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Autor: Frehse, Jens
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A Landesman–Lazer alternative theorem for a class of optimization problems

JENS FREHSE

In [1] we proved an alternative theorem for the existence of minima of functionals F_l defined by $F_l(u) = F(u) - (l, u)$ on, say, a reflexive Banach space B . Here $l \in B^*$ and F satisfies the following conditions

- (1) $F: B \rightarrow \mathbf{R} \cup \{\infty\}$ is lower semi-continuous in the weak topology of B .
- (2) F is of polynomial type, i.e. if for some pair $v, w \in B$
 - (i) $\sup t^{-1}F(w + tv) < \infty \quad (t > t_0 > 0)$ and
 - (ii) $\inf F(w + tv) > -\infty \quad (t \in \mathbf{R})$

then $F(w + tv)$ is constant in t .

- (3) F satisfies a surrogate convexity condition, i.e. for all $u, w \in B, \alpha \in [0, 1]$, $F(w) < \infty$

$$F(1 - \alpha)w + \alpha u \leq K_w + K_w \alpha F(u)$$

with some constant K_w .

- (4) F is semi-coercive, i.e. there exists a continuous projection $Q: B \rightarrow V$ onto a finite dimensional subspace V such that for all $K > K_0$

$$\sup \{ \|u\| / (1 + \|Qu\|) \mid F(u) \leq K \} < \infty$$

- (5) F is bounded from below on B .

Introducing the set

$$D = \{v \in B \mid F(w + tv) \text{ is constant in } t \in \mathbf{R} \text{ for all } w \in B, F(w) < \infty\}$$

we obtained the following

THEOREM 0. Under the conditions (1)–(5) the functional F_l has a minimum if and only if $l \perp D$. Furthermore, $\dim D \leq \dim V$.

A simple corollary (cf. [2], §1) yields that if in addition F has a Gateaux derivative $T: B \rightarrow B^*$ then the range of T is linear and has finite co-dimension.

In this paper we consider perturbations $F_l + G$ of the above functionals F_l where G has a so called *weak sub-asymptote* (cf. definition below). It then turns out that the set of $l \in B^*$ for which $F_l + G$ has a minimum becomes “thicker”, i.e. is open and contains the closed set D . Under additional conditions we can characterize these elements l in the form of an alternative theorem. Our results are in the spirit of the “classical” Landesman–Lazer-alternative theorems, cf. Landesman–Lazer [8]. For a rather complete list of references to this subject, cf. [9] and also [4]. These theorems state that the range of perturbed semi-coercive linear differential operators like $-\Delta u - \lambda u + \arctg u$ subject to boundary conditions is open and can be characterized by the asymptotes of the perturbation.

If $F_l + G$ is Gateaux-differentiable our result yields a Landesman–Lazer-type theorem of the usual form but covers cases with strongly non-linear principal part of polynomial type. Our proof of this result is very simple. The theorem has a non-variational analogue which was presented in [3]. A Landesman–Lazer theorem for a class of equations with strongly non-linear principle part was presented by Hess in [5], [6], [7]. His approach and his results are rather different from the setting in the present paper.

DEFINITION. A mapping $a_0: D \rightarrow \mathbf{R}$ is called a weak sub-asymptote of the mapping $G: B \rightarrow \mathbf{R}$ if for every sequence $(u_i \in B, i = 1, \dots)$ with $\|u_i\| \rightarrow \infty$, $\|u_i\|^{-1}u_i \rightarrow v \in D$ weakly ($i \rightarrow \infty$), $v \neq 0$, we have

$$a_0(v) \leq \liminf \|u_i\|^{-1} G(u_i) < \infty \quad (i \rightarrow \infty) \quad (6)$$

We shall also assume for the perturbation G

$$\sup \|u\|^{-1} G(u) < \infty \quad (u \in B, u \neq 0) \quad (7)$$

and

$$F + G \text{ is lower semi-continuous in the weak topology of } B. \quad (8)$$

THEOREM 1. Let B be a reflexive Banach space and $F: B \rightarrow \mathbf{R} \cup \infty$, $G: B \rightarrow \mathbf{R}$ mappings such that G has a weak sub-asymptote $a_0: D \rightarrow \mathbf{R}$ and F, G satisfy (1)–(5), (7) and (8).

Then the functional $\Phi_l: B \rightarrow \mathbf{R}$ defined by

$$\Phi_l(u) = F(u) + G(u) - (l, u)$$

has a minimum on B for all $l \in B^*$ for which

$$(l, v) < a_0(v), \quad v \in D, \quad v \neq 0. \quad (9)$$

If in addition

$$\liminf t^{-1}(G(w + tv) - G(w)) < a_0(v) \quad (t \rightarrow +0) \quad (10)$$

for all $w \in B$ and $v \in D, v \neq 0$, then (9) is also necessary for the existence of a minimum of Φ_l .

Proof. We may assume that $F \neq \text{const} = \infty$. Let (u_i) be a minimizing sequence for Φ_l . Suppose that (u_i) were unbounded. Then we may assume that $\|u_i\| \rightarrow \infty$ and that $\|u_i\|^{-1}u_i := v_i \rightarrow v$ weakly in $B (i \rightarrow \infty)$. By (4) there is a constant $C > 0$ such that $\|u_i\| \leq C + C\|Qu_i\|$ and hence $1 \leq C \liminf \|Qv_i\| (i \rightarrow \infty)$. Since $\dim QB < \infty$ we have $Qv_i \rightarrow Qv$ strongly and, therefore, $1 \leq C\|Qv\|$, and

$$v \neq 0.$$

We intend to show that $v \in D$. By the convexity condition (3)

$$F(1 - \alpha)w + \alpha u_i \leq K_w + \alpha K_w F(u_i) = K_w + \alpha K_w [\Phi_l(u_i) - G(u_i) + (l, u_i)]$$

for all w such that $F(w) < \infty$.

Since $\|u_i\| \rightarrow \infty$ we may set $\alpha = t\|u_i\|^{-1}$ for $t > 0, i > i(t)$. Passing to the limit $i \rightarrow \infty$ we obtain in view of the lower semi-continuity of F .

$$F(w + tv) \leq K_w - tK_w \liminf \|u_i\|^{-1} G(u_i) + tK_w (l, v) \quad (11)$$

and by (7)

$$t^{-1}F(w + tv) \leq K_{wt}, \quad t > 1.$$

From (5) and (2) we then conclude that $F(w + tv)$ is constant in $t \in \mathbf{R}$ for all w with $F(w) < \infty$ and hence

$$v \in D.$$

Since G has a weak sub-asymptote $a_0: D \rightarrow \mathbf{R}$, we obtain from (11)

$$(F(w) =)F(w + tv) \leq K_w - tK_w a_0(v) + tK_w (l, v)$$

and passing to the limit $t \rightarrow \infty$ we arrive at the inequality

$$a_0(v) \leq (l, v).$$

This contradicts (9) and hence the assumption of (u_i) being unbounded leads to a contradiction. The first statement follows in view of (8) and the reflexivity of B . The necessity of (9) can be seen from the following simple argument: If u is a minimum of Φ_t on B and if $v \in D$, then

$$F(u) + G(u) - (l, u) \leq F(u + tv) + G(u + tv) - (l, u + tv)$$

$$G(u) \leq G(u + tv) - t(l, v)$$

since $F(u + tv)$ is constant in t . Hence, by (10),

$$(l, v) \leq \liminf t^{-1}(G(u + tv) - G(u)) < a_0(v) \quad (t \rightarrow +0)$$

as claimed. The theorem is proved.

EXAMPLES. In the following let Ω be a bounded connected open set in \mathbf{R}^n and $H^{1,p}$ the usual Sobolev space over Ω . The corresponding Sobolev space of r -vector functions is denoted by $[H^{1,p}]^r$.

(i) Let $B = H^{1,p}(\Omega)$, $l \in B^*$, and

$$F(u) = \frac{1}{p} \int |\nabla u|^p dx, \quad G(u) = \int [u \operatorname{arctg} u - \frac{1}{2} \ln(1 + |u|^2)] dx$$

Here and in the following \int denotes integration over Ω . Then $D = \{z \in H^{1,p} \mid z = \text{const.}\}$ and $a_0(v) = \pi/2 \int |v| dx$. Since F and G satisfy the hypotheses of Theorem 1, cf [1], §3, the functional F_t defined by

$$F_t(u) = F(u) + G(u) - (l, u)$$

has a minimum when

$$|(l, 1)| < \frac{\pi}{2} |\Omega|. \tag{12}$$

The minimum u of F_l is a weak solution of the differential equation.

$$-\sum_{i=1}^n \partial_i (\partial_i u |\nabla u|^{p-2}) + \operatorname{arctg} u = l. \quad (13)$$

It is a simple exercise to prove that the above functional G satisfies condition (10); Hence (12) is also necessary for the existence of a minimum of F_l . The characterization of the range of the operator on the left hand side of (13) can be obtained using the methods of Peter Hess, cf. references.

A non-differentiable variant of this example is obtained when $F(u)$ is replaced by

$$F(u) = \int \left[\frac{1}{p} |\nabla u|^p + |\nabla u| \right] dx$$

and condition (12) remains as the necessary and sufficient condition for the existence of minima of the functional F_l .

(ii) Let $B = [H^{1,p}(\Omega)]^2$, $l \in B^*$ and

$$F(u) = \int [|\nabla u_1|^p + u_1^p + \lambda \sin u_1 + u_1 \partial_1 u_2 + |\nabla u_2|^p] dx, \quad u = (u_1, u_2),$$

$$G(u) = \int [u_2 \operatorname{arctg} u_2 - \frac{1}{2} \ln(1 + |u_2|^2)] dx.$$

Again, F and G satisfy the hypotheses of the theorem. The surrogate convexity of F follows by splitting the integrand into a sum of convex and bounded functions. The set D has the form

$$D = \{(0, c) \in [H^{1,p}(\Omega)]^2 \mid c \in \mathbf{R}\}.$$

The functional F_l , $l = (l_1, l_2) \in B^*$ has a minimum if and only if

$$|\langle l_2, 1 \rangle| < \frac{\pi}{2} |\Omega|.$$

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*Institut für Angewandte Mathematik
der Universität, Beringstraße 4–6
5300 Bonn, West-Germany*

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