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Autor: Hughes, John F. / Melvin, Paul M.

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The Smale invariant of a knot

JOHN F. HUGHES and PAUL M. MELVIN

Smale [S2] associates to each immersion $f: S^n \to \mathbb{R}^k$ an element s(f) in $\pi_n V_n(\mathbb{R}^k)$, where $V_n(\mathbb{R}^k)$ is the Stiefel manifold of n-frames in \mathbb{R}^k . The map s is an isomorphism from the set of regular homotopy classes of immersions of S^n in \mathbb{R}^k to the set $\pi_n V_n(\mathbb{R}^k)$. Smale [S2, p. 329, questions (2) and (3)] asks for a characterization of those elements s(f) where f is an embedding. Kervaire [K3] solves this problem for $k \ge \frac{3}{2}n+1$ and then, together with Milnor [K3] [KM], for k = n+1. (In all of these cases, s(f) = 0 when f is an embedding.) Haefliger [Ha, 4.7] gives a homotopy theoretic solution for all $k \ge n+3$, which, however, does not lend itself to simple computations. We solve the problem for the case k = n+2 in this paper, including an explicit means for computing the Smale invariant (Corollary 2).

If n = 1, then there is only one regular homotopy class, and it is represented by an embedding. The case n = 2 is solved by Smale [S1], who shows that regular homotopy classes correspond to elements of the set $\pi_2 V_2(\mathbb{R}^4) = \mathbb{Z}$, and the integer associated with a self-transverse immersion is the algebraic number of double points of the immersion. Thus there is only one immersion represented by an embedding, and its Smale invariant s(f) is zero.

For n > 2, the group $\pi_n V_n(\mathbb{R}^{n+2})$ can be identified with the group $\pi_n SO(n+2)$. We call the image of s(f) under this identification i(f). The main result of this paper may be stated as follows:

THEOREM. Let $f: S^n \to \mathbb{R}^{n+2}$ be an immersion. Then f is regularly homotopic to an embedding if and only if J(i(f)) = 0.

Here J denotes the Hopf-Whitehead J homomorphism from $\pi_n SO(n+2)$ to $\pi_{2n+2}S^{n+2}$.

The proof consists of identifying i(f) geometrically in a more convenient form than Smale's original definition, understanding the J homomorphism geometrically, and then combining these when f is an embedding to see that J(i(f)) = 0. The proof of the converse is by construction, using examples provided by Brieskorn [Br].

Using known properties of the J homomorphism, it follows that there exist non-trivial embeddings $S^n \hookrightarrow \mathbb{R}^{n+2}$ (i.e. embeddings not regularly homotopic to the standard inclusion) if and only if $n \equiv 3 \pmod{4}$ (Corollary 1). This answers negatively the question raised in Kervaire [K3, §5]: "Is the Smale invariant of an embedding $f: S^n \hookrightarrow \mathbb{R}^k$ with $k \le n+3$ always zero?" Ironically, a proof that J(i(f)) = 0 (properly interpreted) is implicit in [K3], which together with the results of [MK] might have indicated where to look for counterexamples.

1. Preliminaries

 \mathbb{R}^n denotes coordinate *n*-space, which we consider naturally embedded in \mathbb{R}^{n+1} as the points with last coordinate zero. B^n denotes the closed unit ball in \mathbb{R}^n , and S^n the boundary of B^{n+1} .

 $V_n(\mathbb{R}^k)$ denotes the Stiefel manifold of *n*-frames in \mathbb{R}^k , which we identify with the space of injective linear maps from \mathbb{R}^n to \mathbb{R}^k (associating the frame v_1, \ldots, v_n with the linear map sending e_i to v_i). Similarly we identify GL(k), the set of $k \times k$ invertible matrices, with the space $Aut(\mathbb{R}^k)$ of linear automorphisms of \mathbb{R}^k . $GL_+(k)$ denotes the matrices of positive determinant in GL(k), or equivalently the orientation preserving maps in $Aut(\mathbb{R}^k)$. SO(k) denotes the orthogonal matrices of determinant one in GL(k), identified with the rotations of \mathbb{R}^k .

Throughout this paper, all manifolds and maps are smooth. If M is a manifold, then τ_M denotes the tangent bundle of M, and ε^k denotes the trivial bundle over M with fiber \mathbb{R}^k .

Imm (S^n, \mathbb{R}^k) denotes the set of all regular homotopy classes of immersions $f: S^n \hookrightarrow \mathbb{R}^k$. We often do not distinguish between an immersion and its regular homotopy class; thus we may write $f \in \text{Imm } (S^n, \mathbb{R}^k)$.

Emb (S^n, \mathbb{R}^k) denotes the subset of Imm (S^n, \mathbb{R}^k) consisting of all regular homotopy classes containing an embedding.

DEFINITION 1. Let $f: S^n \hookrightarrow \mathbb{R}^{n+2}$ be an immersion. We define two invariants,

$$i(f) \in \pi_n SO(n+2)$$

and the Smale invariant

$$s(f) \in \pi_n V_n(\mathbb{R}^{n+2}),$$

as follows:

The invariant i(f):

Extend f to an orientation preserving immersion

$$F:N(S^n) \hookrightarrow \mathbb{R}^{n+2}$$

where $N(S^n)$ is a neighborhood of the standard S^n in \mathbb{R}^{n+2} . Then dF, the differential of F, maps $N(S^n)$ into $GL_+(n+2)$. Define i(f) to be the homotopy class of the map

$$S^n \to SO(n+2)$$
: $x \mapsto GS \circ dF_x$.

where $GS: GL_+(n+2) \to SO(n+2)$ is the Gram-Schmidt map. It is not hard to see that if n > 1, then i(f) is independent of the choice of F, and in fact depends only on the regular homotopy class of f. Thus there is a well defined map

$$i: \text{Imm } (S^n, \mathbb{R}^{n+2}) \to \pi_n SO(n+2)$$

for n > 1.

The Smale invariant s(f):

Consider S^n as lying in $\mathbb{R}^{n+1} = \mathbb{R}^n \times \mathbb{R}$, and write points in \mathbb{R}^{n+1} as pairs (v, t), where $v \in \mathbb{R}^n$ and $t \in \mathbb{R}$. The northern and southern hemispheres of S^n are then

$$N = \{(v, t) \in S^n : t \ge 0\}$$

$$S = \{(v, t) \in S^n : t \leq 0\}.$$

If x = (v, t), write \bar{x} for (v, -t). Stereographic projection from the south pole, sp = (0, -1), to a plane tangent to the north pole, np = (0, 1), is given by the formula

$$p: S^n - \{sp\} \to \mathbb{R}^n: (v, t) \mapsto \frac{2}{1+t} v.$$

Let $q:\mathbb{R}^n \to \mathbb{R}^{n+2}$ be the inverse of p, followed by the natural inclusion of S^n in \mathbb{R}^{n+2} .

Now alter the immersion f by a regular homotopy so that the restriction of f to the southern hemisphere S agrees with the standard inclusion of S into \mathbb{R}^{n+2} . Define s(f) to be the homotopy class of the map

$$S^n \to V_n(\mathbb{R}^{n+2}): x \mapsto \begin{cases} d(f \circ q)_{p(x)} & x \in N \\ dq_{p(\bar{x})} & x \in S \end{cases}$$

(compare Smale [S2]). It turns out that s(f) is independent of the choice of regular homotopy used to alter f, and so there is a well-defined map

$$s: \text{Imm } (S^n, \mathbb{R}^{n+2}) \to \pi_n V_n(\mathbb{R}^{n+2}).$$

Smale [S2] shows that s is a bijection. In fact, using the operation of oriented connected sum on Imm (S^n, \mathbb{R}^{n+2}) , s is an isomorphism of groups (see Kervaire [K2], Hughes [Hu]).

DEFINITION 2. Let $j:\mathbb{R}^n \to \mathbb{R}^{n+2}$ denote the standard inclusion. Define $\phi: SO(n+2) \to V_n(\mathbb{R}^{n+2})$ by sending h to $h \circ j$. (Here we are thinking of elements of SO(n+2) and $V_n(\mathbb{R}^{n+2})$ as linear maps. On the matrix level, ϕ is simply "drop the last two columns of the matrix".) Observe that ϕ induces an isomorphism

$$\phi_*: \pi_n SO(n+2) \to \pi_n V_n(\mathbb{R}^{n+2})$$

for n > 2. (To see this, consider the commutative diagram

$$GL_{+}(n+2)$$

$$\bigcup \qquad \qquad \downarrow^{\psi}$$

$$SO(n+2) \xrightarrow{\phi} V_{n}(\mathbb{R}^{n+2})$$

where $\psi(g) = g \circ j$. ψ is a fibration with a fiber which is homotopy equivalent to $GL_+(2)$, which is in turn homotopy equivalent to S^1 . Hence ψ induces an isomorphism on π_n for n > 2. The inclusion $SO(n+2) \subset GL_+(n+2)$ is a homotopy equivalence, so induces an isomorphism on π_n for every n.)

Combining definitions 1 and 2 we have a diagram

$$\begin{array}{ccc}
\pi_n V_n(\mathbb{R}^{n+2}) \\
& \stackrel{s}{\searrow} & \stackrel{\phi_*}{\longrightarrow} \\
\text{Imm } (S^n, \mathbb{R}^{n+2}) & \xrightarrow{i} & \pi_n(SO(n+2))
\end{array}$$

(for n > 1) with s and ϕ_* isomorphisms (for n > 2).

PROPOSITION. $s = \phi_* \circ i$. Thus i is an isomorphism for n > 2.

Proof. Let $f \in \text{Imm } (S^n, \mathbb{R}^{n+2})$. As in definition 1, we may assume that f agrees with the standard inclusion on the southern hemisphere S. It is easy to arrange that F (in the definition of i(f)) is the identity in a neighborhood of S in \mathbb{R}^{n+2} .

Notice that since f = F on image(q), we may write $d(fq)_v = d(Fq)_v$ for v in \mathbb{R}^n . Thus s(f) is represented by the map

$$S^{n} \to V_{n}(\mathbb{R}^{n+2}) : x \mapsto \begin{cases} d(fq)_{p(x)} = dF_{x}dq_{p(x)} & x \in \mathbb{N} \\ dq_{p(\bar{x})} & x \in \mathbb{S} \end{cases}$$

(applying the chain rule). This map can be altered by the homotopy

$$(x, t) \mapsto \begin{cases} dF_x dq_{(1-t)p(x)} & x \in \mathbb{N} \\ dq_{(1-t)p(\bar{x})} & x \in \mathbb{S} \end{cases}$$

resulting in

$$s(f) = \left[x \mapsto \begin{cases} dF_x dq_0 & x \in N \\ dq_0 & x \in S \end{cases} \right] = \left[x \mapsto dF_x \circ j \right]$$

where j denotes the inclusion of \mathbb{R}^n into \mathbb{R}^{n+2} . The last equality follows because $dq_0 = j$, as is easily verified. But the map $x \mapsto dF_x \circ j$ is homotopic to $x \mapsto GS \circ dF_x \circ j$, which by definition represents $\phi_*(i(f))$, proving the proposition.

DEFINITION 3. Suppose that M is a manifold, and P and Q are codimension zero submanifolds with $P \cap Q$ a submanifold and $P \cup Q = M$. Given a map $f: P \cap Q \to GL(k)$, denote by

$$\beta(P, Q, f)$$

the \mathbb{R}^k -bundle whose total space is $(P \times \mathbb{R}^k) \cup (Q \times \mathbb{R}^k)/\sim$, where \sim is the equivalence relation identifying $(x, v) \in P \times \mathbb{R}^k$ with $(x, f(x)v) \in Q \times \mathbb{R}^k$, for all x in $P \cap Q$. The projection map for this bundle sends (x, v) to x.

It follows from the homotopy axiom for vector bundles that if f and g are homotopic maps from $P \cap Q$ to GL(k), then $\beta(P, Q, f)$ and $\beta(P, Q, g)$ are isomorphic bundles. Also, if \tilde{f} is defined by $\tilde{f}(x) = f(x)^{-1}$, then $\beta(P, Q, f) \cong \beta(Q, P, \tilde{f})$ and $\beta(P, Q, f) \oplus \beta(P, Q, \tilde{f}) \cong \varepsilon^{2k}$.

If an orientable bundle ξ over M is trivial away from a point (almost parallelizable), then there is an isomorphism $\xi \cong \beta(P, Q, f)$ with $Q = B^{n+1}$, $P \cap Q = S^n = \partial B^{n+1}$, and $f: S^n \to SO(k)$. The class $[f] \in \pi_n SO(k)$ is called the obstruction to framing ξ .

2. The main theorem

From the previous section, there is a commutative diagram:

$$\pi_n V_n(\mathbb{R}^{n+2})$$

$$\downarrow^{\phi_*}$$

$$\text{Emb}(S^n, \mathbb{R}^{n+2}) \subset \text{Imm}(S^n, \mathbb{R}^{n+2}) \xrightarrow{i} \pi_n SO(n+2) \xrightarrow{J} \pi_{2n+2}(S^{n+2}).$$

Our main result is:

THEOREM.
$$s(\text{Emb}(S^n, \mathbb{R}^{n+2})) = \phi_*(\text{ker}(J)).$$

Proof. It suffices to show $i(\text{Emb}(S^n, \mathbb{R}^{n+2})) = \ker(J)$. The proof is in two steps.

STEP 1. If
$$f \in \text{Emb}(S^n, \mathbb{R}^{n+2})$$
, then $J(i(f)) = 0$.

Extend f to an embedding $f: M_0 \hookrightarrow \mathbb{R}^{n+2}$ of some compact oriented (n+1)-manifold M_0 with $\partial M_0 = S^n$. $(M_0$ is called a Seifert surface for f.) Consider the closed, smooth manifold

$$M = M_0 \cup B^{n+1}$$

the union being along $\partial B^{n+1} = S^n = \partial M_0$. We will show that i(f) is an obstruction to framing the stable normal bundle of M. Step 1 then follows from Lemma 1 of [MK]. The details follow:

A suitable neighborhood U of B^{n+1} in M can be identified with \mathbb{R}^{n+1} . Thus we view $\mathbb{R}^{n+2} = \mathbb{R}^{n+1} \times \mathbb{R} = U \times \mathbb{R} \subset M \times \mathbb{R}$. The standard orientation on \mathbb{R}^{n+2} induces an orientation on $M \times \mathbb{R}$. Within $M \times \mathbb{R}$, we identify M with $M \times \{0\}$. Set $V = M - \{0\}$ (here 0 denotes the origin of $\mathbb{R}^{n+1} = \text{center of } B^{n+1}$).

Now further extend f to an orientation preserving embedding

$$F: V \times \mathbb{R} \hookrightarrow \mathbb{R}^{n+2}$$

(see Figure 1). Let

$$g = dF \mid S^n : S^b \rightarrow GL_+(n+2).$$

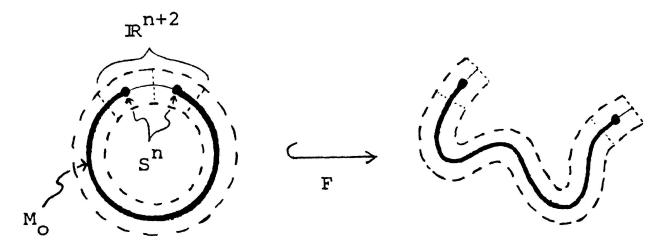


Figure 1

Then

$$\tau_{\mathbf{M}\times\mathbb{R}} \mid \mathbf{M} \cong \boldsymbol{\beta}(\mathbf{B}^{n+1}, \mathbf{M}_0, \mathbf{g}). \tag{1}$$

An explicit isomorphism between the bundles is given by assigning to the tangent vector v to $M \times \mathbb{R}$ at the point x in $M = M \times \{0\}$, either

$$(x, v) \in B^{n+1} \times \mathbb{R}^{n+2}$$

if $x \in B^{n+1}$ (here we think of $B^{n+1} \subset \mathbb{R}^{n+1}$, so $v \in \mathbb{R}^{n+2}$), or

$$(x, dF_{\mathbf{x}}(v)) \in M_0 \times \mathbb{R}^{n+2}$$

if $x \in M_0$. This is well-defined, for if $x \in M_0 \cap B^{n+1} = S^n$, then $(x, v) \in B^{n+1} \times \mathbb{R}^{n+2}$ is identified with $(x, g(x)v) = (x, dF_x(v)) \in M_0 \times \mathbb{R}^{n+2}$, by the definition of $\beta(B^{n+1}, M_0, g)$ and g.

Let $h = GS \circ g$, so that

$$h: S^n \to SO(n+2)$$
.

Note that [h] = i(f), by definition. Furthermore, g and h are homotopic maps (in $GL_{+}(n+2)$), so we have

$$\tau_{\mathbf{M}} \bigoplus \in {}^{1} \cong \tau_{\mathbf{M} \times \mathbb{R} \mid \mathbf{M}} \cong \beta(B^{n+1}, M_{0}, g) \quad \text{(by (1))}$$

$$\cong \beta(B^{n+1}, M_{0}, h).$$

Now using the Whitney embedding theorem, embed M in S^{2n+3} and let ν be the normal (n+2)-plane bundle of the embedding. Then $(\tau_M \oplus \varepsilon^1) \oplus \nu \cong \varepsilon^{2n+4} \cong \beta(B^{n+1}, M_0, h) \oplus \beta(B^{n+1}, M_0, \tilde{h})$ (where $\tilde{h}(x) = h(x)^{-1}$), and so

$$\nu \cong \beta(B^{n+1}, M_0, \tilde{h}) \cong \beta(M_0, B^{n+1}, h)$$

(both bundles are stable normal bundles of M). Since [h] = i(f),

$$i(f)$$
 is the obstruction to framing ν . (2)

By Lemma 1 of [MK], it follows that J(i(f)) = 0.

Remark. For the reader's convenience, here are the details of a proof of the lemma cited above:

Embed M in S^{2n+3} so that it is perpendicular to the equatorial S^{2n+2} , intersecting it in the standard $S^n \subset S^{2n+2}$, with M_0 lying in the northern hemisphere of S^{2n+3} (see Figure 2). This may be accomplished by taking a height function for S^{2n+3} , making it transverse to the embedding of M, and then identifying a minimum point. An isotopy taking a neighborhood of this minimum onto the southern hemisphere alters the embedding to one satisfiying the conditions above.

Consider the normal framing \mathbb{F} on $S^n = M \cap S^{2n+2}$ in S^{2n+2} , given by assigning to a point $x \in S^n$ the frame $\binom{0}{h(x)} \in V_{n+2}(\mathbb{R}^{2n+3})$. The Thom-Pontrjagin construction applied to this framed submanifold of S^{2n+2} gives an element of $\pi_{2n+2}S^{n+2}$

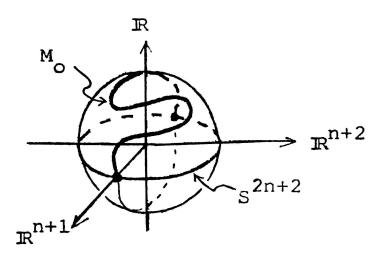


Figure 2

which can be identified with J([h]): Both elements are represented by the map

$$S^{2n+2} \subset \mathbb{R}^{2n+3} = \mathbb{R}^{n+1} \times \mathbb{R}^{n+2}$$

$$\downarrow$$

$$S^{n+2} \subset \mathbb{R}^{n+3} = \mathbb{R}^{n+2} \times \mathbb{R}$$

sending the minimal geodesic arc joining $x \in S^n \times \{0\}$ with $y \in \{0\} \times S^{n+1}$ to the minimal geodesic arc joining the south pole with the north pole of S^{n+2} and passing through $h(x)y \in S^{n+1} \times \{0\}$. (Explicitly, J([h]) maps $(u, v) \in S^{2n+2}$ to $(0, 1) \in S^{n+2}$ if u = 0, and to $(2 ||u|| h(u/||u||)v, ||v||^2 - ||u||^2)$ otherwise.) Compare Kervaire [K1, 1.8].

Finally observe that the framing \mathbb{F} on S^n extends over M_0 : $\beta(M_0, B^{n+1}, h)$ is abstractly isomorphic to the normal bundle ν of M in S^{2n+3} . We may choose an isomorphism over B^{n+1} which is standard over $S^n = \partial B^{n+1}$ (i.e. maps the standard frame on \mathbb{R}^{n+2} to the standard frame on $\{0\} \times \mathbb{R}^{n+2} \subset \mathbb{R}^{n+1} \times \mathbb{R}^{n+2} = \mathbb{R}^{2n+3}$), and extend this to an isomorphism Ψ over the rest of M. But on $S^n = \partial M_0$, the standard frame on \mathbb{R}^{n+2} maps to \mathbb{F} under Ψ . Hence the image under Ψ of the standard frame on \mathbb{R}^{n+2} over M_0 provides an extension of \mathbb{F} .

Now because the framing extends over M_0 , the Thom-Pontrjagin construction yields 0 in $\pi_{2n+2}(S^{n+2})$, hence so must J.

STEP 2. If J(x) = 0, then there exists $f \in \text{Emb}(S^n, \mathbb{R}^{n+2})$ with i(f) = x.

Bott [Bo] computes

$$\pi_n SO(n+2) = \begin{cases} \mathbb{Z} & \text{if } n \equiv 3 \text{ or } 7 \pmod{8} \\ \mathbb{Z}_2 & \text{if } n \equiv 0 \text{ or } 1 \pmod{8} \\ 0 & \text{otherwise.} \end{cases}$$

Furthermore, by the work of Adams, $J: \pi_n SO(n+2) \to \pi_{2n+2} S^{n+2}$ is injective for $n \equiv 0$ or $1 \pmod 8$ (see Switzer [S, p. 487]). Thus there is nothing to prove except in the case $n \equiv 3$ or $7 \pmod 8$, i.e. $n \equiv 3 \pmod 4$.

So let n = 4m - 1. Write j_m for the order of the image of $J: \pi_{4m-1}SO(4m+1) \to \pi_{8m}S^{4m+1}$. Identifying $\pi_{4m-1}SO(4m+1)$ with \mathbb{Z} , it suffices to produce an embedding $f: S^{4m-1} \to \mathbb{R}^{4m+1}$ with $i(f) = \pm j_m$.

First consider the collection of all closed, oriented, almost-parallelizable 4m-manifolds M. The associated signatures $\sigma(M)$ form a subgroup of \mathbb{Z} ; let $\sigma_m > 0$ denote the generator. Similarly let $p_m > 0$ denote the generator of the group of all top Pontrjagin numbers $p_m(M)$. Observe that if $\sigma(M) = \sigma_m$, then by

the Hirzebruch Index Theorem, $p_m(M) = p_m$. Also, it is known that $\sigma_m \equiv 0 \pmod{8}$ (see [KM, p. 531]).

Case 1: m > 1. Let f be the inclusion of the Brieskorn homotopy (4m-1)-sphere $\sum (2, \ldots, 2, 3, 6(\sigma_m/8) - 1)$ into $\mathbb{R}^{4m+1} = S^{4m+1} - \{\text{point}\}$, bounding the Milnor fiber $M_0 \subset S^{4m+1}$ [Br]. Brieskorn computes

$$\sigma(M_0) = \pm \sigma_m$$

so by Kervaire-Milnor [KM, 7.5] and the h-cobordism Theorem [S3], ∂M_0 is diffeomorphic to S^{4m-1} . Capping off M_0 with a 4m-ball to get a closed, almost-parallelizable 4m-manifold M, we have $\sigma(M) = \pm \sigma_m$, and so

$$p_m(M) = \pm p_m$$

Case 2: m = 1. Let M be the Kummer surface (see, for example Milnor [M]), and let M_0 be the complement of an open ball in M. Note that

$$p_1(M) = p_1 = 48.$$

It is known that M_0 can be constructed from the 4-ball by attaching 2-handles with even framings [Hr][AK] from which it follows easily that there is an embedding $M_0 \hookrightarrow \mathbb{R}^5$ (cf. Ruberman [R]). Let f be the restriction of this embedding to $\partial M_0 = S^3$.

Now in either case we have an embedding $f: S^{4m-1} \hookrightarrow \mathbb{R}^{4m+1}$ whose image bounds a submanifold M_0 , with

$$p_m(M) = \pm p_m,$$

where M is M_0 capped off with a 4m-ball. By Theorems 1 and 2 in Milnor-Kervaire [MK]

$$p_m = \pm a_m (2m-1)! j_m,$$

where a_m is defined to be 1 for m even and 2 for m odd. Also, by Lemma 2 in [MK]

$$p_m(M) = \pm a_m(2m-1)! o,$$
 (3)

where o is the obstruction to framing the stable normal bundle ν of M. Thus

$$o = \pm j_m$$
.

But by (2) in Step 1,

$$i(f) = o. (4)$$

Hence

$$i(f)=\pm j_m,$$

and so f is the desired embedding.

This completes the proof of the Theorem.

Since $J: \pi_n SO(n+2) \to \pi_{2n+2} S^{n+2}$ is a monomorphism if $n \not\equiv 3 \pmod 4$ (as noted above), $\pi_{2n+2} S^{n+2}$ is finite, and $\pi_n SO(n+2) = \mathbb{Z}$ if $n \equiv 3 \pmod 4$, we deduce:

COROLLARY 1. Emb (S^n, \mathbb{R}^{n+2}) is isomorphic to \mathbb{Z} if $n \equiv 3 \pmod{4}$ and to 0 otherwise.

In fact in the case $n \equiv 3 \pmod{4}$ (say n = 4m - 1), one may identify explicitly the subgroup $\text{Emb}(S^n, \mathbb{R}^{n+2}) = j_m \mathbb{Z}$ of $\text{Imm}(S^n, \mathbb{R}^{n+2}) = \mathbb{Z}$ using the following formula for j_m :

$$v_2(j_m) = v_2(m) + 3$$

$$v_p(j_m) = \begin{cases} v_p(m) + 1 & \text{if } m \equiv 0 \pmod{\frac{p-1}{2}} \\ 0 & \text{otherwise} \end{cases}$$
(for p an odd prime)

where $v_p(k)$ denotes the exponent of the prime p in the prime decomposition of k. This formula follows from Lemma 3 in [MK] and the Adams conjecture (compare Switzer [S, pp. 479, 488]). The first few values of j_m are $j_1 = 24$, $j_2 = 240$, $j_3 = 504$, and $j_4 = 480$.

One may also give a formula relating the invariant i(f) (for an embedding $f: S^n \hookrightarrow \mathbb{R}^{n+2}$) to the signature of a Seifert surface for f:

COROLLARY 2. If $f: S^n \hookrightarrow \mathbb{R}^{n+2}$ is an embedding, n = 4m-1, and M_0 is an oriented 4m-manifold in \mathbb{R}^{n+2} with $\partial M_0 = f(S^n)$, then identifying $Imm(S^n, \mathbb{R}^{n+2})$

with Z we have

$$i(f) = \pm \frac{m}{2^{2m-1}(2^{2m-1}-1)B_m a_m} \sigma(M_0)$$

where B_m is the m-th Bernoulli number and a_m is 1 or 2 depending upon whether m is even or odd.

Proof. Let M denote M_0 capped off with a 4m-ball $(\sigma(M) = \sigma(M_0))$. By (3) and (4) of the proof of the theorem

$$i(f) = \pm \frac{1}{a_m^*(2m-1)!} p_m(M).$$

The Hirzebruch Index Theorem (see [MK, p. 457]) gives

$$p_m(M) = \frac{(2m)!}{2^{2m}(2^{2m-1}-1)B_m} \sigma(M),$$

as M is almost parallelizable, and the Corollary follows.

For example, if m = 1, then $i(f) = \pm \frac{3}{2}\sigma(M_0)$.

Remark. Our viewpoint also sheds light on the case of embeddings $S^n \hookrightarrow \mathbb{R}^k$ for k > n+2: If $\operatorname{Emb}_F(S^n, \mathbb{R}^k)$ denotes the set of regular homotopy classes containing embeddings which bound framed submanifolds of \mathbb{R}^k , then one has by an analogous argument to the proof of the theorem

$$s(\operatorname{Emb}_F(S^n, \mathbb{R}^k)) = \phi_*(\ker(J))$$

where

$$\phi_*: \pi_n SO(k) \to \pi_n V_n(\mathbb{R}^k)$$

is the natural map. (Note that ϕ_* is generally not an isomorphism.) As a consequence, for example, one has

$$s(\operatorname{Emb}_{\mathbf{F}}(S^3,\mathbb{R}^6))=0$$

(in fact Emb $(S^3, \mathbb{R}^6) = 0$ by [S2]), and

$$s(\operatorname{Emb}_{F}(S^{7}, \mathbb{R}^{10})) = 720\mathbb{Z} \oplus \{0\} \subset \mathbb{Z} \oplus \mathbb{Z}_{4} = \pi_{7}V_{7}(\mathbb{R}^{10}).$$

QUESTIONS. (1) Is $\operatorname{Emb}_F(S^n, \mathbb{R}^{n+3}) = \operatorname{Emb}(S^n, \mathbb{R}^{n+3})$? (2) For a given n, what is the largest value of k for which $\operatorname{Emb}(S^n, \mathbb{R}^k) \neq 0$?

Added in proof: Sylvain Cappell has informed us that our theorem can be deduced from an unpublished version of his paper with J. Shaneson, "Singularities and immersions", Ann. of Math. 105 (1977), 539–552.

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Department of Mathematics Bryn Mawr College Bryn Mawr, PA 19010

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