let M be a compact surface in S^3 . Then Geom(M) is a linear combination of $L_0(M)$, $L_1(M)$ and $L_2(M)$:

Geom
$$(M) = \pi^3 L_2(M) + 4\pi^3 L_1(M) + 2\pi^2 \text{ Vol } G(4, 2)L_0(M).$$

Proof. We have

$$\int_{D} |l \cap M| = \pi^{2} \int_{G(4,2)} |l \cap M| = \pi^{3} L_{2}(M) \quad \text{by II.1.}$$

Also

$$\int_{D} |\mu|(M \cap \Sigma, \mathscr{F}(y)) = \pi \int_{D(4,3,1)} |\mu|(M \cap \Sigma, \mathscr{F}(y))$$

$$= \pi \int_{G(4,3)} 4\pi L_0(M \cap \Sigma) = 4\pi^3 L_1(M) \quad \text{by II.6.}$$

Finally

$$\int_{D} |\mu|(M, \mathcal{F}(l)) = \pi^{2} \int_{G(4,2)} |\mu|(M, \mathcal{F}(l))$$

$$= 2\pi^{2} \operatorname{Vol}(G(4,2)) L_{0}(M) \quad \text{by definition of } L_{0}(M).$$

COROLLARY III.3.

Geom(M) =
$$\int_{M} \pi^{3} + 2\pi h_{1}(x) + \frac{\pi}{2} \text{Vol } G(4, 2) |K(x)|.$$

Proof. This follows immediately from Theorem III.2 and the local formulae.

IV. Geometry of $M^{n-1} \subset S^n$

Let D = D(n, n-1, ..., 1) be the space of flags $\Delta = (\Sigma^0 \subset \Sigma^1 \subset \cdots \subset \Sigma^n = S^n)$ each Σ^i and *i*-dimensional geodesic sphere of S^n . Define $\mathscr{F}(i, i+2)$ to be the (singular) foliation of Σ^{i+2} by geodesic i+1 spheres that contain Σ^i . Denote $M \cap \Sigma^{i+2}$ by M_i when M is in general position with respect to Δ (we subsequently assume this).

We define the geometry of M with respect to Δ .

Geom
$$(M, \Delta) = |M \cap \Sigma^1| + \sum_{i=2}^n |\mu| (M_i, \mathcal{F}(i-2, i)).$$

As in the proof of III.1 one has:

THEOREM IV.1. Let $M^{n-1} \subset S^n$ be in general position with respect to the flag Δ . Then there is an $\varepsilon > 0$ and foliation $\mathscr{F} = \mathscr{F}(\Delta)$ of $S^n - B(x, \varepsilon)$, $x \in \Sigma^0$, satisfying:

- Geom $(M, \Delta) = |\mu|(M, \mathcal{F})$, and
- \mathcal{F} is smoothly equivalent to a foliation of \mathbb{R}^n by parallel hyperplanes.

THEOREM IV.2. Geom(M) is a linear combination of $L_0(M)$, $L_1(M)$, ..., $L_{n-1}(M)$;

Geom
$$(M)$$
 = $\int_D \text{Geom}(M, \Delta) = \sum_{i=0}^{n-1} c_i L_i(M)$,

where c_0, \ldots, c_{n-1} are dimension constants.

COROLLARY IV.3. For $M^{n-1} \subset S^n$, one has

$$\sum_{i=0}^{n-1} c_i L_i(M) \ge \beta(M),$$

 $\beta(M)$ the sum of the Betti numbers of M.

V. The geometry of submanifolds $M \subset S^n$ of arbitrary codimension

Similar results can be obtained in higher codimension. The construction of the foliation associated to a complete flag is unchanged. Therefore we can extend the results obtained in \mathbb{R}^n (see [C-L], [Fe], [L-R]).

THEOREM V.1. Let V be a compact manifold immersed in S^n . Then

$$Geom(V) \ge \sum_{i} \beta_{i}$$

where the β_i are the Betti numbers of V.

If V is the sphere S^p and is embedded, the condition

implies that V is an unknotted sphere (topologically and differentiably for p = 1, all n; p = 2 n = 4; $p \ge 5$, n = p + 2).

The integral geometric construction requires one more step. For example, in the codimension 2 case $(V^{n-3} \subset S^{n-1})$, we need to consider the "quasi flag space" D(n, n-2, n-1, n-2) of

$${h \subset k \supset l, \dim(h) = n - 2, \dim(k) = n - 1, \dim(l) = n - 2}.$$

Notice that the dimension of the fiber bundle \mathfrak{D} on V

$$\mathfrak{D} = \{ x \in V, h_x \subset k \supset l, \dim(k) = n - 1, \dim(l) = n - 2 \},$$

where h_x is the vector space spanned by the geodesic sphere tangent at x to V, is 2(n-2), the same as that of the Grassmann manifold G(n, n-2).

THEOREM V.2. A curve C embedded in S³ satisfies

$$\int_{C} |k_g| + 1 \ge 2\pi$$

$$\int_{C} |k_g| + 1 \ge 4\pi$$

if C is knotted, and more precisely

$$\int_{C} |k_{g}| + 1 \ge 2\pi \cdot (bridge \ number \ of \ C).$$

The first result was already proved by Banchoff [Ba]; the two others extend results of Fenchel, Fary and Milnor [Fe], [Fa], [M₁], [M₂]; and Sunday [Su].

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