

**Zeitschrift:** IABSE reports = Rapports AIPC = IVBH Berichte  
**Band:** 67 (1993)  
  
**Rubrik:** Session 3: Analytical evaluation of bridges

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## **SESSION 3**

### **ANALYTICAL EVALUATION OF BRIDGES**





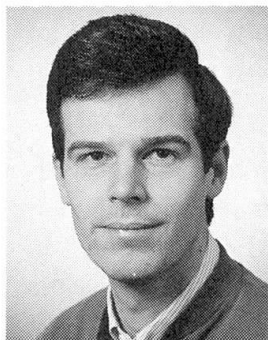


KEYNOTE SPEAKER



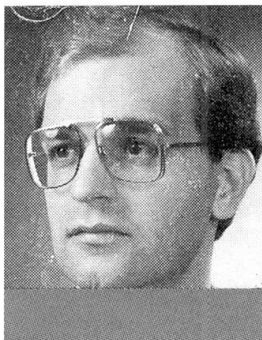
**Finite Element Prediction of a Destructive Field Test of a Bridge**  
**Prédiction de la charge de rupture d'un pont au moyen des éléments finis**  
**Vorausberechnung einer Betonbrücke im zerstörenden**  
**Feldversuch mittels Finiter Elemente**

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## SUMMARY

Nonlinear finite element analyses have been carried out to predict the load-carrying capacity of a forty-year old, three-span skewed-slab bridge. By sensitivity studies the uncertainty in the boundary conditions and the possible impact of the existing damage on the failure load have been assessed. Proper lower and upper-bound finite element solutions have been obtained in this way. The numerically predicted failure load appeared to underestimate the experimental collapse load by less than 10%.

## RÉSUMÉ

Une analyse non linéaire par éléments finis a été utilisée pour prédire la résistance d'un pont biais à trois travées, construit il y a 40 ans. L'influence des conditions aux limites et des dommages au pont ont été pris en compte par une étude de sensibilité, et les bornes inférieures et supérieures de la résistance du pont ont ainsi été calculées. La prédiction de la charge de rupture a été trouvée légèrement inférieure (10%), à la charge réelle constatée expérimentalement.

## ZUSAMMENFASSUNG

Die Traglast einer vierzig Jahre alten, dreifeldrigen gekrümmten Plattenbrücke wurde aufgrund einer nichtlinearen Finite-Element-Studie vorhergesagt. Der Streubereich der Randbedingungen und der Einfluss von Vorschädigungen auf die Traglast wurde im Rahmen einer Parameterstudie abgeschätzt. Auf diese Weise ergaben sich obere und untere Schrankenlösungen. Die vorausberechnete Traglast lag mit weniger als 10 % auf der sicheren Seite der experimentell bestimmten Traglast.



## 1. INTRODUCTION

After a thirty-year development the finite element method has become a powerful tool for analysing structural behaviour. By now, deflections and stresses under service load levels can be predicted within a tolerance that is narrower than the scatter in material properties and the uncertainty due the boundary conditions, which are often not known precisely. Unfortunately, this statement cannot always be carried over to the failure regime. Especially for concrete and masonry structures there is still a lack of robust computational tools which can provide *reliable predictions* of the structural performance in the failure and the post-failure regime. Predictions of the load-carrying capacity that exceed the experimental failure load by a factor two are not uncommon, and at some instances a proper failure load cannot be obtained at all. Publications in which the failure load of such structures is computed accurately mostly relate to *postdictions* rather than to *predictions*.

In this contribution we shall describe *predictive* finite element analyses of a three-span, skewed-slab bridge, which has been tested to failure afterwards by a team of the University of Cincinnati and Wiss, Janney and Elstner [1]. The bridge was built in 1953 and was located on Route 222 in Clermont County, Ohio. Visual inspection prior to the analyses and the testing revealed that the concrete had experienced extensive deterioration and that there was corrosion in some bars.

In the non-linear finite element analyses concrete cracking and plastification of reinforcement and concrete in compression have been taken into account. The sensitivity of the model to the various material parameters has been investigated by means of parametric studies. In this way the effect of the existing damage on the load-carrying capacity could be quantified. Furthermore, the possible impact of the assumed boundary conditions on the predicted failure load was assessed.

## 2. DESCRIPTION OF THE BRIDGE AND THE FIELD TEST

The bridge which has been analysed and tested is a three-span, skewed-slab bridge and is shown in Figure 1, see also Reference [1], which provides the necessary details on the lay-out of the reinforcement as well. Inspection prior to the analyses and the testing revealed that severe damage had occurred, especially near the sides of the bridge [1], while the driving lanes were in a reasonable condition. In the areas of visible damage of the concrete the reinforcing bars had corroded severely. The visual inspection was hampered by the existing asphaltic overlay, which was removed only shortly before the final destructive testing.

To obtain a better judgement of the concrete properties cores were drilled at several places. The concrete test specimens were then subjected to uniaxial compression tests which resulted in values for the mass density  $\rho$  and for the uniaxial compressive strength  $f_c$  which ranged from 2450 kg/m<sup>3</sup> to 2470 kg/m<sup>3</sup> and from 49 MPa to 56 MPa respectively. The value for Young's modulus  $E$  appeared to be around 33000 MPa. As will be detailed below, in the analyses the possible effect on the remaining structural capacity of the observed poor quality of the concrete was modelled by adopting artificially low values for Young's modulus and for the uniaxial compressive strength. Properties for the reinforcing steel could be derived from uniaxial tension tests on rebars, see for instance Figure 2 [1].

Prior to the final destruction test modal tests were carried out in order to obtain data on the boundary conditions which would have to be applied in the analyses. In contrast to the final destruction test the modal test were conducted with the asphaltic layer still in place, and resulted in a lowest eigenfrequency of approximately 8.3 Hz [1].

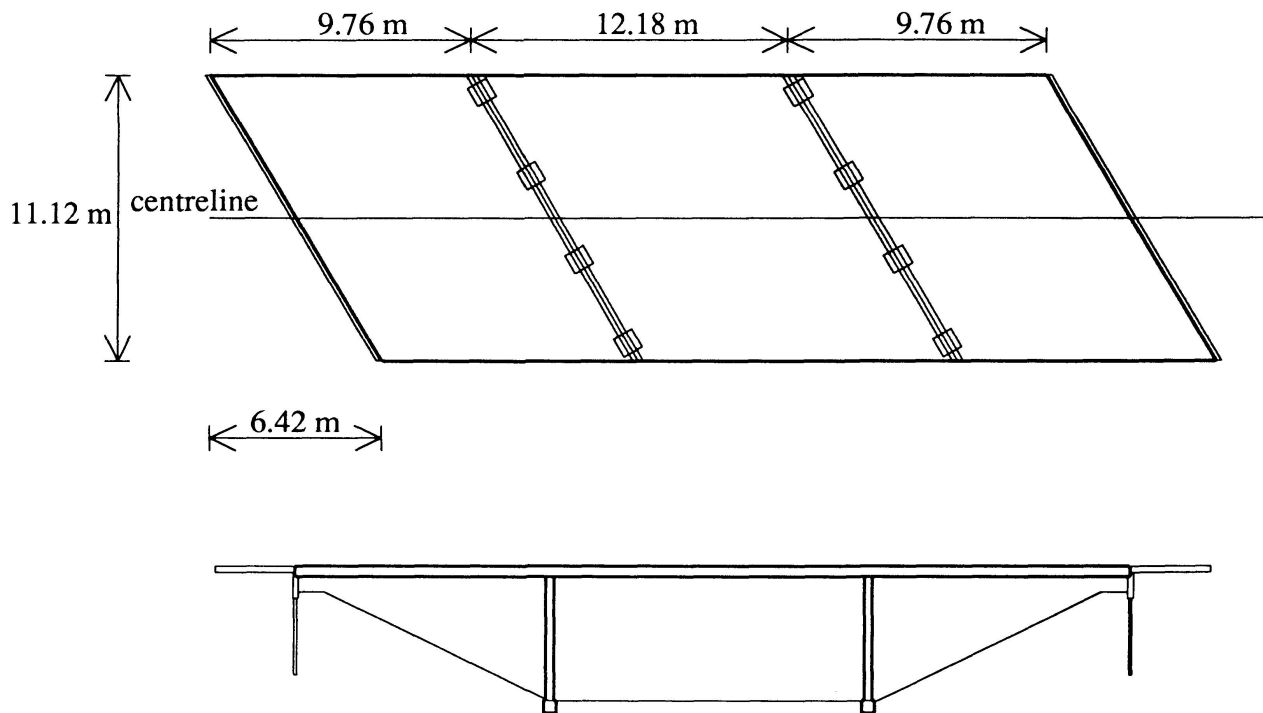


Figure 1 Plan view and side view of the bridge.

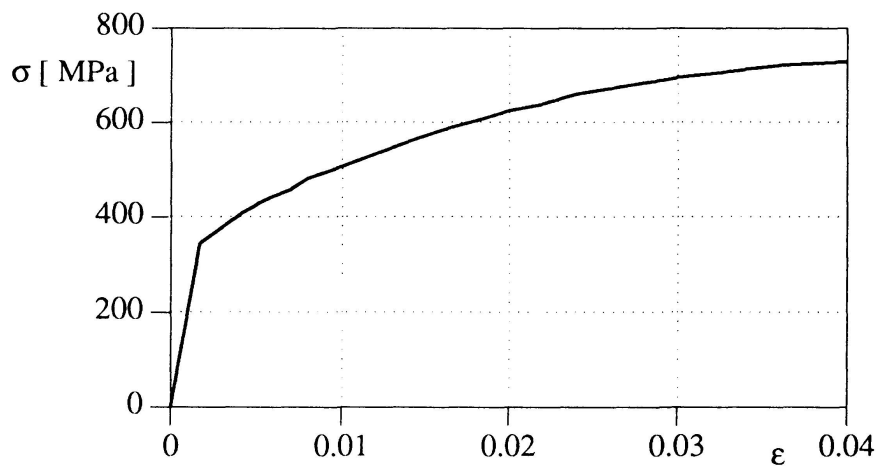


Figure 2 Experimentally obtained stress-strain curve of a tension test on a reinforcing bar.

The actual destructive tests were carried by pulling down two concrete blocks of 0.6 m by 1.8 m, which were placed on the bridge deck in order to distribute the forces exerted by servo-controlled hydraulic actuators. On each block two of such actuators were placed. Rock anchors were attached to the actuators to provide the reaction force that was needed to load the bridge. The total load at which failure occurred was 3.24 MN. In the remainder of this article we shall always refer to the load that was exerted on one of the blocks only, so that collapse occurs at a load level of 1.62 MN.



### 3. PREDICTIVE ANALYSES

#### 3.1 Analytical yield line analyses

When the authors started their non-linear finite element analyses a rough estimate of the final collapse load had been obtained by the investigators at the University of Cincinnati. They had carried out yield line analyses assuming four different yield line patterns [1]. For the boundary conditions that have been used in the Delft finite element analyses and for the material data used in the reference finite element calculation (see below), the collapse load per loading block varied from 1.5 MN to 2.67 MN [1].

#### 3.2 Discretization and loading configuration

The finite element mesh that was adopted in the analyses which have been carried out with the DIANA finite element package is shown in Figure 3. It consists of 144 eight-noded degenerated plate/shell elements with a  $2 \times 2$  Gauss integration in the plane and a nine-point Simpson integration through the depth. Reinforcement was modelled using an embedded approach, that is the interpolation functions of the concrete were used also for the reinforcement. The reinforcement grid has its own integration stations, which do not have to coincide with the layers of the plate/shell element. The discretization of Figure 3 was considered sufficiently refined for the expected bending-type failure. Analyses with different meshes should have been tried to verify this, but, because of time restrictions - the analyses had to be completed before the actual bridge testing - this has not been done.

The loading blocks have been modelled as two line loads which were each placed at the edges of two elements, see Figure 3. Linear dependence relations have been supplied to ensure that all nodes beneath a line load had the same vertical displacements.

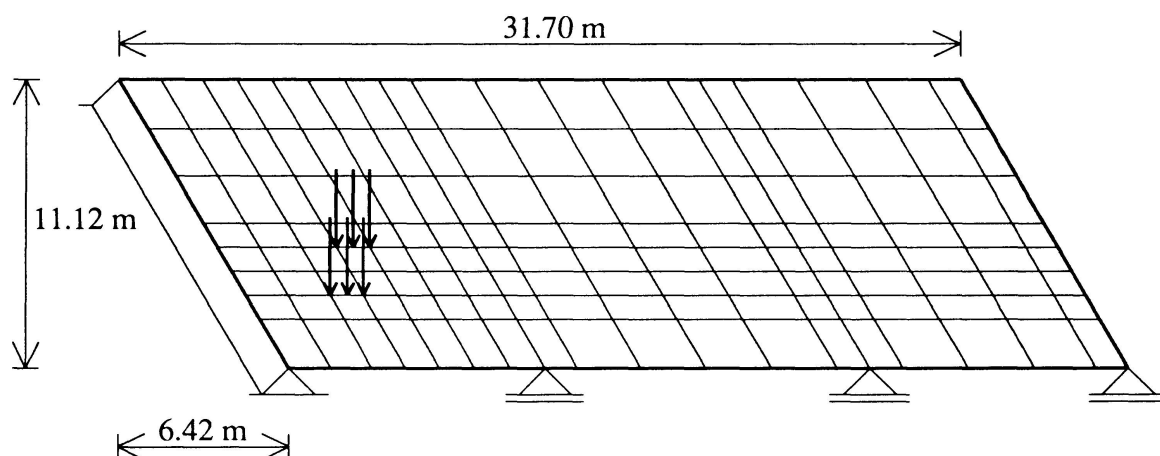


Figure 3 Finite element model for the Delft FE analysis of the bridge and position of the loads.

#### 3.3 The numerical solution procedure

All load-deflection curves that will be presented in the remainder of this article correspond to converged solutions in which a force norm of  $10^{-2}$  was satisfied after 4-5 equilibrium iterations with a Modified Newton-Raphson scheme, in which the stiffness matrix was set up at the beginning of each loading step. For the plasticity models this matrix was the tangent stiffness matrix and for the cracking model the secant stiffness matrix was substituted. At the points were

the calculations have been terminated further analysis was always possible. Rather large steps have been taken, approximately fifty for the upper bound solution and only five for the lower bound solution. The upper bound solution calculations in which the step size was halved showed that for this structure even the coarse loading steps were fine enough.

### 3.4 Assessment of the boundary conditions

The piers have not been modelled in the predictive analyses, because they have no influence on the final collapse load or the failure pattern. However, there is some influence on the load-deflection pattern, not only because of the neglected axial stiffness of the piers, but also because the piers act as rotational springs on the bridge deck. From a hand calculation it appeared that the maximum axial shortening of the piers would be approximately 0.1 mm, which is negligible. The rotational stiffness of the piers was not taken into account either. This simplification will be justified below.

A most important issue when modelling an existing structure is the interaction of the structure with the environment. At the abutments as well as at the piers we have the question whether the most appropriate boundary condition would be a clamped support, a hinged support, or a roller support. The question of clamped support vs hinged support can be partly resolved by carrying out eigenvalue analyses and comparing the numerical results with the lowest eigenfrequency that comes out of the modal test ( $\approx 8.3$  Hz). In the finite element analyses with the mesh of Figure 3 the mass density of the concrete was taken as  $\rho = 2370 \text{ kg/m}^3$  and Young's modulus  $E$  and Poisson's ratio were assumed as 24800 MPa and 0.2 respectively. The reduced value for Young's modulus was adopted to model the observed deterioration of the concrete. In the first analyses all supports were assumed to be hinged. When the influence of the asphaltic concrete cover was neglected an eigenfrequency of 7.43 Hz was computed, whilst the slightly lower value of 6.76 Hz was found for the analysis in which the asphaltic concrete cover was included. These values are much closer to the experimentally determined eigenfrequency than the value of 22.69 Hz that was obtained for the case with clamped ends and hinged supports at the piers. This indicates that (i) the supports at the abutments are not clamped and (ii) neglecting the bending stiffness of the piers is reasonable. However, the issue of hinged vs roller supports cannot be answered by modal analyses and will be investigated below.

### 3.5 Model parameters for non-linear finite element analysis

In the non-linear analyses the following data have been used. For the reinforcement an elastic-plastic model was utilized with a Young's modulus  $E_s = 200000 \text{ MPa}$ , an initial yield strength  $\sigma_{sy} = 345 \text{ MPa}$  and a hardening modulus  $h = 7000 \text{ MPa}$ , which is in agreement with the experimentally supplied data. The inelastic behaviour of concrete in tension has been modelled by the multiple fixed crack model of de Borst and Nauta [2] and Rots [5]. The shear retention factor  $\beta$  was set equal to 0.2 in all analyses. For the expected type of bending failure a variation of  $\beta$  hardly has any impact on the results.

To account for the stiffness of the concrete between the smeared-out cracks a tension-stiffening model was adopted with a linear softening branch and an ultimate strain at which the residual load-carrying capacity is exhausted  $\epsilon_u = 1/2 f_{sy}/E_s$ . The factor  $1/2$  has been introduced because previous experience has shown that this generally leads to a better prediction of the structural behaviour [4] and because a hand calculation for a rectangular cross section showed that taking  $\epsilon_u = f_{sy}/E_s$  would result in a moment at which the steel starts yielding,  $M_{sy}$ , that is larger than the moment at which collapse ultimately occurs ( $M_u$ ).

The concrete stresses in biaxial compression were limited by a Drucker-Prager yield contour,



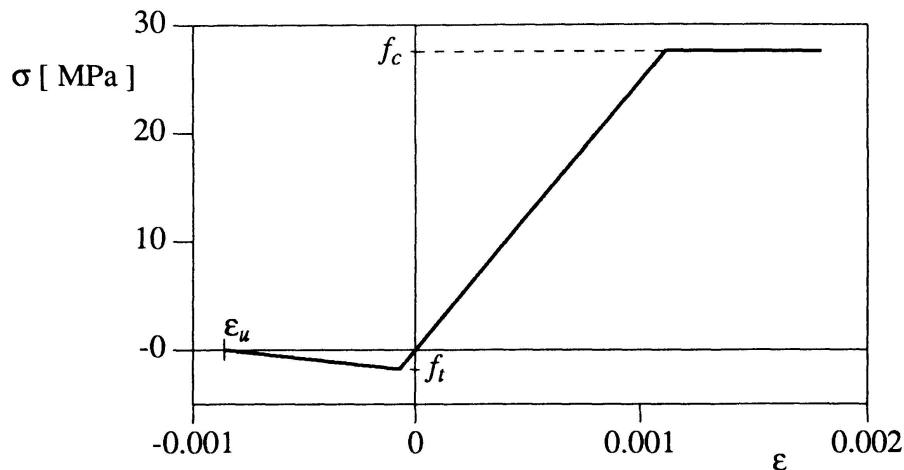


Figure 4 Uniaxial response of concrete for the reference set of model parameters.

which was fitted such that the pure biaxial compressive strength  $f_{bc}$  equals 1.16 times the uniaxial compressive strength  $f_c$ . Perfectly plastic behaviour was assumed thereafter, because any introduction of softening in compression would result in an extreme mesh sensitivity, which cannot yet be modelled properly. The uniaxial compressive strength  $f_c$  itself was set equal to 27.5 MPa. This is a relatively low value, and was adopted to account for observed damage in the concrete. The tensile strength was initially set equal to  $f_t = 3.2$  MPa, which is the value that had been suggested by investigators of the University of Cincinnati [1], but later the value  $f_t = 1.8$  MPa has been used which follows from applying  $f_t = 0.75 \cdot (1 + f_c/20)$ , which formula is used in the Dutch Codes of Practice. In parameter studies it later appeared that the tensile strength affects the load-deflection curve only in the first stages of cracking. The uniaxial stress-strain curve that results from the adopted set of reference parameters is shown in Figure 4.

### 3.6 Numerical results

When carrying out non-linear finite element analyses it is sensible to first concentrate on the most important causes of the non-linear structural behaviour, cf. the almost pedagogic treatise of Meyer [3]. For 90% of all reinforced concrete structures cracking and yielding of the reinforcement are the dominant non-linear phenomena which govern the structural response. Therefore, firstly analyses were carried out in which concrete plasticity was not taken into account. These analyses were carried out under arc-length control with a novel and very robust method for estimating the load increment in a step [6]. The results are the upper and lower curves of Figure 5. In these figure half the total load has been plotted against the deflection of the outermost loading block. The upper curve was obtained under the assumption that all supports (at the abutments and at the piers) were hinges, while the lowermost curve was obtained assuming that all supports were rollers except for one of the abutments.

We observe that this variation in boundary conditions has a tremendous impact on the structural response of the bridge. This phenomenon can be explained as follows. In the latter case (the lower-bound solution) cracks due to the bending moments penetrate deep into depth of the slab which causes large horizontal strains in the midplane of the slab. As a consequence an axial elongation of the midplane occurs. On the other hand, this elongation is entirely prevented in case of hinges at all supports. This means that additional in-plane forces prestress the slab. These membrane forces effectively prevent collapse of the bridge, as an almost linearly ascending load-displacement curve

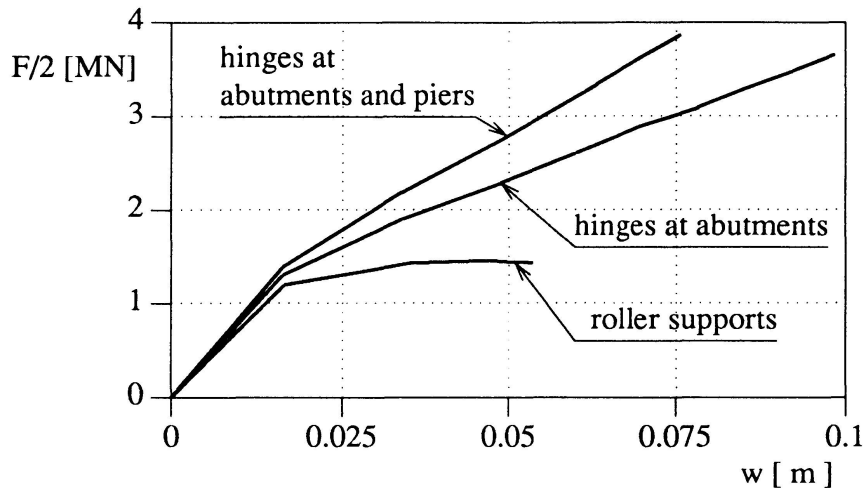


Figure 5 Influence of boundary conditions on load-bearing capacity.

was computed up to a displacement of 0.2 m, at which point the calculations were stopped. At this point a large part of the reinforcement was yielding. Because no real collapse load could be identified at this point, which is far beyond the failure loads predicted by yield line solutions, the role of the membrane forces seems unrealistically high for these boundary conditions.

To further illustrate the important role of the membrane forces an additional analysis was undertaken in which the piers were roller-supported, but where both abutments were modelled as hinges. The membrane actions that develop are now distributed over all three spans and, as a result, the load-displacement curve nicely falls between both extremes. At a deflection of 0.2 m significant yielding of the reinforcement was again observed, but there were no signs of impending collapse.

The solutions with hinges at all supports and with hinges at only one abutment can be considered as upper and lower bound solutions respectively. Because the precise boundary conditions were unknown a more accurate prediction of the collapse load could only be obtained by improving the upper and lower bounds. To this end first the effect of a variation of the hardening modulus of the reinforcement was considered. In particular it was thought that the almost linear rising branch of the analysis with the hinged supports might be caused by the hardening of the reinforcement after first yielding. Therefore analyses were carried out with the same data, but with an ideally-plastic behaviour of the reinforcement. Surprisingly, for both types of boundary conditions the differences were well within 1%.

Next, it was investigated how the type of loading affected the computed load-deflection response. In the actual test the loading was first carried out under load control and when the collapse load was approached a switch was made to displacement control. This could not be simulated in the finite element analyses. As stated most analyses were carried out under arc-length control with equal loads on both loading blocks. Although the precise form of loading should not influence the collapse load the deflections can be affected by a different control scheme. Therefore an analysis was also made under pure displacement control, in which both loading blocks were pushed down by the same amount in each loading step. In this loading arrangement there is no relative tilting of the outermost loading block compared to the other block, which results in a somewhat stiffer response. However, the differences in displacements remained within 10-15% for a given load level.

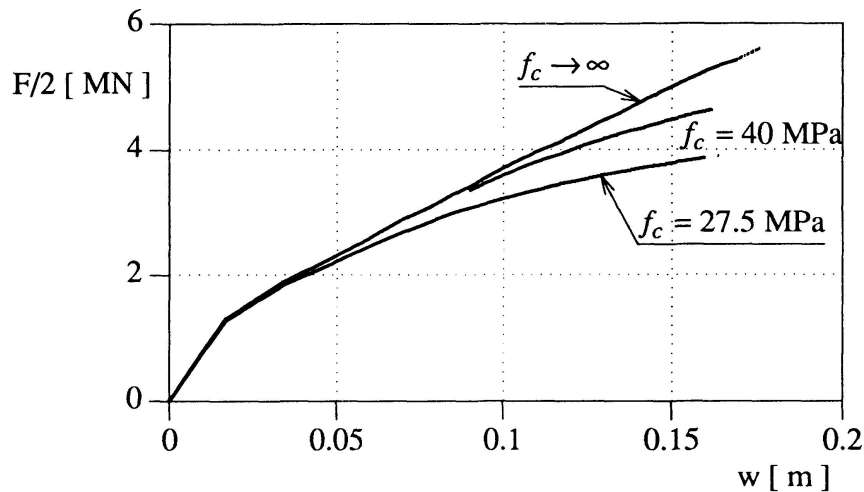


Figure 6 Influence of concrete plasticity on failure load for the case that there are hinges assumed at the abutments and roller supports at all piers.

The most important parameter that influences the upper bound solution is the compressive strength  $f_c$ . Figure 6 shows the effect of varying  $f_c$  on the load-deflection curves of the upper bound solution. The calculation in which the compressive stresses were not limited, gives the stiffest structural response, but computations with  $f_c = 40$  MPa and  $f_c = 27.5$  MPa give a markedly softer response. In fact, we consider the calculation with  $f_c = 27.5$  MPa as the best upper bound solution, and the structural response should be between this solution and the lower bound solution of Figure 5. It is finally remarked that the lower-bound solution is not affected by adopting a plasticity model to bound the compressive regime, since the maximum compressive stresses remain well below the uniaxial compressive strength  $f_c$ .

#### 4. DISCUSSION OF THE RESULTS AND FAILURE MECHANISM

The authors expected that the lower bound solution would be closer to the experiment than the upper bound solution, since it was believed that the abutment was not sufficiently rigid to sustain the large horizontal forces without undergoing horizontal displacements. Accordingly, the most realistic assumption for the conditions at the abutments would be roller supports rather than hinges. This expectation was confirmed when the testing had been carried out, Figure 7.

Although the numerically predicted lower-bound solution for the failure load and the experimentally obtained collapse load agree extremely well, this is not completely the case for the failure mechanism. From observations on the experimental failure pattern it seems that first a pure bending type failure has occurred, but that after significant deformations the shear capacity was exhausted. This point, that is when the capacity to sustain external loads starts to decrease, is marked by the onset of the softening branch in Figure 7. This hypothesis is strengthened by the following observations. Firstly, the used plate/shell elements can only predict accurately bending type failures. Yet, it predicted the experimental failure load very well. Secondly, not only did our (lower-bound) numerical solution, in which membrane effects played no role, match the experimental failure load, also the yield line solutions obtained at the University of Cincinnati [1] fall in the same range, indicating that at the peak of the experimental load-deflection curve only bending effects have played a role of importance. Exhaustion of the shear capacity and subsequent punching only comes into play after significant yielding of the reinforcement.

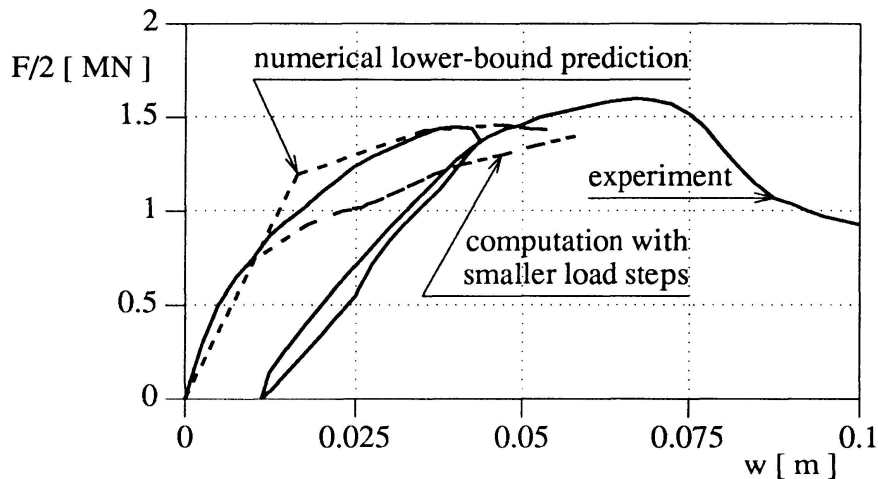


Figure 7 Numerically obtained lower-bound solution and the experimental failure load.

In the numerical simulations yielding started at a load level of  $F/2 = 1.05$  MN at the edge of the outermost loading block near the abutment. The extent of the area in which the bottom reinforcement was yielding at a load level of  $F/2 = 1.40$  MN is shown in Figure 8. The maximum plastic strains at this point were approximately 0.27%. A recalculation, conducted with smaller load steps, resulted in a somewhat softer response, but the computed failure load was hardly affected, Figure 7.

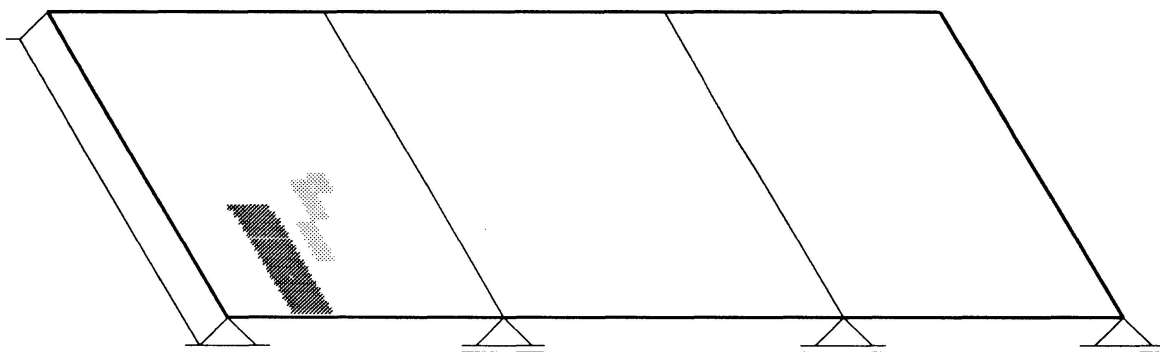


Figure 8 Spread of zone in which the bottom reinforcement is yielding at  $F/2 = 1.40$  MN.  
The lighter shaded area has experienced less plastic flow.

## 5. CONCLUDING REMARKS

The numerical simulations have shown that the uncertainty in the boundary conditions of the bridge was more important than the fact that the material parameters could not be determined exactly. Nevertheless, reasonable predictions for upper and lower bounds of the failure load could be obtained by a proper combination of sensitivity studies on the influence of the boundary conditions and the material data. The actual field test resulted in a collapse load that was marginally above the predicted numerical lower bound solution.

## ACKNOWLEDGEMENTS

Partial financial support from the Commission of the European Communities through the Brite-Euram programme (Project BE-3275) to the first author is gratefully acknowledged.



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## SELECTED PAPERS



**Analytical Modelling for Fatigue Assessment of the Clifton Suspension Bridge**  
**Modèle analytique d'évaluation de la fatigue du pont suspendu de Clifton**  
**Analytisches Modell zum Ermüdungszustand der Clifton-Hängebrücke**

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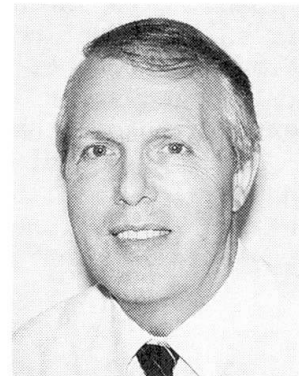
M. Stuart Cullimore, born 1920, graduated in civil engineering from Bristol University in 1940. Reader in Structural Engineering until 1985. Reserach latterly on fatigue of structural joints and bridge decks. Now Visiting Fellow at University of Bristol.

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William Smith, born 1941, graduated in Civil Engineering at the University of Edinburgh, Scotland. Obtained his PhD (vibration of bridges) at the University of Bristol where he now studies dynamic loading and fatigue of bridges.

## SUMMARY

The Clifton Suspension bridge is an iron eye-bar chain suspension bridge of 214 m span. Despite its age (128 years) it is a vital link in the traffic system of Bristol, carrying nearly 4 million vehicles per year. An extensive structural assessment of the bridge has been carried out. This has required global analytical modelling, load testing, strain monitoring under traffic, and fatigue appraisal of the major components.

## RÉSUMÉ

D'une portée de 214 m, le pont suspendu de Clifton est supporté par des chaînes formées de barres à oeil. Malgré son âge de 128 ans et avec près de 4 millions de véhicules par année, il constitue un élément de liaison essentiel pour le trafic routier de Bristol. Au cours de l'évaluation de la sécurité à la ruine à l'aide d'un modèle analytique appliqué à la structure complète, il a été procédé à des essais de charge et à des mesures de déformation sous charge mobile, ainsi qu'à la vérification de la fatigue de tous les éléments porteurs principaux.

## ZUSAMMENFASSUNG

Die Clifton-Hängebrücke mit 214 m Spannweite wird von Ketten aus eisernen Augenstäben getragen. Trotz ihres Alters von 128 Jahren stellt sie mit fast 4 Mio. Fahrzeugen pro Jahr eine Hauptverbindung im Verkehrsnetz von Bristol dar. Bei der notwendigen Tragsicherheitsüberprüfung anhand eines analytischen Modells des gesamten Tragwerks wurden Probelastungen, Dehnungsmessungen unter Verkehr und Ermüdungsnachweise aller Hauptkomponenten durchgeführt.





## 1. INTRODUCTION

The Clifton Suspension Bridge was designed originally by the eminent Victorian engineer Isambard Kingdom Brunel. The bridge was completed in 1864, after his death, with a number of important modifications to his design [1]. The spectacular setting of the bridge spanning the Avon Gorge makes it an important tourist attraction and focus of civic pride (Fig 1). But it is also an important link in the traffic system of Bristol carrying nearly 4 million vehicles per year, although there is a gross weight limit of 40 kN.

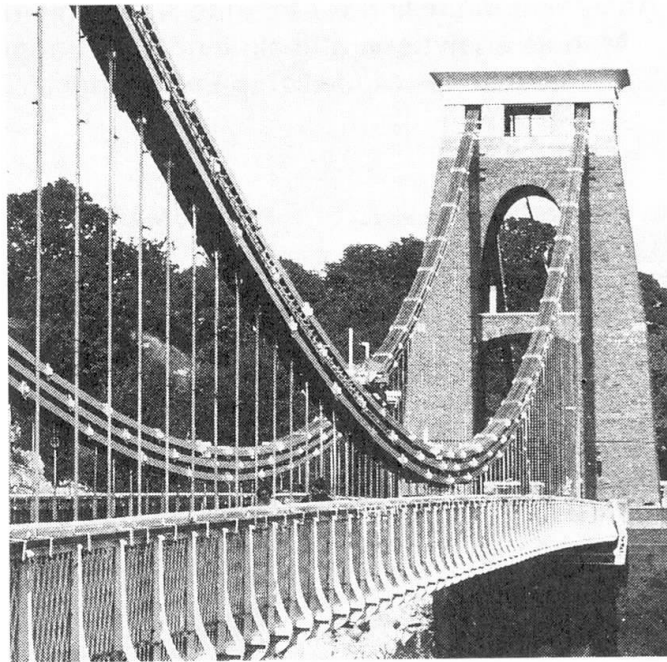


Fig 1 Clifton Suspension Bridge

Structurally the bridge is a wrought iron eye-bar suspension chain with a suspended structure carrying an asphalt surfaced timber deck (Fig 2). There are three chains on each side of the roadway, arranged one above the other as shown in Fig 1. They are made up of 175mm x 25mm wrought iron bars with special eye joints forged to each end. Each link is made up of ten or eleven bars arranged side by side, interleaved with the bars of the next link, and connected with a pin through the eye joint. Successive suspender rods, at intervals of 2.44m (8 feet) are attached to each of the three chains in turn, (see Fig 1), so that the eye-bars are approximately 24 feet in length depending on the local slope of the chain. The wrought iron suspended structure (Fig 2) consists of longitudinal riveted plate girders, under each set of chains, lattice cross-girders and longitudinal lattice parapet girders. The roadway deck is timber with mastic asphalt surfacing.

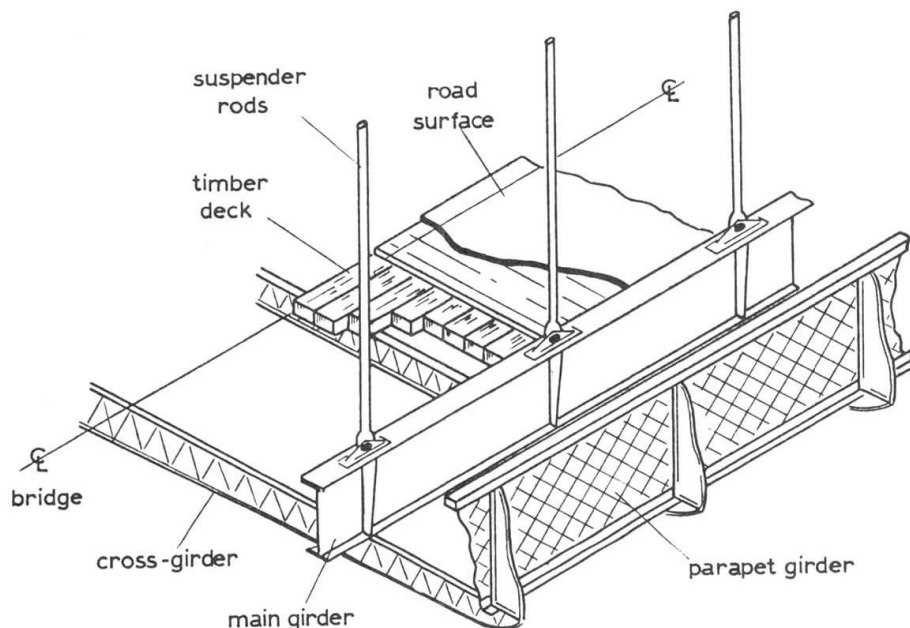


Fig 2 The suspended structure

A number of studies of the structural capacity of the bridge have been undertaken this century, some of them resulting in remedial or strengthening works [1,2]. The collapse of the Point Pleasant Bridge over the Ohio river in 1967, resulting from corrosion-fatigue in an eye bar, prompted an extensive fatigue appraisal of the Clifton Bridge [3]. It was concluded that there was an adequate margin of safety against fatigue failure at that time. However, traffic loading was steadily increasing and there was concern over progressive deterioration of the riveted joints of the parapet girder and other signs of wear or damage. It was decided that a global analysis of the structure should be carried out, using modern analytical methods, so that the effects of a range of load cases could be studied.

## 2. FINITE ELEMENT MODEL

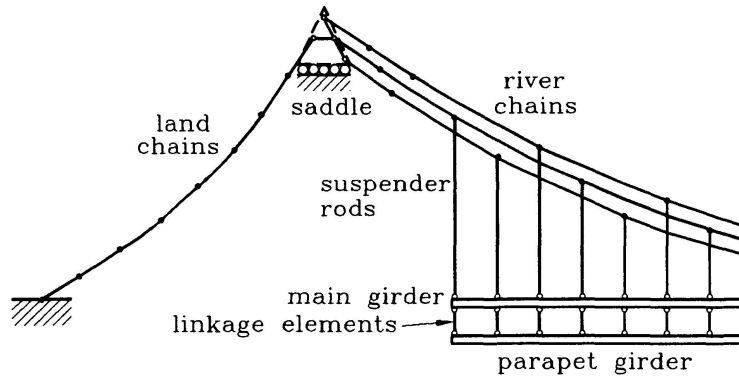
### 2.1 Modelling assumptions and analytical procedure

Suspension bridge behaviour under load is geometrically non-linear. This is because the cable or chain adapts its shape when a concentrated load is applied at a particular point on the structure. In most suspension bridges, as at Clifton, the longitudinal girder provides some stiffening and effectively distributes these deformations over part of the structure. For this reason it was decided to use a finite element program which had geometrically non-linear solution capabilities.

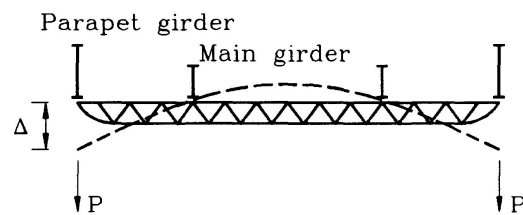
The finite element model was designed to represent the effects of vertical loading on the structure. For this purpose a two-dimensional model was considered to be adequate. Dead load and traffic load in both lanes is symmetrical about the longitudinal axis of the bridge and therefore only one half of the bridge needed to be modelled, i.e. one set of three chains supporting the main girder and parapet girder. Eccentric traffic loads, in the form of single vehicles or traffic in one lane only, were dealt with by means of a separate torsional analysis.

A schematic diagram of the node and element geometry is shown in Fig 3a. From the left anchorage to the tower the three chains were represented by a single chain of beam elements. The final link was connected by a pin joint to the saddle elements. The saddle nodes were all effectively constrained to move horizontally as a single unit, simulating the roller bearing that exists at the top of each tower. The three chains of the main span were represented by beam elements of the same length as each eye bar link. Thus the correct sequence of connection to the suspender rods could be modelled as shown. Each link of ten, eleven or twelve bars, was modelled by a single element of equivalent area. It has been observed that the chain links behave as if they are rigidly connected to each other over the main part of the span. The pins work freely only at the tower saddles. The main girder was modelled by beam elements pin connected to the vertical rods as shown. There is no vertical or horizontal restraint to movement of the main girders of the bridge. However, in order to avoid computational instability, a soft horizontal spring restraint was connected to the middle node of the deck.

The behaviour of the cross girders and parapet girder were modelled by suspending longitudinal beam elements from the main girder elements by means of vertical linkages. The stiffness of the linkage elements was determined from the stiffness of the cross girder in shear between points of connection of the main and parapet girders as shown in Fig 3b. In order to avoid the problem of horizontal instability it was sufficient to introduce horizontal coupling between main and parapet girders at mid-span.



(a) Schematic diagram of node and element geometry

Stiffness of linkage element,  $k = P/\Delta$ 

(b) Modelling of cross-girder stiffness

Fig 3 Finite Element Model

## 2.2 Analysis of eccentric loading

It was mentioned earlier that eccentric loads, such as single vehicles or traffic in one lane only, could be dealt with by introducing a torsional component. This is illustrated in Fig 4 where it can be seen that the loading can be resolved into symmetric and torsional components at the line of the chains. If the cross girder is rigid, then because of its rotation about the centre line, it forces the parapet girder to deflect more than the main girder in the torsional case. Hence the effective stiffness of the parapet girder, if it is transposed to the same plane as the main girder and the chains, becomes:

$$I_{\text{eff}} P_A = I_P (B/b)^2 \quad (1)$$

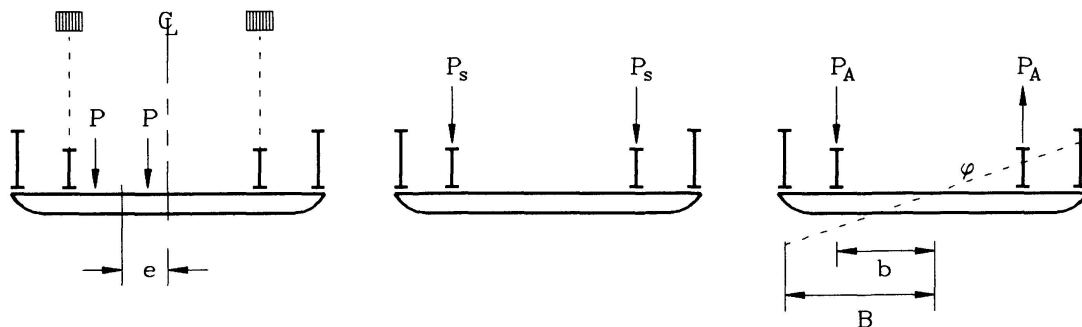
Symmetric component  $P_s = P$ Torsional component  $P_A = P.e/b$ 

Fig 4 Analysis of eccentric loading

In this way it would be possible to analyse the problem as two separate load cases and add the results, provided that it could be assumed that deflection of the chains was linear with changes in live load applied at a point. In practice it was possible to combine the symmetric and torsional components into a single eccentric load case. This was done by evaluating the effective stiffness of the parapet girder when transposed to the line of the chains with both symmetric and torsional component loads present. The formula is as follows:

$$I_{\text{effp}} = I_p \left[ \frac{B^2}{B^2 + fb^2} \right] (1 + f) ; \text{ where } f = P_a/P_s \quad (2)$$

Further refinements were included which took account of cross girder flexibility in the torsional case, but are outside the scope of this paper.

### 2.3 Load tests and comparison with analytical model

In order to confirm the analytical model, loading tests were carried out on the bridge at night. The weight limit on the bridge is 40 kN. This represents vehicles such as ambulances, loaded vans and pick-up trucks. Two loading cases were identified as follows:

#### (a) Dual vehicle symmetric loading

The maximum concentrated load occurs when two 40 kN vehicles, travelling in opposite directions, pass each other on the span. Assuming a load distribution of 15 kN at front axles and 25 kN at rear axles the load case is as shown in Fig 5. Although the front axles are in opposite lanes of the carriageway, and would produce an anti-symmetric torsional component of loading, it was assumed that this would be a small localised effect and that the load could be treated as symmetric as shown.

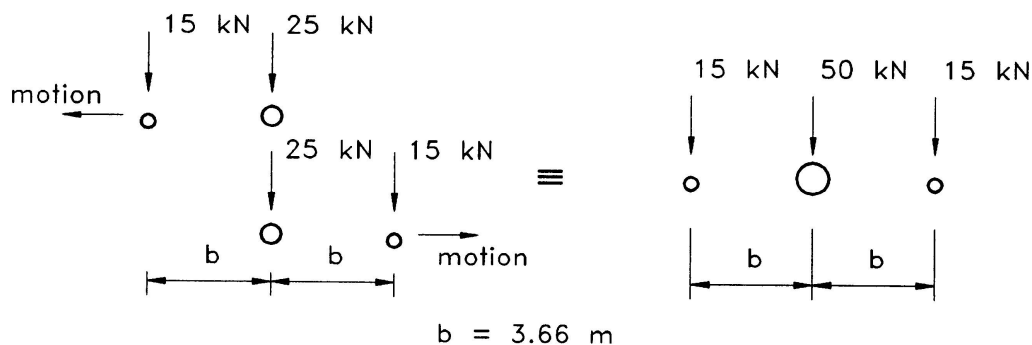


Fig 5 Dual vehicle load case (symmetric)

#### (b) Single vehicle eccentric loading

The bridge is torsionally flexible and therefore it was considered important to study the effects of a single 40 kN vehicle travelling in one lane of the carriageway, thereby applying an eccentric loading to the structure. The eccentricity of the vehicle in the analysis was taken as 1.0 m from the centre line of the carriageway.

For the loading tests on the bridge, two pick-up trucks were hired and loaded with boxes of nails to provide the appropriate distribution. Strain gauges were fixed to the top and bottom flanges of one parapet girder and both main girders at 1/4 span. The signals were logged by a computer data acquisition system while the vehicles were crossing the span in the loading configurations described above.



The results of a typical analysis are shown in Fig 6 and the results of a single vehicle load test run are shown in Fig 7. Similarity in the shapes of the curves is evident. The test run results are effectively influence lines for strain at 1/4 span when the vehicle passes over the span. The analysis represents the distribution of deflection and bending moments when the vehicle is stationary at the 1/4 point. But since the wheel base of the vehicle is very short compared with the span, and there is evidence of linearity under live loads, it may be considered that the analysis results approximate to influence lines. It may also be noted that the bending in the main girder is sharper than that of the parapet girder directly under the load. This is because flexibility of the cross girder results in transfer of bending from the main to parapet girder to be distributed longitudinally to some extent. A further point to note about the results is that the parapet girder bending moment is of the same order as that of the main girder. It is not known if this structural action of the parapet girder was taken into account in the original design.

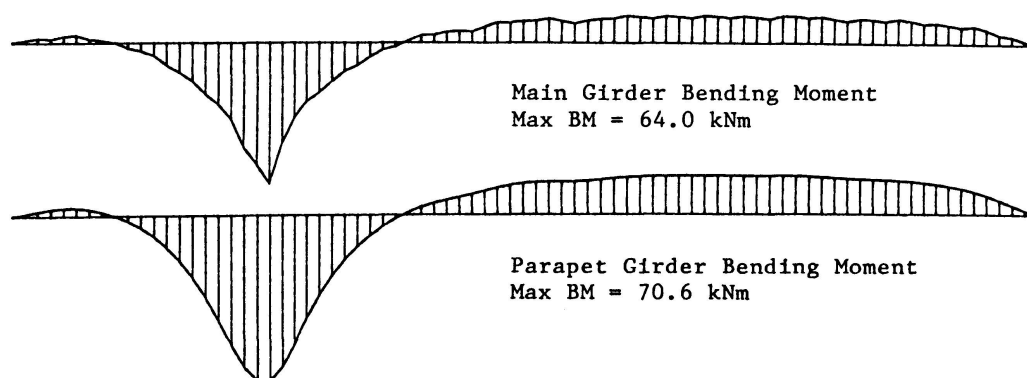


Fig 6 Finite element analysis of eccentric 40 kN load at 1/4 span

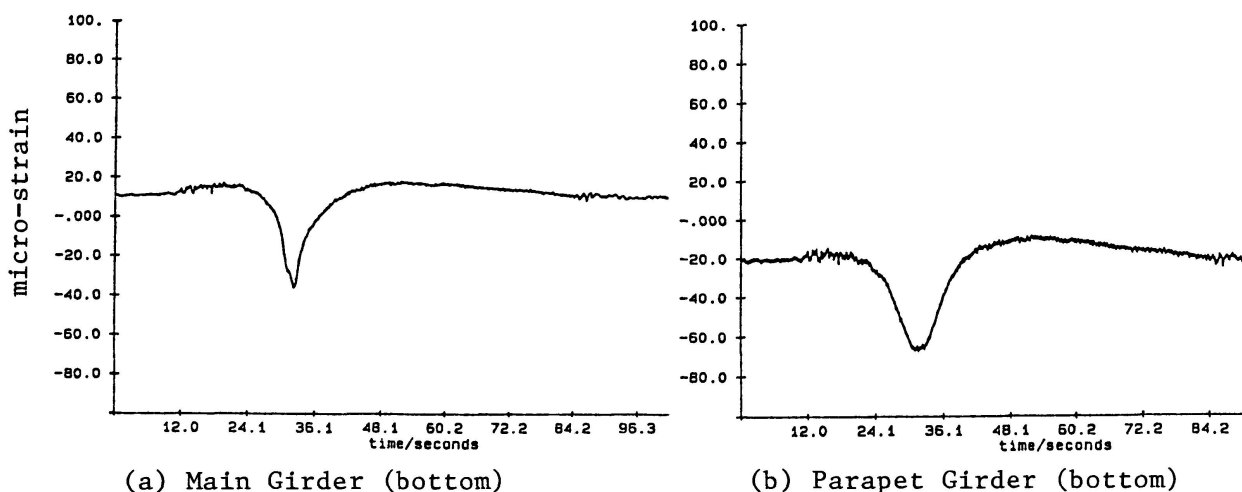


Fig 7 Strains at 1/4 span under action of 40 kN vehicle eccentric load

In order to obtain quantitative comparison between the experimental results and the analysis it was necessary to convert the observed strains at top and bottom of the girders to equivalent bending moments. This was done using the measured sectional properties of the girders and a value of  $E$  for wrought iron of  $192 \text{ GN/m}^2$ . The results are compared in Table 1 below.

Table 1 Bending Moments at 1/4 span in kNm (analysis in parentheses)

LOAD	POSITION	MAIN GIRDER		PARAPET GIRDER		TOTAL MOMENT	
8 ton	1/2 span	18.2	(19.7)	13.1	(24.6)	38.4	(44.3)
symm.	3/8 "	3.3	(4.0)	5.3	(1.8)	11.6	(5.8)
	1/4 "	-89.1	(-111.7)	-64.1	(-86.3)	-170.6	(-198.0)
	1/8 "	-2.1	(-8.5)	-7.0	(-10.6)	-18.8	(-19.1)
4 ton	1/4 "	-56.4	(-64.0)	-43.7	(-70.6)	-111.2	(-134.6)
ecc.							

In Table 1 the experimental moments were evaluated from the strain gauge data so as to provide a comparison with the analysis. The analytical results are generally greater than the experimental results. This is probably a result of the influence of the deck which acts like an additional flange to the main girder. This was difficult to include in the analytical model although some allowance was made by modifying the girder section properties to simulate the shift of the neutral axis.

The 'Total Moment' in Table 1 is the sum of the girder moments in the case of the analysis. However, the longitudinal forces introduced by the presence of the deck could be evaluated from the strain gauge data together with the girder moments. Hence, the 'Total Moment' of the experimental results is always greater than the direct sum of the girder moments.

### 3. CONTINUOUS MONITORING OF GIRDER STRAINS UNDER NORMAL TRAFFIC

#### 3.1 Installation and use of "Stress Analyser"

The same strain gauge locations, as used in the vehicle loading tests, were monitored continuously under normal traffic for several one week periods. The equipment for doing this, called a "Stress Analyser" [4], was capable of amplifying the signal from the gauges, detecting peaks and troughs of the fluctuating signal, and performing a "rainflow" count in real time.

"Rainflow" counting is an accepted method for interpreting a varying amplitude signal in terms of an equivalent number of simple cycles of different amplitudes. The fatigue damaging potential of the signal may then be assessed by summing the fatigue damage contributions of all the simple cycles.

The data are provided in the form of numbers of cycles of different strain ranges. The mean strain was not recorded because, although it has an effect it is generally accepted that, for materials such as wrought iron with many defects, strain range is the dominant factor affecting fatigue life.

#### 3.2 Prediction of strain range cycle count and comparison with observations

The results of the global analysis were used to make a prediction of the strain range cycle count under normal traffic. This was achieved by looking at the output from the analysis of the bridge under a 40 kN eccentric load as shown in Fig 6. It has already been said that this figure approximates to an influence line and therefore the range of bending moment at the 1/4 span when a 40 kN vehicle crosses the bridge may be deduced from the maximum and minimum of this figure. It was further assumed that the bending moments at this point were linear with load within the range of live loading. Hence, it was possible to evaluate strain ranges occurring under the passage of a range of vehicle weights as they cross the bridge.

A classification count was carried out on the bridge, grouping weekday traffic into seven weight classes. Cars were relatively easy to classify according to weight, but estimates had to be made for larger vehicles such as pick-up



trucks, vans and ambulances. A count was also made of the number of times vehicles travelling in opposite directions were applying load to a particular cross girder simultaneously. The count is set out in Table 2 below.

**Table 2 Number of loadings of a cross girder by vehicles of different weight**

Vehicle weight	8	10	14	20	25	30	40 (kN)
Left lane	264	633	252	26	22	11	2
Right lane	343	819	243	41	22	11	3
Both	21	184	56	10	1		

The weights were converted into strains at the top of the main girder and a table of the number of loading cycles within strain range bands was compiled. Data on the number of vehicle crossings was available from the toll records and amounted to 72,000 vehicles per week during the period of the study. The number of cycles for the short count (four hours in total) was then factored up to give the number of cycles that would occur at the same rate during one week of normal traffic. The predicted cycle count was compared with the data obtained using the "Stress Analyser" and is shown in Table 3.

**Table 3 Strain range cycle count: Predicted v. Stress Analyser**

Strain Range ( $\times 10^{-6}$ )	Number of Loading Cycles		
	Predicted Short count Seven days	Stress Analyser (avg of 3 seven day periods)	
0 - 10	343	8,332	124,022
10 - 20	1,326	32,210	20,713
20 - 30	695	16,882	12,403
30 - 40	469	11,393	6,989
40 - 50	82	1,992	3,328
50 - 60	25	607	1,356
60 - 70	21	510	519
70 - 80	1	24	174
80 - 90	2	48	59
90 - 100			18
100 - 110			7
110 - 120			3
120 - 130			1

Considering the difficulties of assessing the loads from the visual classification count the correlation is remarkably good. The large number of cycles occurring in the smallest strain range may be the result of small vibrations and electronic noise. A further comparison can be made by evaluating the fatigue damage done by each loading cycle. This can be achieved by assuming a power law for fatigue life with an index of 3, together with Miner's law of cumulative damage. It is then possible to calculate the equivalent strain range per vehicle, if applied repetitively, that would yield the same fatigue damage as the actual variable loads. This quantity (ESRV) is given by

$$ESRV = (n_i S_i^m / 72,000)^{1/m} \quad (3)$$

where  $n_i$  is the number of cycles of strain range  $S_i$  and  $m$  is the index of the power law.  $m=3$  is a reliable mean value for fatigue of wrought iron.



Using the data in Table 3 the following comparison may be made:

$$\begin{aligned}\text{ESRV predicted} &= 26.4 \times 10^{-6} \\ \text{ESRV experiment} &= 26.8 \times 10^{-6}\end{aligned}$$

This result confirms that the method of prediction provides a very accurate measure of fatigue damage.

#### 4. FATIGUE ASSESSMENT OF MAJOR COMPONENTS

##### 4.1 Saddle link

Rotation of the chain links attached to the saddle bearings at the tops of the towers were found to produce significant variations in principal stress while vehicles crossed the bridge. In an earlier study this was found to be the most significant fatigue loading on the bridge [3]. The results of the load tests carried out on the bridge at that time were found to compare favourably with the global analysis. Hence the conclusion of the earlier assessment, that there was sufficient factor of safety against fatigue or fracture, was confirmed.

##### 4.2 Main girders

The strains observed in the main girder under normal traffic (Table 3) were converted to stress cycles. These were compared with S-N curves for riveted girders [5,6]. Assuming traffic totalling 4 million vehicles per year the fatigue life of the main girder was calculated to be 468 years.

##### 4.3 Parapet girders

For fatigue loading the critical location is the spliced joint in the top flange of the parapet girder. Strains were obtained using the same procedure as for the main girders and were converted to stress ranges. The joints have been progressively deteriorating in recent years and a new friction grip bolted assembly has been designed as a replacement. Using the current UK code for fatigue assessment, the life of the joint was estimated to be 197 years.

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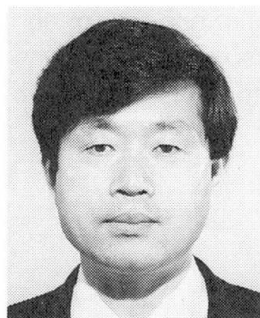
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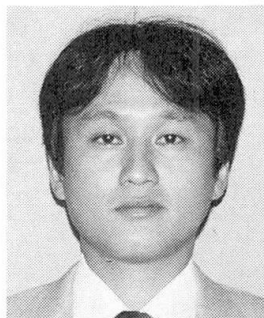
# **Long-term Prediction of Behaviour of Cable-Stayed Bridges** **Prédiction du comportement à long terme de ponts à haubans** **Voraussage des langfristigen Verhaltens von Schrägseilbrücken**

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## SUMMARY

Presented herein is a method to predict the long-term change of cable forces and slip of cables out of sockets in cable-stayed bridges. Employed are full-scale long-term tension tests of cables to determine the visco-elastic constants of the cables and the sockets. Based on the experimental results, the analytical prediction of bridges were made through the finite element visco-elastic analysis together with the Laplace transform and the results were compared to the site measurement values.

## RÉSUMÉ

Cet article présente une méthode pour évaluer le comportement à long terme des contraintes des câbles d'un pont à haubans, ainsi que le comportement au glissement de ses ancrages. Des essais du câble en vraie grandeur ont été effectués afin de déterminer les propriétés visco-élastiques des câbles et des ancrages. La méthode des éléments finis combinée avec la transformation de Laplace est appliquée à l'analyse et les résultats analytiques sont comparés avec les mesures effectuées sur le chantier.

## ZUSAMMENFASSUNG

Es wird eine Methode vorgestellt, mit der langfristige Veränderungen in den Seilkräften, einschliesslich Schlupf in den Verankerungen, vorausberechnet werden können. Dazu waren im Massstab 1:1 Versuche zur Bestimmung der viskoelastischen Eigenschaften von Seilen und Ankerköpfen nötig. Mit diesen Daten wurden Finite-Element-Berechnungen für Brücken unter Verwendung der Laplace-Transformation durchgeführt und die Ergebnisse mit In-Situ-Messungen verglichen.



## 1. INTRODUCTION

Presented herein is a method to predict the long-term change in the cable forces and cables slip-out from their sockets in cable-stayed bridges. Based on long-term tension tests on full-scale cables of 5m length, a very simple analytical model is proposed and an effort is made to determine the visco-elastic constants of the cables and sockets, taking into account the scale effect of the length of the cables, by extrapolating the results of the measurements carried out in cables with limited length to actual cables with arbitrary length. In addition, visco-elastic F.E.M. analysis using the experimental results was carried out to predict the long-term behavior of several existing bridges and these results were compared to the measured values at the site.

Due to the fact that the erection of bridges is usually completed within a period of one year or one year and a half at the site, the visco-elastic constants of the cables and sockets were determined emphasizing first, the initial relatively short period of the erection stages and, secondly, focusing on the control of the cable forces for the much longer period of service life.

## 2. LONG-TERM TEST OF PROTOTYPE CABLES

### 2.1 Experimental Method

When investigating the time-dependent behavior of materials, there are two types of tests, namely, creep and relaxation tests. The former being carried out under constant loading with increasing deformation, and the latter under constant deformation with decreasing stress. The type of test carried out in the present study is a combination of both types [1].

The measurement system is presented in Fig.1, where the load is measured by a load cell and the relative displacements between the cable and the steel frame, by displacement transducers. To investigate the visco-elastic characteristics of the cables due to the difference in cable strength, two types of cables (Specimen types 1 and 2) were tested. In addition, four different combinations of cables and sockets (Specimen types 3 to 6) were tested, in a total of 6 specimens. Table 1 shows the specimen dimensions and characteristics.

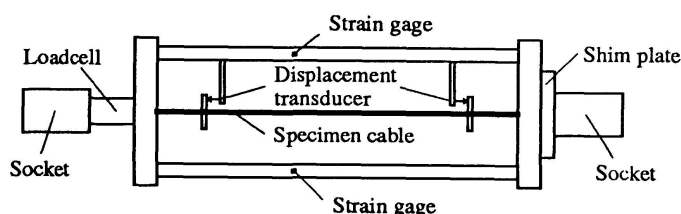


Fig.1 Measurement System

Table 1 Dimensions and Characteristics of the Test Specimen

Specimen Name	Type 1	Type 2	Type 3	Type 4	Type 5	Type 6
Cable Length (m)	5.9	5.9	5.4	5.4	5.4	5.4
Diameter of Wire (mm)	5.0	5.1	7.0	7.0	7.0	7.0
Number of Wires	127	127	19	19	19	19
Cable Type	PWS	PWS	PWS	PWS slightly twisted	PWS	PWS slightly twisted
Anchorage Length(cm)	44.0	44.0	16.3	16.3	30.7	30.7
Anchorage Type	Zinc-poured	Zinc-poured	HiAm	HiAm	Zinc-poured (Incl. 2% Cu)	Zinc-poured (Incl. 2% Cu)
Cross Sectional Area (cm <sup>2</sup> )	24.94	25.94	7.31	7.31	7.31	7.31
Breaking Force (kN)	4400	3910	1137	1137	1137	1137
Initial Cable Force (kN)	1400	1310	380	377	368	371

## 2.2 Test Results

Fig.2 shows the time variation of the tensile force in the cables. As it can be observed, the forces in specimen types 3 and 4 tend to stabilize in a relatively short time (about 20 days), whereas in the other cables, continue to decrease even after one year's measurement.

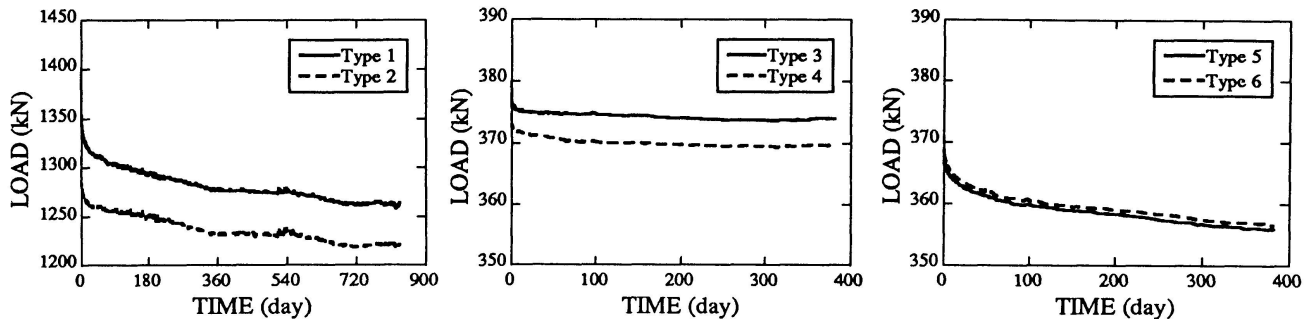


Fig.2 Time Variation of Cable Tensile Force

Although the tested cables and sockets were the same as the ones used in actual bridges, the cable length of the specimens differed from the actual cables, thus, it was decided herein to consider the cables and sockets separately. Fig. 3 illustrates the time-dependent strain of each cable type and Fig.4, the slip-out behavior of the different types of sockets.

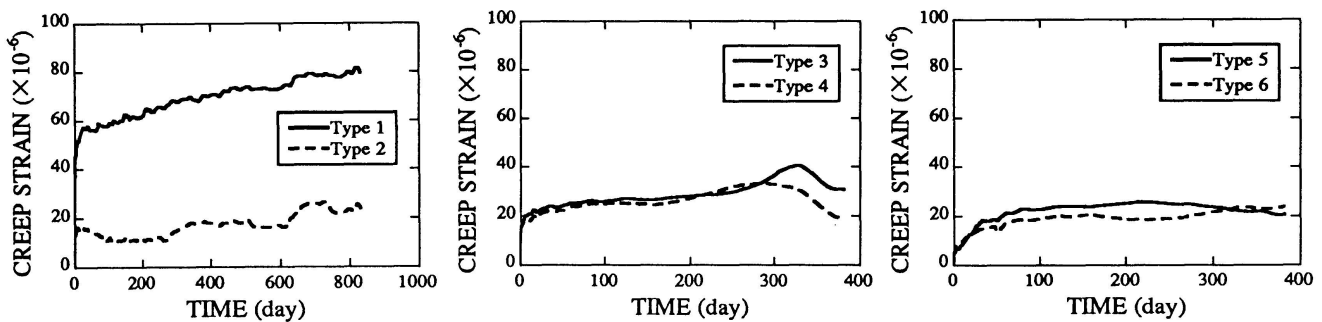


Fig.3 Time-dependent Behavior of Cables

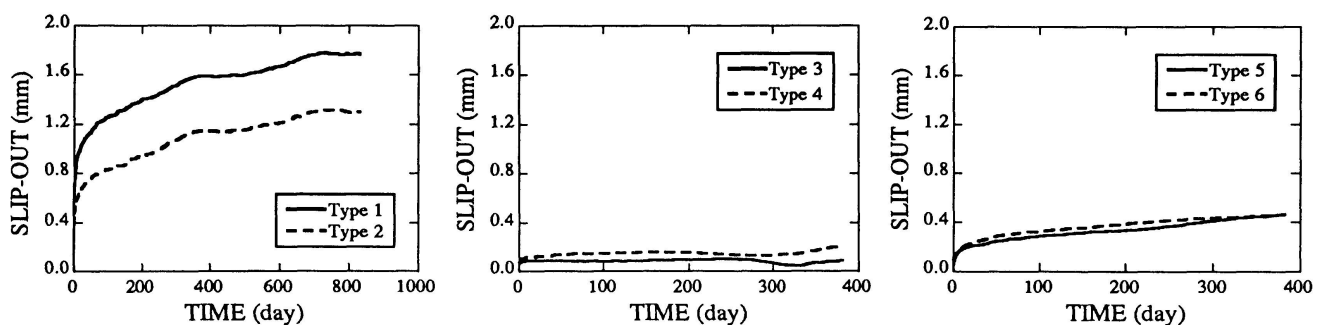


Fig.4 Time-dependent Behavior of Sockets

Specimen types 1 and 2 presented large values for the amount of slip-out from the sockets, compared to the values of cable creep. Specimen type 3 and 4, 5 and 6 have respectively the same sockets. In the formers, the forces, as well as the amount of slip-out stabilized in relatively short time (20 days); whereas in the latters, the amount of slip-out continued to increase.

Cable material of the specimen types 3 and 5, 4 and 6, being respectively the same, presented similar values for the final creep. However, time variation between cables of the same type were different, suggesting the influence of their sockets.



### 3. MODEL TO EVALUATE TIME-DEPENDENT CONSTANTS

#### 3.1 Mechanical Model

Due to its simplicity, the analytical model adopted is the three-element model shown in Fig.5 [2]. The total strain of the model  $\epsilon$ , can be expressed as the sum of the elastic ( $\epsilon_e$ ) and viscous ( $\epsilon_v$ ) strain:

$$\epsilon = \epsilon_e + \epsilon_v \quad (1)$$

For the total stress  $\sigma$ , the strain-stress relation-ship can be expressed as follows:

$$\sigma = \sigma_e = E_1 \epsilon_e \quad (2)$$

$$\sigma = \sigma_v = E_2 \epsilon_v + \eta \dot{\epsilon}_v \quad (3)$$

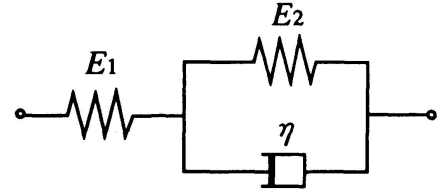


Fig.5 Three-element Visco-elastic Model

where  $E_1$ ,  $E_2$  are the elastic coefficients and  $\eta$  the viscosity coefficient of the three-element model. Differentiating Eq.1 and Eq.2 in relation to time  $t$  and introducing them in Eq.3, it yields the following equation, after some arrangement.

$$\dot{\sigma} + \frac{E_1 + E_2}{\eta} \sigma = E_1 \left( \dot{\epsilon} + \frac{E_2}{\eta} \epsilon \right) \quad (4)$$

#### 3.2 Evaluation of Time-dependency

The visco-elastic constants of the model were evaluated according to the three different methods described below.

##### 3.2.1 Method 1

Focusing on the viscous part of the model in Fig.5 (Eq.3) the following approach curve for the strain due to the viscosity was assumed.

$$\epsilon_v = \bar{\epsilon}_v (1 - e^{-\lambda t}) \quad (5)$$

The coefficient  $\lambda$  can be obtained through the least square method. The results of the evaluation for one of the cables is shown in Fig.6, with the corresponding slip-out from the sockets shown in Fig.7 and the viscosity constants thus evaluated are presented in Table 2.

This method is effective for cables in which the phenomena of creep and slip-out from the sockets stabilize in a short time, however, in cases in which the time dependent curves are not steep and long-term variation is observed, the curves tend to diverge from the predicted values.

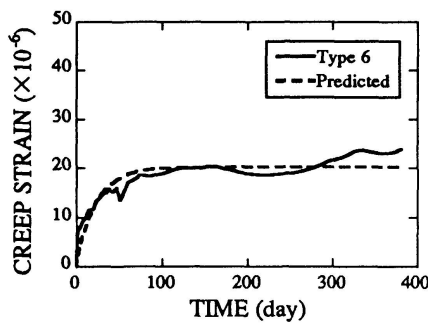


Fig.6 Predicted Time-dependent Behavior of Cables (Method 1)

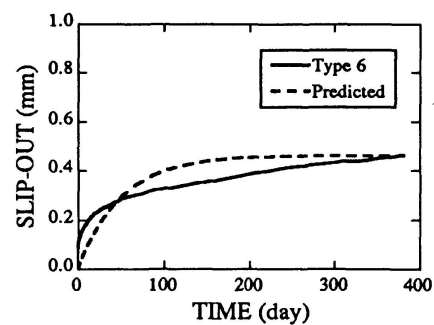


Fig.7 Predicted Time-dependent Behavior of Sockets (Method 1)

Table 2 Evaluated Visco-elastic Constants (Method 1)

Specimen	Cable				Socket			
	$1/\lambda$ (day)	$E_1$ (GPa)	$E_2$ (GPa)	$\eta$ (year GPa)	$1/\lambda$ (day)	$K_1$ (MN/m)	$K_2$ (MN/m)	$\eta$ (year MN/m)
Type 1	2.97	217	6272	51.0	80.0	381	704	154
Type 2	0.26	196	30184	21.5	113.6	543	948	295
Type 3	1.168	202	19306	61.8	0.153	210	4192	1.76
Type 4	1.043	201	20690	59.1	1.188	228	2454	7.99
Type 5	25.5	191	20482	1428.4	75.0	785	769	158
Type 6	23.0	198	24304	1533.1	50.3	582	769	106

### 3.2.2 Method 2

The prediction of the time dependent behavior of bridges during their construction stages requires more accurate values for the initial steep part of the time variation curves. Thus, in the second method, the equations used in Method 1 were applied to a relatively short time interval corresponding to the average interval of time between the prestress of one of the cables and the prestress of the cable of the succeeding stage. This method converges for the initial part of the time variation curves and leads to reliable values for the initial 40 days. Fig.8 shows one of the curves evaluated by this method with the respective experimental curve. Table 3 presents the visco-elastic constants evaluated for specimen types 1,2,5 and 6.

Table 3 Evaluated Visco-elastic Constants for Sockets (Method 2)

Specimen	$1/\lambda$ (day)	$K_1$ (MN/m)	$K_2$ (MN/m)	$\eta$ (year MN/m)
Type 1	0.921	381	1491	3.76
Type 2	1.043	543	2154	6.16
Type 5	2.48	785	2030	13.8
Type 6	1.319	582	1910	6.90

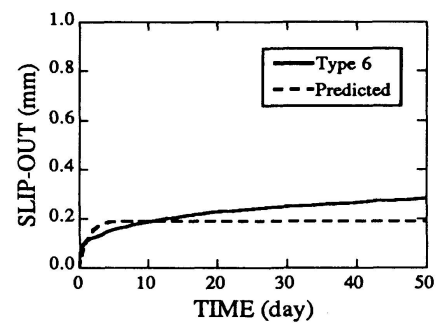


Fig.8 Predicted Time-dependent Behavior of Sockets (Method 2)

### 3.2.3 Method 3

For the maintenance of the bridge during its service life, a long-term prediction is necessary and the strain variation for the time period succeeding the one considered in Method 2, shall be assumed as it follows.

$$\varepsilon_v = \bar{\varepsilon}_v (1 - \alpha e^{-\lambda t}), \text{ where } \lambda = E_2 / \eta \quad (6)$$

Considering  $\bar{\varepsilon}_v$  as a determined parameter,  $\alpha$  and  $\lambda$  can be determined by the least square method. Fig.9 illustrates the results of the analysis for one of the specimens and Table 4 shows the evaluated visco-elastic constants for specimen types 1, 2, 5 and 6.

Table 4 Evaluated Visco-elastic Constants for Sockets (Method 3)

Specimen	$\alpha$	$1/\lambda$ (day)	$K_1$ (MN/m)	$K_2$ (MN/m)	$\eta$ (year MN/m)
Type 1	0.450	351	344	684	658
Type 2	0.541	413	491	866	980
Type 5	0.748	607	505	479	797
Type 6	0.588	178	406	731	356

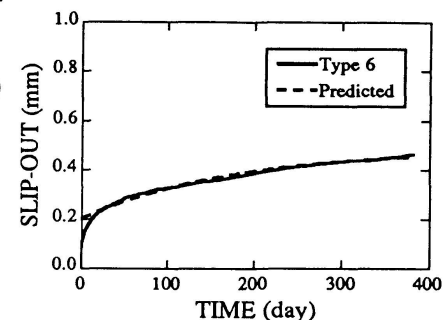


Fig.9 Predicted Time-dependent Behavior of Sockets (Method 3)



#### 4. PREDICTION OF TIME-DEPENDENT BEHAVIOR OF A CABLE-STAYED BRIDGE

##### 4.1 Finite Element Formulation

The equilibrium equations for the cable, tower and girder elements after applying Laplace transform leads to a linear system of equations, whose stiffness matrices  $K_{ij}$  are as presented bellow.

$$\bar{K}_{ij}(s) = \sum_{i=1}^m \sum_{j=1}^n \int_V B_{im} \bar{E}_{mn}(s) B_{nj} dV \quad (7)$$

where  $B_{im}$  and  $B_{nj}$  are strain matrices and  $E_{mn}(s)$  is the elastic modulus corresponding to the Laplace space:

$$\bar{E}_{mn}(s) = \frac{s + \frac{E_2}{\eta}}{s + \frac{E_1 + E_2}{\eta}} E_1 \quad \text{for visco-elastic elements} \quad (8-a)$$

$$\bar{E}_{mn}(s) = E_1 \quad \text{for elastic elements} \quad (8-b)$$

The F.E.M. analysis as above described provides solutions in the Laplace space which has to be converted into the real time domain, so as to give the final solution. Therefore, an inverse transformation has to be carried out [2].

In case of cable-stayed bridges, the cables, towers and girders have different visco-elastic constants and therefore, different intervals of convergence, which makes it difficult to perform a numeric inverse transform considering, simultaneously, all the structural elements visco-elastic. Thus, the bridge analysis was carried out considering each element, separately, visco-elastic (case 1,..., case n) and the final solution was assumed to be a linear combination of all the n cases [3]. The contribution factor for each of the terms of the linear combination is determined by means of the least square scheme in the Laplace image space and the use of the Regula-Falsi method.

##### 4.2 Model Bridge

The model bridge, as presented in Fig.10, is a cable-stayed bridge with a central span of 238.0m and the side spans supported by a PC rigid frame bridge. The structural analysis was carried out for half the bridge, considering its structural symmetry and the cables actually used in this bridge were of type 4 and type 6.

Thus, the following cases were considered for the analysis:

- case 1: only the cables are linearly visco-elastic;
- case 2: only the concrete members of the PC rigid frame bridge are linearly visco-elastic, and
- case 3: final solution assumed as a linear combination of the former cases.

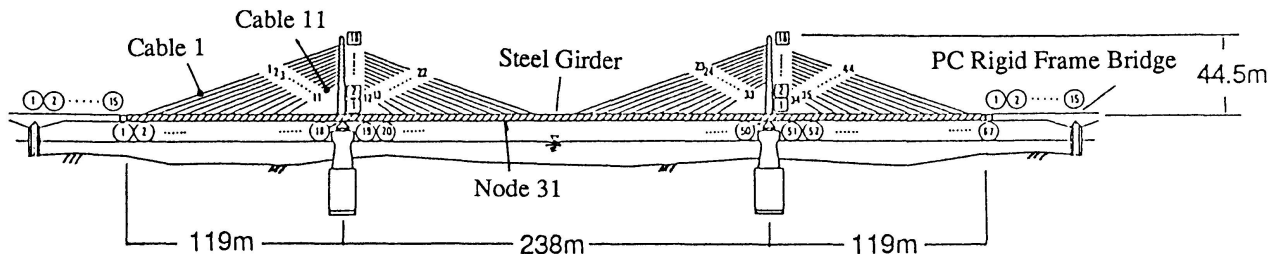
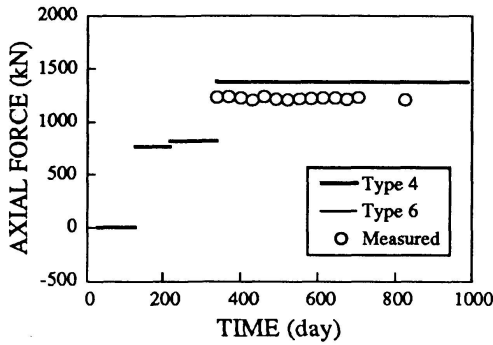


Fig.10 Model Bridge

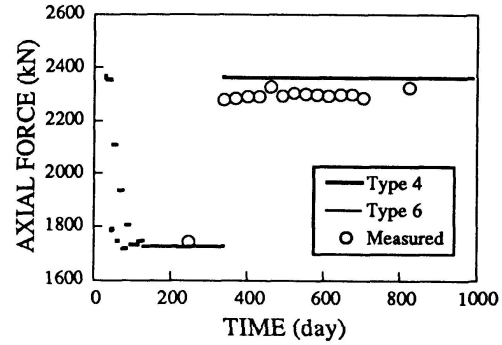
##### 4.3 Analytical Results

The structural analysis was performed using the experimental values of the specimen types 4 and 6, which, although having the same cable material, had different types of sockets. Fig.11 presents the time variation of the axial force in cable No.1 (one of the longest cable) and Fig.12, the time variation

of the axial force in cable No.11 (one of the shortest cables). The forces stabilized in a short time, presenting similar values for both types of cables.

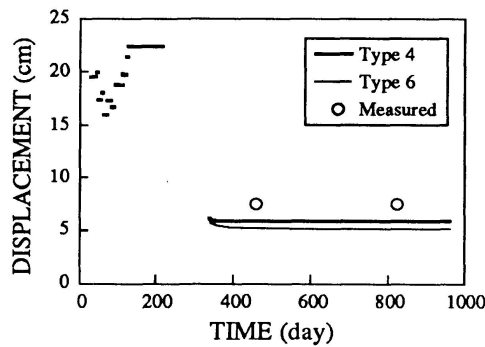


**Fig.11** Variation of the Cable Force  
Cable No.1 (Types 4 and 6)

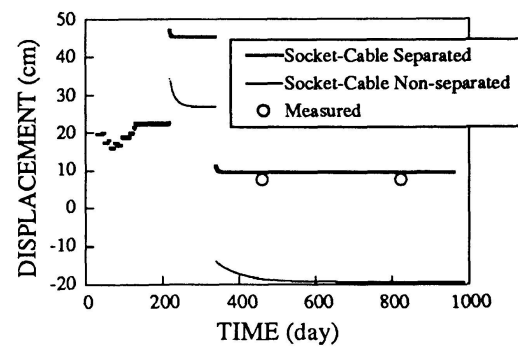


**Fig.12** Variation of the Cable Force  
Cable No.11 (Types 4 and 6)

On the other hand, as it can be noticed in Fig.13, the time-dependent behavior of the nodal displacements were more remarkable in type 6, whose socket is of a more sensitive type. The effectiveness of considering the cables and sockets separately in the evaluation of the visco-elastic parameters is shown in Fig. 14, where the curves for the case in which cable and sockets are considered separately provides values closer to that of the data measured in situ.

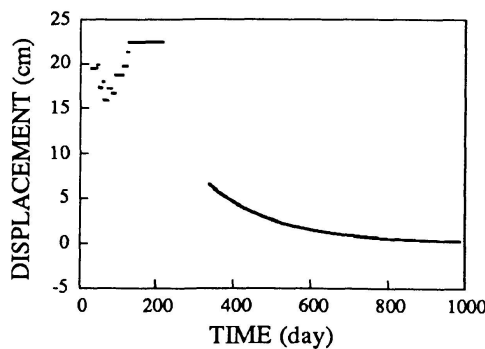


**Fig.13** Displacement of Node No.31  
(Types 4 and 6)

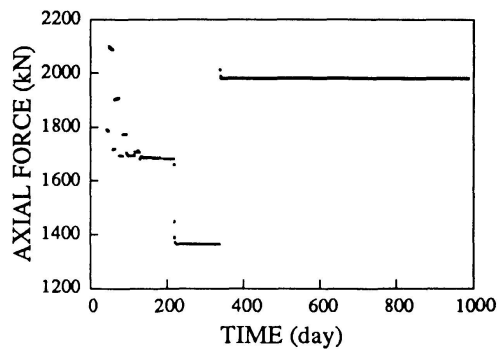


**Fig.14** Displacement of Node No.31  
Comparison between (i) Socket-Cable  
Separated and (ii) Not Separated

A simulation was also performed using a fictitious type of cable, assuming elastic constants similar to that of type 1 ( $E_1=200\text{GPa}$ ,  $E_2=4000\text{GPa}$ ) and the delay-time ( $T=\eta/E_2$ ) of 50 days, which correspond to the values of locked coiled rope [1]. Fig.15 illustrates the time-dependent behavior of the nodal displacement when using the fictitious cable.

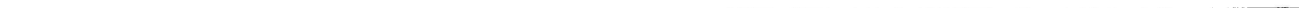


**Fig.15** Displacement of Node No.31  
(Fictitious Cable)



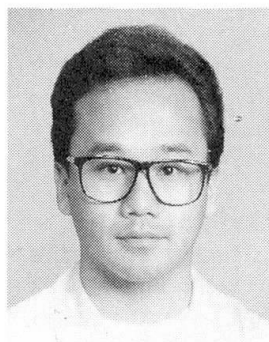
**Fig.16** Variation of the Cable Force  
Cable No.11 (Fictitious Cable)





**Spatial Behaviour of Plate Girder Bridges under Redecking**  
**Comportement spatial des ponts à poutres à âme pleine lors**  
**de la rénovation de la chaussée**  
**Räumliche Wirkung von Plattenbalken-Brücken bei Fahrbahnerneuerung**

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#### **SUMMARY**

Spatial behaviour of plate girder bridges under redecking is studied experimentally and theoretically. A series of static loading tests were conducted under several loading and structural conditions which may occur when the bridge is partially open to traffic during redecking. A finite element method was developed in order to analyze the spatial behaviour of plate girder bridges and the results of analysis are compared with the test results. Both the displacements and the stresses obtained from these analyses show good agreement with those of tests. Validity and efficiency of the theoretical method are shown.

#### **RÉSUMÉ**

L'article présente l'étude du comportement théorique et expérimental des ponts à poutres à âme pleine, lorsque l'on maintient la circulation sur une partie de la chaussée au cours de sa rénovation. A cet effet, ont été élaborés aussi bien une série d'essais statiques pour différents états de charge et conditions structurales, qu'une analyse méthodique spatiale au moyen de la méthode des éléments finis. La comparaison des résultats de calculs avec ceux des mesures fait apparaître une très bonne concordance tant des déplacements que des contraintes. Enfin, l'auteur montre la validité et l'efficacité de cette méthode de calcul.

#### **ZUSAMMENFASSUNG**

Theoretisch und experimentell wurde die räumliche Wirkung von Plattenbalken-Brücken studiert, wenn infolge Fahrbahnerneuerung nur Teile für den Verkehr geöffnet sind. Zu diesem Zweck wurde eine Serie statischer Belastungstests für mehrere Last- und Tragwerkszustände sowie eine Methodik zur räumlichen Analyse mittels Finite-Elementen entwickelt. Beim Vergleich der Rechen- mit den Messergebnissen zeigt sich eine gute Übereinstimmung in den Verschiebungen und Spannungen. Validität und Effizienz des Berechnungsverfahrens werden aufgezeigt.



## 1. INTRODUCTION

In recent years, many reinforced concrete (RC) floor slabs of highway bridges have been deteriorated or damaged and require rehabilitation, repair and replacement. This is caused by the increase in traffic volume and the illegal passing of over-loaded heavy vehicles. Although many studies have been reported in reference to the repairing or strengthening method of damaged RC floor slabs, the redecking method by orthotropic steel deck has become of major interest in the view of the reduction of the dead load and the expected remaining life of bridge lately[1,2]. The authors have been studied the useful method of replacing damaged floor slabs with the prefabricated steel deck of Battledack Floor Type[3] which is easily manufactured[4,5]. The bridge has to be partially open to traffic because a long traffic close of bridges with heavy traffic is usually not allowed in the work of replacing. Therefore, it is important to clarify the spatial behavior as a whole system and local stresses of plate girder bridges during the redecking.

This paper presents the results of statical loading tests for a large scale model and the finite element analysis for plate girder bridges. In the analysis, the RC floor slab is modelled by thin plate elements having six degrees of freedom for one node and the main girder by equivalent substituted truss system. The supporting cross beam and the cross frame are modelled by beam-column elements. Since the shear connector transfers the load primarily by shear, it is assumed that their flexural and torsional stiffness can be neglected. Validity and efficiency of the theoretical method are examined by comparing with the experimental results. Many useful information for redecking design are obtained from the results of tests and analyses.

## 2. SUMMARY OF LOADING TEST

### 2.1 Test model

Although the test model is designed to simulate the replacement of a damaged RC floor slab with the steel deck, a bridge model with the steel deck in place of the RC floor slab is used here. This is due to the practical reason that the thin concrete slab in the model may cause the structural unbalance between the floor slab and steel girders and it may be difficult to conduct the casting and removing operations of the RC floor slab in the testing frame.

The bridge model is composed of three main girders, the prefabricated steel deck, supporting cross beams and cross frames. The steel deck used is the Battledack Floor Type with welded longitudinal ribs as shown Fig.1 and is connected by high strength bolts to the main girders. In order to simulate the behavior of the actual bridge under redecking, the steel deck is divided into two panels along the length. The supporting cross beam is corresponding to the transverse rib of the orthotropic steel deck and is fastened by high strength bolts to main girders.

### 2.2 Test procedure

The objectives of the experimental programme are to investigate the spatial structural behavior of the girder bridges as a whole system and the local stress during the redecking. The statical load is applied at the centre of the span through 300mm x 120mm hard rubber plates which are placed on the steel deck. The loading conditions and the applied load are summarized in Table 1. The test procedure corresponding to the actual replacement of the RC floor slab with the steel deck is selected and consists of a total of seven steps as shown in Table 2. The models of STEP 1 & 2 are composed of three main girders and

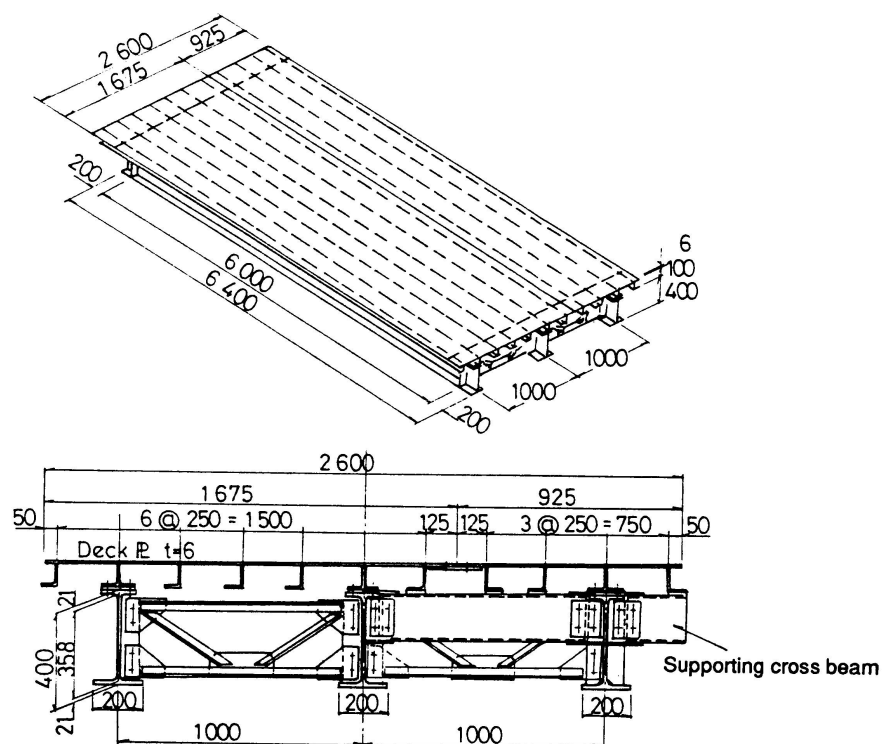


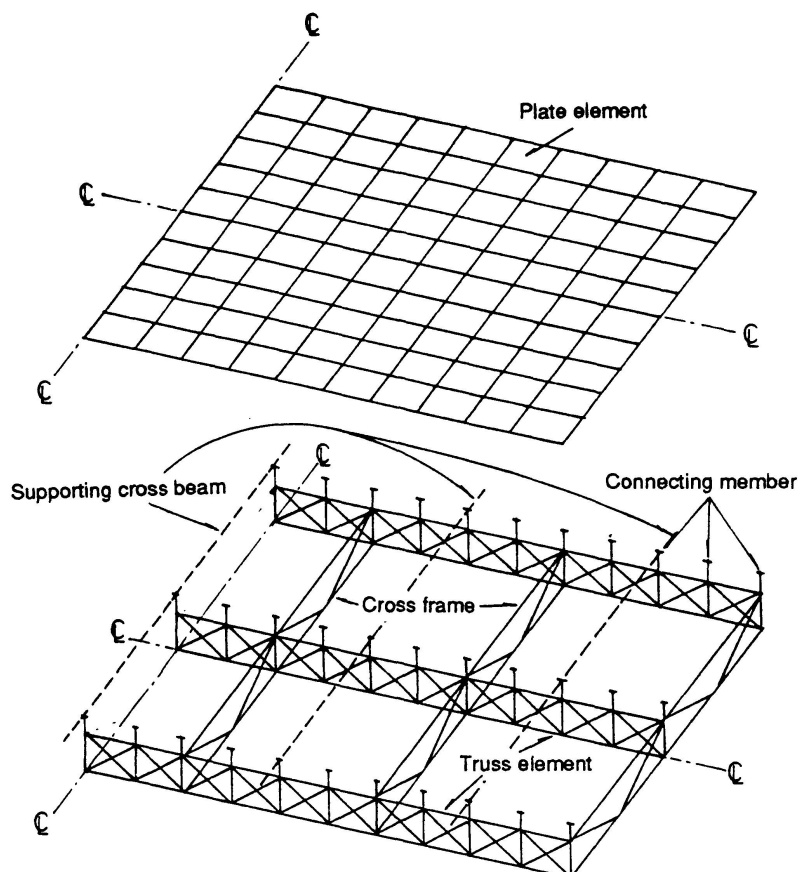
Fig. 1 General layout of the bridge model

Table 2 Test procedure

Table 1 Loading cases

	Max. Load (kN)	Loading Conditions
CASE I	150	
CASE II	70	
CASE III	100	
CASE IV	150	
CASE V	70	

	Loading Conditions
STEP 1	CASE I } CASE III
STEP 2	CASE I } CASE III
STEP 3	CASE I } CASE V
STEP 4	CASE I } CASE V
STEP 5	CASE I } CASE V
STEP 6	CASE I } CASE V
STEP 7	CASE I } CASE V



**Fig. 2** Theoretical model

cross frames without the steel deck, and for the model of STEP 2 supporting cross beams are installed in addition to cross frames. Measurements of strains in the main girders, steel deck and supporting cross beams were made by using strain gages. The deflection of the steel girders and the shear slip between the deck plate and the main girder were measured using electrical and cantilever type displacement meters, respectively.

### 3. SUMMARY OF ANALYSIS

#### 3.1 Theoretical model

The theoretical model used for the analysis of the plate girder bridge which composed of steel deck, main girders, supporting cross beams and cross frames is shown in Fig. 2. The steel deck is modelled by triangular thin plate elements having six degrees of freedom for one node. The stiffness matrix of the plate element is derived with the consideration for in-plane flexural stiffness[6]. The supporting cross beam is modelled by thin-walled beam-column elements[7] and the cross frame by truss elements. The main girder is modelled by an equivalent truss system which can store the same amount of strain energy with that stored in the plate girder. With reference to Fig. 3, the cross sectional areas of the substituted truss members are given by the following equations[8]:

$$\text{Upper chord member: } Acc = \frac{I}{(hc+ht)hc}$$

$$\text{Lower chord member: } Act = \frac{I}{(hc+ht)ht}$$

$$\begin{aligned} \text{Vertical member: } A_v &= \frac{6AwG}{\mu E \tan \theta} \\ \text{Diagonal member: } A_d &= \frac{3AwG}{2\mu E \sin \theta \cos^2 \theta} \end{aligned}$$

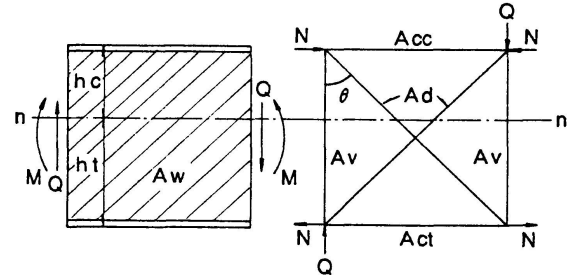


Fig. 3 Substituted truss

where  $I$  is the moment inertia of the girder cross section about the neutral axis,  $h_t$  and  $h_c$  are the distances from the neutral axis to each outermost fiber, respectively,  $E$  and  $G$  are the Young's modulus and the shear modulus,  $\mu$  is the shape factor and  $A_w$  is the cross sectional area of the web plate. Though the steel deck is connected by high strength bolts to main girders, the shear connector is modelled by cantilever elements which permits only the horizontal shear at the free end of element.

### 3.2 Computation method

The computation was carried out for the half of the girder bridge considering the symmetrical condition at the midspan. The deck plate is divided into 10 elements both along the length and the width of the deck. In the modeling, the cross sectional shape of the theoretical model is used the rectangular determined according to the condition that the flexural stiffness of the deck plate section equals those of experimental model. The bridge, part of which steel deck is removed, is modelled in the same way, but the thickness of deck plates supposed to be removed is assumed to be negligibly small (0.001cm) in the analysis.

## 4. RESULTS AND DISCUSSIONS

### 4.1 Load distribution effect of cross frames and supporting cross beams

The load distribution effects of cross frames and supporting cross beams are examined at the test steps 1 & 2 (without the steel deck) for the loading CASE I ~ III.

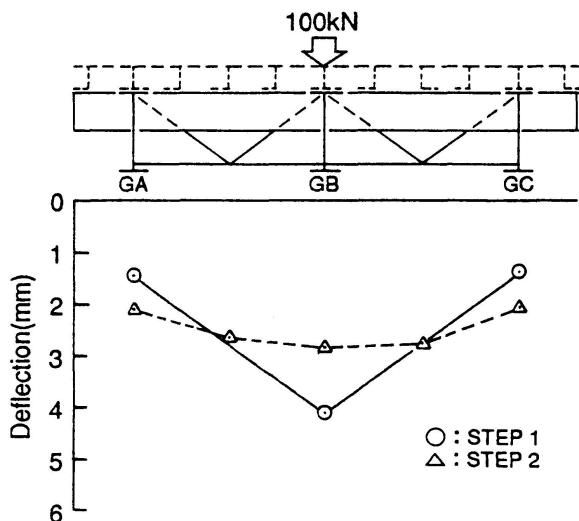


Fig. 4 Deflection of main girders at midspan

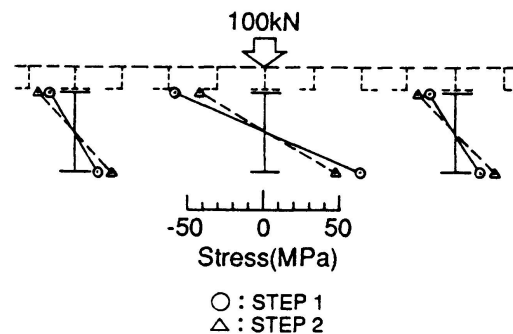


Fig. 5 Stress distribution of main girders at midspan

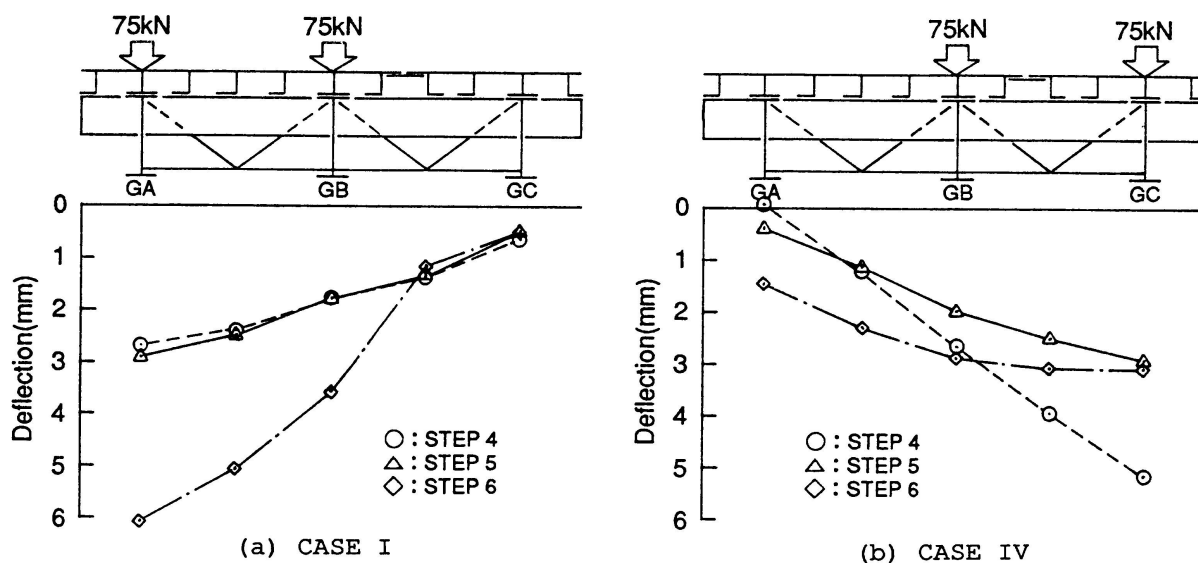


Fig. 6 Deflection at midspan for each STEP

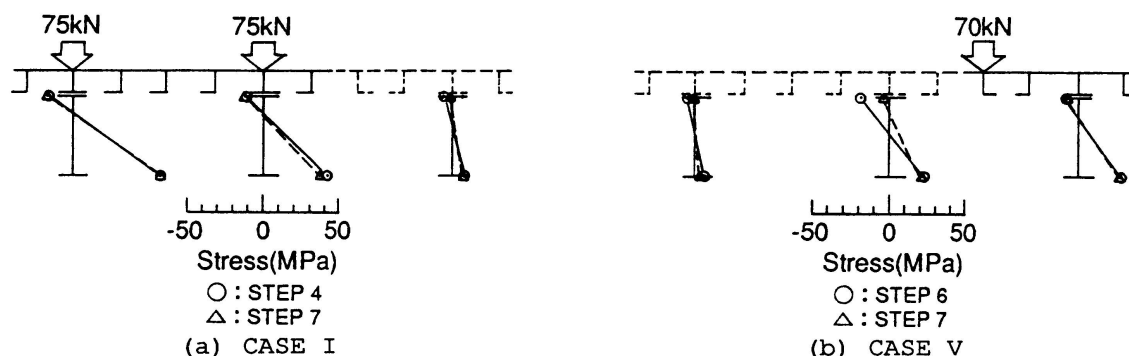


Fig. 7 Distribution of normal stresses at midspan

Figs. 4 and 5 show the deflection at midspan and the distribution of normal stresses on the girder under concentrated load at the midspan, respectively. It can be seen that 40% of the applied load is distributed to the exterior girders by using cross frames (STEP 1) and for the model of STEP 2 by using supporting cross beams in conjunction with cross frames 50 ~ 60% of the applied load is distributed to the exterior girders. From these test results, we can recognize that the use of supporting cross beams in the prefabricated steel deck system can give large effects of the load distribution.

#### 4.2 Behavior during redecking

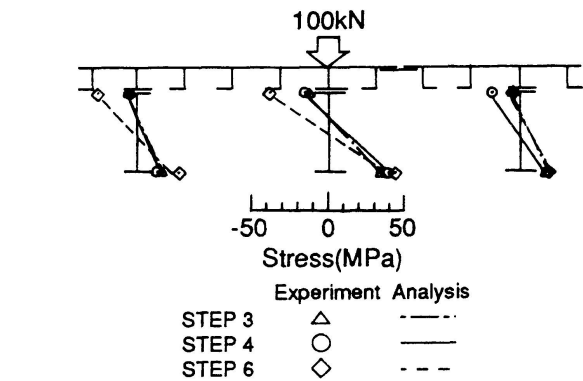
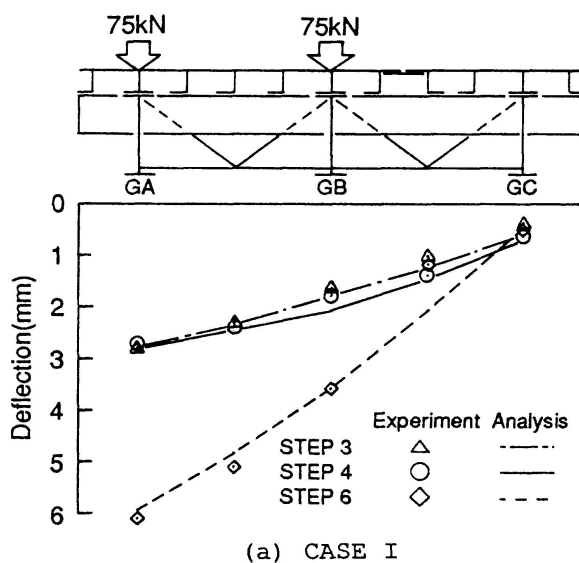
The deflection at midspan subjected to a lateral load at the midspan for STEP 4~6 are shown in Fig. 6. It may be found that the deflection for STEP 4 in CASE IV and STEP 6 in CASE I are larger than those of the other loading cases. This is due to the reason that the loads are directly applied to the main girders where part of the deck plate is removed. Fig. 7 shows the distribution of normal stresses on main girders at midspan for STEP 4,7 in CASE I and STEP 6, 7 in CASE V. By comparing the stress in the low flange of main girders with (STEP 7) and without (STEP 6) the deck plate, we notice that the stress of main girder without a part of deck plate is relatively small and is nearly equal to those of a complete system (STEP 7). The reason of this is that the moment inertia of the composite section is 2 ~ 3 times larger than that of a main girder and this section is mainly in charge of the applied load. From test results, it can be noticed that the supporting cross beams play satisfactory

**Table 3** Comparison of test and analysis for each slip modulus  $k$

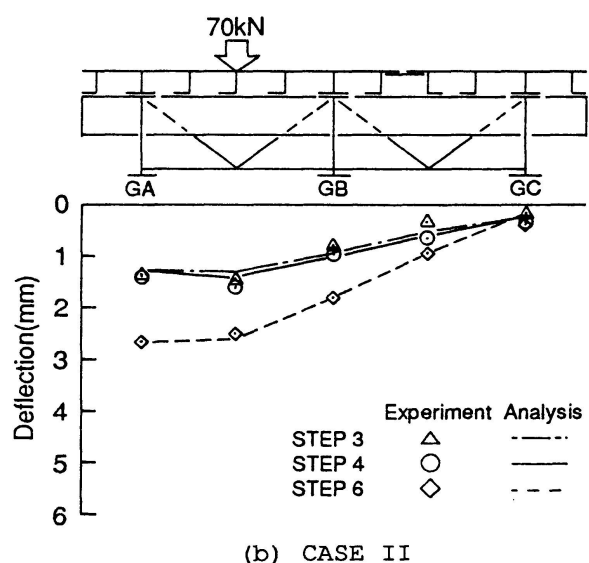
(a) Deflection Unit:mm						
	GA		GB		GC	
Experiment	0.90	1.32	1.42	1.31	0.94	
Analysis	$k=9.8$	0.86	1.16	1.31	1.16	0.86
	98	1.16	1.31	1.48	1.31	1.16

(b) Stress Unit:MPa						
	GA		GB		GC	
	Comp	Tens	Comp	Tens	Comp	Tens
Experiment	5.2	16.5	12.2	34.4	4.8	15.8
Analysis	$k=9.8$	3.8	16.0	9.2	34.1	3.8
	98	6.0	17.0	16.6	34.8	6.0



**Fig. 9** Stress distribution at midspan



**Fig. 8** Comparison of deflection at midspan between theory and experiment

role for the load distribution in transverse direction together with for the outer girder without the deck.

#### 4.3 Comparison of tests and theory

To determine the slip modulus  $k$  of the shear connector prior to model analysis, the complete models (STEP 3) subjected to a lateral load at midspan were analyzed for two  $k$  values,  $k=9.8$  and  $98$  (N/m/m), based on the previous studies [4,5]. The comparisons of tests and the theory for deflection and stress of main girders are given in Table 3. The slip modulus  $k=9.8$  (N/m/m) was adopted in this analysis because it tends to give overestimated conservative results in comparison with test results. The deflection at the midspan for STEP 3~6 in CASE I and II are shown in Fig. 8. Though the small differences between the theoretical and experimental results for STEP 6 in CASE I is observed, it can be noticed that the good agreement exists between the two sets of results. Fig. 9 shows the normal stress distributions on three main girders at the midspan for CASE III. The theoretical results correspond to the experimental results quite well. In spite of small differences for some loading cases, it can be seen that the results of the present analysis have fairly good correspondence with the test results as a whole. The validity of the present





method can be recognized. This numerical method will be utilized to investigate the spatial behavior of existing plate girder bridges under redecking.

## 5. CONCLUSIONS

Spatial behavior of plate girder bridges under redecking is studied experimentally and theoretically. From this study the following conclusions can be drawn.

- 1) The redecking procedure of actual bridges with deteriorated RC slabs is simulated well by the experiment.
- 2) It is recognized that the use of supporting cross beams in the prefabricated steel deck system can give large effects of the load distribution.
- 3) In spite of small differences for some loading cases, it can be seen that the results of the present analysis show good agreement with the test results as a whole. The validity of the present method can be recognized.
- 4) The present method will be utilized to investigate the spatial behavior of existing plate girder bridges under redecking.

The writers express his thanks to Mr. K. Ishii, Kajima Ltd., the former graduate student of Kumamoto University, for his valuable assistance in numerical computations.

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**Method for Evaluating the Load Carrying Capacity of Existing Bridges**  
**Méthode d'évaluation de la capacité portante des ponts**  
**Eine Methode zur Tragfähigkeitsbewertung bestehender Brücken**

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#### **SUMMARY**

On the basis of inspection, testing and analysis for a number of existing bridges, the factors which have influence on the load carrying capacity of existing reinforced concrete bridges are identified and a finite element model for evaluating the load capacity is developed. A simulation method for the evaluation is proposed, by which the load testing of bridges can be simulated by means of computers and the characteristics of the load carrying capacity of existing bridges can be calculated.

#### **RÉSUMÉ**

Sur la base d'inspections, d'essais et d'analyses d'un grand nombre de ponts, les facteurs qui influencent la capacité portante des ponts en béton armé ont été identifiés et un modèle par éléments finis a été développé. Une méthode de simulation pour l'évaluation est présentée, par laquelle l'essai de charge du pont peut être simulé au moyen de l'ordinateur; les caractéristiques de la capacité portante des ponts peuvent être ainsi également calculées.

#### **ZUSAMMENFASSUNG**

Auf Grund der Untersuchungen, Proben und Analysen von zahlreichen bestehenden Brücken werden die Hauptfaktoren, die Einfluss auf die Tragfähigkeiten von bestehenden Stahlbetonbrücken ausüben, festgestellt und ein Finite-Elemente-Modell für die Tragfähigkeitsbewertung entwickelt. Mittels dieser Methode kann die Belastungsprobe der Brücken mit Hilfe von Computern simuliert und dadurch können die Kennziffern der Tragfähigkeit von Brücken berechnet werden.



## 1. INTRODUCTION

With the development of transportation, the load carrying Capacity of a number of existing bridges are found to be insufficient due to progressing deterioration and increased loads. There are nearly 136,000 highway bridges in China, About 5,000 of these are judged to be functionally obsolete or inadequate for current requirements, the service age of these bridges are ranged from 30—years to 40—years. In addition, some of bridges constructed over the last 20 years are considered to be structurally deficient because of deterioration or distress[1][2].

While replacing all the deficient bridges mentioned above with new bridges is often extremely difficult and expensive, a moderate increase of structural capacity through rehabilitation and repair is fairly cheap and easy to obtain. To avoid high costs of rehabilitation and repair, the evaluation of the bridges must accurately reveal the present load carrying capacity and any further changes in the capacity in the applicable time span. In recent years, many method for evaluating the load carrying capacity of existing bridges have been developed. these method can be roughly divided into three kind: Knowledge—based method; computational method; and load testing method. The knowledge—based method has the advantage of assessing the damage state of the bridges, but can not give exact index about the load carrying capacity. Most computational methods are similar to design methods, the hypothesis on which design methods based are not quite the same as practical behavior of existing bridges, and computational results may be doubtful. load testing on bridges can directly examine the load capacity and the results are more reliable than other methods. However, it would be very expensive to test all the deficient bridges. In order to explore the load carrying capacity of existing bridges, it is necessary to develop an inexpensive evaluation method which can fully take into account the real behavior of existing bridges and give reliable results about the load capacity.

The objective of this paper is to identify the factors which affect the load carrying capacity of the bridges and develop a simulation method for the evaluation. Using the method, the load testing of the bridges can be simulated by means pf computers and the index about the load carrying capacity can be caculated. An example of evaluating a T-beam bridge is also presented.

## 2. FACTORS AFFECTING THE LOAD CAPACITY OF R. C. BRIDGES

Over the years of servicing, various forms of deterioration would appear on beams, piers and bases of bridges and all affect the load carrying capacity. So the load carrying capacity include the capacity of upper structure which composed of beams and deck and that of lower structure constituted by piers and bases. Only the upper structural capacity is studied in this paper.

In order to assesss the damage state of old bridges and identify the factors which affect the load carrying capacity of the bridges, a thorough field survey of old R. C. bridges located in Guangdong province in China was made and static and dynamic load tests were performed on some of these bridges[3]. Inspection and testing show that the deterioration emerged on beams and deck are main factors which influence the load carrying capacity. The deficiencies on the attachment such as discharge orifices and expansion joints results in the damages on beams and deck, then have indirect influence on load capacity. Various types of deterioration -efflorescence, leakage, cracking and spalling-can contribute to the reduction of bridge's load capacity to different degree. Ignoring the deficiencies which have little influence on the load capacity and only beams and deck are considered, main factors affecting the R. C. bridge's load capacity can be identified as shown in Fig. 1.

Among the factors, cracking of concrete is very important to estimate the load capacity. The density, width, length and pattern of cracks are significant indexes for the estimation. The factors given in Fig. 1 must be take fully into account in the computational model for evaluation of R. C. bridge' s load carrying capacity.

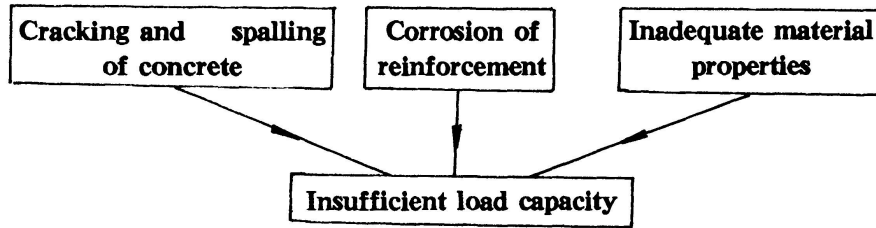


Fig. 1 Main factors affecting load capacity

### 3. COMPUTATIONAL MODEL FOR R. C. BRIDGE' S LOAD CAPACITY

#### 3.1 Mathematical Model

Theoretically, for a given loadings and structure type, a bridge' s load carrying capacity can be determined in terms of the parameters such as load components, dimensions, strength of materials, etc. The evaluation philosophy of an existing bridge must differ from the design philosophy of a new bridge. In this study, the load carrying capacity index,  $R$ , is defined as follows:

$$R = g[s(t), f(t), x(t), \varphi(t)] \quad (1)$$

where  $S(t)$  represents load effect;  $f(t)$  represent strength of materials;  $x(t)$  represent dimensions;  $\varphi(t)$  is structural integrity and is equal to  $(1 - d)$ , in which  $d$  is damage. All of these parameters are functions of service time  $t$ . Assuming that,  $R$  is differentiable continuous function of all the parameters, the change of load capacity,  $\Delta R$ , can be derived from Eq. (1) as:

$$\Delta R = (\partial g / \partial s) \Delta s + (\partial g / \partial f) \Delta f + (\partial g / \partial x) \Delta x + (\partial g / \partial \varphi) \Delta \varphi \quad (2)$$

in which  $\Delta s$ ,  $\Delta f$ ,  $\Delta x$  and  $\Delta \varphi$  denote the changes of load effect, strength of materials, dimensions and structural integrity, respectively. Over the years of performance, the actual load carrying capacity,  $R_t$ , at the time of evaluating,  $t$ , is written as:

$$R_t = R - \Delta R \quad (3)$$

The resistance coefficient,  $k$ , can be defined as:

$$K = (R_t - G) / S \quad (4)$$

where  $G$  represents dead load effect;  $S$  represent the effect of the live loads used for evaluation.

#### 3.2 Finite Element Model

To reveal the real load carrying capacity of bridges, a rational computational model must be established. Actual behavior and the factors affecting the load capacity must be fully considered in the model. The finite element method is appropriate for dealing with non — homogeneous materials, nonlinear constitutive relationships and complicated boundary conditions. It is easy to dispose



deterioration or distress which contributes to reduction of the load capacity by using the finite element method. Thus a finite element model can be developed to calculate the load carrying capacity index,  $R$ . The major factors in Fig. 1 can be taken into account in the finite element model and constitutive relationships (Fig. 2)

Fig. 3(a) shows a damaged simply supported T-beam, which has four cracks located at A, B, C, and D, respectively. Spalling occurs at location E, and result in corrosion of parts of reinforcing bars. Meanwhile, expansion bearing lose its efficacy. Finite element model of the beam is illustrated in Fig. 3. (b). Details of the model will be described in the following.

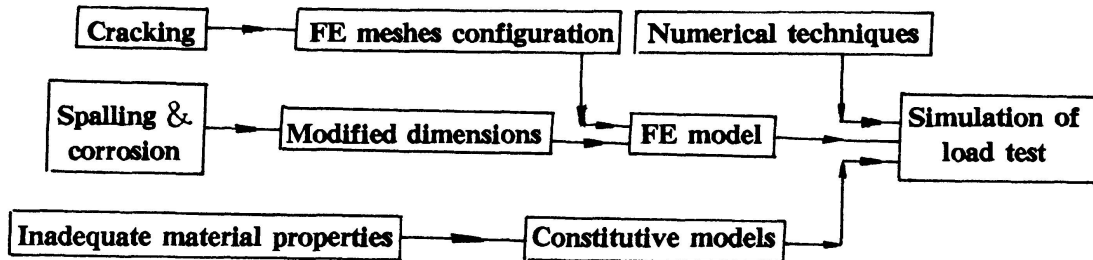
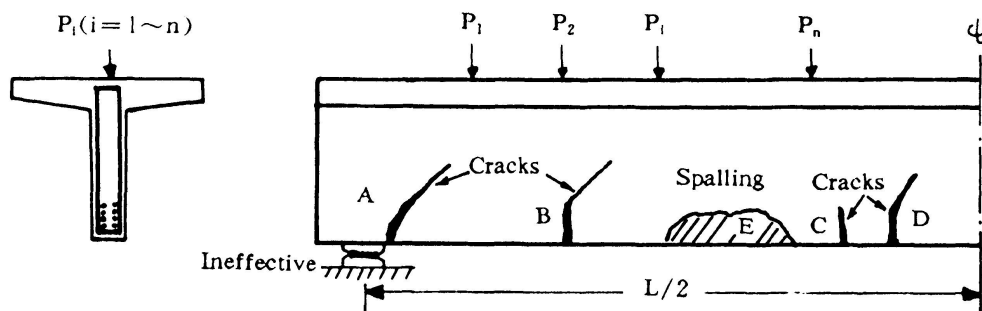
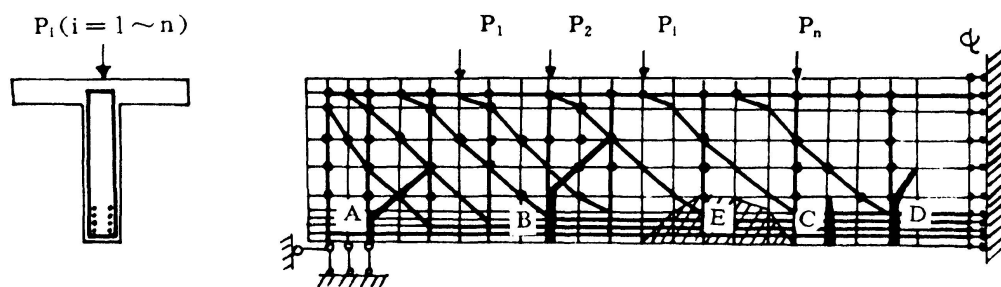


Fig. 2 Management of the factors affecting load capacity



(a) Deteriorated beam



(b) Finite Element Idealization

Fig. 3 Finite element model of deteriorated beam

### 3. 2. 1 Concrete

The assumption of the plane stress is considered to be reasonable for T-beam subject to loadings in—web plane. Reduction of concrete section due to spalling is taken into account by the modified element

thickness,  $T_c$ , defined as;

$$T_c = K_c T \quad (5)$$

where  $K_c$  is modification coefficient,  $T$  is original thickness.

Existing cracks are modelled with two techniques; Discrete model and smeared crack model. The discrete model approaches a single fully separative crack by disconnecting nodal points (Fig. 4(a)). Interlock elements are placed across the incompletely separative cracks to simulate aggregate interlock (Fig. 4(b))

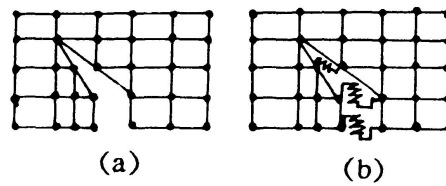


Fig. 4 Discrete crack model

The smeared crack model represent overall influence of many discrete cracks existing in the domain of the element. the constitutive equation is expressed by [8];

$$\begin{bmatrix} d\sigma_1 \\ d\sigma_2 \\ d\sigma_3 \end{bmatrix} = \begin{bmatrix} E_1 & 0 & 0 \\ 0 & E_2 & 0 \\ 0 & 0 & G_{cr} \end{bmatrix} \begin{bmatrix} de_1 \\ de_2 \\ d\gamma_{12} \end{bmatrix} \quad (6)$$

where  $G_{cr}$  is reduced shear modulus which reflects the density, width and degree of separation of the cracks.

### 3. 2. 2 Steel reinforcement

Main reinforcing bars are represented by axial force elements with two translational degrees of freedom defined at each node. Corrosion of rebars is considered by reduction of the cross sectional area of the bars. Secondary reinforcement, such as stirrups is assumed to be distributed over concrete elements and forms composite concrete — steel element. The material stiffness of the element is defined as follows [8];

$$[D] = [D^c] + \sum_{i=1}^n [D_i^s] \quad (7)$$

where  $[D^c]$  and  $[D_i^s]$  are the concrete and reinforcement material stiffness matrices, respectively.

### 3. 2. 3 Bond between steel reinforcement and concrete

If the influence of bond slip is considered, linkage elements must be set up to model bond behavior, so the number of nodal points will increase greatly. For the sake of utilizing memory capacity of computer



effectively, reinforcement may be assumed to be connected directly to the concrete at the nodal points.

#### 4. CONSTITUTIVE RELATIONS FOR THE CONSTITUENT MATERIALS

Material properties have a significant influence on the load capacity. Actual material parameters must be used in constitutive relations. Biaxial nonlinear constitutive relations and failure theories should be applied to explore the realistic load capacity of existing bridges.

The concrete constitutive model and failure criteria of Balakrishnan & Murray[5] are introduced in this study. The model divides the uniaxial response curve for concrete into five damage regions described as linear elastic; compressive strain hardening; compressive strain softening; tensile strain softening; and tensile stiffening regions. When used under biaxial stress conditions, the model is considered orthotropic after cracking. The effect of biaxial stress conditions on peak strength is represented by a variation of the Kupfer—Hilsdorf failure curve in stress space in which the compressive and tensile envelopes are separately specified[4][5]. In the tension—compression region, tensile stress less than  $0.5 f_t$  does not reduce compressive strength. If  $\sigma_1 > 0.5 f_t$ , the ultimate strength may be described as;

$$f_{tu} = 2f_c / (1/2 + 2f_c/f_t) \quad (8)$$

$$f_{cu} = (-1.5 + f_{tu}/f_t) |f_c| \quad (9)$$

In compression—compression region, the ultimate compressive strength may be written as;

$$f_{cu} = (1 + 3.65)f_c / (1 + \alpha)^2 \quad (10)$$

in which  $\alpha = \sigma_1/\sigma_2$ ,  $\sigma_1$  and  $\sigma_2$  are major and minor principal stresses respectively,  $f_{cu}$  and  $f_{tu}$  are peak compressive and tensile stresses respectively. Details of the model are described in reference[5]. The parameters in the model such as cylinder compressive strength  $f_c$ , elastic modulus  $E$ , should be determined with nondestructive inspection such as sonic pulse velocity measurements. If necessary, cores are taken from bridge for compressive and split test.

Reinforcing steel is assumed to be elastic perfectly plastic material. Actual values of the yield strength  $f_y$  and elastic modulus  $E_s$  are used. The strain—hardening region may be considered, if necessary.

The bond stress—slip relationships of Mirza and Houde is used, expressed as[6]:

$$\tau = (54 \times 10^2 S - 25.7 \times 10^5 S^2 + 5.98 \times 10^8 S^3 - 0.558 \times 10^{11} S^4 \sqrt{f_c/41.5}) \quad (11)$$

in which  $\tau$  is the bond stress in MPa,  $S$  is the slip in cm.

Interlock elements are employed to model the interface shear transfer across the crack by aggregate interlock and friction. The stiffness of the element is derived from Horde & Mirza's shear stress—displacement relation as[6]:

$$K_g = 63.85(1/C)^{3/2} \sqrt{f'_c/35A} \quad (12)$$

in which  $A$  is the area for which one element is responsible, in  $\text{cm}^2$ ;  $f'_c$  in MPa;  $C$  is crack width in cm;  $k_f$  in N/cm.

## 5. EVALUATING PROCEDURE

Based on the mathematical model and the finite element model aforementioned, a finite element program can be developed and implemented into a particular computer code to simulate the load tests of R. C. bridges. For T-beam bridges, each beam of the bridge is evaluated as a single unit. Simulation results of all beams are synthesized and analyzed to give the resistance factor of the whole bridge. The evaluating procedure is described in the following.

### 5.1 Field Survey and Review of Design Documents

A thorough field survey is needed to obtain the information about deterioration of the bridge, including crack location and size, corrosion of reinforcement, actual material properties, and as-built dimensions. The presence and location of reinforcement can be determined through review of design documents. If the design drawings are not available, the reinforcement location may be determined using a pachometer which locate steel magnetically. The parameters needed in the computational model can be defined through field survey and review of design documents.

### 5.2 Determination of Loading pattern and Finite Element Meshes

According to loads for evaluation, the most detrimental loading pattern can be decided. The transverse distribution of loads must be taken into account to determine the detrimental loading pattern applied to each beam evaluated. Generally for simply supported beam, the internal forces such as bending moments and shear forces at beam ends and mid-span control the position of loads. After defining the load pattern, finite element meshes are constructed. Data file are prepared and inputted into computer to start simulation of load test using incremental load procedure described in the next.

### 5.3 Incremental Loading

For the  $i$ th T-beam, the loading factor is defined as  $w_{ij}$  in the  $j$ th loading increment. If failure occurs or the specified indexes, such as deflection and crack width, are reached at  $m$ th loading increment. The resistance coefficient for the beam is defined as:

$$K_i = \sum_{j=1}^m w_{ij} \quad (13)$$

### 5.4 Evaluating the Load Carrying Capacity

If the bridge consist of  $n$  of beams and the resistance coefficient for every beam is caculated, the resistance coefficient of the bridge is given as:

$$K = \varphi_T \cdot \text{Min}(K_1, K_2, \dots, K_n) \quad (14)$$

where  $\varphi_T = 1 - d_T$ ,  $\varphi_T$  and  $d_T$  are integrity and damage of the transverse diaphragms, respectively;  $k_i(i$





$= 1, 2, \dots, n$ ) is the  $i$ th beam's resistance coefficient.

If  $k > 1$ , the load carrying capacity of the bridge is enough to meet the need of present traffic. Otherwise, repairs or rehabilitation must be made to restore or increase the load capacity.

## 6. EXAMPLE OF BRIDGE EVALUATION

Using the computational model given in this paper, a computer program RCBM for simulating the load tests of R. C. bridges is developed. The proposed approach is illustrated by an example. The load capacity is evaluated for one beam of a T-beam bridge which is located in chengdu city in China. The bridge, built in 1961, is a three-span simply supported T-beam bridge. The cross section are composed of 12 T-beams. The span length is 16.3m. The mid-span cross section of one beam is shown in Fig. 5. There are 14 main unnotched rebars which have diameter of 32mm. Concrete design compressive strength is 18.4MPa. A field survey was conducted. Spalling, corrosion of rebars, several inclined and vertical cracks were found. Actual concrete compressive strength is only 8.3MPa. One beam was taken from the bridge for failure test in order to judge whether the load capacity is enough or not. The load pattern is shown in Fig. 6 [7].

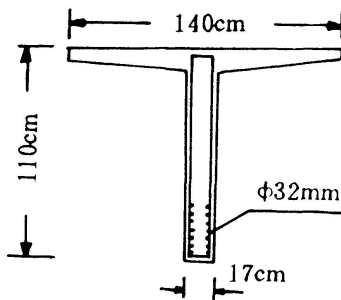


Fig. 5 Mid—span cross section

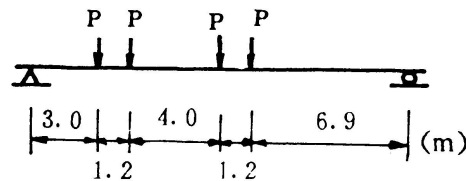


Fig. 6 Loading pattern

The design load  $p$  is 70.5KN, corresponding to the bending moment of 782.6KN—M in mid—span. The program RCBM is employed to simulate the failure test and evaluate the experimental results as shown in Table 1. The load—mid—pan deflection curves of the beam are shown in Fig. 7. It can be seen, from Table 1 and Fig. 7, that the proposed simulation method gives a good approximation to failure test of the T—beam, the evaluation results are available.

Table 1 Comparison of simulation results with test results

	Max. Load(4P) (KN)	Mid—span bending Moment (KN—m)	The resistance coeffcient
Design	282	782.6	
Simulation	540	1497	1.91
Test	600	1665	2.13

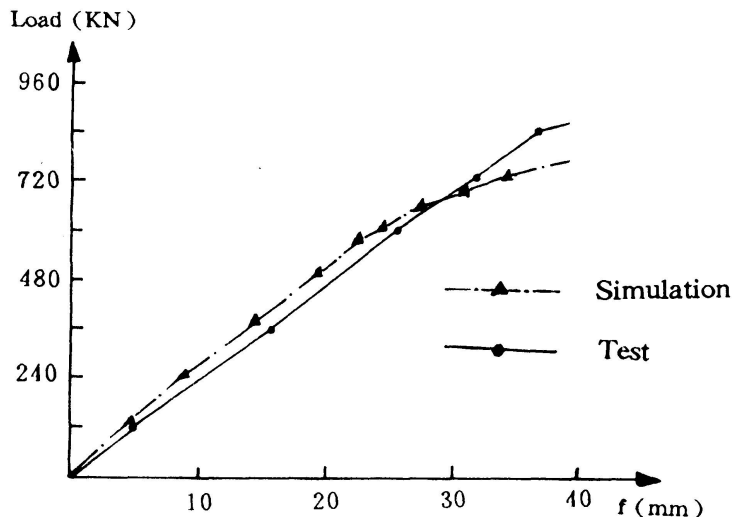


Fig. 7 Load—mid-span deflection curve

## 7. CONCLUSIONS

—An evaluation method for load carrying capacity of existing bridges should distinct from methods in design of new bridges. A finite element model for evaluating the load capacity is developed, in which the factors influencing the load capacity are taken into account. Nonlinear constitutive relationships and failure criteria under biaxial stresses are employed to explore the realistic load carrying capacity.

—A simulation method is proposed to estimated the load capacity of existing bridges. Using the method, load tests can be simulated in order to given reliable resistance coefficient of the bridge. The method is effective and inexpensive, since it may replace many load tests. Although the present approach is developed for R. C. bridges, it can be used in the evaluation of various types of bridges, such as steel bridges and composite bridges.

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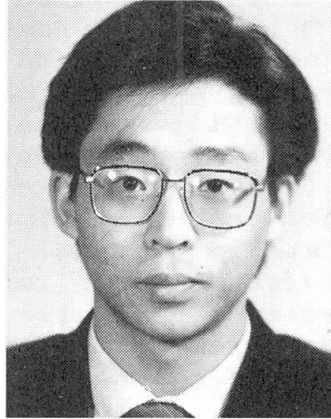
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**Damage Assessment and Remaining Life Prediction for Structures**  
Evaluation des dommages et de la vie restante des structures  
Schadensbewertung- und Restlebensdauer-Prognose für Tragwerke

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#### **SUMMARY**

This paper firstly gives a brief review on the research of damage assessment and remaining life prediction for existing bridge structures in China. Secondly, a discussion on this topic is also presented. Finally a prototype expert system for damage assessment of railway bridges is introduced.

#### **RÉSUMÉ**

Après une introduction sur les recherches et l'évaluation des dommages et de la vie restante des structures de pont en Chine, et des commentaires sur les méthodes existantes, l'auteur propose un projet de système expert pour déterminer l'état des dommages et de la vie restante des structures de ponts ferroviaires.

#### **ZUSAMMENFASSUNG**

Der Beitrag gibt eingangs einen kurtzen Überblick über die chinesische Forschung bezüglich Schadensbewertung und Vorhersage der Restlebensdauer von Brückentragwerken. Nach einer Diskussion der Problematik wird der Prototyp eines Expertensystems für Schäden an Eisenbahnbrücken vorgestellt.



## 1. INTRODUCTION

The safety of railway transportation has been focused serious attention of railway administration, research and design branches, not only because railway accidents always induce heavy loss of the life and property of peoples, but also because the most important is it is directly related to traffic schedule of railway transportation. Of a lot of factors affecting railway traffic safety, it is the service state of railway track and railway structures which plays a significant role to. Firstly, railway construction, especially railway bridges have a long service life and difficult rehabilitation characteristics. Secondly repair expense of railway bridge is very great. Hence railway maintenance branches has a very important, long-time task which is bridge service state inspection. Since 1950's, damage assessment of railway bridges has been investigated and a lot of experimental data and experience have also been obtained. But due to the complexity of the problem, it is still a very important research project to start deepgoing investigation on damage assessment and remaining life prediction method for existing structures. At the end of the paper, a prototype expert system to diagnose damage state of railway bridges will be briefly introduced.

## 2. BRIEF REVIEW ON THE RESEARCH

For a long time, railway bridge inspectors and researchers in China have been searching for a reasonable and effective method to assess service state of railway bridges. But up till present, no well method has been developed, owing to the limit of experience and research work as well as the complexity of the problem. Existing approaches may be classified into two kinds: physical inspection and mechanical measurement, such as structural outward appearance observation for cracks and dynamic response test. Physical means for interior inspection include ultrasonic method etc. Not all of the existing methods is effective.

In Northern China, railway has served for a considerably long time. Bridge damage is more serious. Hence Harbin Railway Administration Bureau has paid more attention to the research and practice of damage state inspection and assessment for bridges. Since 1979's, a lot of situ test data for dynamic response and time-domain properties of railway bridges have been accumulated, and a great deal of experience for diagnosing damage state of bridges has been obtained. They applied maximum transver dynamic displacement of bridge pier and some peculiarities of vibration wave of pier-head displacement as identifying rule to sum up into 10 types of damage for bridge pier.

China Academy of Railway Sciences started the investigation and research work on this topics in last 1970's. At the first stage of research, CARS has gathered a lot of situ dynamic test data



for existing bridges, which have been also analyzed, for example, the effects of damage on frequencies, modes, time-domain and frequency-domain peculiarity of bridges. Classifying the test data of about 80 bridge piers, CARS has suggested a standard for damage diagnosing of bridge pier.

The investigation on damage assessment for superstructure of bridges in China started in middle 1980's. CARS firstly did a lot of inspection work on riveted and welded steel bridges. Then a great amount of tests on fracture mechanics and fatigue properties of situ samples of bridge elements. For these kinds of bridges, CARS has done about 10-year investigation and has obtained some preliminary results. In recent years, CARS still does an amount of researches on damage assessment method for reinforced and prestressed concrete railway bridges, as well as strengthening method for damaged bridge rehabilitation.

According to present research state, the investigation and research on damage assessment and remaining life prediction approaches for existing railway bridges must be continued.

### 3. PREPARE WORK IN DAMAGE ASSESSMENT PROCEDURE

Prepare work for damage assessment of existing structures is composed of two stages:

- \* situ inspection and testing
- \* laboratory testing and analysis

The main objective in the first stage is to acquire practical structure geometric, physical and mechanical knowledge and information about the bridge to be assessed. The methods to inspect the bridge include outward appearance observation, physical measurement for cracks etc. as well as mechanical test to measure free vibration frequencies, modes and dynamic response to loading etc.

#### 3.1 Situ Inspection and Testing

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##### Outward appearance observation

Outward appearance observation for railway bridges is one of the routine duties of bridge maintenance branches. From the inspection, we can obtain basic knowledge and information about bridge service state, such as

- cracks: length, location, direction, depth etc.
- crust of reinforcement: location, extent etc.
- deterioration of concrete: location extent etc.
- inclination of bridge pier: direction, degree etc.
- link of bridge and piers: state, relative displacement etc.



**foundation: state**

#### **Interior defect inspection**

On the basis of outward appearance observation, interior defect inspection for existing bridges is mainly to survey interior damage of bridge structures by means of physical method, for example using ultrasonic approach to measure crack depth and interior cracks of structures.

#### **Situ mechanical testing**

The aim of situ mechanical testing is to acquire basic mechanical properties of the bridge to be assessed, generally using dynamic testing to measure free vibration frequencies, modes and dynamic response to vehicle loading. In addition, situ testing work also include obtaining samples for laboratory test and some basic material property experiment such as concrete strength test etc.

### **3.2 Laboratory Testing and Analysis**

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The main tasks in this stage composed of data treatment for the first stage, necessary laboratory test of situ samples in order to deliver sufficient information for damage assessment and remaining life prediction of the bridge assessed. Laboratory test is generally to measure fundamental properties, fracture mechanics and fatigue properties of samples of bridge structure and materials.

Time-domain and frequency-domain analysis as well as dynamic parameter identification are very useful to assess bridge service state. The second work in this stage is posttreating dynamic testing data recorded in situ test, including analysing and identifying physical and modal parameters, time-domain and frequency-domain peculiarities of the bridge.

## **4. DAMAGE ASSESSMENT AND REMAINING LIFE PREDICTION**

From the prepare work, we have obtained some knowledge and information for geometric, physical and mechanical properties of bridge assessed. The remained work is to assess service state of the bridge and to predict its remaining life. How to do this work? The first problem is how to model and quantify damage. As discussed above, damage phenomena are very different and complex. So it is considerably difficult modelling damage of structures.

As an example, we investigate effects of damage on dynamic properties of bridge pier in following so as to find some variables sensitive to damage.

# (1) Frequencies of bridge pier

Dr. Sun [2] investigated frequencies of bridge pier with and without cracks in 1991. The first four frequencies of a pier is listed in Table 1, from which we may know the effect of damage on frequencies of bridge pier.

Table 1. Frequencies of a bridge pier (Hz)

Mode	1	2	3	4
Normal pier	17.05	18.93	113.95	137.21
Cracked pier	16.39	17.42	110.51	-----

# (2) Modal shape of bridge pier

Convex point may be found near cracks in modal shape of cracked pier.

# (3) Modal damping of bridge pier

Chen [3] found that modal damping of damaged bridge pier becomes greater and greater as damage becomes larger.

# (4) Maximum pier-head displacement

With the reduction of pier stiffness, maximum pier-head displacement under vehicle loading becomes greater.

# (5) Time-domain peculiarity

Forced vibration response wave is smooth, similar to harmonic wave for good state bridge piers, but it may emerge some singular peculiarities for damaged piers.

# (6) Frequency-domain peculiarity

Power spectrum of damaged pier may be found with some differences to that of normal pier, such as with a wider band and smaller value at low frequency, a continuous spectrum and a greater number of peaks etc.

For superstructure of railway bridge, the effect of damage is more complex. In general, dynamic response parameters reflect the synthesized properties of structures. Some local damages have no evident effect on dynamic parameters. From identification of system parameters, we can only obtain a global and average damage description.

Here we classify damages of structures into two categories: local damage and global damage. The first may also called nonstructural damage, and the second structural damage. "Nonstructural" and "structural" do not mean without or with effect on structural capacity. But nonstructural damage only affects local stress and deformation of structures, and does not greatly affect macroscopic global displacement of structures. However the second is directly reflected from global mechanical response, such as frequencies, modes etc.





The first kind of damage includes local cracks, corrosion of reinforcement, exposure of concrete etc. The second is the worsening of structural materials.

#### 4.1 Damage Tolerance Method

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For the first kind of damage, we can use several characteristic variables to measure it. For example, using crack length  $l$ , crack depth  $a$  and crack open displacement  $d$  to describe a local crack in structures. In general,

Characteristic variables:  $\{ A_i / i=1,2,\dots,n \}$

Assume the damage produce a response quantity  $J$  to local stress, deformation etc. of the structure:

Response quantity:  $J$

Through fracture analysis and material test, we may obtain a critical value of  $J$  as  $J_c$ . A simple method to define local damage is

$D=J/J_c$	
$D=0$	when $J=0$ undamaged structure
$D=1$	when $J=J_c$ local failure

This method for the first kind of damage is similar to the main idea of Damage Tolerance Method of fracture mechanics.

#### 4.2 Combined Damage Theory-System Identification Method

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According to damage theory, if there are cracks or vacancy in materials, elastic modulus of material will be reduced. The author [5] obtained:

$$\tilde{\underline{E}} = (\underline{I} - \underline{D}) : \underline{E}$$

where  $\tilde{\underline{E}}$  and  $\underline{E}$  are elastic tensors of damaged and undamaged materials respectively.  $\underline{D}$  is called damage tensor.  $\underline{I}$  is a unit tensor. In case of isotropy, it can be simplified as

$$\tilde{E} = (1 - D)E$$

where  $D$  is a damage scalar.

Applying system identification method, we can obtain elastic modulus distribution of damaged bridges. Therefore damage state of the bridges may be also identified.

The approach discussed above is called Combined Damage Theory-

## System Identification Method.

### 4.3 Remaining Life Prediction

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In order to predict remaining life of existing structures, it is necessary to model damage evolving property of bridges. In general,

$$\dot{D}=f(D, t, F)$$

or

$$\delta D / \delta N = g(D, N, F)$$

where  $F$  represents external act.  $N$  represents loading cycles.

It is a very complex work to obtain the damage evolving equation. Firstly we have to do deep investigation on damage mechanism. Secondly we must grasp a lot of experiment results for bridge materials and elements with and without typical damages.

If damage evolving equation has been developed, remaining life of bridges assessed can be predicted from the present damage state and the future loading spectrum of the bridges.

$$N_r = N_f - N_s$$

$$D(N + dN) - D(N) = g(D(N), N, F)(N + dN - N)$$

$$D = D_s \quad \text{when } N = N_s$$

$$D = 1 \quad \text{when } N = N_f$$

where  $D_s$  represents the present damage of the bridge.

## 5. A PROTOTYPE EXPERT SYSTEM FOR BRIDGE PIER ASSESSMENT

The expert system, DREPM-DP, is a prototype system developed by China Academy of Railway Sciences, which is based on an expert system tool DREPM. In acquisition of knowledges, domain knowledge and expert knowledge as well as an analyse module are used. The system has two kinds of knowledge representation method: frame representation and productive representation. A ask-answer blackboard is designed, which makes the system has a good human-machine interface.

DREPM-DP has been used to assess damage state of about 20 bridge piers. The diagnosing results are identical to practical situation.

### Example: Haoshi River Bridge on Han-Dan Railline

The piers of the bridge is of a circular cross-section, enlargement foundation on rough sand with gravel layer. Bridge maintenance branch reported that Pier No.3 rocked greatly when train passed the bridge. In 1988, Zhengzhou Bridge Inspection Branch did situ vibration testing to the bridge. According to the



results recorded in the test, DREPM-DP gives such diagnosing results:

Pier No.2: little worse state,  $D=0.4$   
Pier No.3: very worse state,  $D=0.1$   
Pier No.4: worse state,  $D=0.25$

## 6. CLOSE REMARKS

Damage state assessment and remaining life prediction for railway bridges are closely related to transportation safety. Deepgoing investigation on how to assess the state and to predict the life is very significant at present. According to the discussion above, it has been found following topics must be done further studies:

- (1) Modelling method for damage of bridges
- (2) Damage criterion and damage-servicability relation
- (3) Damage evolving properties

**ACKNOWLEDGEMENT:** The author would like to express his heartfelt thanks to Prof. Qingguo Cheng and Dr. Ning Sun for their invaluable help and discussion with the author on this paper.

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**Probabilistic Response of Reinforced and Prestressed Bridge Cross-Sections**  
**Réponse probabiliste de sections de ponts en béton armé et précontraint**  
**Wahrscheinliche Belastungsantwort von vorgespannten**  
**Stahlbetonbrückenquerschnitten**

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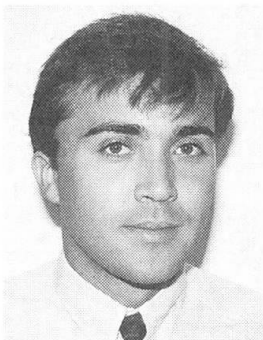


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## SUMMARY

This paper is concerned with the recent available data obtained for modeling geometrical and material uncertainties for concrete bridges, and the use of these models to obtain the probabilistic response of reinforced and prestressed concrete bridge cross-sections. A parametric analysis is performed for explaining the basic features to evaluate the real response of existing bridges for reliability analysis and identifying the more relevant parameters for quality control or testing tasks.

## RÉSUMÉ

L'article résume les données obtenues pour la modélisation de l'incertitude relative à la géométrie et les propriétés des matériaux employés dans la construction des ouvrages d'art en béton armé et précontraint, et leur utilisation pour la détermination de la réponse probabiliste de sections transversales de ponts. Une analyse paramétrique permet de mettre en évidence les principaux critères pour l'évaluation de la réponse réelle des ponts existants, d'analyser la fiabilité, et d'identifier les paramètres les plus importants à considérer dans le contrôle de qualité ou la rationalisation d'essais.

## ZUSAMMENFASSUNG

Dieser Artikel beschreibt die neuesten verfügbaren Daten, die für die Modellierung von Geometrie- und Materialunsicherheiten bei Betonbrücken bestimmt wurden und die Verwendung dieser Modelle zur Bestimmung der wahrscheinlichen Belastungsantwort von vorgespannten Stahlbetonbrückenquerschnitten. Einer Parameterstudie wird durchgeführt, um die Hauptmerkmale der Bestimmung der wirklichen Belastungsantwort von existierenden Brücken sowie deren Zuverlässigkeitsanalyse zu erklären, ausserdem bestimmt sie die wichtigsten Parameter für die Qualitätskontrolle oder vorzunehmende Tests.



## 1.- INTRODUCTION

In order to obtain an accurate reliability analysis of existing or future structures it is necessary to use more realistic models for materials, geometrical variabilities and structural analysis, taking into account the non-linear behavior [1]. The use of analytical or semi-empirical relations for the obtention of the bridge section resistance available in design code must be improved.

The statistical parameters of geometrical variability and the uncertainties in the physical properties of the involved materials has been normally derived for the available literature data for building [2]. Nevertheless, in bridge construction both the construction considerations stipulated are different and more accurate techniques are used. Thus, a higher quality construction can be obtained. On the other hand, the available data are not directly suitable for other countries with different modes of construction or quality control. So that, more information should be obtained.

Recently, numerical methods to evaluate the structural cross-section response of prestressed and reinforced girders have been developed to obtain ultimate moment and shear responses and the moment-curvature relationship [3], and they have been widely used for bridge evaluation and code calibration [4]. There is a need for the analysis of other concrete bridge typical cross-sections.

## 2.- GEOMETRICAL VARIABILITY

The parameters involved in the geometrical shapes, alignment, configuration of building components are subjected to uncertainties due to different sources: form works, placement of reinforcing or prestressing steel, placing of concrete, assemblage procedures, etc. Geometrical variations affect both, the self weight of the structural elements, (dead load) and the cross section response (effective depth, concrete covers, etc.) Most of the different literature data available has been collected in Western Europe, USA and Japan, mainly for building structures [5] [6].

### 2.1.- Experimental data and proposed models

A large experimental data bank has been collected until now in different bridges recently built in Barcelona area (post-tensioned concrete slabs and one box girder bridge). Also, a large data has been obtained from a group of reinforced and prestressed concrete bridges (slabs and girder bridges) demolished, for urbanistic reasons because of the 1992 Olympic Games and the construction of new infrastructure, in Barcelona.

The parameters collected have been: Deck thickness in slab-girder bridges, geometric definition of girders, depth of slabs, thickness of top and bottom slabs in box girder bridge, effective depth of reinforcing, diameter of voids in voided slab, thickness of asphalt.

The measurements of all these variables have been analyzed in order to obtain the statistical parameters. A Kolmogorov-Smirnov test has been used to derive the theoretical probabilistic model. The probability distribution function included in these study were: Normal, Lognormal, Truncated Lognormal, Gamma and Truncated Gamma. For each of these distributions the Kolmogorov-Smirnov test provide a rational measurement of the approach. In many cases, all of these functions fitted well the sample, thus to simplify the rational use of the theoretical models the criteria was to select the Normal or Lognormal probability density distributions. The results are summarized in Table 1.

## 3.- MATERIAL UNCERTAINTIES

The available data and modeling for the physical uncertainties involved in the material and mechanical properties is very large [7] [8] [9]. Anywise, to obtain accurate models it is necessary to define the source and to process the samples that are homogeneous, in order to establish a suitable probability functions for a well definite random variable to use in further calculations.

In this paper, the data collected is restricted to materials recently used in concrete bridge construction in Spain, with a mean quality control of the materials and high quality control of construction.

Parameter X	Xnominal (mm)	$\frac{X_{mean}}{X \text{ nominal}}$	$\frac{X_{min.}}{X_{mean}}$	$\frac{X_{max.}}{X_{mean}}$	$\frac{\text{Standard Dev}}{X_{mean}}$	Type of distribution
Deck Slab Girder Thick.	250.0	1.00	0.79	1.13	0.07	Normal
Horizontal dimensions of Girders	250 - 600	0.99-1.003	0.99	1.007	0.003 -0.007	Normal
Vertical dimensions of Girders	150 600	0.94 - 1.025	0.95	1.05	0.025 0.003	Normal
Depth of cast in situ Slabs	300 1800	0.996	0.94	1.05	0.026 0.015	Normal or Lognormal
Depth of top Reinf.	266	1.006	0.91	1.07	0.045	Normal
Depth of bottom Reinf.	50	1.41	0.48	1.83	0.27	Normal
Thickness of top slab in Box Girder	250	0.95-1.03	0.89-0.92	1.06-1.10	0.02-0.07	Normal
Thickness of bottom slab in Box Girder	200 350-450	1.002 0.95-1.1	0.987 0.95-0.97	1.012 1.03-1.05	0.011 0.016-0.025	Normal
Diameter of voids (Slab)	1200-1400	0.97	0.98	1.02	0.007-0.008	Normal
Thickness of asphalt	45 - 80	0.95-1.14	0.58-0.76	1.25-1.53	0.26-0.11	Normal or Lognormal

The measurements of geometrical definition of girder cross- sections have been classified in vertical and horizontal dimensions.

Table 1.- Geometrical variability

### 3.1 - Concerning Concrete

Different samples of compressive strength of concrete have been processed to get the statistical parameters and to obtain a good fit. Normal and Lognormal PDF provide a rational approach for modeling this parameter. It is recommended to use Normal distribution for high quality concrete. The statistical data are summarized in Table 2, for three types of concrete.



Specified f <sub>c,k</sub> (MPa)	Age at test (days)	f <sub>c</sub> , mean (MPa)	f <sub>c,min</sub> f <sub>c,mean</sub>	f <sub>c,max</sub> f <sub>c,mean</sub>	C.O.V.	Type of distribution
25	7	22 - 30	0.71-0.85	1.13-1.19	0.08-0.11	Normal Lognormal
25	28	28 - 33	0.74-0.82	1.20	0.09-0.11	Normal Lognormal
30	7	34	0.81	1.19	0.14	Normal Lognormal
30	28	36	0.70	1.20	0.11	Normal Lognormal
35	7	30 - 35	0.72-0.88	1.09-1.16	0.07-0.11	Normal Lognormal
35	28	40 - 42	0.77-0.94	1.05-1.16	0.03-0.10	Normal Lognormal

Table 2.- Compressive concrete strength

### 3.2 - Concerning prestressing steel

A large data bank has been processed for two different types of strands, 0.5" and 0.6", and steel 270K (186/167 MPa). The source has been the more important manufacturer of prestressing steel in Spain, which provided hundreds of quality control tests, conform to ASTM A-416 specifications. All these data corresponds to prestressing steel used in post-tensioning concrete bridges in the last 3 years. Analysis of data and results of the Kolmogorov-Smirnov test are summarized in Table 3. An example of the sample is shown in Figure 1.

Type of strand	Parameter X	X mean	X nominal	X <sub>min</sub> X <sub>mean</sub>	X <sub>max</sub> X <sub>mean</sub>	C.O.V.	Type of distributi.
0.5 "	E modul.	197.0	190.0	0.96	1.04	0.018	Normal Lognormal
0.5 "	Ty, 0.2%	180.6	166.0	0.92	1.08	0.028	Normal Lognormal
0.5 "	T max	195.5	186.0	0.95	1.06	0.017	Normal Lognormal Gamma
0.6 "	E modul.	196.5	190.0	0.95	1.06	0.019	Normal Lognormal
0.6 "	Ty, 0.2%	247.0	238.0	0.94	1.08	0.022	Tr. Gamma Tr. Lognor
0.6 "	T max	271.6	266.0	0.96	1.07	0.018	Lognormal Normal

E = Deformation module (kN/mm<sup>2</sup>), T<sub>max</sub> = Tensile strength (kN) and Ty,0.2%= Yield force (kN).  
Tr. Gamma= Truncated Gamma Tr. Lognorm= Truncated Lognormal.

Table 3.- Prestressing Steel (270K) properties.

### 3.3 - Concerning reinforcing steel

The available data for reinforcing steel is not as large as in the case of prestressing. Different quality controls, made in some bridges, provide us the data. The mechanical properties are very related with the bar diameter in the analysis performed. The results are presented in Table 4 although its can not be significant until the data bank will be more representative.

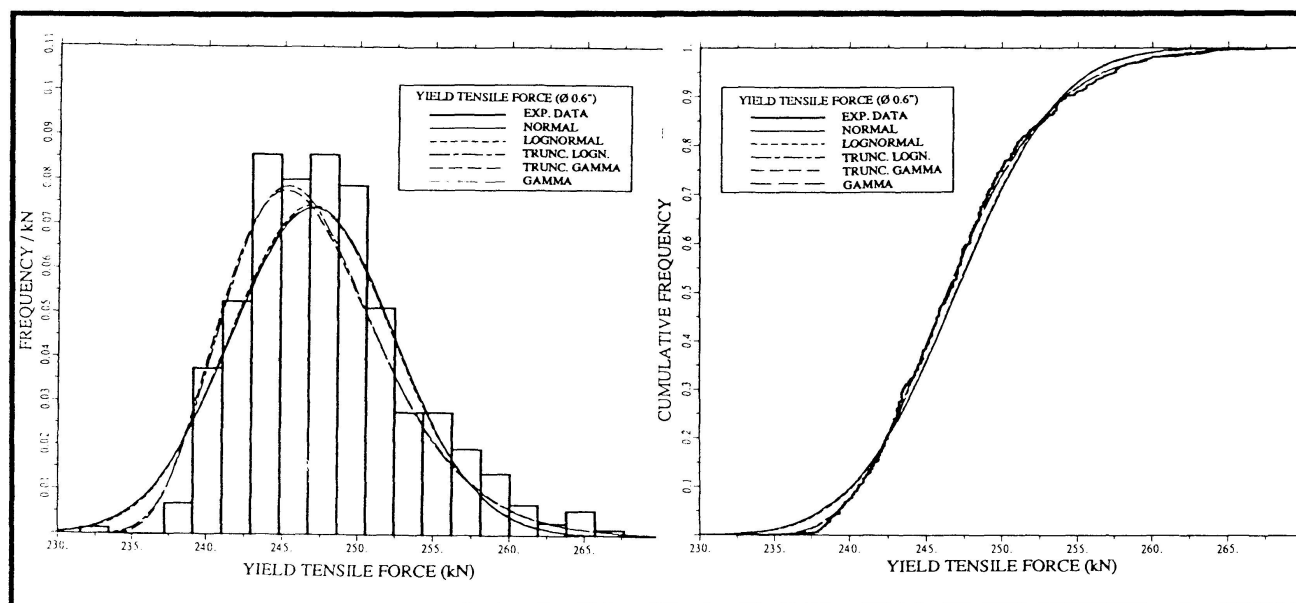


Figure 1.- Histogram, PDF and CDF curves, for yield tensile force prestressing steel. (strand 0.6")

Parameter X	X nominal	X mean	$\frac{X_{min}}{X_{mean}}$	$\frac{X_{max}}{X_{mean}}$	C.O.V.	Type of Distribution
$\frac{Area_{real}}{Area_{nom}}$	1.0000	1.003	0.98	1.05	0.002	Normal Lognormal
$f_y$ (kN/mm <sup>2</sup> )	51.0	58.0	0.91	1.10	0.057	Lognormal
$f_{max}$ (kN/mm <sup>2</sup> )	60.0	67.9	0.98	1.10	0.050	Lognormal

Table 4.- Reinforcing steel parameters ( $f_y$  = yield tensile stress ,  $f_{max}$ = maximum tensile stress)

### 4.- RESISTANCE MODELS

Accurate resistance reliability models to obtain the real response of cross sections must take into account the real strain-stress relationship of the materials involved, and consider the uncertainty in the geometry and material properties [4].

A numerical procedure has been developed, considering the above mentioned needs, to obtain the moment, shear and torque response and the moment-curvature relationship of typical cross-sections





of reinforced and prestressed concrete bridges, conform to CEB Model Code [10]. The model has been computerized for easy application. In order to predict the probabilistic response and to fit a theoretical probability distribution a 400 Monte-Carlo simulations, for each case, were performed. The following assumptions were made:

- Strain-stress curves from CEB Model Code.
- The theoretical PDF used in the simulations are in conformity with data bank collected. The user can also use the experimental histogram.
- All parameters involved to define the cross-section geometry and strain-stress curves are considered as a independent random variable, in statistical sense.
- In each simulation all the above mentioned parameters are actualized.

Sensitivity analysis is made, in a recently built bridge in Barcelona (Fig. 2), to reveal the effects on the random response due to selected parameters such as:

- C.O.V of vertical and horizontal magnitudes of geometry, diameter of voids,  $f_c$ ,  $f_{ct}$ , yield stress of prestressing, effective steel prestress after losses, depth of prestressing.

The parametric analysis concerning C.O.V. is because of this statistic is directly correlated with quality of materials and construction and human error, for new bridges, or with the level of uncertainty in the unknown involved parameters of existing bridges. Thus, the more relevant parameters in the resistance evaluation can be selected and used to rationalize the test tasks and inspections.

#### 4.1- Voided Slab, Margenat Bridge in Barcelona.

This is a simply supported prestressed concrete voided slab, cast in situ in 1991, with a span length of 27.40 m, the cross-section and the placement of prestressing are shown in Figure 2 [11]. The Moment-curvature relationships are shown in Figure 3, with design values (factored resistance) and with mean and characteristic values of parameters involved. Numerical results of the response value analyzed are given in Table 5. Due to the lack of space only the most relevant results of parametric study are summarized in Figures 4, 5, 6 and 7.

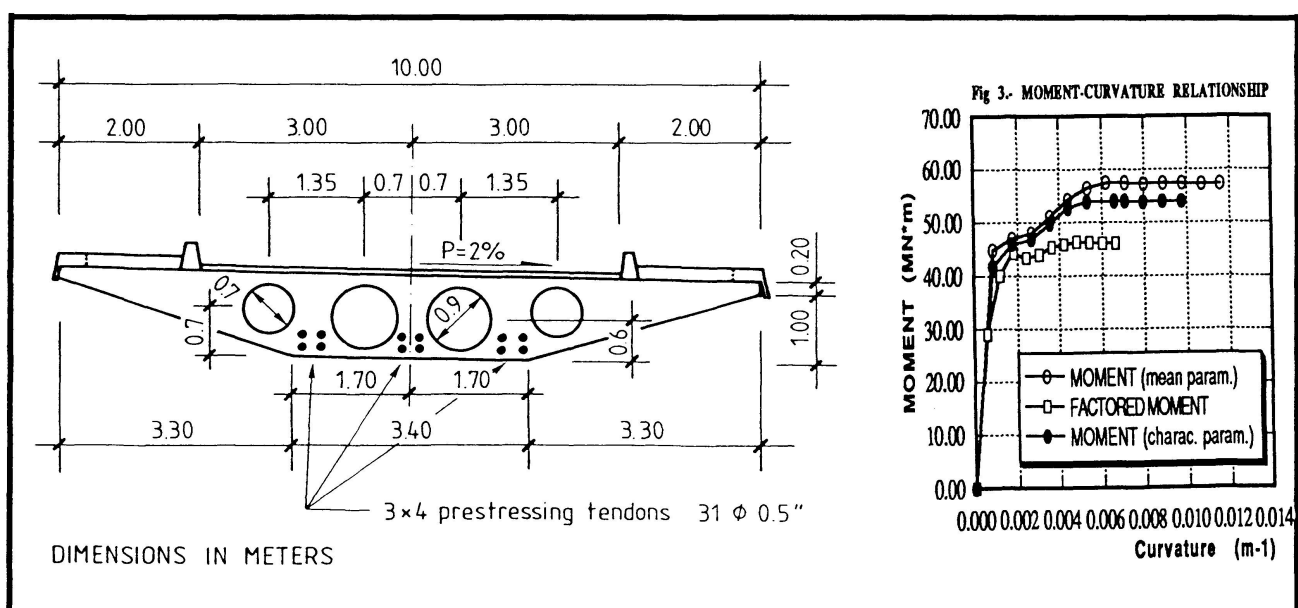


Figure 2.- Margenat bridge. Typical cross-section. Figure 3.- Moment-curvature relationship from decompression of concrete

Parameter X	$\frac{X_{mean}}{X_{nominal}}$	X mean	$\frac{X_{min}}{X_{mean}}$	$\frac{X_{max}}{X_{mean}}$	C.O.V.	Type of Distribution
Ultimate Bending- Moment (MN*m)	1.254 * 1.067	57.45	0.92	1.10	0.034	Normal Lognormal
M, crack (MN*m)	1.00	32.48	0.90	1.14	0.046	Normal Lognormal Gamma
Inertia section (m <sup>4</sup> )	1.00	0.829	0.75	1.23	0.089	Lognormal Tr. Lognor. Gamma
Area section (m <sup>2</sup> )	1.00	6.657	0.91	1.08	0.032	Normal Lognormal

Table 5.- Simulation results. ( \* design value, factored resistance  $\phi_c = 1.5$  and  $\phi_s = 1.15$ ). Nominal values conform to CEB Model Code, with characteristic parameters.

The real case of cross-section herein studied yield a good example to evaluate the main important parameters involved in its ultimate resistance and serviceability behaviour. It is easy to realize that the most important parameters are related with geometry and not with those concerning with strength of material, due to the ductile behaviour. In the same way, the parametric study varying C.O.V of void diameters and with yield tensile stress of prestressing shows a not important correlation with the section properties analyzed.

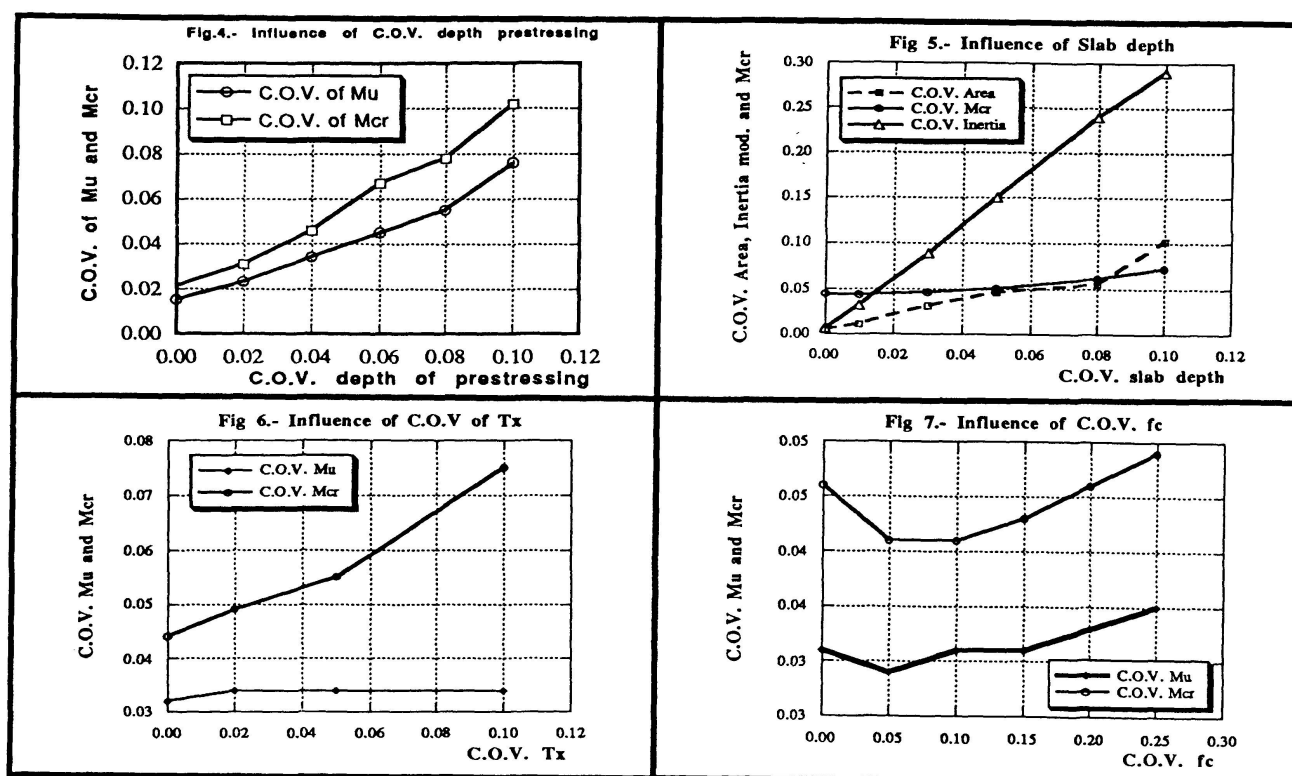
## 5.- CONCLUSIONS

### 5.1.- Conclusions concerning geometrical and material variability.

Due to the lack of data available for modeling geometrical and material variability in concrete bridges an important experimental data has been collected and presented. The statistical analysis of data fairly shows that different statistical parameters has to be considered in the analysis of reinforced and prestressed concrete bridges, which usually have a more accurate construction than buildings.

### 5.2. - Conclusions concerning probabilistic response of concrete bridges

The scarcity of analysis of the most typical cross-sections in concrete bridges has conducted to develop a numerical procedure to obtain the probabilistic response, in terms of moment, torque and shear, taking into account the non-linear behaviour of materials and the uncertainties in the parameters involved. A parametric study has been presented as a guideline to determine the sensitivity of resistance and geometrical properties of the cross-section to different varying C.O.V. of main parameters. The results show that the most important parameters to be correctly and accurately evaluated are cross-section geometry and depth of prestressing steel.



Note:  $T_x$ =prestress after losses,  $f_c$ = compressive concrete strength.

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**Dynamic Behaviour in Existing Concrete Bridges and Damage Detection**  
**Comportement dynamique des ponts en béton et détection des dommages**  
**Dynamisches Verhalten bestehender Betonbrücken zur Schadenerkennung**

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## **SUMMARY**

In this paper, the sensitivities of the dynamic behaviour of concrete bridges constituted by natural frequency, mode shape, damping and phase angle in damage detection is studied utilizing an analysis of the complex eigenproblem considering non-proportional damping and using dynamic loading tests on an existing bridge in which some specified artificial damage had been included. Also, a method of damage assessment for concrete bridges integrated from both the concise detection of damage location based on the difference in the sensitivities of modal parameters and the exact evaluation by localization and quantification of multiple damage based on the system identification method, is discussed.

## **RÉSUMÉ**

Les sensibilités du comportement dynamique des ponts en béton constituées par la fréquence naturelle, la forme modale, l'amortissement et le déphasage sont examinées en vue de la détection des dommages, avec le recours à l'analyse de problèmes propres complexes, et en tenant compte de l'amortissement non proportionnel et des essais en charge dynamiques sur des ponts existants où quelques dommages artificiels spécifiques ont été induits. On y discute également une méthode d'estimation des dommages des ponts en béton intégrée à la fois par une détection concise de la localisation du dommage selon la différence des sensibilités des paramètres modaux et par une évaluation exacte par localisation et quantification des dommages multiples selon la méthode d'identification des systèmes.

## **ZUSAMMENFASSUNG**

In dieser Arbeit wird die Empfindlichkeit im dynamischen Verhalten, ausgedrückt durch natürliche Frequenz, Modalform, Dämpfung und Phasenwinkel, von Betonbrücken in der Schadenserkennung untersucht. Dabei wird die Analyse von komplexen Eigenproblemen unter Berücksichtigung der nicht-proportionalen Dämpfung und dynamischer Belastungstests auf vorhandenen Brücken, bei denen spezifizierte künstliche Lasten aufgebracht wurden, eingesetzt. Ausserdem wird eine Methode der Schadensbewertung von Betonbrücken diskutiert, bei der die schnelle Erkennung der Schadenslage und die genaue Bewertung der Lage und Quantifizierung von mehrfachen integriert sind. Erstere basiert auf dem Unterschied der Empfindlichkeit modaler Parameter, während für letztere die Systemidentifikation eingesetzt wird.



## 1. INTRODUCTION

The need for damage assessment of existing concrete bridges by a combination of visual inspections, loading tests and analytical studies, has been pointed out with reference to the diagnosis of bridge serviceability [1]. Since there are a number of factors included in the relationship between the damage to existing bridges and dynamic behavior, it is necessary to develop an efficient method for damage detection based on dynamic loading tests [2]. The most important aspect of this problem is to focus on the dynamic sensitive parameters to the damage, because this has a significant influence on the accuracy of assessment.

In this paper, the sensitivities of dynamic behavior constituted by the natural frequency, the mode shape, the damping constant and the phase angle, for damage detection was studied using an analysis of the complex eigenproblem considering non-proportional damping and also dynamic loading tests. For the analytical study, the component mode synthesis (CMS) method, which is one type of coupling technique for substructures in the dynamic analysis was applied to the complex eigenproblem for simplification and an iterative analyses for damage detection was utilized. The system identification (SI) method was developed based on sequential linear programming (SLP), combined with the dynamic sensitivity analysis, to quantify the degree of damage for each member in the whole system.

For the application of this method to existing concrete bridges, parametric analyses for simply supported RC-T beam bridges in service were executed to evaluate the sensitivities of damage to dynamic behavior and to construct a concise flow for damage detection. Furthermore, the SI method was applied to the results from the dynamic loading tests, performed on an existing bridge in which some specified artificial damages were induced. Finally, the concise flow and the SI method were integrated, to enable an efficient damage assessment by multi-level and multi-aspect approaches.

## 2. ANALYTICAL METHOD FOR DAMAGE DETECTION OF EXISTING BRIDGES

### 2.1 Modeling of bridges

For existing concrete bridges, stiffness reduction of the main girder has been caused due to the interactive effect of flexural cracks and retrogression in the modulus of elasticity of the concrete. The safety of bridges is strongly influenced by this process as due to a change of load distribution and hence a reduction in load carrying capacity. In this research, the stiffness reduction and change of damping constant were considered to be the damage factors. The modeling of the target bridge was carried out by using a lumped mass gridform model of finite beam elements and spring elements for the elastic restraint of rotation at the supports. Fig.1 shows an example of the model for an existing RC-T beam bridge, "Nakaibashi" located in Hyogo prefecture in Japan.

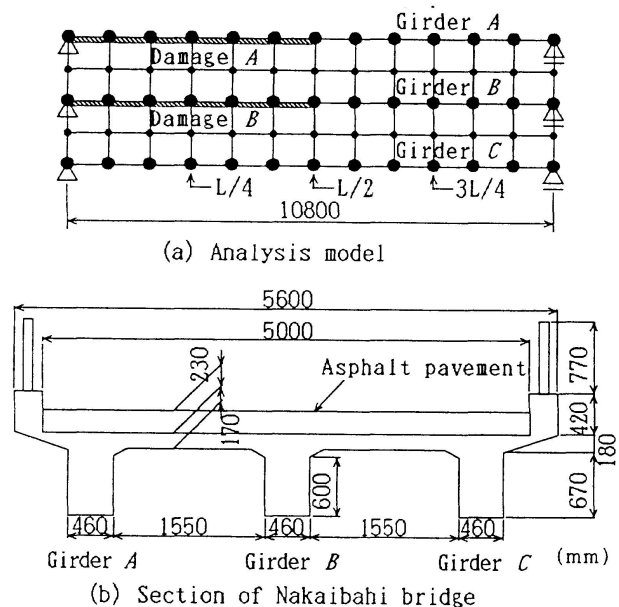


Fig.1 Modeling of existing RC-T beam bridge

### 2.2 Component mode synthesis method in the complex eigenproblem

The CMS method deals with the equation for the whole structure in modal coordinates obtained by synthesis of the boundary modes of substructures previously evaluated by modal analysis in the physical coordinates. When the whole structure is divided into  $n$  pieces of substructures, the equation of motion for the substructure  $i$  can be expressed by:

$$\begin{bmatrix} M_{aa}^i & M_{ab}^i \\ M_{ba}^i & M_{bb}^i \end{bmatrix} \begin{Bmatrix} \ddot{\delta}_{ia} \\ \ddot{\delta}_{ib} \end{Bmatrix} + \begin{bmatrix} C_{aa}^i & C_{ab}^i \\ C_{ba}^i & C_{bb}^i \end{bmatrix} \begin{Bmatrix} \dot{\delta}_{ia} \\ \dot{\delta}_{ib} \end{Bmatrix} + \begin{bmatrix} K_{aa}^i & K_{ab}^i \\ K_{ba}^i & K_{bb}^i \end{bmatrix} \begin{Bmatrix} \delta_{ia} \\ \delta_{ib} \end{Bmatrix} = \begin{Bmatrix} 0 \\ f \end{Bmatrix} \quad (1)$$

where subscript  $a, b$  denote the internal area and the boundary area, respectively.

By using Guyan reduction of the stiffness matrix, a correlation between the displacement in the internal area and the boundary area can be expressed by:

$$\delta_{ia} = -[K_{aa}]^{-1}[K_{ab}]\delta_{ib} = T_i \delta_{ib} \quad (2)$$

After this, an analysis of the complex eigenproblem for the synthesized whole structure, of which the matrix size is reduced to the degree of freedom for the boundary area of each substructure, is carried out. Displacement at the boundary area  $b$  can be evaluated in the form of complex conjugates by linear combination of each mode as:

$$y_b = \phi_b \xi_b \quad (3), \quad \text{where } \phi_b = [\phi_{b1}, \bar{\phi}_{b1}, \phi_{b2}, \bar{\phi}_{b2}, \dots, \phi_{bk}, \bar{\phi}_{bk}] : \text{the complex mode matrix,}$$

$k$  denotes the adopted number of modes,  $y_b = \{\delta_b, \bar{\delta}_b\}^T$ ,  $\xi_a = \{\xi_{1b}, \xi_{2b}, \dots, \xi_{nb}\}^T$ : the modal coordinates.

On the other hand, carrying out the analysis of the constrained mode for each substructure, displacement at the internal area  $a$  for each substructure can be expressed by:

$$y_{ia} = [T_i \phi_{ib}, \phi_{ia}] \xi_i \quad (4), \quad \text{where } \phi_{ia} = [\phi_{ia1}, \bar{\phi}_{ia1}, \phi_{ia2}, \bar{\phi}_{ia2}, \dots, \phi_{iam}, \bar{\phi}_{iam}] : \text{the complex mode matrix,}$$

$m$  denotes the adopted number of modes,  $\xi_i = \{\xi_{ib}, \xi_{ia}\}^T$ ,  $T_i = \begin{bmatrix} T_i & 0 \\ 0 & T_i \end{bmatrix}$

Displacement of the whole structure can be expressed by using the modes at the boundary area and the internal area, as:

$$\{y_b, y_a\}^T = X \{\xi_b, \xi_a\}^T = X \xi \quad (5), \quad \text{where } y_a = \{y_{1a}, y_{2a}, \dots, y_{na}\}^T, \xi_a = \{\xi_{1a}, \xi_{2a}, \dots, \xi_{na}\}^T,$$

$$X = \begin{bmatrix} \phi_b & 0 \\ T \phi_b & \phi_a \end{bmatrix}, \quad T = \begin{bmatrix} T_1 & & 0 \\ & T_2 & \\ 0 & & T_n \end{bmatrix}, \quad \phi_a = \begin{bmatrix} \phi_{1a} & & 0 \\ & \phi_{2a} & \\ 0 & & \phi_{na} \end{bmatrix}$$

Finally, the equation of motion for the whole structure can be written as:

$$X^T P X \ddot{\xi} + X^T Q X \dot{\xi} = 0 \quad (6), \quad \text{where } P = \begin{bmatrix} 0 & M_{bb} & 0 & M_{ba} \\ 0 & M_{ab} & 0 & M_{aa} \\ M_{bb} & C_{bb} & M_{ba} & C_{ba} \\ M_{ab} & C_{ab} & M_{aa} & C_{aa} \end{bmatrix}, \quad Q = \begin{bmatrix} -M_{bb} & 0 & -M_{ba} & 0 \\ -M_{ab} & 0 & -M_{aa} & 0 \\ 0 & K_{bb} & 0 & K_{ba} \\ 0 & K_{ab} & 0 & K_{aa} \end{bmatrix}$$

By analyzing the eigenproblem for Eq.(6), the modal parameters for the whole structure can be obtained. Furthermore, substituting the modes evaluated by Eq.(6) into Eq.(5), the modes of the whole structure in the physical coordinates can be obtained. The degree of freedom for this analysis is the sum of the adopted number of modes for the whole structure synthesized by the modes for the boundary area of all substructures;  $2k$ , and the adopted number of modes for the internal area of all substructures;  $2\sum m_i$  ( $i=1, n$ ,  $n$ : number of substructures), and it can be seen to be much less than the total degree of freedom for the whole structure. Through study of the accuracy of this method using the existing bridge model shown as Fig.1, it was founded that the results of this analysis were sufficiently accurate for the target modes of bridge vibration as shown in Fig.2, even if the adopted degree of freedom for the whole structure was half the total degree of freedom.

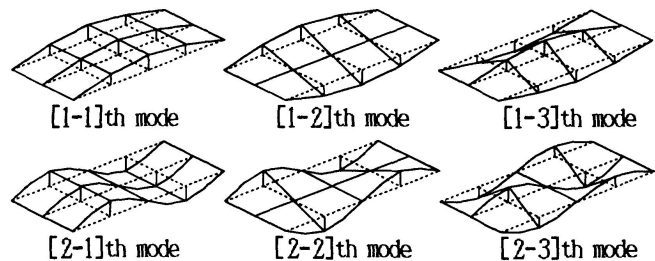


Fig.2 Shape of target modes

### 2.3 SI method using sensitivity analysis

The SI method [3] is one type of back analysis method, which can be used to identify system parameters such as the flexural rigidity corresponding to the degree of damage in the problem, by minimizing the error between the mechanical behavior as obtained from test and analysis. Here, the existing concrete bridge was modeled as shown in Fig.1, considering spring elements for the friction





restraint of rotation at the supports. In this research, the sensitivity analysis of damage to mechanical behaviors and the SLP method were integrated. The objective function was defined as minimizing the total squared error between the mechanical behavior obtained from the field test and the analysis, by:

$$F = W_1 \left( \frac{\mu_p}{\mu_p^m} - 1 \right)^2 + W_2 \sum_{k=1}^n \left( \frac{Z_{pk}}{Z_{pk}^m} - 1 \right)^2 \rightarrow \min \quad (7)$$

where  $p$  is the order of normal vibration,  $n$  is the number of measuring points,  $\mu$ ,  $\mu^m$  are the eigenvalues obtained from the analysis and the field test, respectively,  $Z$ ,  $Z^m$  are the normalized modes of vibration, and  $W_1$ ,  $W_2$  are the weights for the eigenvalue and the vibration modes. Here, it is assumed that  $W_1=1.0$ ,  $W_2=1/n$ .

The sensitivity (derivative) of the design variable (for identification, here assign it the rigidity  $K_i$ ,  $i=1 \sim l$ ,  $l$ : the number of members) to the objective function, can be expressed by:

$$\frac{\partial F}{\partial K_i} = \frac{2W_1}{\mu_p^m} \left( \frac{\mu_p}{\mu_p^m} - 1 \right) \frac{\partial \mu_j}{\partial k_i} + \sum_{k=1}^n \frac{2W_2}{Z_{pk}^m} \left( \frac{Z_{pk}}{Z_{pk}^m} - 1 \right) \frac{\partial Z_j}{\partial k_i} \quad (8)$$

where

$$\frac{\partial \mu_p}{\partial k_i} = Z_p^T \frac{\partial K}{\partial k_i} Z_p, \quad \frac{\partial Z_p}{\partial k_i} = \sum_{j=1}^n \left( -\frac{1}{\mu_j^m - \mu_p^m} Z_j^T \frac{\partial K}{\partial k_i} Z_p \right) Z_j$$

and  $K$  is the stiffness matrix of the whole structure.

Following this, identification of the design variables can be performed by applying the SLP method using the objective function and its derivative for the design variables. Fig.3 shows the flow of the SLP method for the dynamic problem. Firstly, the initial values of the design variables are evaluated by analysis. Linearization of the objective function is then carried out within the region of movement limits for the design variables, and a search for the minimum point of the objective value is tried using the simplex method. In the event that the change of design variables exceeds the movement limits, reanalysis of the modal parameters and restart of the search for the minimum values from updated initial values are executed by the same procedure iteratively up to the stage at which the objective function is within the allowable limits.

### 3. APPLICATION TO AN EXISTING RC BRIDGE WITH ARTIFICIAL DAMAGE

#### 3.1 Outline of target bridge

The target existing bridge "Oyasubashi" is 27 years old and a simply supported 4 girder RC-T beam bridge with a skew angle of 46 degrees and a span length of 14.7m. This bridge seemed to be almost intact according to the results of visual inspections. Fig.4 shows an outline section for this bridge.

#### 3.2 Inducement of artificial damage

The artificial damage corresponding to

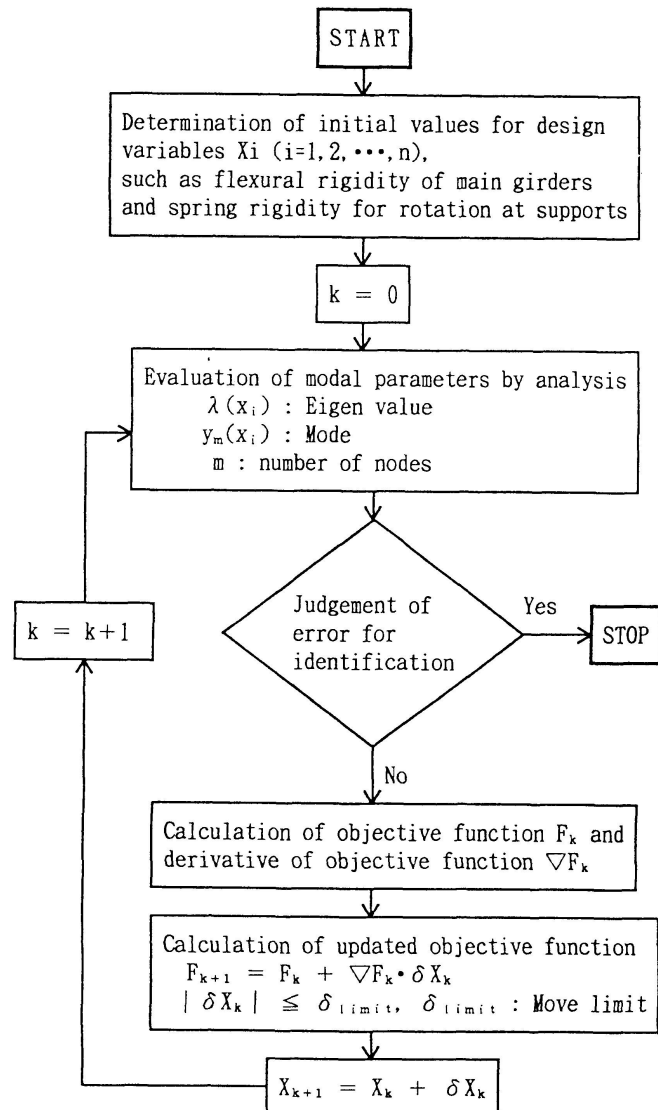


Fig.3 Flow of SLP (for dynamic problem)

flexural cracks in concrete in the tensile region were induced partially in the girders *A* and *B* as shown in Fig.5. Introduction of cracks was carried out by core boring along a vertical line from the bottom surface of concrete in the tensile region to the neutral axis, as shown in Fig.6. The core concrete blocks were then replaced in the holes from which they had been extracted, in order to avoid altering the weight of the girders.

### 3.3 Procedure for field test [4]

Prior to the field test, the target bridge was modeled as the lumped mass system shown in Fig.7, and the modal parameters were evaluated by analysis. From this a measurement method was determined focusing the antinodes of target vibration modes, as shown in Fig.5. Positions of forced vibrations by falling mass were arranged to obtain the various modes of vibration and the mass dropping was carried out from about 70cm height for ten times at the same loading point to cancel white noise and to obtain a stable average value. The modal analysis [5] was then applied to the acceleration data to identify the modal parameters.

### 3.4 Identification of damage parameters

The stiffness reduction of main girders was identified by the SI method based on the [1-1]th eigenvalue and eigenvector obtained from the field tests, using the following procedure:

- (1) For the target bridge before inducement of the artificial damage, the system parameters constituted by the stiffness of main girders and cross beam, and the spring coefficient of rotation at the supports, were identified.
- (2) After inducement of the artificial damage, the stiffness of the main girder in the damaged region and the spring coefficient of rotation at supports were identified under the condition that the girder stiffness except for damaged region was fixed at the value identified in (1).

Table.3 shows the results of the above procedure. According to the results, the change of natural frequency due to inducement of artificial damage is about 8% i.e. relatively great. The results of the SI method can be seen to show that the spring rigidity of rotation at the supports changed sharply due to inducement of the damage, although this bridge has simple support conditions in its design. In such cases, the SI method considering the spring rigidity of rotation at the supports as the design variables is effective. Identified girder stiffness before inducement of the damages was equivalent to the theoretical value considering the stiffness of concrete in the tensile region, and it agreed with the results of visual inspections and material tests of concrete cores extracted from the target bridge. Also the evaluated degree of damage was then relatively great and qualitatively matched the theory.

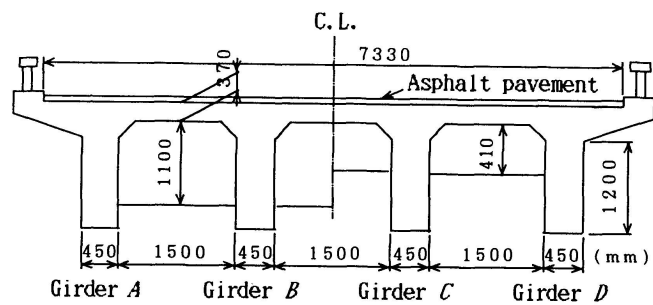


Fig.4 Section of Oyasubashi bridge

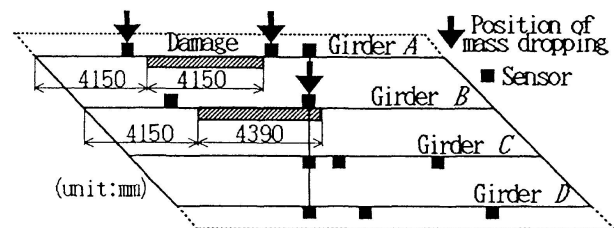


Fig.5 Outline of dynamic loading test

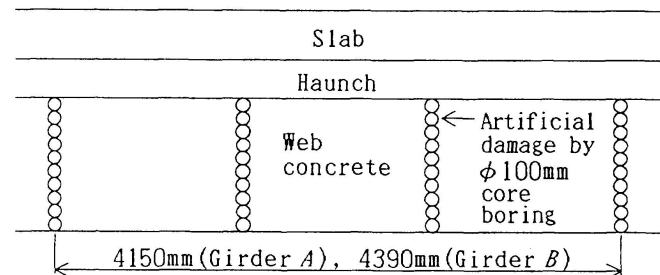


Fig.6 Inducement of artificial damage

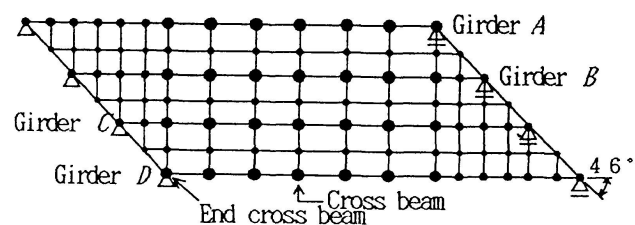


Fig.7 Analysis model for Oyasubashi bridge





Table 1 Results of damage detection for Oyasubashi bridge

	Girder stiffness( $\times 10^{12}$ Kg $\cdot$ cm $^2$ )				Spring rigidity of rotation at supports ( $\times 10^8$ kg $\cdot$ cm/rad)								1st natural frequency  (HZ)
	G i r d e r				G i r d e r								
	A	B	C	D	A		B		C		D		
Theoretical value	7.198	6.755	6.755	7.255	—		—		—		—		—
Identified value without damage	8.242	7.701	7.160	6.346	1.310	1.310	1.100	1.100	0.900	0.900	0.690	0.690	12.69
Identified value with damage	5.496*	5.671*			0.0203	0.0122	0.0100	0.0089	0.0075	0.0073	0.0046	0.0044	11.71

\* : Value at damaged region

#### 4. EFFECTIVENESS OF MODAL PARAMETERS IN DAMAGE DETECTION

##### 4.1 Modeling of bridge with damage

The target bridge is shown in Fig.1, and this was modeled considering partial damage. For the damage condition, the change of damping constant in the region of 0~30% in the region of A, B were assumed.

##### 4.2 Damping characteristics

Fig.8 shows the relationship between the change of damping constant in the damaged area and that for the whole bridge system. For the [1-1]<sup>th</sup> mode of vibration, the sensitivities of damage A and B are the same and have linearity, independently of the change of damping constant in the non-damaged area. On the other hand, according to the results for the [1-2]<sup>th</sup> mode, damage B in girder B which is the node of vibration has no influence on the whole bridge system. Accordingly, localization of the damage can be carried out using the damping characteristics for both the [1-1]<sup>th</sup> and [1-2]<sup>th</sup> modes.

##### 4.3 Phase angle

Fig.9 a)~c) shows the relationship between the change of damping constant in the damaged area and the difference in phase angle for each girder for the [1-1]<sup>th</sup> mode of vibration. Here, the difference in phase angle was evaluated on the basis of the phase angle at the midpoint of girder B. The difference in phase angle in the damaged girder is greatest, in particular, the influence of damage A is significant. The sensitivities of these parameters have linearity independently of the change of damping constant in the non-damaged area. On the other hand, Fig.9 d) shows the result for the [2-1]<sup>th</sup> mode and it can be seen that the sensitivity of damage A is great and the difference in phase angle between girder A and C is about 0.5rad i.e. largest. Accordingly, localization of the damage can be carried out by using these characteristics, similar to the above-mentioned damping characteristics.

##### 4.4 Flow of damage detection based on modal parameters

Fig.10 shows the flow of damage detection by localization and quantification based on the sensitivities of modal parameters to damages. Firstly, a brief evaluation for the location of damage can be carried out using all or a portion of modal parameters constituted by natural frequencies  $f_{1-1}$ ,  $f_{1-2}$ ,  $f_{2-2}$ , damping constants  $\zeta_{1-1}$ ,  $\zeta_{1-2}$ , and phase differences  $\psi_{1-1}$ ,  $\psi_{2-1}$ . At the first

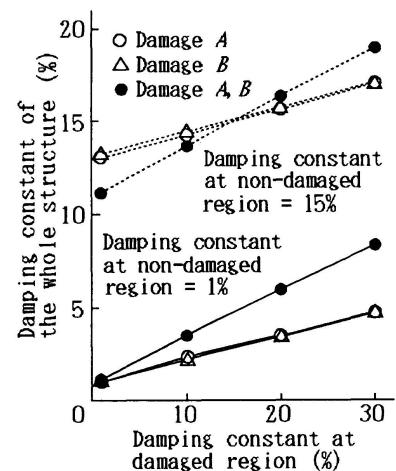
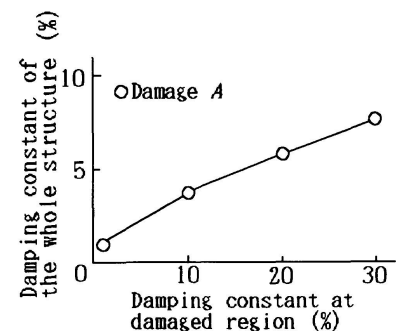
(a) [1-1]<sup>th</sup> mode(b) [1-2]<sup>th</sup> mode

Fig.8 Damping characteristics

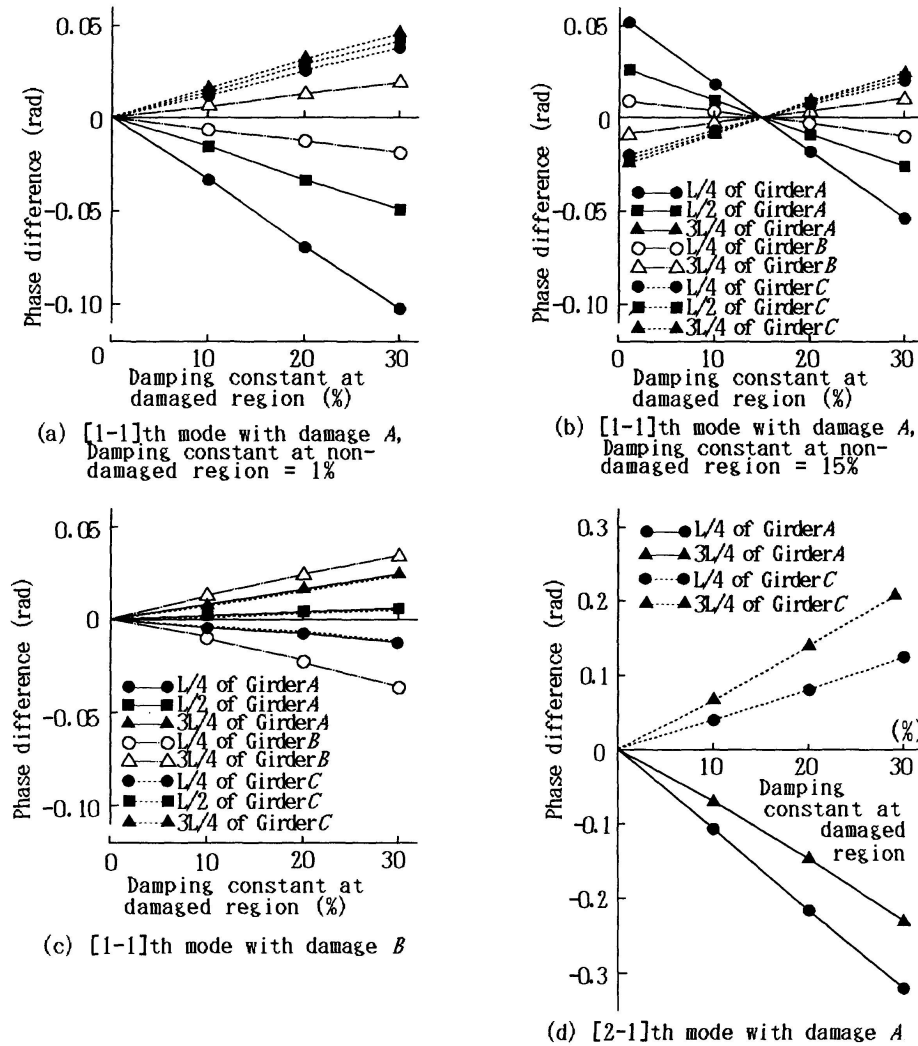


Fig.9 Characteristics of phase angle

step, the existence of damage can be detected by searching whether the parameters ( $f_{1-1}$  and  $f_{2-1}$ ),  $\zeta_{1-1}$ ,  $\psi_{1-1}$  indicate large values. After this, at the second step, localization of the damages i.e. the distinction between damage the inside girder or the outside girder, can be carried out by searching whether parameters  $f_{2-2}$ ,  $\zeta_{1-2}$ ,  $\psi_{2-1}$  indicate large values. Though the above evaluation can be carried out independently for each modal parameter, the final decision for damage detection should be carried out comprehensively by comparison among the results from all parameters. Furthermore, the exact evaluation by localization and quantification of multiple damages can be carried out by the SI method. As the above mentioned procedure, the concise flow and the SI method can be integrated, to enable an efficient damage assessment by the multi-level and multi-aspect approaches.

## 5. CONCLUSIONS

The main conclusions obtained from this study can be summarized as follows:

- (1) For the simplification of analysis of the complex eigenproblem considering non-proportional damping, the CMS method was applied and its suitability was demonstrated.
- (2) The SI method based on dynamic sensitivity analysis and the SLP method has been studied and applied to the results of dynamic loading tests performed on an existing concrete bridge in which some specified artificial damage was induced.
- (3) The sensitivities of dynamic behaviors to damage were evaluated by analysis and the results could be seen to show that the [2-1]<sup>th</sup> and [2-2]<sup>th</sup> natural frequencies, the [1-1]<sup>th</sup>, [1-2]<sup>th</sup> and [2-1]<sup>th</sup> damping constants, and the [1-1]<sup>th</sup> and [2-1]<sup>th</sup> phase differences had high sensitivity.

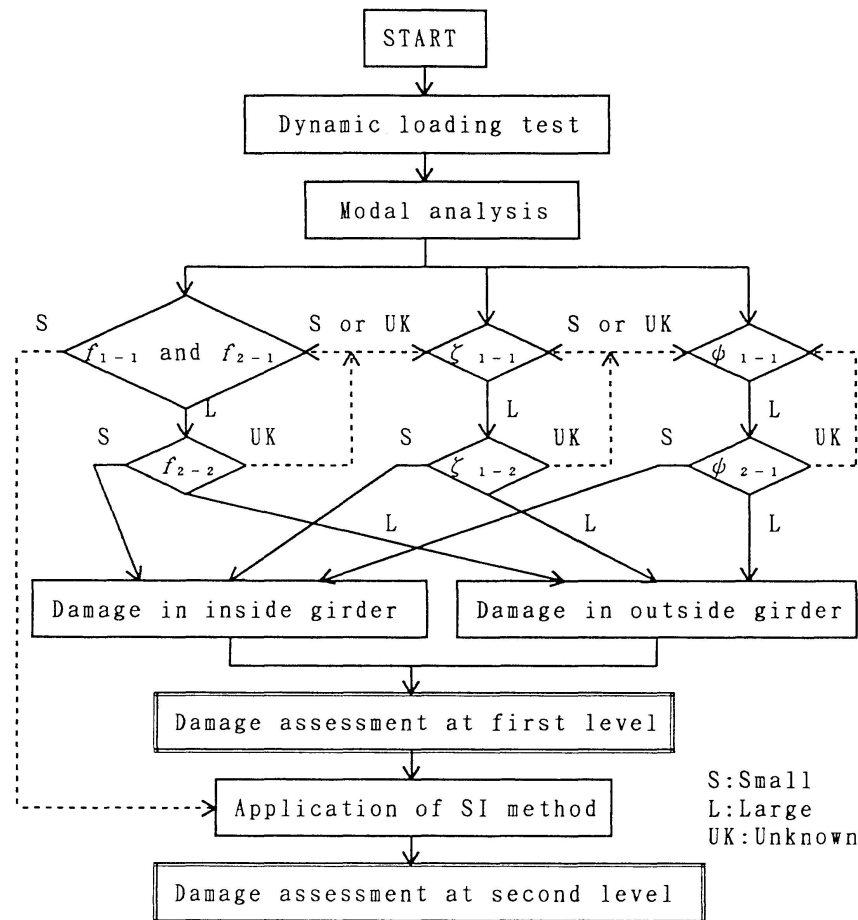


Fig.10 Flow of damage detection

(4) By using these modal parameters, a concise flow of the damage detection without any complex analysis was constructed. Furthermore, this concise flow and the SI method were integrated, to allow efficient damage assessment by multi-level and multi-aspect approaches.

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