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# Sphere-packing and volume in hyperbolic 3-space

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# I. INTRODUCTION

A hyperbolic 3-manifold is a Riemannian manifold of constant sectional curvature -1. We will restrict our attention to complete orientable hyperbolic 3-manifolds M; as such, we can think of M as  $H^3/\Gamma$  where  $\Gamma$  is a discrete torsion-free subgroup of  $\text{Isom}_+(H^3)$ , the orientation-preserving isometries of hyperbolic 3-space. We will generally work in the upper-half-space model  $H^3$  of hyperbolic 3-space, in which case  $PGL(2, \mathbb{C})$  acts as orientation-preserving isometries on  $H^3$  by extending the action of  $PGL(2, \mathbb{C})$  on the Riemann sphere (boundary of  $H^3$ ) to  $H^3$ . An orbifold is a space locally modelled on  $\mathbb{R}^n$  modulo a finite group action. Complete orientable hyperbolic 3-orbifolds Q correspond to discrete subgroups  $\Gamma$  of  $PGL(2, \mathbb{C})$ . If the discrete group  $\Gamma$  corresponding to M or Q has parabolic elements then M or Q is said to be cusped.

Unless otherwise stated, we will assume all manifolds and orbifolds are orientable. Mostow's theorem implies that a complete, hyperbolic structure on a 3-orbifold of finite volume is unique. Consequently, hyperbolic volume is a topological invariant for orbifolds admitting such structures. Jørgensen and Thurston proved (see [T] section 6.6) that the set of volumes of complete hyperbolic 3-manifolds is well-ordered and of order type  $\omega^{\omega}$ . In particular, there is a complete hyperbolic 3-manifold of minimum volume  $V_1$  among all complete hyperbolic 3-manifolds, and a cusped hyperbolic 3-manifold of minimum volume  $V_{\omega}$ . Further, all volumes of closed manifolds are isolated, while volumes of cusped manifolds are limits from below (thus the notation  $V_{\omega}$ ).

Modifying the proofs in the Jørgensen-Thurston theory yields similar results for complete hyperbolic 3-orbifolds (this result is folklore, and we will not prove it here). In particular, there is a hyperbolic 3-orbifold of minimum volume  $V'_1$ , and a cusped hyperbolic 3-orbifold of minimum volume  $V'_c$ .

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In [M1] and [M2] it is proved that

$$0.00064 < V_1 \le \text{vol} (M_{(5,1)}) \approx 0.98$$
  

$$\sqrt{3}/4 \le V_{\omega} \le \text{vol} (S^3 - \text{figure-eight knot}) = 2V \approx 2.02988$$
  

$$0.0000013 < V_1' \le 2 \cdot \text{vol} (\bigcirc \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc ) \approx 0.072$$
  

$$\sqrt{3}/24 \le V_c' \le \text{vol} (H^3/PGL_2(\mathcal{O}_3)) = V/12 \approx 0.0846$$

where  $M_{(5,1)}$  is the manifold obtained by performing (5, 1) Dehn surgery on the figure-eight knot in the 3-sphere, V is the volume of the ideal regular tetrahedron in  $H^3$ ,  $\longrightarrow$  denotes the (non-orientable) tetrahedral orbifold with that Coxeter diagram (see [T] theorem (13.5.3)), and  $\mathcal{O}_3$  is the ring of integers in  $\mathbf{Q}(\sqrt{-3})$ .

The left-hand inequalities of all of these estimates can be improved by using sphere-packing arguments. In this paper we prove,

 $0.00082 < V_1 \le 0.98 \dots^{(2)}$  $V/2 \le V_{\omega} \le 2V^{(3)}$  $0.0000017 < V'_1 \le 0.07177 \dots$  $V/12 \le V'_c \le V/12$ 

From the last set of inequalities we see  $V'_c = V/12$ , i.e.

THEOREM. The orbifold  $Q_1 = H^3/PGL_2(\mathcal{O}_3)$  has minimum volume among all orientable cusped hyperbolic 3-orbifolds.

*Remark.* The four right-hand inequalities above are simply a list of the lowest volume orbifolds and manifolds of the various types known to date. These volumes are computed by decomposing the orbifold or manifold into hyperbolic

<sup>&</sup>lt;sup>2</sup> Jeff Weeks has found a hyperbolic 3-manifold with less volume than  $M_{(5,1)}$  (Princeton Univ. Ph.D. thesis, 1985).

<sup>&</sup>lt;sup>3</sup>Colin Adams has improved the left-hand inequality for  $V_{\omega}$  by a factor of 2 (preprint, 1985).

tetrahedra and then using Lobachevsky's formula to compute the volumes of these tetrahedra (see [T] chapter 7 for the case of ideal hyperbolic tetrahedra, and [La] for the case of non-ideal tetrahedra – actually, these tetrahedra must be further decomposed into "doubly-rectangular" tetrahedra). The decomposition into tetrahedra for tetrahedral orbifolds is trivial. The tetrahedral decomposition of the figure-eight knot complement in the 3-sphere is carried out in [T] pages 3.6 and 3.7. Finally, solving the holonomy equations in section 4.6 of [T] for (p, q) = (5, 1) produces a decomposition of  $M_{(5,1)}$  into ideal hyperbolic tetrahedra (off of the surgered geodesic).

# **II. Sphere-packing**

We will be concerned with how densely equal radius balls can be packed without overlapping. In general, the density of S with respect to (finite volume) T is

$$d(S, T) = \frac{\operatorname{vol}(S \cap T)}{\operatorname{vol}(T)}.$$

We can extend this notion to Euclidean *n*-space  $\mathbf{E}^n$ , i.e.  $T = \mathbf{E}^n$  and S = (the union of non-overlapping, equal-radius balls), by defining upper and lower densities

$$d_U = \limsup_{r \to \infty} d(S, B(p, r))$$
 and  $d_L = \liminf_{r \to \infty} d(S, B(p, r))$ 

where B(p, r) is the radius r ball in  $\mathbf{E}^n$  centered at p. If  $d_L = d_U$  then we have a notion of global density for  $\mathbf{E}^n$ . The fact that  $d_L$  and  $d_U$  are independent of the base point p chosen is proven in [FT] pages 161, 162 (see also pg. 261). The argument hinges on the fact that

$$\lim_{r\to\infty}\frac{\operatorname{vol}\left(B(p,\,r+\varepsilon)\right)}{\operatorname{vol}\left(B(p,\,r)\right)}=1.$$

Attempting to use this notion of global density in hyperbolic *n*-space  $H^n$  is problematic because

$$\lim_{r \to \infty} \frac{\operatorname{vol} \left( B(p, r + \varepsilon) \right)}{\operatorname{vol} \left( B(p, r) \right)} = e^{\varepsilon(n-1)}$$

(in  $H^3$ , vol  $(B(p, r)) = \pi(\sinh(2r) - 2r)$ ). We will avoid this problem by dealing with a "local" notion of density. Given a collection  $\mathcal{B}$  of equal radius, non-overlapping balls in  $H^n$  we define the *local density* of a ball B in  $\mathcal{B}$  to be

$$\ell d(B, \mathcal{B}) = \frac{\operatorname{vol} (B \cap D)}{\operatorname{vol} (D)} = d(B, D)$$

where  $D = \{p \in H^n : p \text{ is closer to } B$  than to any other ball B' in  $\mathfrak{B}\} := D(B, \mathfrak{B})$  is the Dirichlet region for B with respect to  $\mathfrak{B}$ . This notion is ideally suited to studying volumes of hyperbolic 3-manifolds  $M = H^3/\Gamma$  because, given an embedded ball in M, the collection of all lifts of this ball to  $H^3$  gives a packing  $\mathfrak{B}$  of  $H^3$  upon which  $\Gamma$  acts transitively, and  $D(B, \mathfrak{B})$  for any B in  $\mathfrak{B}$  is a fundamental domain for  $M = H^3/\Gamma$  (see [G] Section 2.5). A similar notion holds for orbifolds  $Q = H^3/\Gamma$ , but we may have to "chop" B and D due to torsion elements in  $\Gamma$ . That is, if  $\Gamma_b$  is the stabilizer of the center b of B, then  $D/\Gamma_b$  is a fundamental domain for  $Q = H^3/\Gamma$  (see [Be] Section 9.6). This is not a problem, because  $d(B, D) = d(B/\Gamma, D/\Gamma_b)$ .

We can generalize local density to deal with a horoball packing ("horoball" is defined in Section III). The notion of a Dirichlet region  $D = D(B, \mathcal{B})$  still makes sense if we define the distance of a point p from a horoball B to be the length of the unique perpendicular geodesic from p to the horosphere boundary of B. The fact that  $B \cap D$  and D have infinite volume creates some problems. Thus, we define *local density*  $\ell d(B, \mathcal{B})$  in a 2-step procedure: Assume we are in upper-half-space  $H^3$  and that B is centered at the point at infinity. Then, we define

$$d_t = \lim_{c \to \infty} \frac{\operatorname{vol} \left( B \cap D \cap A(t, c) \right)}{\operatorname{vol} \left( D \cap A(t, c) \right)}$$

where  $A(t, c) = \{(x, y, z): -c < x < c, -c < y < c, and z \ge t\}$ . This definition is independent of the choice of origin (here the origin is (0, 0, t)); the independence-of-origin proof is a re-working of the proof for  $\mathbf{E}^n$  mentioned above, using the fact that horoballs have Euclidean structures on their horosphere boundaries and that vol  $(A(t, c)) = c^2/2 \cdot t^2$ . Since  $d_t$  is an increasing function of t, we can define  $\ell d(B, \mathcal{B}) = \lim_{t\to 0} d_t$ .

This is the appropriate notion of local density to use in studying hyperbolic 3-manifolds  $M = H^3/\Gamma$  with cusps. If we know that a cusped manifold contains an embedded cusp neighborhood, then lifting these cusp neighborhoods to  $H^3$  gives a collection  $\mathcal{B}$  of disjoint horoballs B upon which  $\Gamma$  acts transitively; but  $D(B, \mathcal{B})$ is no longer a fundamental domain for  $\Gamma$ . To get a fundamental domain F for  $\Gamma$  we simply take F to be a fundamental domain for the action of  $\Gamma_c$  on  $D(B, \mathcal{B})$ where  $\Gamma_c$  is the stabilizer of the center c of B ( $\Gamma_c$  is made up entirely of parabolic transformations). Using the above definition of local density for horoball packings, we have

$$\ell d(B, \mathcal{B}) = \frac{\operatorname{vol}(B \cap F)}{\operatorname{vol}(F)}.$$

The above holds verbatim for cusped orbifolds  $Q = H^3/\Gamma$  except that  $\Gamma_c$  may have elliptic as well as parabolic transformations.

We now state Böröczky's theorem (which applies to constant curvature spaces of arbitrary dimension) in the case of hyperbolic 3-space (See [B] theorems 1 and 4):

THEOREM (Böröczky). Consider 4 spheres of radius r in  $H^3$  each touching all the others. Their centers determine a regular tetrahedron T of edge length 2r and dihedral angles  $2\alpha$  where sec  $(2\alpha) = 2 + \text{sech}(2r)$ . Let S be the union of the 4 balls of radius r bounded by the 4 spheres. Then, for any radius r sphere-packing  $\mathcal{B}$  in  $H^3$  the local density satisfies

$$\ell d(B, \mathcal{B}) \leq \frac{\operatorname{vol}(S \cap T)}{\operatorname{vol}(T)} = \frac{(6\alpha - \pi)(\sinh(2r) - 2r)}{\operatorname{vol}(T)} := d(r)$$

This result holds for horosphere packings as well, in which case the centers of the horoballs (points of tangency with  $\partial H^3$ ) determine an ideal regular tetrahedron T, and

$$\ell d(B, \mathcal{B}) \leq \frac{\operatorname{vol}(S \cap T)}{\operatorname{vol}(T)} = \frac{4(\sqrt{3}/8)}{V} = \frac{\sqrt{3}}{2V} \approx 0.853, \quad \text{where} \quad V = \operatorname{vol}(T).$$

*Remark.* It was shown in [BF] that d(r) is an increasing function of r. The number  $d(0) \approx 0.7797$  is the density (with respect to the regular tetrahedron they determine) of 4 mutually touching equal radius balls in  $\mathbf{E}^3$ . The 4 horoball packing can be extended uniformly to all of  $H^3$ . In some sense, this is the densest packing of equal radius spheres in  $H^3$ . The densest packing of equal radius spheres in  $H^3$ . The densest packing of equal radius for  $\mathbf{E}^n$ . The difficulty is that the above tetrahedral packing does not extend uniformly to a global packing of  $\mathbf{E}^3$  (See [SL] and [R]).

# III. Remarks on hyperbolic space

As mentioned in Section 1, we are working in the upper-half-space model for hyperbolic 3-space,  $H^3 = \{(x, y, z): z > 0\}$  with metric  $ds^2 = (dx^2 + dy^2 + dz^2)/z^2$ and volume form  $dV = dx dy dz/z^3$ ;  $\partial H^3 = \mathbb{C} \cup \{\infty\}$ . The orientation-preserving isometries of hyperbolic 3-space can be identified either with  $PGL_2(\mathbb{C}) = GL_2(\mathbb{C})/\mathbb{C}^*$  or  $PSL_2(\mathbb{C}) = SL_2(\mathbb{C})/\pm I$  (See [S] pg. 448-449). But note that if  $\mathcal{O}_d$  is the ring of integers in  $\mathbb{Q}(\sqrt{-d})$  then  $PGL_2(\mathcal{O}_d)/PSL_2(\mathcal{O}_d) = \mathbb{Z}/2\mathbb{Z}$  where  $PGL_2(\mathcal{O}_d) = GL_2(\mathcal{O}_d)/\{\lambda I: \lambda \in \mathcal{O}_d^*\}$  and  $PSL_2(\mathcal{O}_d) = SL_2(\mathcal{O})_d/\pm I$  (See [H] pg. 346). Thus, the use of  $PGL_2(\mathcal{O}_d)$ , and not  $PSL_2(\mathcal{O}_d)$ , in the statement of Theorem 1.

In  $H^3$  a horoball B is either:

1) a Euclidean ball in  $\{(x, y, z): z \ge 0\}$  which is tangent to the xy plane, the point of tangency being the *center* of B; or it is

2) a half space of the form  $\{(x, y, z): z \ge a > 0\}$ , in which case the center of B is the point at  $\infty$ .

Note that the hyperbolic metric on  $H^3$  induces the Euclidean metric  $ds^2 = (dx^2 + dy^2)/a^2$  on  $\partial B \cap H^3 = \{(x, y, z) : z = a\}$ , that is the bounding horosphere of the horoball B is flat. There is no real distinction between horoballs of type 1 and type 2, because there are isometries of  $H^3$  taking either to the other. In particular, all horospheres are flat.

A discrete group  $\Gamma$  is said to have a *cusp* if  $\Gamma$  contains a parabolic element  $\gamma$ . Let the fixed point of  $\gamma$  be  $p \in \partial H^3$ ; then  $\Gamma_p$ , the stabilizer of p, is of importance.  $\Gamma_p$  contains no hyperbolic elements (See [Be] theorem 5.1.2). In the manifold case  $\Gamma_p$  contains only parabolic transformations. In the orbifold case  $\Gamma_p$  may have elliptic elements.

# **IV. Sphere-packing and volume**

It can be proved that short geodesics (length less than approximately 0.107) in complete hyperbolic 3-manifolds have embedded tubular neighborhoods ("solid tubes"), and that the shorter the geodesic the bigger the volume of the solid tube (See [M1]). This solid tube construction can be used to produce a lower bound for the volume of complete hyperbolic 3-manifolds (without cusps). The argument is as follows. A non-cusped hyperbolic 3-manifold  $M = H^3/\Gamma$  must have either an embedded ball of radius r or a geodesic of length less than 2r. If we take r = 0.053475 then the embedded ball B(0.053475) contributes at least 0.00064 to the volume of M, while a geodesic of length at most 2r = 0.10695 has an embedded tubular neighborhood of volume at least 0.00068 (See [M1]). Thus, the volume of a closed hyperbolic 3-manifold must be greater than 0.00064. By

choosing a smaller r we get more volume in the solid-tube case, but less in the embedded-ball case; thus the overall volume estimate is lower. The value r = 0.053475 was chosen to maximize the overall volume estimate; call this value or r the "trade-off value". (Since cusped hyperbolic 3-manifolds have volume greater than  $\sqrt{3}/4$  we have that all complete hyperbolic 3-manifolds have volume at least 0.00064, i.e.  $V_1 > 0.00064$  (See [M1]).)

Böröczky's theorem can be used to improve the lower bound of 0.00064. Specifically, Böröczky's theorem yields an improved volume contribution in the embedded-ball case. The argument is as follows. As mentioned in Section 2, the lifts of an embedded ball B(r) to  $H^3$  yield a packing  $\mathcal{B}$  of  $H^3$ ; and a Dirichlet domain  $D(B, \mathcal{B})$  for any ball B in the packing is a fundamental domain for  $\Gamma$ . Using Böröczky's theorem, we have vol  $(B(0.053475))/\text{vol}(H^3/\Gamma) = \text{vol}$  $(B(0.053475))/\text{vol}(D(B, \mathcal{B})) \le d(0.053475)$ . Thus  $\text{vol}(H^3/\Gamma) \ge \text{vol}(B(0.053475))/$ d(0.053475) > 0.00082, and we have improved our estimate if an embedded ball of radius 0.053475 sits in M. This technique does not effect the solid-tube contribution; thus, if r is taken as 0.053475 then our lower bound is still 0.00064. However, we can take a smaller value of r and improve our solid-tube volume contribution while only marginally effecting our embedded-ball volume. In particular taking r = 0.053463 yields a solid-tube volume greater than 0.00082 while the embedded-ball volume is still greater than 0.00082. Thus, we have that 0.00082 is a lower bound for the volume of complete hyperbolic 3-manifolds; that is  $V_1 > 0.00082$ .

For orbifolds  $Q = H^3/\Gamma$  without cusps the analysis is essentially the same except that the relevant "trade-off" radius is 0.0535 and the volume of the "chopped" solid ball is roughly 0.00000134 (see [M2]). Thus by the density argument vol (Q) > 0.0000017, i.e.  $V'_1 > 0.0000017$ .

In dealing with cusped manifolds  $M = H^3/\Gamma$  we do not have to resort to this trading-off argument. In [M1] it is shown that there is a cusp neighborhood C in M of volume at least  $\sqrt{3}/4$ . This neighborhood yields a horoball packing  $\mathcal{B}$  of  $H^3$ . Further, given B in  $\mathcal{B}$  centered at p we have that a fundamental domain F for the action of  $\Gamma_p$  on  $D(B, \mathcal{B})$  is a fundamental domain for  $\Gamma$ . Applying Böröczky's theorem, we have

$$\frac{\operatorname{vol}(C)}{\operatorname{vol}(M)} = \frac{\operatorname{vol}(B \cap F)}{\operatorname{vol}(F)} = d(B, \mathscr{B}) \le \sqrt{3}/2V.$$

Thus,  $\operatorname{vol}(M) \ge \operatorname{vol}(C)/(\sqrt{3}/2V) \ge (\sqrt{3}/4)(2V/\sqrt{3}) = V/2$  and  $V_{\omega} \ge V/2 \approx 0.5072$ .

This argument works for cusped orbifolds  $Q = H^3/\Gamma$  as well, except that the cusp neighborhood C in Q in the worst case only contributes  $\sqrt{3}/24$  to the volume

of Q (See [M2]). Thus vol  $(Q) \ge (\sqrt{3}/24)(2V/\sqrt{3}) = V/12$ ,  $V'_c \ge V/12 \approx 0.0846$ . Since  $Q_1 = H^3/PGL_2(\mathcal{O}_3)$  has volume V/12 we have (See Section 1):

THEOREM.  $Q_1 = H^3/PGL_2(\mathcal{O}_3)$  has minimum volume among all orientable cusped hyperbolic 3-orbifolds.

*Remark.* There are cusped orbifolds on which Dehn surgery cannot be performed. Consequently, unlike the manifold case, there are cusped hyperbolic 3-orbifolds whose volumes are isolated— $Q_1$  is such an orbifold. The question of finding "the least limiting orbifold" remains open.

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