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# A Note on the Intrinsic Join of STIEFEL Manifolds

by S. Y. Husseini

### Introduction

In [1] Bott defines a map,

$$\lambda^E: S(O_{n,k} \wedge O_{m,k}) \rightarrow O_{n+m,k}$$
,

of the suspension of the reduced join  $O_{n,k} \wedge O_{m,k}$  of the real (complex, quaternionic) STIEFEL manifolds of the orthonormal k-frames in real (complex, quaternionic) n- and m-space to  $O_{n+m,k}$ , the STIEFEL manifold of orthonormal k-frames in real (complex, quaternionic) (n+m)-space. James defines ([2], or [1], p. 256) a map

$$\lambda^{J}: O_{n,k} * O_{m,k} \to O_{n+m,k},$$

of the join of  $O_{n,k}$  and  $O_{m,k}$  to  $O_{n+m,k} \cdot \lambda^E$  and  $\lambda^J$  have the same range; and since  $S(O_{n,k} \wedge O_{m,k})$  and  $O_{n,k} * O_{m,k}$  are of the same homotopy type,  $\lambda^E$  and  $\lambda^J$  have equivalent domains of definition as well. Bott showed in [1] that  $\lambda^E$  and  $\lambda^J$  are equivalent when k=1 and asked about their relation in general. The aim of this note is to answer his question, by first defining an auxiliary map  $\lambda^B$  (in (1.2)) and showing that it is equivalent to  $\lambda^E$ , and then proving that  $\lambda^B$  is equivalent to  $\lambda^J$ . The precise statement is given in Proposition (4.1) below.

1. Suppose that K is the real, complex or quaternionic field. Let  $K^{n+m}$  be the vector space of (n+m)-tuples over K with the usual inner product. Let  $a_1, \ldots, a_{n+m}$  be the usual basis. We shall find it convenient to write  $W(i_1, \ldots, i_k)$  for the subspace of  $K^{n+m}$  generated by the basic vectors  $a_{i_1}, \ldots, a_{i_k}$ . Denote by  $O_{n+m}$  the group of orthogonal transformations of  $K^{n+m}$ . Thus  $O_{n+m}$  is the real, unitary or symplectic group when K is the real, complex or quaternionic field. Let  $i: O_n \to O_{n+m}$  be the imbedding induced by the map which takes  $K^n$  onto  $W(1, \ldots, n)$  and  $i': O_m \to O_{n+m}$ , the imbedding induced by the map which takes  $K^m$  onto  $W(n-k+1,\ldots,n+m-k)$ . Define  $\chi_i$  to be the orthogonal transformation which leaves  $W(1,\ldots,n-k)+W(n+1,\ldots,n+m-k)$  pointwise fixed and is a rotation through an angle of  $\frac{\pi}{2}t$  in each of the planes W(n-k+j,n+m-k+j) for  $j=1,\ldots,k$ . Thus

$$\chi_t \cdot a_{n-k+j} = \cos \frac{\pi}{2} t \ a_{n-k+j} + \sin \frac{\pi}{2} t \ a_{n+m-k+j}$$

$$\chi_t \cdot a_{n+m-k+j} = -\sin\frac{\pi}{2}t \ a_{n-k+j} + \cos\frac{\pi}{2}t \ a_{n+m-k+j}$$

for  $j = 1, \ldots, k$ .

Suppose  $g^o$  is the frame  $(a_{n+m-k+1}, \ldots, a_{n+m})$ . Then  $O_{n+m,k}$ , the STIEFEL manifold of k-frames in  $K^{n+m}$ , can be identified with  $O_{n+m}/O_{n+m-k}$  by making the coset  $xO_{n+m-k}$  correspond to the frame  $xg^o$ . We wish to define a map of  $O_m/O_{m-k} * O_n/O_{n-k}$ , the join of  $O_m/O_{m-k}$  and  $O_n/O_{n-k}$  into  $O_{n+m,k}$ . So let us recall the necessary notions.

**Definition (1.1).** Let A and B be two countable CW-complexes, and consider the disjoint union  $A \cup A \times B \times I \cup B$ , where I is the unit interval [0, 1]. Identify (a, B, 0) with a in A and (A, b, 1) with b in B. The resulting space is the *join* A \* B. Following James we denote the image of (a, b, t) in A \* B by the same symbol. If  $a_0$  and  $b_0$  are the basepoints of A and B, then we take  $(a_0, b_0, 1)$  to be the basepoint in A \* B. There is an alternative way of looking at the join. By  $A \wedge B$  one understands the space obtained from  $A \times B$  by collapsing the sum  $A \vee B = A \times b_0 \cup a_0 \times B$  to a point.  $A \wedge B$  is called the *reduced join*. The suspension of  $A \wedge B$  is obtained from  $(A \wedge B) \times I$  by collapsing the subset  $(A \wedge B) \times 0 \cup (A \wedge B) \times 1 \cup (a_0 \wedge b_0) \times I$  to a point. The natural map  $a \in A * B \to S(A \wedge B)$  is a homotopy equivalence.

Consider the map

$$\lambda: O_m \times O_n \times I \rightarrow O_{n+m,k}$$

such that  $\lambda(y, x, t) = \chi_t y' \chi_t^{-1} x \chi_t y'^{-1} \chi_t^{-1} x^{-1} \cdot g^o$ , where x stands for ix and y' stands for i'y. Notice that  $\lambda(y, x, t)$  does not vary when y is changed by an element in  $O_{m-k}$ , the subgroup of  $O_m$  which leaves  $W(n-k+1, \ldots, n)$  pointwise fixed. Also  $\lambda(y, x, t)$  does not vary when x is changed by an element in  $O_{n-k}$ , the subgroup of  $O_n$  which leaves  $W(n-k+1, \ldots, n)$  pointwise fixed. Moreover,  $\lambda(y, x, 0)$  is independent of x and  $\lambda(y, x, 1)$  is independent of y, since x and  $\chi_1 y' \chi_1^{-1}$  commute. Hence  $\lambda$  induces a map

$$\lambda^{B}: O_{m}/O_{m-k} * O_{n}/O_{n-k} \to O_{n+m,k}$$
 (1.2)

Take  $e_m$ , the identity in  $O_m$ , to be the basepoint, and its image,  $\tilde{e}_m$ , to be the basepoint in  $O_m/O_{m-k}$ ; hence  $(\tilde{e}_m, \tilde{e}_n, 1)$  is the basepoint in  $O_m/O_{m-k} * O_n/O_{n-k}$ , and  $\lambda^B$  takes  $(\tilde{e}_m, \tilde{e}_n, 1)$  to  $\tilde{e}_{n+m}$ . We claim that  $\lambda^B$  is equivalent to the Bott map  $\lambda^E$  of [1]. Our argument is as follows: it is easy to see that  $\lambda$  also induces a map  $\tilde{\lambda}^B: S(O_m/O_{m-k} \wedge O_n/O_{n-k}) \to O_{n+m,k}$ , such that  $\tilde{\lambda}^B \circ q = \lambda^B$ , where  $q: O_m/O_{m-k} * O_n/O_{n-k} \to S(O_m/O_{m-k} \wedge O_n/O_{n-k})$  is the natural equivalence. Consider now the map

$$r: O_n \times O_m \times I \rightarrow O_m \times O_n \times I$$

such that r(x, y, t) = (y, x, t). Then  $\lambda \circ r$  induces the map

$$\lambda^{E}: S(O_{n}/O_{n-k} \wedge O_{m}/O_{m-k}) \rightarrow O_{n+m,k}$$

which Bott introduced in [1] (p. 252). Observe that  $\lambda^E = \tilde{\lambda}^B \circ r$  where  $\tilde{r}: S(O_n/O_{n-k} \wedge O_m/O_{m-k}) \to S(O_m/O_{m-k} \wedge O_n/O_{n-k})$  is the homeomorphism induced by r. Hence

$$\lambda^B = \lambda^E \circ \tilde{r}^{-1} \circ q$$
, and  $q$  and  $\tilde{r}^{-1}$  are (1.3)

homotopy equivalences.

## 2. Consider next the homeomorphism

$$T: O_n/O_{n-k} * O_m/O_{m-k} \to O_m/O_{m-k} * O_n/O_{n-k}$$
 (2.1)

which takes (x, y, t) to (y, x, 1-t). (Observe that T does not preserve base-points; but, since  $(e_m, e_n, 1)$  and  $(e_m, e_n, 0)$  are connected by a contractible segment, T can (in most cases) be regarded as preserving basepoints. Hence

$$\lambda^B \circ T: O_n/O_{n-k} * O_m/O_{m-k} \to O_{n+m,k}$$

is induced by the map of  $O_n \times O_m \times I \rightarrow O_{n+m,k}$ , which takes (x, y, t) to

$$\chi_{1-t}y' \chi_{1-t}^{-1} x \chi_{1-t}y'^{-1} \chi_{1-t}^{-1} x^{-1} \cdot g^o = \chi_t^{-1} y'' \chi_t x \chi_t^{-1} y''^{-1} \chi_t x^{-1} \cdot g^o$$

where  $y'' = \chi_1 y' \chi_1^{-1}$ . Notice that  $\lambda^B \circ T$  preserves basepoints although T does not. Let us consider now the map

$$F: (O_n \times O_m \times I) \times I \rightarrow O_{n+m,k}$$

such that  $F((x, y, t), s) = \chi_{(1-s)t}^{-1} y'' \chi_{(1-s)t} x \chi_t^{-1} y''^{-1} \chi_{s+(1-s)t} x^{-1} g^o$ . Observe that F((x, y, t), s) does not change when x and y are varied by an element in  $O_{n-k}$  and  $O_{m-k}$  respectively. Moreover, F((x, y, 0), s) is independent of y since x and y'' commute, and F((x, y, 1), s) is independent of x since  $x \chi_1^{-1} y''^{-1} \chi_1 x^{-1} \cdot g^o = g^o$ . Thus F induces a homotopy

$$\widetilde{F}_s: O_n/O_{n-k} * O_m/O_{m-k} \to O_{n+m,k}$$
 (2.2)

such that  $\tilde{F}_o = \lambda^B \circ T$ , and the basepoint is stationary during the homotopy, i.e.,  $F(\tilde{e}_n, \tilde{e}_m, 1) = g^o$ , for  $0 \le s \le 1$ .

Define  $\mu = \tilde{F}_1$ . Then

$$\mu: O_n/O_{n-k} * O_m/O_{m-k} \to O_{n+m,k}$$
 (2.3)

is induced by the map of  $O_n \times O_m \times I \to O_{n+m,k}$  which takes (x, y, t) to  $y'' \times \chi_t^{-1}(y''^{-1} \chi_1 g^o) = y'' \times \chi_t^{-1}(\chi_1 g^o)$ , since

$$y''^{-1} \chi_1 = \chi_1 y'^{-1} \chi_1^{-1} \cdot \chi_1$$
  
=  $\chi_1 y'^{-1}$ , and  $y'^{-1} g^o = g^o$ . Summing up we have

**Proposition (2.2).** The maps  $\mu$ ,  $\lambda^B \circ T : O_n/O_{n-k} * O_m/O_{m-k} \to O_{n+m,k}$  are homotopic. Here  $\lambda^B$  is the map defined in (1.2) and T and  $\mu$  are the maps defined above in (2.1) and (2.3).

3. Let  $O_{n,k}$  and  $O_{m,k}$  be the STIEFEL manifolds of orthonormal k-frames in  $W(1,\ldots,n)=K^n$  and  $W(n+1,\ldots,n+m)=K^m$ , respectively. Suppose that  $f^o$  is the k-frame which consists of the last k basic vectors of the image of  $K^n$ , i.e.,  $f^o=(a_{n-k+1},\ldots,a_n)$ . Then  $O_{n,k}$  can be identified with  $O_n/O_{n-k}$  by making the coset  $xO_{n-k}$  correspond to the k-frame  $xf^o$ . Similarly  $O_{m,k}$  can be identified with  $O_m/O_{m-k}$  by making the coset  $yO_{m-k}$  correspond to the k-frame y''  $y^o$ , where  $y''=\chi_1 y'$   $\chi_1^{-1}=\chi_1 i'y$   $\chi_1^{-1}$ . We claim

**Proposition (3.1.)** If  $f = (f_1, \ldots, f_k) \in O_{n,k}$  and  $g = (g_1, \ldots, g_k) \in O_{m,k}$ , and if  $x \in O_n$  and  $y \in O_m$  be such that  $xf^o = f$  and  $y''g^o = g$ , then

$$\mu(\widetilde{x},\widetilde{y},t) = \left(-\cos\frac{\pi}{2}t\right)f + \left(\sin\frac{\pi}{2}t\right)g,$$

where  $\tilde{x}$  and  $\tilde{y}$  are the images of x and y in  $O_n/O_{n-k}$  and  $O_m/O_{m-k}$ .

*Proof.* By the definition of  $\mu$  in (2.3)

$$\mu(\tilde{x}, \tilde{y}, t) = y'' x \chi_t^{-1}(\chi_1 g^o) = -y'' x \chi_t^{-1} f^o$$

since  $\chi_1 g^o = -f^o = (-a_{n-k+1}, \ldots, -a_n)$ . Notice that  $x \cdot g^o = g^o$  and  $y'' \cdot f^o = f^o$ . Hence

$$\mu(\tilde{x}, \tilde{y}, t) = \left(-\cos\frac{\pi}{2}t\right)f + \left(\sin\frac{\pi}{2}t\right)g.$$

4. Suppose that  $\varrho_0$  is the element of  $O_n$  which has -1 along the diagonal and zeroes everywhere else. Then  $\varrho_0$  induces a homeomorphism of  $O_n/O_{n-k}*O_m/O_{m-k}$  by sending  $(\tilde{x}, \tilde{y}, t)$  to  $(\varrho_0 \tilde{x}, \tilde{y}, t)$ . Denote this homeomorphism (which is related to what James calls in [2] a "row operation") by the same letter  $\varrho_0$ . Proposition (3.1) implies that the James map  $\lambda^J$  (the map h' of [2], p. 513) is  $\mu \varrho_0$ . Now we can conclude

**Proposition (4.1).** If  $\lambda^B: O_m/O_{m-k} * O_n/O_{n-k} \to O_{n+m,k}$  is the map of (1.2) and  $\lambda^J: O_n/O_{n-k} * O_m/O_{m-k} \to O_{n+m,k}$ 

is the James map ([2], p. 513), then  $\lambda^B \circ T$  is homotopic to  $\lambda^J \varrho_0$ .

Since  $\lambda^B$  and  $\lambda^E$  are quivalent (see (1.3)), Proposition (4.1) implies that  $\lambda^E$  and  $\lambda^J$  are equivalent.

Remark. If k = 1, and if d is the dimension of K over the real field, then  $O_{n,1}$ ,  $O_{m,1}$  and  $O_{n+m,1}$  become the unit spheres  $S^{dn-1}$ ,  $S^{dm-1}$ , and  $S^{d(n+m)-1}$ 

in  $K^n$ ,  $K^m$ , and  $K^{n+m}$ , respectively. Moreover,  $\lambda^J$  reduces to the usual join of sphere  $h': S^p * S^q \to S^{p+q+1}.$ 

where h' takes (x, y, t) to  $\left(x\cos\frac{\pi}{2}t, y\sin\frac{\pi}{2}t\right)$  ([2], p. 512). If h' is used to orient  $S^{dm-1}*S^{dn-1}$  and  $S^{dn-1}*S^{dm-1}$ , then T becomes a map of degree  $(-1)^{(dn)}$  ([2], p. 512) and  $\varrho_0$  is a map of degree  $(-1)^{(dn)}$ . Hence when K is the complex or quaternionic field,  $\lambda^B$  and  $\lambda^J$  have the same degree. In the real case they also agree if n(m+1) is even; otherwise they agree up to a sign.

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