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DISCUSSION PRÉPARÉE / VORBEREITETE DISKUSSION / PREPARED DISCUSSION

**The Plastic Design of Braced Multi-Storey Frames**

Calcul plastique de portiques à plusieurs étages renforcés

Plastische Bemessung unverschieblicher Stockwerkrahmen

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University of Cambridge

INTRODUCTION There are two essential steps in the design of a steel frame which is required to carry given loads. First, a set of structural forces must be determined which is in equilibrium with the applied loads; secondly, individual members must be proportioned to carry those equilibrium forces. These two steps cannot always be separated in the design process, as will be seen, but they are in fact logically distinct.

The first step has led to the proliferation of different methods of structural analysis, all of which "are nothing more than a ready way of finding a reasonable equilibrium solution that works in practice" [1]. This situation has been discussed elsewhere [2] with particular reference to the use of plastic theory for finding the basic equilibrium solution. (It may be noted here that the whole of the discussion in the present paper is confined to the case where deflexions are not the primary design criterion. That is, member sizes are determined on the basis of the strengths of the various portions of the structure, and it is assumed that any necessary deflexion checks will be made as a secondary matter).

The use of plastic theory as a design tool implies the use of load factors to give the required margin of safety to the actual structure. Thus the working values of the loads acting on a frame are hypothetically increased to certain factored values, and the frame is then designed to resist the action of those factored loads. The actual value of the factor used in the calculations depends on the type of structure and loading being considered, and is different in



different countries and at different dates. In England it is usual to apply a factor of 1.75 to both dead and superimposed loading in the design of simple factory buildings. However, a recent report [3] on the design of braced multi-story frames recommends the use of the factor 1.5, providing the design is carried out by the methods proposed in the report. This particular recommendation is examined in more detail below.

The function of the load factor is essentially two-fold. In the first place it provides a margin of safety against imperfections in the structure itself, which can be introduced at any stage in the processes of design, fabrication, and erection. Secondly, there is always some uncertainty in the actual values of the loads; that is, the real loading on a structure can only be assessed on a probabilistic basis. Thus the use of a load factor of 1.5, for example, implies that the probability of a 50% overload occurring is acceptably small.

However, a load factor need not be used only in conjunction with a plastic method of design. As an immediate example, the limit state of a column in a multi-storey frame may be governed by elastic instability; in this case, the designer would wish to check that the column remains stable under the factored loading. Again, this particular aspect is discussed more fully below.

THE DESIGN OF BRACED FRAMES There is some measure of agreement about the way in which braced multi-storey frames should be designed, even if considerable differences of detail are apparent between different proposals. Thus the report of a Joint Committee [3] referred to above outlines certain steps that will lead to a satisfactory design, and these steps are reflected, for example, in recent work in the US [4]. The two key moves in the Joint Committee's proposals are (a) the plastic design of the beams, and (b) the use of a limited substitute frame for the stability check of the columns.

Plastic design of beams is usually direct; that is, the determination of suitable equilibrium bending moment diagrams and the actual design of the beams proceed simultaneously. On relatively infrequent occasions it may be necessary to make iterative calculations, for example when a column section proves on later examination to be inadequate to carry the required full plastic moment of the beam. Leaving aside such anomalies, all the beams in a braced multi-storey frame may be designed virtually span by span just to carry the factored dead and superimposed loading.

By contrast all the methods so far developed for column design involve two distinct processes for (a) the determination of column bending moments and

(b) the actual proportioning of a particular column. The Joint Committee

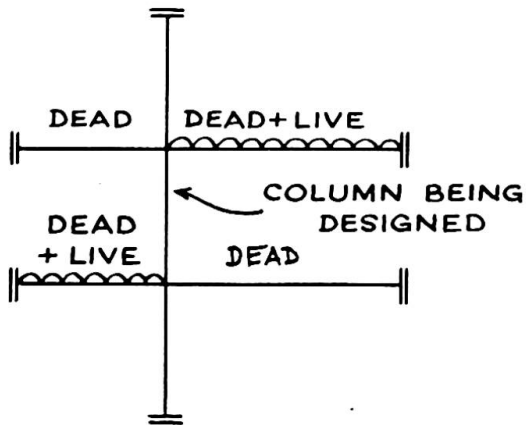


Fig. 1

propose a limited substitute frame that should be considered for the design of each column length; in Fig.1, the column being investigated is regarded as connected to the adjacent members but there is no further "spread" into the structure as a whole. This substitute frame can be traced back to the work of the Steel Structures Research Committee [5], and the use of the frame greatly simplifies the work. The analysis must proceed

by trial and error, since a column size has to be assumed in order to determine the elastic bending moments in the substitute frame. The stiffnesses of the members are calculated, and out-of-balance bending moments are then distributed either by the Hardy Cross method or by a one-step formula given by the Joint Committee.

The Joint Committee requires the calculations to be carried out using factored values of the loads; a typical beam loading pattern is shown in Fig.1, and the load factor 1.5 is supposed to be applied to both dead and live (superimposed) loading. Now, under full factored dead plus live loading, a beam will be on the point of collapse, and the state of the substitute frame of Fig. 1 will be as shown in Fig.2(a). The collapsing beams cannot absorb any further

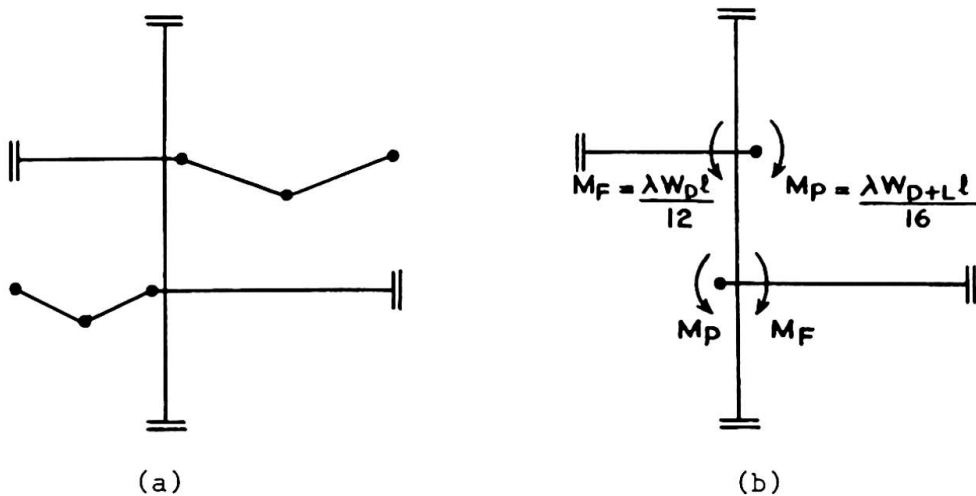


Fig. 2

bending moment, and, in any moment distribution process, their stiffnesses must be assumed to be zero. The reduced substitute frame of Fig.2(b) is therefore used for checking the columns under these conditions; the collapsing beams have been replaced by "dead" moments of value  $M_p$ .

The out-of-balance bending moments in Fig.2(b) are distributed, and lead to values of terminal bending moments in the central column length; these values, together with that of the (factored) axial load, can then be used to check the suitability of the chosen column according to any required criterion (e.g. stability or the condition that the column shall just remain elastic).

There seem to be two anomalies in the method just outlined, the discussion of one of which is straightforward. In the first place, it is clear that more severe conditions would arise for the central column length in Fig.2(b) if the dead load moments ( $M_F$ ), opposing the full plastic moments ( $M_p$ ), were not factored. The use of an overall load factor (of value 1.5) on both dead and live loading allows the dead load to partially relieve the bending moments. In such cases, it might be appropriate to use a load factor of unity on the dead load, or of value 0.9 in accordance, for example, with current recommendations [6] on limit state design or with the French regulations for steelwork [7]. Thus the value of  $M_F$  in Fig.2(b) should be calculated with the factor  $\lambda$  set equal to unity or 0.9.

Retaining, however, the notion of an overall load factor of 1.5 to be applied to both dead and live loading, there is another sense in which the frames of Fig.2 may be criticized. Had the calculations of column moments been made under working values of the loads for the pattern shown in Fig.1, then there would have been no question of any of the beams collapsing. The fixed-end moments at the ends of the loaded beams would then have values  $W_{D+L} \ell / 12$ , as shown in Fig.3, instead of the values  $\lambda W_{D+L} \ell / 16$  of Fig.3. In addition,

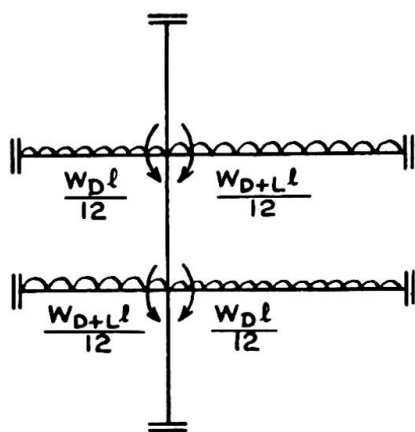


Fig. 3

the stiffnesses of all the beams should have their full values in the distribution process.

A numerical example (below) confirms that the column moments resulting from Fig.3, when post-multiplied by the load factor, can exceed the moments resulting from Fig.2(b), in which the loading is pre-multiplied by the load factor. It becomes essential at this point to be clear about the nature of the check that

is made to confirm the suitability of the columns.

The column is a potentially unstable structural element, and, if the designer is to be completely assured of the safety of an entire structure, he must be satisfied that there is no danger of premature failure due to instability. Thus there must be an adequate margin of safety between the values of end moments and axial thrust computed for a particular column length and the corresponding values that would just cause failure of the column. If the calculations are made for the nominal working values of the loads, Fig.3, the column can be computed to have a certain margin of safety, and this margin may well be less than that given by the apparently more "real" configuration of Fig.2(b).

SAMPLE COLUMN CALCULATIONS The design of a large laboratory block has been reported [8], and some of the calculations afford a convenient basis for comparison. Fig.4 shows the three substitute frames for the calculations for a

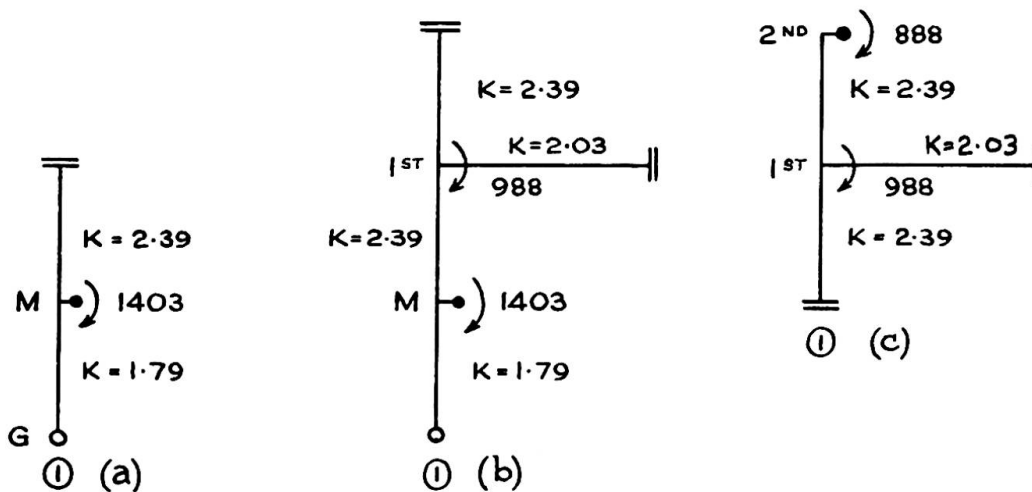


Fig. 4

typical external column; the column length under consideration is the lowest, centre and upper storey in Figs.4(a), (b) and (c) respectively. Note the introduction of the plastic hinges in accordance with Fig.2. The resulting bending moments in the individual column lengths are shown in Fig.5. A load factor of 1.5 has been used in these calculations, and the axial loads marked in Fig.5 are factored values.

The calculations made for unit load factor proceed using the substitute frames shown in Fig.6. The resulting bending moments are shown in Fig.7, to be compared with the values marked in Fig. 5. Comparing these two figures, it will

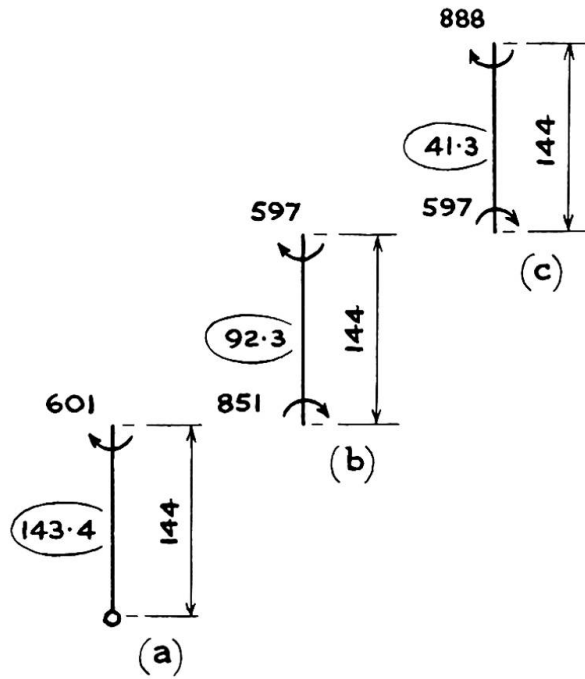


Fig. 5

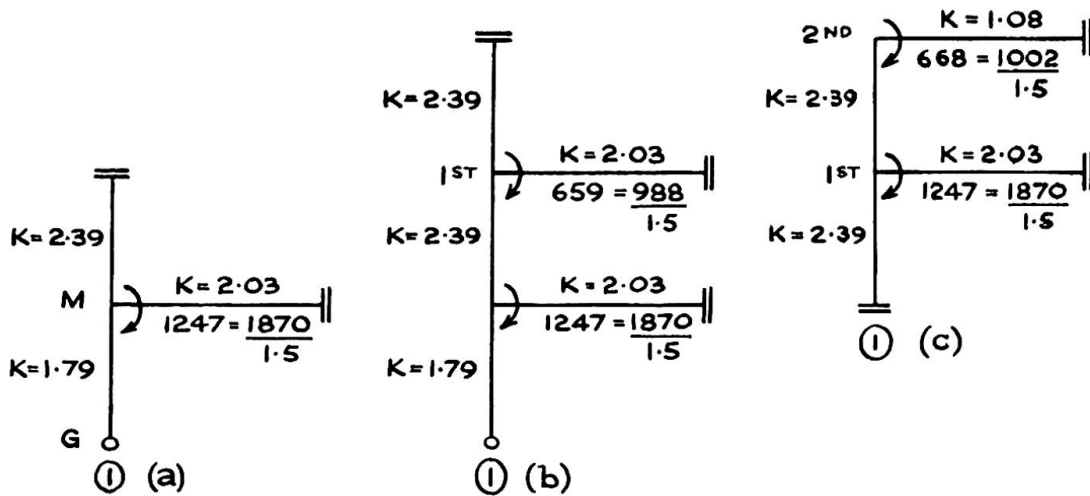


Fig. 6

be seen that for this case of an external column, the original design approach, using factored loads, leads to the more severe design condition. This result is typical for external columns, but the reverse is true for internal columns.

Fig. 8 reproduces the design conditions for an internal column [8], and Figs. 8(b) and (c) show the factored design conditions for single and double curvature bending. The alternative calculations using working loads and a completely elastic frame, are displayed in Fig. 9. It will be seen that the resulting bending moments in the column when post-multiplied by the load factor

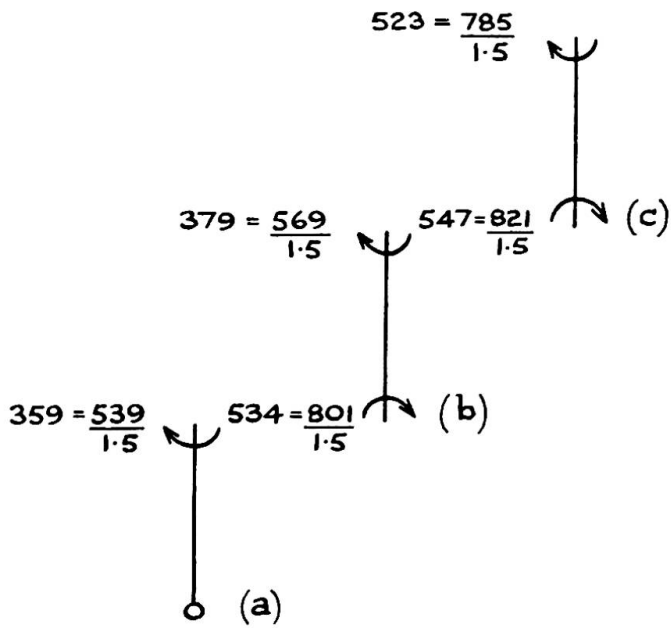


Fig. 7

1.5, are some 50% higher than the corresponding bending moments marked in Fig. 8.

Thus the apparent margin of safety would be less if the calculations were performed according to the substitute frame of Fig. 9 rather than that of Fig. 8.

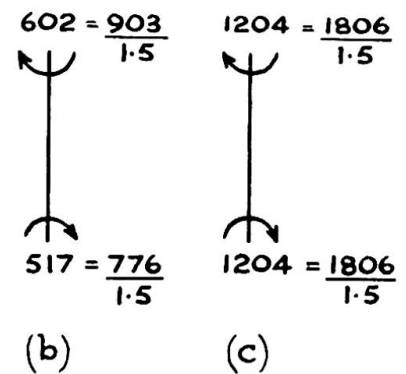
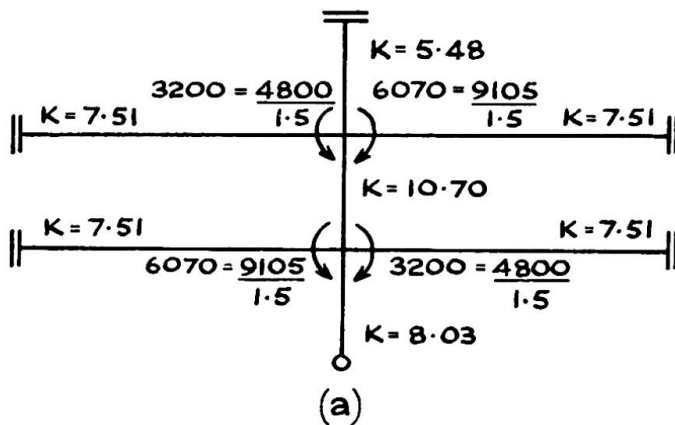
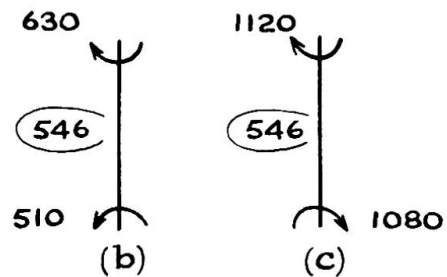
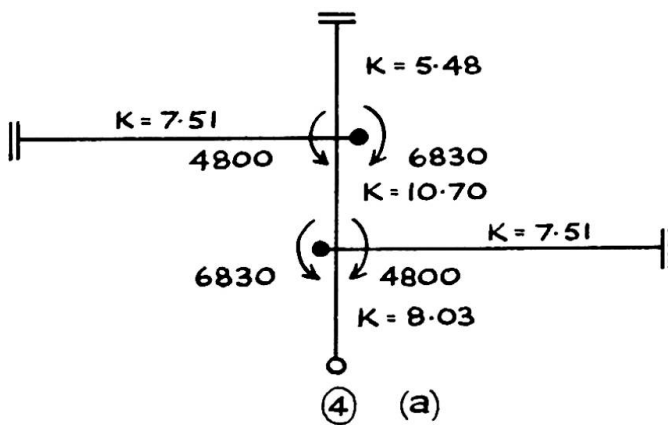


Fig. 9

DISCUSSION In a sense, this Paper is nothing more than an attempt to consider the concept of load factor which is so important in the design process. The idea of working loads gradually increased in proportion leads on the one hand to the idea of plastic collapse of a steel frame (which can be observed readily and accurately both in the laboratory and in the field), and on the other to the mathematical development of master theorems of structural design, concerned, for example, with the overall safety of a frame. The fact remains that the concept of a collapse load factor is reflected only in an insignificantly small probability of an actual overload of a real structure in practice. It is the nominal working loads that are of interest, and, in this sense, plastic theory is an easy and economical way of designing a frame under working loads.

There are no difficulties in the calculations by simple plastic theory of the beams in a multi-storey frame; The ratio collapse load to working load can be calculated uniquely for each beam. However, the determination of elastic bending moments in the columns is sensitive to the development of plastic hinges in the beams. Thus the apparent margin of safety of a column will depend on whether the calculations are made for the working values of the loads or for their fully-factored collapse values. If the second approach is adopted, and an attempt made to allow for the "real" behaviour of the frame by the insertion of plastic hinges in the beams, then less severe conditions may arise for the columns than if the frame were assumed to remain completely elastic.

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## SUMMARY

A convenient way of making the design of a multi-storey braced frame is to allow a plastic method for the beams, and to ensure that the columns remain elastic and stable under all loading conditions. The plastic design of beams is straightforward, but the determination of the worst loading conditions for the columns is more difficult; a limited substitute frame can greatly shorten the work. The use of a load factor requires some care, or designs can result which are less safe than those intended by the designer.

## RÉSUMÉ

Une façon pratique de projeter un portique à plusieurs étages renforcé consiste à dépasser la limite d'élasticité seulement pour les poutres, en garantissant que les colonnes restent élastiques et stables dans tous les cas de charge. Le calcul plastique des poutres est simple, mais la détermination du cas de charge déterminant pour les colonnes est plus difficile; un portique-modèle simplifié peut raccourcir le travail considérablement. Des précautions sont requises lors de l'utilisation d'un facteur de charge, sinon il pourrait résulter des constructions d'une moins grande sécurité que projetée.



## ZUSAMMENFASSUNG

Ein gangbarer Weg, die Bemessung unverschieblicher Stockwerkrahmen vorzunehmen, besteht darin, für die Riegel plastische Rechnung zu erlauben, während für die Stützen angenommen wird, dass diese elastisch und für alle Lasten stabil bleiben. Einfach ist die plastische Bemessung für die Riegel, hingegen bereitet die Bestimmung der schlimmsten Laststellung für die Stützen Schwierigkeiten; ein begrenzter Ersatzrahmen kann die Rechnung erheblich kürzen. Die Verwendung der Lastfaktoren erfordert Sorgfalt, sonst kann die Bemessung unsicherer als diejenige des Verfassers sein.

### IIIa

#### Plastic Design

Calcul en plasticité

Plastische Bemessung

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It is appropriate to consider at the outset the basic principles underlying the theory of plastic design of steel structures and to compare this theory with its predecessor, the elastic theory. The elastic design is based on the working loads, a conservative but realistic set of loads that may be actually applied to the structure, and the allowable unit stresses, which must not be exceeded under the most unfavourable load combinations. The stress analysis is supposed to be conducted in conformity with the acceptable theory and the current engineering practice, and this of course implies a tacit acceptance of some degree of error. The allowable stress forms a certain fraction of the yield stress of structural steel of the particular grade used, and the reciprocal of this fraction is usually called the factor of safety. This factor is in effect the factor of ignorance covering a multitude of uncertainties and faults of all kinds associated with design, detailing, fabrication, construction, loads, materials, etc. It covers also, to some extent, mistakes which may be expected in design, as in all human activities.

Plastic design, on the other hand, restricted in its application to statically indeterminate flexural frames, is concerned not with the working but with the failure condition of the structure, which is defined as a state of a very large deformation. This condition is expected to be attained under a load whose intensity exceeds the working load by a quantity known as the load factor or, more correctly, the overload factor. This factor is the equivalent of the factor of ignorance of the elastic design. Nominally the overload factor provides for no uncertainties other than in loads; actually, of course it does provide for them in an indirect way, and in doing this it ceases to be a measure of overload in view of the variability of the other relevant factors involved. The load factor is thus another variety of the factor of safety-factor of ignorance, somewhat misnamed, and in no way better in principle than its conventional counterpart.

The implications involved in the existence of the two acceptable but different factors of safety were apparently not appreciated at the time of incorporation of plastic design into the American and Canadian specifications. As it stands now, a structure may be found as underdesigned by the elastic standards and overdesigned by the plastic. An elastic designer could justify the same structure on the basis of a higher allowable stress,

but the specifications would not permit this. Yet if he changes his approach to plastic the weak design becomes acceptable, —a situation hardly making any sense. A coexistence of two distinct and contradictory systems is no more rational in engineering practice than in any other realm of human endeavours.

The pioneers of plastic design claimed the advantages of their method over its elastic counterpart in the simplicity of calculation, requiring no recourse to indeterminate theory, and in the economy of the resultant structure. This, however, was before they fully realized that the mechanism theory, used in plastic design, while elegant in its simplicity, is insufficient for practical purposes, and that the examinations of instability of the structure and of the change in its geometry are all-important. (This is the field of the so-called non-rigid plastic theory). With instability occurring under partly elastic and partly inelastic conditions the plastic theory suddenly became a most complex assembly of numerous assumptions and hypotheses claimed to be justified by experimental evidence, which however strikes an independent observer as limited and questionable. The alleged economy of the theory also became doubtful in certain areas. Here are some other major uncertainties of plastic theory.

Flexural strength of a member is proportional to its yield strength, but this property of the material is highly indeterminate, varying by more than 50% from the average value for the same grade of structural steel.

Realistic treatment of live and other variable loads, comparable to the procedures used in the elastic design, is not available. There exist highly complicated plastic theories of incremental failure and alternating plasticity but the value of the load factor with which these theories must be associated is unknown apart from the fact that it should be smaller than the one used in the conventional plastic design, because failure under live load requires numerous applications of the load of limiting intensity, while a heavy steady load causes failure in a single application. To the writer's knowledge no attempts to correlate the two plastic load factors have ever been made.

There are no procedures or methods in existence of the non-rigid plastic analysis, as distinct from design; in other words there is no way to determine the load factor of a structure not conforming to the empirical formulae prescribed for prevention of different types of instability.

It is appropriate at this stage to make reference to the common criticism of the elastic theory advanced by the plasticians, that the allowable stress used in this theory is a fiction, because it excludes several participation stresses, (i.e. non-load-carrying stresses), like local stress concentrations, residual stresses etc. This criticism is invalid because the exclusion of the participation stresses is intentional. The non-load-carrying stresses must be excluded, because such

is the nature of the elastic theory and not because the theory is incomplete or inaccurate. A comprehensive review of the weaknesses of plastic theory may be found in the writer's papers (50), (51), (52).

The preceding discussion has been directed mostly at the plastic design of low frames. Tall or multi-storey frames, restrained from sidesway by rigid cores or diagonal bracing, are not too different in their action from the low frames.

In the design of tall frames with sidesway it is necessary to contemplate not only the instability of the individual members but also of the whole frame or its major parts. This compounds the difficulties and calls for more assumptions. The situation may be illustrated on the approach proposed by Professor Horne. He uses an empirical relation in which the true load factor is expressed through two others: the rigid plastic, which ignores instability, and the fully elastic. Since the latter is impossible to find, it is replaced by pseudo-elastic factor based on an imaginary rigid-plastic-rigid stress-strain relationship of the material. Apparently the proponent of the method expects designers to use it for all structures including the ones involving human occupancy. The writer can hardly share this view. His detailed appraisal of the method is found in his discussion of the Horne's paper (53).

The statement made earlier to the effect that the elastic and plastic factors of safety and overload are two different but equally legitimate in principle factors of ignorance, must be re-evaluated now. From all that has just been said, the writer feels that the difficulties encountered in the development of plastic theory have proved unsurmountable and the theory failed signally to live up to its claims.

There is however, something to say in favour of the plastic theory of low frames. Firstly, it assists in understanding structural behaviour of frames by giving an insight into their action at failure, and secondly, it points to desirability of using a variable allowable stress in the conventional elastic design and provides information for establishment of its numerical values. As an alternative to the elastic method of design the plastic theory is unnecessary. Its alleged rationality and economy are pure fictions, and its existence alongside the elastic design merely exposes a deficiency of logic in the specifications. Attempts to apply plastic design to multi-story buildings have no justification. Elastic design of a tall building, allowing for the deformation of the structure under load is complex enough even with the use of electronic computer and iteration procedure. The same problem under elasto-plastic conditions appears insoluble, and the attempts at its solution with the assistance of the proposed simplifying assumptions, seem unreliable.

The inclusion of plastic theory in the design specifications is mostly the work of the American plasticians, and their failure to meet and to counter, if possible, the closely defined objections of the opponents tends to cast further doubt on the validity and the applicability of their

theory. The continued research activity in the field of plastic design is no proof of its soundness, but is merely a testimonial to the tenacity of its proponents and to the availability of liberal funds.

The writer feels that the author's characterization of the method of plastic design as "by no means complete" is much too moderate.

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#### SUMMARY

Although in principle the plastic design in steel is comparable to the conventional elastic design, in actuality it is inferior to it for several reasons, including the inability to analyze different types of buckling failure, the difficulty with the live load action and the wide variability of the plastic properties in the same grade of the material. The existence in the specifications of two distinct but equally acceptable methods of design the elastic and the plastic, leading to different solutions, is unsound.

#### RÉSUMÉ

En principe, l'analyse plastique et l'analyse élastique conventionnelle se valent dans la construction métallique. En fait, l'analyse plastique est inférieure à bien des égards: Par exemple par son incapacité d'analyser plusieurs types de ruine par voilement, la difficulté qu'on a avec l'action de la charge de service et les grandes divergences des propriétés plastiques dans une même qualité de matériau. Il n'est donc guère justifié de parler du calcul élastique et du calcul plastique comme de deux méthodes également valables, mais conduisant à des résultats différents.

## ZUSAMMENFASSUNG

Obwohl die plastische Berechnungsmethode im Stahlbau im allgemeinen mit der konventionellen, elastischen Methode vergleichbar ist, so ist sie ihr doch aus verschiedenen Gründen unterlegen, inbegriffen die Unfähigkeit, verschiedene Bruchformen aus Beulen zu analysieren, sowie die Schwierigkeit der Verkehrslastbewegung und die weite Streuung der Plastizitätswerte desselben Materials. Es ist also nicht stichhaltig, von zwei gleich annehmbaren, ebenbürtigen Berechnungsmethoden zu reden, nämlich der elastischen und der plastischen, die zu verschiedenen Ergebnissen führen.

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### IIIa

#### **Research on Plastic Design of Multi-Story Frames at Lehigh University**

Recherche sur le calcul plastique des portiques multiétagés à l'Université de Lehigh

Forschung über das Traglastverfahren von Stahlhochbaurahmen an der Lehigh Universität

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#### 1) Introduction

The research team at the Fritz Engineering Laboratory of Lehigh University has extended a major effort since 1958 to the development of Plastic Design Methods for Planar Multi-Story Steel Frames. The principal motivation of this effort was the conviction that Plastic Design is both more rational and more economical than Allowable-Stress Design.

This research work can be subdivided into the following categories:

- 1) Research on Component behavior
- 2) Development of design and analysis methods
- 3) Experimental verification on frames

The summary of this research, as well as design methods and design examples for braced and unbraced multi-story frames, is given in Ref. 33 of the general report by Messrs. Steinhardt and Beer. The following brief comments are a review of the present status of this research and they are intended to provide additional information to that given in the General Report, especially emphasizing the Lehigh work.

#### 2) Studies on Component and Subassemblage Behavior

A knowledge of the load-deformation behavior of the components of a structure is basic information required for a structural analysis. All the various components of a structure, such as wide-flange beams and beam-columns and many types of connections, were studied in several major research programs. In addition, the load-deformation behavior of subassemblages consisting of several members was thoroughly investigated. The purpose of this research has been the need to define the geometric and material limits which must be fulfilled for a successful application of Plastic Design procedures.



In the inelastic range the load-deformation relationship is highly non-linear, and it depends on yielding, strain-hardening, geometry changes, initial imperfections and on lateral-torsional and local buckling. A typical moment-rotation curve for a beam (Fig. 1) illustrates the initial elastic behavior (OA), the reduction in stiffness due to yielding in the presence of strain-hardening (AB), the point of instability due to combined local and lateral-torsional buckling (C) and the reduction of moment capacity in the unloading range (CD). The relationship is usually idealized in plastic design as a rigid-plastic (EF) or an elastic-plastic (OGF) relationship. However, some analysis methods utilize a bilinear curve (OGI) (Ref. 1) and in some applications the actual complete M- $\theta$  curve of beam-columns is utilized (Ref. 2, for example).

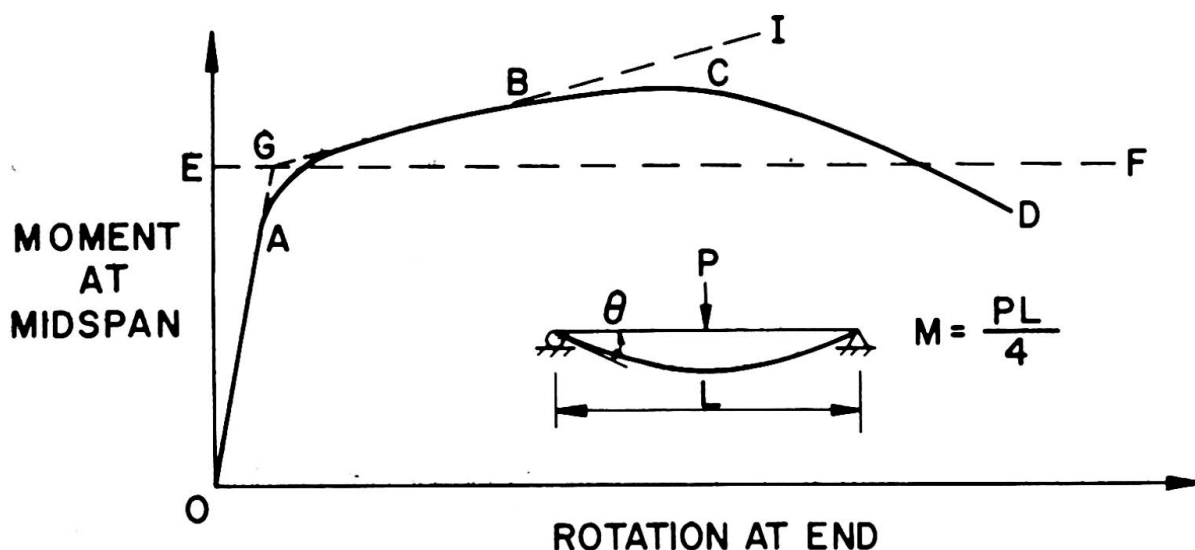


Fig. 1 Moment-Rotation Relationship of Beam

The research on components has concentrated on developing theoretical models whereby the whole M- $\theta$  curve, or significant portions of it, can be predicted. Many experiments were also performed to substantiate or complement these theoretical predictions.

#### Research on Beams

Numerous experiments were performed on wide-flange beams under uniform moment (Ref. 3) and moment gradient (Ref. 4), with various types of lateral bracing (Ref. 5), and on beams of high strength steel (Ref. 6), to study the post-yield behavior. Theoretical models, based on the concept that failure results when local and lateral-torsional buckling occur simultaneously, permitted a prediction of the limits of inelastic rotation capacity, and a definition of the required maximum flange and web width-thickness ratios and maximum bracing spacing (Refs. 7 through 12). For example, the maximum flange width-thickness ratios for steels with yield points of 36 and 50 ksi, respectively, were found to be 18 and 14. The corresponding maximum unbraced lengths for beams under uniform moment were determined to be, respectively,  $38r_y$  and  $28r_y$ , where  $r_y$  is the weak axis radius of gyration.

### Research on Beam-Columns

This work concentrated on the theoretical determination of the in-plane end moment-versus-end rotation curves of beam-columns, extending the work of Chwalla (Ref. 12.28 of the general report) to wide-flange members containing residual stress (Refs. 13 and 14; a summary of this work is given in Chap. 9 of Ref. 33 of the general report). The solution of the problem was achieved by numerical integration procedures, and non-dimensional curves for use in design are presented in Ref. 15. Experiments have given excellent verification of the theoretically obtained curves over a wide-range of the relevant parameters (Refs. 16 and 17). Theoretical studies on inelastic lateral-torsional buckling of unbraced beam-columns bent about their major axis have also shown good agreement with experiments (Refs. 18 and 19). Design procedures, based on this research, have been developed. These are summarized in Chap. 4 of Ref. 33 cited in the general report.

### Research on Connections

Extensive experimental programs were performed on various types of rigid corner connections and rigid beam-to-column connections (for a review of this work see Chap. 8 of Ref. 12.27 of the general report). Design procedures, based on this work, were developed to assure that connections have adequate rotation capacity and a greater moment capacity than the members to be joined. These procedures are summarized in Chap. 5 of Ref. 33 given in the general report.

### Research on Subassemblages

The basic design element for multi-story frames was found to be a "subassembly" consisting of one beam-column with a restraining beam framing into it at its upper and lower end. The load-deformation behavior of such a subassembly can be determined, using equilibrium, compatibility, and the moment-rotation relationships of its three elements (Chaps. 9, 10 and 17 in Ref. 33 of the general report and Refs. 2 and 20). Excellent correlation was noted between theoretically predicted and experimentally measured behavior (Ref. 17). These tests also provided experimental confirmation of individual beam, beam-column and connection behavior.

### 3) Frame Design Procedures

Following a phase of planning and layout, the design and analysis procedure can be divided roughly into three phases. These are (1) preliminary analysis, (2) selection of members, and (3) evaluation and revision of the preliminary design. The challenge in the preliminary analysis is to determine sets of forces on each member resulting from the expected loading which will permit selection of members in a straightforward fashion while using the knowledge which has been gained about component behavior. Frequently, the preliminary forces must be determined based on very limited information about the actual member sizes of the structure. It is also highly desirable that the preliminary force information be obtained in a form which permits selection of member sizes with a minimum of additional computation. Member selection should be followed by procedures for evaluation of the design or at least give a conservative measure of the relative performance of the structure. Evaluation procedures which will do an accurate job for a localized portion of the structure are especially

valuable. They permit revision of an unsuitable design before proceeding to additional parts of the structure.

#### 4) Design of Braced Frames

The development of preliminary analysis and design procedures for braced frames resulted in methods which were exactly what would have been expected on the basis of earlier methods for low buildings. Beams were designed to develop three-hinge mechanisms in the clear span between column flange faces under full factored gravity load. The end moments of the beams were distributed arbitrarily to the columns above and below each joint, but can be justified by some other distribution. Though this practice might seem questionable to some, the lower bound theorem may be interpreted as supporting it. If only one distribution of internal forces could support the applied loads without violating the plasticity conditions, it would have to be the correct distribution of forces.

Design procedures for x-type diagonal bracing were formulated on the assumption that slender members would be used which could only carry tension and would buckle in the elastic range under compression. The bracing members were assumed to carry all lateral shears and to resist all shears due to the  $P\Delta$  effect in simple truss action without assistance from the frame. Evaluation of the probable actual behavior of such a structural system would reveal that the frame must accept part of the lateral shear in order to deform sufficiently to allow the bracing members to deform enough to accept the lateral force. The usual design practice imposing a smaller load factor for gravity loads in combination with wind or earthquake loads allows the frame designed for gravity loads to retain some capacity for resisting lateral loads in combination with the diagonal bracing. Of course some revisions may be necessary in beams and columns adjacent to the diagonal bracing in order to resist axial force components imposed by the diagonal members.

Summaries of the design methods for braced frames are given in Refs. 21, 22 and 23.

#### 5) Tests of Braced Frames

Tests of four frames which approximate the concepts of Steinhardt and Beer's Fig. 4a and 5a have been made. (Refs. 24, 25 and 26) All four frames had three 10 ft. stories and two 15 ft. bays but they were subjected to different combinations of loading. Twelve inch deep beams and 6W columns were used in all frames. Fig. 2 shows a load-deflection curve of one of the tests and a comparison typical of all the tests with a theoretical prediction ignoring the  $P\Delta$  effect. The photograph in Fig. 2 shows the loading frame used to support the specimen laterally so a single plane frame could be tested alone. Also shown is the system of gravity load simulator devices which allow the application of truly vertical loads even though the frame sways laterally in its plane. The details of the experimental techniques are given in Ref. 27.

Conclusions of the test series were that lateral loading had no significant effect on the ability of the frames to reach the vertical load predicted on the basis of first order theory. Diagonal bracing carried most of the lateral load and the rigid frame was required to resist only 14 to 26 percent of the total lateral load. Very slender brac-

ing performed best when it was tightened during erection so that sag and slack were removed and diagonals subject to compression would remain in tension until the maximum expected lateral load was applied to the frame.

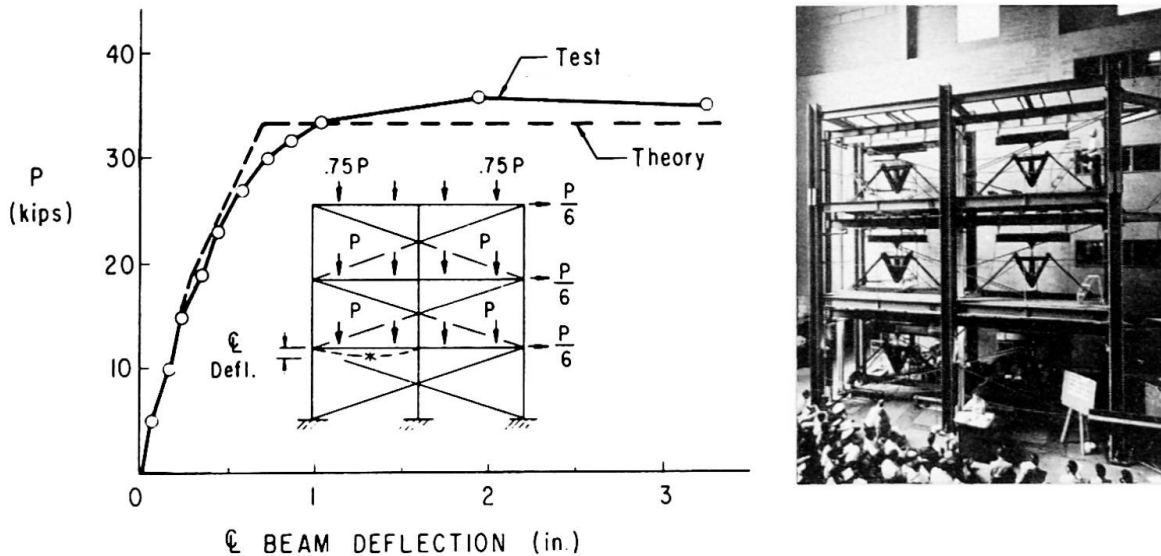


Fig. 2 Results of Braced Frame Test

#### 6) Design and Analysis Procedures for Unbraced Frames

Three key quantities based on elementary statics form the basis of preliminary design procedures for unbraced frames subjected to combined gravity and wind or earthquake loading. A sum of column end moments in a story can be based on the total shear in the story caused by lateral loads and the  $P\Delta$  effect initially estimated from an assumed story sway. The sum of girder end moments within one floor level can be based on an arbitrary reasonable assignment (such as one-half) of the sums of column end moments in the stories immediately above and below the floor. The third key quantity is the limiting end moment of a framed girder subjected to transverse loads in combination with the anti-symmetric moment pattern resulting from lateral loads. Many current design proposals avoid this issue by placing all loads at the joints, but this does not reflect the actual capacity of the members. For most loadings there will be a substantial beam moment at the lee column due to gravity load alone. Addition of the lateral loading causes this moment to increase to the plastic hinge value rapidly, thus revising the strength and stiffness characteristics of the beam for the duration of loading. Design charts giving important ordinates of the moment diagrams for usual loadings are available (Ref. 33 of the general report and Ref. 28).

The final operation of the analysis made for preliminary design purposes is a process called moment balancing. This process is primarily a "bookkeeping" method for assigning the general sums of column and girder end moments determined from prior steps to discrete locations within the story so that beams and columns may be selected each for their own separate force system.

Progress is being made in developing computer programs to parallel the manual computation procedures for preliminary design of unbraced frames. A program has been developed to handle the routine effort of tabulating forces on each member from tributary areas of floors, calcu-

lating story moments and shears, and performing the moment balance to determine all beam and column moments (Ref. 29). The designer then needs to select beams from standard economy tables for plastic design and columns from design charts of reduced plastic moments.

The trial design resulting from the preliminary procedure reflects a complete disregard of compatibility and an assumed story sway which is at best a guess. The subassembly method of analysis has been developed to give an insight into the probable behavior of the structure selected (Refs. 30 and 31). This method uses the properties of the actual members to determine both the load vs. lateral deflection behavior of individual subassemblies and the behavior of a larger assemblage consisting of a whole story. It is necessary to construct load-deflection curves for each column in a story from design charts and then combine the curves for a whole story in order to use the subassembly method manually. The complexity of this process is currently the largest barrier to practical application of plastic design of unbraced multi-story frames. Fortunately a computer program in the FORTRAN Language has been developed to compute the complete load-deflection curve for a story having known member sizes (Ref. 28).

Another computer program gives the elastic-plastic second order load-deflection curve of a complete unbraced multi-story frame up to maximum load (Ref. 32). It uses an iterative process for solution and requires surprisingly little computer capacity to handle frames up to thirty stories high and five bays wide. The disadvantage of such a program is that it ceases to function when it reaches the maximum load of the frame. Information as to the true relative suitability of less heavily loaded portions of the structure is lacking. This points up the main advantage of the other computer program based on the subassembly method which discloses maximum strength of each story as well as deflections in the elastic range.

### 7) Tests of Unbraced Frames

Two series of unbraced frame tests were conducted. One series resulted from a frame stability investigation (Ref. 33). Two three-story frames 10 ft. wide were tested. Beams were 6 in. deep members and columns were 4 inch wide-flange members with strong axis slenderness ratios of 40 or 45. A typical test result is shown in Fig. 3.

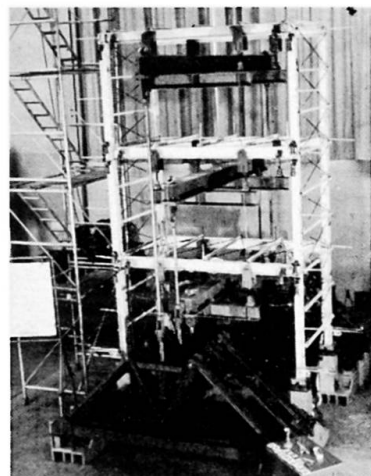
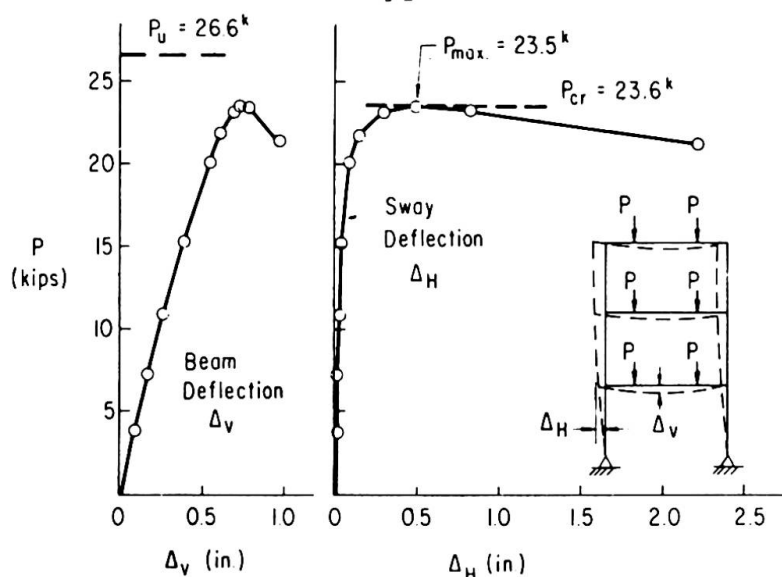


Fig. 3 Results of Frame Buckling Test



Results show that the reduction of the frame buckling load below the load to form a mechanism was predictable. The best method of prediction was a small lateral load method which used a load-deflection solution for the vertically loaded frame subjected to a simultaneous lateral load of one percent of vertical load or less. Both buckling test results exceeded the prediction based on an accidental lateral load equal to one-half percent of the vertical load.

The second series of unbraced frame tests was conducted on two three-story one-bay frames and one three-story two-bay frame subjected to combined vertical and horizontal loads in the plane of the frames (Ref. 34). All stories were 10 ft. high and all bays were 15 ft. wide. Various combinations of 8, 10 and 12 inch deep beams were used with 5 and 6 inch deep columns. A typical test result is shown in Fig. 4. The inadequacy of the first-order theory for prediction of behavior was de-

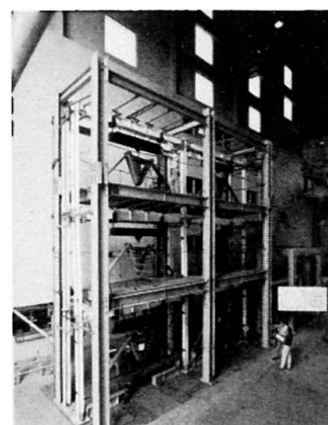
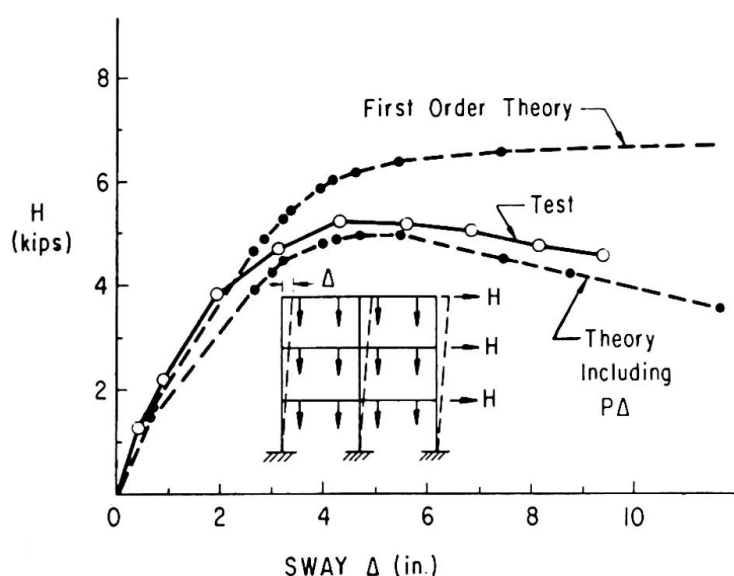


Fig. 4 Results of Unbraced Frame Tests

monstrated. Adequate predictions were obtained by using a linearized elastic-plastic second-order analysis which considered the  $P\Delta$  a small number of cycles of reversed static loading providing data to assist in future earthquake resistant design studies.

## 8. Summary

The brief review of the research on component behavior shows the importance which was attached to the attainment of an understanding of the limiting capacity of beams, beam-columns and connections. Without such an understanding, Plastic Design would be impossible. Fortunately, the limits imposed by the component capacities can be achieved in practical design without offsetting the advantages of economy gained by Plastic Design of the total structure.

The understanding of component behavior is by no means complete. Many problems remain to be solved. Among these the following are currently under study: biaxial bending of beam columns, subassemblies with unbraced beam-columns, the post-yield material properties of new types

of high-strength steel, web local buckling, and behavior of components under repetitive reversed loading into the plastic range. Furthermore, the behavior of connections and of beams under moment gradient is under renewed study.

The outlook for adoption of a plastic design method for braced multi-story frames is promising. The 1968 revision of the American Institute of Steel Construction Specification will extend plastic design coverage to braced multi-story steel frames will soon be published and distributed (Ref. 23). It is significant to note that the plastic design method has already been applied successfully to the design of a braced eleven-story apartment building (Ref. 35).

The continuing efforts to produce practical methods for unbraced frames should bear fruit in the not-so-distant future. Experience with and refinement of these new methods can be expected to eventually lead to the economic limit of ordinary beam and columns skeleton type framing. There is no need to apologize when these limits are reached. The knowledge gained about component behavior and new procedures will help when new and better framing systems are developed.

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## SUMMARY

The research team at the Fritz Engineering Laboratory of Lehigh University has extended a major effort since 1958 to the development of Plastic Design Methods for Planar Multi-Story Steel Frames. The highlights of this work are presented in this discussion. The following topics are described: 1) component behavior, 2) development of design and analysis methods, and 3) experimental verification on frames.

## RÉSUMÉ

L' équipe de recherche du Fritz Engineering Laboratory de l' université de Lehigh a porté, depuis 1958, son principal effort dans le domaine des méthodes de calcul plastique pour des structures multi-étagées planes en acier. Les résultats de ces recherches avancées sont présentés dans cet exposé. Les sujets suivants sont décrits: 1) facteurs impliqués dans le comportement des structures, 2) exposé du calcul et des méthodes d'analyses, et 3) vérification expérimentale sur portiques.

## ZUSAMMENFASSUNG

Die Forschungsgruppe des Fritz Engineering Laboratory an der Lehigh Universität hat seit 1958 einen erheblichen Aufwand gemacht an der Entwicklung des Traglastverfahrens für ebene Stahlochbaurahmen. Die wichtigsten Erfolge dieser Forschung sind hier zusammengefasst. Die folgende Themen werden beschrieben: 1) das Verhalten von Fachwerkskomponenten, 2) die Entwicklung von Methoden für Dimensionierung und für Berechnung der Traglast, und 3) experimentelle Prüfung an Rahmen.

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### IIIa

#### Tests on a Full-Scale Rigid Jointed Multi-Storey Steel Frame

Tests à échelle réelle d'un cadre en acier de plusieurs étages

Prüfung eines maßstäblichen, steifknotigen Stockwerkrahmens

F.H. NEEDHAM  
Great Britain

#### Introduction

The use of rigid jointed multi-storey steel frames, and the achievement of the economies which undoubtedly would accrue, has been inhibited for two reasons. Firstly, the difficulty of achieving in practice the necessary degree of continuity at the joints and secondly the complexity of design. With the development of site welding and its feasibility for effecting truly rigid joints (together with the development of the High Strength Friction Grip bolt) the former problem has been largely overcome. The latter problem, the evolution of a practical design method, has been the subject of study by a committee, set up jointly by the Institute of Welding and the Institution of Structural Engineers in 1957. Their first Report was published in December 1964. Rigorous analysis, taking into account full continuity and all possible loading combinations, remains intractable. However, by making certain simplifying assumptions, and by presenting in tabular form the results of a computer programme, this Report presents a logical and practical method of design for such frames. This contribution describes briefly a series of tests on a full scale frame carried out to verify the method and to determine the degree of error inherent in the simplifying assumptions.

#### Summary of Design Principles

The basic principle of the Report method is that of ultimate load design and being more accurate than simple design hitherto common it proposes that an overall load factor of 1.5 can safely be adopted, (instead of the usual 1.75).

The fundamental assumptions are as follows:-

- (a) Steel is mild steel to British Standard 15, with a yield stress of 16.0 ton f/in<sup>2</sup> (25.2 kgf/mm<sup>2</sup>).
- (b) Connections between beams and columns have the full rigidity that can be made possible by welding. (The Report applies also to frames in which full rigidity of connections can be provided by HSFG bolts).

- (c) The beams receive no assistance from composite action with the floors they support, and the columns no assistance from encasement.
- (d) Lateral forces are resisted separately by walls or bracing, the steel frame being thus relieved of sway.

Individual beams and columns are designed on the following principles:-

(i) Major-Axis beams, i.e. beams which at both ends bend or restrain the columns about their major axes, are designed in accordance with the plastic theory. In general, a major-axis beam is designed on the assumption that the beam is "fixed-ended", developing under factored loading three plastic hinges, one at each end and one in the middle. The assumption of "fixed ends" is justified provided that at each end of the beam the sustaining moment supplied by the adjoining beam and columns is at least equal to the hinge moment at that end. Where this condition is not satisfied, the magnitude of the moment at the end of the beam reduces to that of the sustaining moment.

(ii) Minor-Axis beams, i.e. those other than major-axis beams, are designed elastically for factored loading to a limiting extreme fibre stress of  $16.0 \text{ tonf/in}^2$ , in order to provide elastic restraint to the columns about their minor axes. Here the stress in the beam is dependent on the loading and stiffness of all other members of the frame, and hence exact assessment is most complex. To overcome this difficulty the report introduces the "limited-frame" concept. This assumes that it is sufficiently accurate to consider only that limited part of the frame to which the member is connected (in the plane of bending). Further, that the remote ends of this limited frame can be considered as fixed. (See Fig. 1)

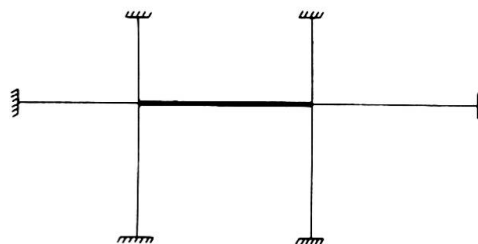


FIG 1 THE LIMITED FRAME FOR BEAM DESIGN

Having established the critical combination of dead and live loading applied to the limited frame, the support moments at the ends of the beam are found by a moment distribution procedure.

### (iii) Columns

Evaluation of bending moments entails the use of the limited-frame concept in a manner similar to that employed in the design of minor-axis beams, except that in this case two limited-frames need to be considered, one in the plane of the major-axis and one in the plane of the minor-axis (see Fig. 2). Axial and bending stresses can then be found.

To these stresses are added firstly those due to axial load acting on the initially curved columns, and secondly those extra stresses arising from the axial load operating on the column as bent by the beams.

These incremental stresses have been evaluated on a computer for a wide range of values of axial stress, joint stiffness ratios, type of curvature and slenderness ratio. The results are presented in the Report in the form of design tables of reduced permissible column stresses (i.e. yield stress less the incremental stresses).

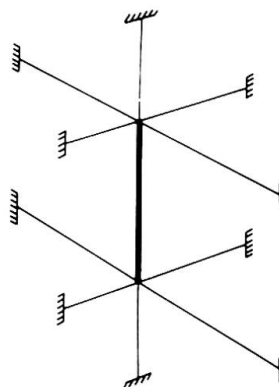


FIG 2 THE LIMITED FRAME FOR COLUMN DESIGN

The design criterion adopted is that of attainment of yield stress at the extreme fibres in single curvature bending under factored load. This recognises that some plasticity will occur at the ends of a column under double curvature bending but can be safely accommodated.

### Experimental Procedure

The experimental work was carried out through a collaborative agreement between the British Iron & Steel Research Association and the Government Building Research Station, whereby BISRA designed and secured a frame and BRS provided laboratory accommodation and services. Testing to a jointly agreed programme was carried out by personnel from both organisations.

### Details of Test Frame

In order fully to verify the Report a 5-storey 5 x 5 bay frame would be needed. Consideration was given to testing a model but was rejected on various grounds.

Having regard to the available laboratory space, a 3 storey 2 x 1 bay frame was designed having the form shown in Fig. 3. The frame was designed to sustain at failure the following loadings:-

|           | <u>Roof Level</u>                                 | <u>2nd Floor Level</u>                            | <u>1st Floor Level</u>                            |
|-----------|---|---|---|
| Dead Load | 50 lb/Ft <sup>2</sup><br>(244 kg/m <sup>2</sup> ) | 75 lb/Ft <sup>2</sup><br>(366 kg/m <sup>2</sup> ) | 75 lb/Ft <sup>2</sup><br>(366 kg/m <sup>2</sup> ) |
| Live Load | 80 lb/Ft <sup>2</sup><br>(391 kg/m <sup>2</sup> ) | 90 lb/Ft <sup>2</sup><br>(439 kg/m <sup>2</sup> ) | 90 lb/Ft <sup>2</sup><br>(439 kg/m <sup>2</sup> ) |

It was assumed that one way spanning floor slabs, with intermediate beams, would be carried as uniformly distributed load for minor-axis beams and centre point loads for major-axis beams. For the test, point loads at quarter-points represented U.D.L. The range of available sections is such that many members were over-designed.

Sway was prevented by tying the frame to the laboratory balconies. Rigid joints were effected with High Strength Friction Grip bolts. Intermediate beams were made heavy so as to exclude premature yielding in them.

The average yield stress of the steel was found to be 19 tonf/in<sup>2</sup> (30 kgf/mm<sup>2</sup>). This was not taken into account in design.

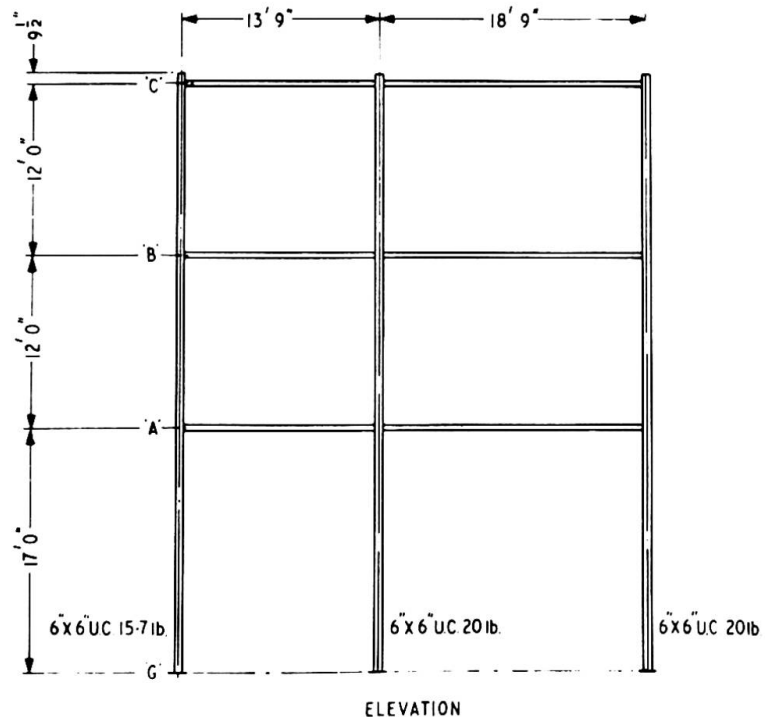
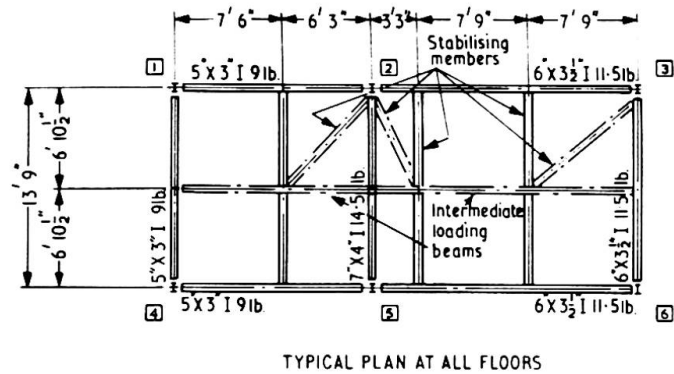


FIG 3 OVERALL FRAME DIMENSIONS

### Loading and Instrumentation

Loading was applied to beams and columns by means of spreader beams acted upon by cables passing through the laboratory strong floor. These were tensioned by hydraulic jacks reacting against the underside of the floor. A total of 396 electrical resistance strain gauges were fixed to the structure in groups of four, at the beams and columns at the joints, and at the mid-span of the beams. Transducers measured deflections of beams at mid-span and of columns at five points about both axes. Load cells measured cable forces.

### Test Programme

In an ideal test frame, at the factored working load major-axis beams should have developed three plastic hinges, and minor-axis beams and columns should have attained yield at the extreme fibres. To achieve this the following conditions should obtain:-

- (i) A wholly accurate design method.
- (ii) The ability to provide sections with exactly the right properties.
- (iii) An accurate knowledge of the yield stress.

These conditions cannot be achieved in practice and it was item (i) which was being investigated in this case.

Testing was therefore carried out in the following stages:

#### Stage 1

Stanchions and beams were loaded in turn to their design loads (i.e. working load x 1.5).

#### Stage 2

Stanchions and beams were loaded up to their limiting values, as calculated by the Report method, taking discrepancies due to (ii) and (iii) above into account.

#### Stage 3

Test loads were successively increased until strain and deflection measurements confirmed that limiting conditions, as defined by the Report, had been attained. (Thus the difference between Stage 2 and Stage 3 would indicate the degree of conservatism in the design method).

#### Stage 4

Loading was continued to outright collapse of columns, by imposing additional axial load (major-axis beams having already attained full plasticity.)

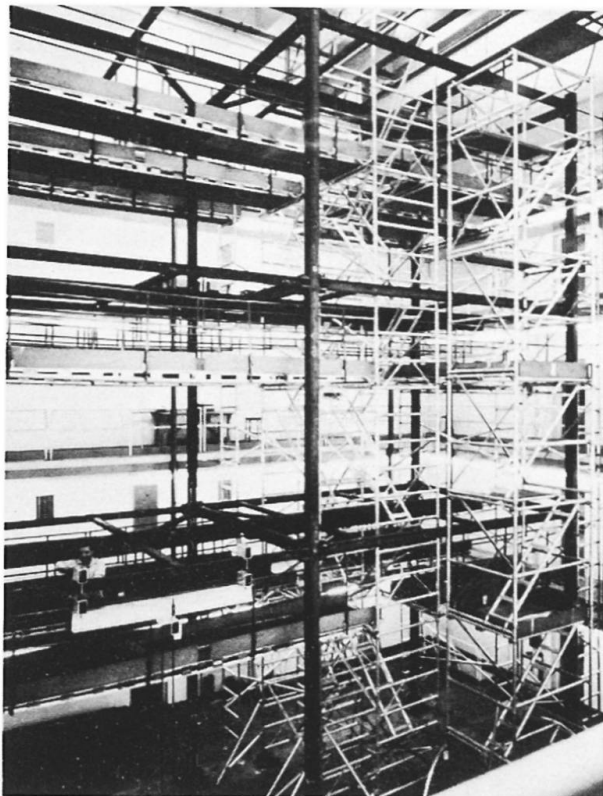


Fig. 4 - Overall View of Test Frame



## Summary of Results

### Stage 1

As was to be expected all frame members remained elastic throughout.

### Stage 2

Major-axis beams achieved central plastic hinges, but although some plasticity was achieved at the supports, full plastic hinges were not developed there.

Adjacent to the centre columns, minor-axis beams reached yield stress.

Peak stresses in the columns were in all cases less than the yield stress.

### Stage 3

Major-axis beams reached full plasticity at three points.

Minor-axis beams yielded.

Columns were loaded so as to produce the maximum single curvature bending condition and axial load was applied to produce yielding.

In general the loads applied to a group of members under test were increased until one or other of these members reached its limiting condition. When that occurred the load on that member was maintained whilst the loads on the remaining members were increased until the next failure, and so on. Thus at this stage loading departed from a hypothetical floor loading.



Fig. 5 - Major-Axis Beam at Collapse

### Stage 4

Three column lengths were loaded to collapse, one at each floor level. They were first subjected to the same beam end moments as in Stage 3 and then direct axial load was applied until collapse.

## Conclusions

Having in Stage 2 applied loads which compensate for the chosen sections and for a yield stress of  $19 \text{ tonf/in}^2$  ( $30 \text{ kg f/mm}^2$ ), it can be asserted that the design method is safe.

From the results of Stage 3 loading the following broad conclusions can be drawn:-

- (i) Major-axis beam design was slightly conservative, the ultimate loads being underestimated.
- (ii) The minor-axis beams were slightly underdesigned in that the limited frame concept gave slightly smaller design moments than an accurate elastic analysis.
- (iii) The measured column stresses were consistently slightly less than the stresses predicted by the Report. It was clear from Stage 4 loading that a considerable margin for the addition of axial load exists beyond the limiting condition as defined by the Report, i.e. the attainment of yield in the extreme fibres under single curvature bending. These results show that the criterion of column design could be considerably improved by subsequent research leading to an accurate criterion for collapse with increased plasticity.

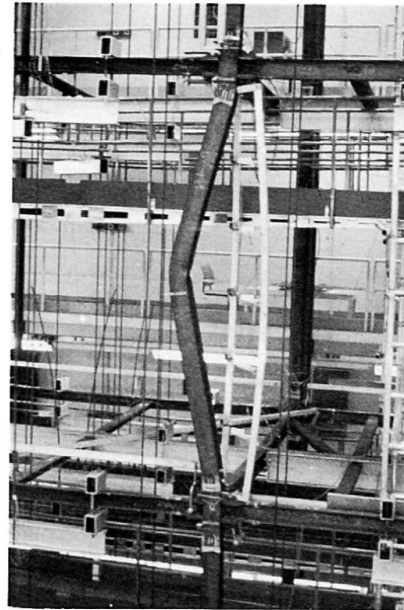


Fig. 6 - Column at Collapse

In short, the Joint Committee Report presents a logical design method for rigid jointed frames, which is reasonably accurate and which can be applied with confidence.

#### Future Work

Following the publication of the first Report, the Joint Committee has been reconvened to extend the method to include such things as the use of High Tensile Steel, composite action of beams, concrete encased columns, plastic design of minor-axis beams, etc.

At the time of writing it is hoped that a second frame will be tested by the same procedure. It will be of larger dimensions, incorporating an internal column, and will be of High Tensile Steel to BS.968.

#### Acknowledgements

This work is more fully reported in a paper presented to the Institution of Structural Engineers in April, 1968 by R.H. Wood, R.F. Smith and the present author, who would like here to pay tribute to his colleague's work.

This project formed part of the respective programmes of the Building Research Station and BISRA and is published by permission of the Directors.

## SUMMARY

This contribution briefly describes a new design method, based on certain simplifying assumptions, for treating rigid-jointed multi-storey frames, and which was published in 1964. By a collaborative arrangement a 2 bay x 1 bay frame, 3 stories high was designed by BISRA to this method and tested at the Building Research Station Laboratory. A series of tests were carried out at working load and to failure, to verify the design method and to establish actual load factors.

## RÉSUMÉ

Ceci est la brève description d'une nouvelle méthode d'études, basée sur certaines hypothèses simplificatrices, du traitement des cadres à plusieurs étages, publiée en 1964.

Un cadre de trois étages, consistant en un arrangement de 2 x 1 cadre fut conçue selon cette méthode par BISRA et testée au Building Research Laboratory. Une série de tests fut menée dans les conditions de travail et jusqu'au point de rupture, pour vérifier la méthode d'étude et pour établir les facteurs de charge réelle.

## ZUSAMMENFASSUNG

Dieser Beitrag beschreibt in knappen Worten eine neue Bemessungsregel für steifknotige Stockwerkrahmen, die auf einigen vereinfachenden Annahmen beruht und 1964 veröffentlicht worden war. Ein 2mal eine Abteilung umfassender, dreistöckiger Rahmen ist von der BISRA entworfen und beim Building Research Station Laboratory geprüft worden. Eine Versuchsreihe ist für Arbeits- und Traglast durchgeführt worden, um die plastische Bemessung zu erhärten und Nutzlastwerte zu finden.

### IIIa

#### Die Traglast von eingespannten Geschoß-Stützen mit I-Querschnitt bei Biegung um beide Hauptachsen

Ultimate Strength of I-shaped Restrained Columns in Biaxial Bending

Charge de rupture de colonnes en I encastrées soumises à des moments  
de flexion autour des deux axes principaux

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#### 1. Einleitung

Für die Berechnung der Grenzlaster von ebenen Rahmentragwerken aus Stahl stehen Verfahren der Plastizitätstheorie zur Verfügung, die mit ausreichender Genauigkeit die stabilen, indifferenten und labilen Gleichgewichtszustände im unelastischen Bereich beschreiben (z.B. [1], [2], [3]). Bei Hochhäusern ist das Verhalten der Stützen von ausschlaggebender Bedeutung für die Stabilität des ganzen Gebäudes. Sind die Stützen Teile eines ebenen, rahmenartigen Skeletts, so können sie nach einem der bekannten Verfahren dimensioniert werden. Häufig werden diese Stützen jedoch durch rechtwinklig zu den Hauptrahmen verlaufende "Sekundär-Rahmen", biegesteif angeschlossene Quer-Unterzüge oder durchlaufende Decken auch rechtwinklig zur Hauptrahmenebene auf Biegung beansprucht. Die genaue Traglastberechnung solcher zweiachsig aussermittig gedrückter Stützen ist - schon bei statisch bestimmter Lagerung - sehr schwierig und kompliziert, wie die wenigen bisher bekannten Veröffentlichungen auf diesem Gebiet zeigen ([4], [5], [6]).

Im Folgenden wird ein Verfahren entwickelt, mit dessen Hilfe die Traglasten von eingespannten - seitlich unverschieblichen - Geschosstützen mit I-Querschnitt bei Biegung um beide Hauptachsen näherungsweise mit geringem Rechenaufwand ermittelt werden können. Dies ist die Erweiterung einer früher veröffentlichten Untersuchung ([3], [6]), in der die Traglast von Geschosstützen bei Biegung in einer Ebene behandelt wurde.

Mehrere Traglastversuche an Stützen natürlicher Grösse dienen der Verbesserung und Bestätigung der theoretischen Ergebnisse.

#### 2. Theoretische Traglast-Ermittlung

##### 2.1. Vorbemerkung

Bei eingespannten Stützen werden die Biegemomente durch die Auflagerverdrehungen der angeschlossenen Riegel, Unterzüge oder Decken erzeugt. Diese Biegemomente sind abhängig von der Steifigkeit der Stützen, d.h. von den vorhandenen Axiallasten und vom Grad der Plastifizierung. Es ist daher sinnvoll, neben den Axiallasten nicht die Biegemomente sondern direkt die Kopf- und Fuss-Drehwinkel  $\varphi_x$  (um die x-Achse) und  $\varphi_y$  (um die y-Achse) als weiteres Beanspruchungsmass für die Stützen einzuführen. Diese Winkel können wegen der im Verhältnis zur Stützen-

steifigkeit grossen Steifigkeit der Deckenkonstruktion und wegen der geringen Grösse der aufnehmbaren Stützenendmomente im Versagenszustand als Auflagerdrehwinkel der an den Stützen frei drehbar gelagert gedachten Decken bzw. Unterzüge ermittelt werden. Damit können auch die Einflüsse von zusätzlichen Kriechdurchbiegungen bei Stahlbeton oder Verbundträgerdecken leicht erfasst werden.

## 2.2 Voraussetzungen der Näherungstheorie

- Es gilt das bekannte idealelastisch-idealplastische Spannungs-Dehnungs-Gesetz für Baustahl mit der Fließgrenze  $\sigma_F$ .
- Die Traglast der Stütze ist erreicht, wenn durch Bildung einer genügenden Anzahl von Fließgelenken (mindestens 3) eine kinematische Kette entstanden ist.
- Die Ausbreitung teilplastischer Zonen neben den Fließgelenken wird vernachlässigt.
- Werden sowohl der Stützenkopf als auch der Stützenfuss verdreht, so sei das Verhältnis  $\varphi_y/\varphi_x$  an Kopf und Fuss gleich gross.
- Die verformte Achse der Stütze liegt im Traglastzustand in einer durch die Lage der Fließgelenke definierten Ebene. Torsionsmomente infolge der tatsächlich räumlich gekrümmten Stabachse werden vernachlässigt (s.a. [4]).
- Der Einfluss der Verformungen auf das Kräfte-Gleichgewicht wird berücksichtigt.
- Der Einfluss der Axiallast auf die Stützensteifigkeit und auf das aufnehmbare vollplastische Moment wird ebenfalls berücksichtigt.

Es sei darauf hingewiesen, dass die Voraussetzungen f) und g) notwendig sind, um das Traglastproblem richtig als Stabilitätsproblem ohne Gleichgewichtsverzweigung zu behandeln. Die Voraussetzungen b) und c) hingegen führen gegenüber der genaueren Untersuchung (z.B. [4], [5], [10]) zu einer wesentlichen Vereinfachung der Rechnung.

## 2.3 Die Komponenten des aufnehmbaren vollplastischen Moments des dünnwandigen doppelsymmetrischen I-Querschnitts bei schiefer Biegung mit Normalkraft

Für die Herleitung der den Einfluss von Normalkraft und schiefer Biegung erfassenden Reduktionsfaktoren  $\gamma_x$  und  $\gamma_y$  für die vollplastischen Momente um die x- und um die y-Achse können die Momentenanteile der Spannungen in den Stegflächen vernachlässigt werden. Es wird also das I-Profil mit unendlich dünnem, jedoch Schubsteifem Steg untersucht.

Bei schiefer Biegung und Normalkraft sind im Zustand der vollständigen Durchplastifizierung zwei Fälle für die Lage der Spannungsnulllinie möglich:

- Die Nulllinie verläuft durch beide Flansche (Bild 2.1.a).
- Die Nulllinie verläuft nur durch einen Flansch (Bild 2.1.b).

Im Fall a) ergibt sich mit Bild 2.1.a und den folgenden Bezeichnungen

$$M_{plx}^* = bt(h - t)\sigma_F \quad (\text{Vollplast. Moment bei Biegung um x-Achse allein})$$

$$M_{ply}^* = \frac{tb^2}{2} \sigma_F \quad (\text{Vollplast. Moment bei Biegung um y-Achse allein})$$

$$N_{pl} = F\sigma_F = 2bt\sigma_F \quad (\text{Vollplast. Normalkraft bei Druck allein})$$

aus den Gleichgewichtsbedingungen im Querschnitt  $\sum N = 0$ ,  $\sum M_x = 0$  und  $\sum M_y = 0$  :

$$M_{plx,N} = \int M_{plx}^* \quad (2.1.a)$$

Hierin bedeuten:

$$\chi = \frac{N}{N_{pl}} = \frac{N}{F_F} \quad (2.4)$$

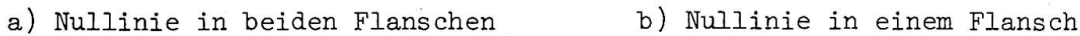


Bild 2.1: Vollplastizierter I-Querschnitt bei schiefer Biegung und Normalkraft

zur x-Achse ausdrücken:

$$tg \varphi = \frac{M_{ply,N}}{M_{plx,N}} = \frac{1 - \rho^2 - \chi^2}{\rho} \cdot \frac{\frac{1}{2}tb^2\sigma_F}{bt(h-t)\sigma_F} = \frac{1 - \rho^2 - \chi^2}{2\rho} \cdot \frac{b}{(h-t)} \quad (2.5.a)$$
$$y = \frac{\operatorname{tg} \varphi}{b/(h-t)} \quad (2.6.a)$$
$$g = -\gamma_{(-)}^{(+)} \sqrt{\mu^2 + (1-x^2)} \quad (2.7)$$
$$M_{\text{plx},N} = (1 - \alpha) M_{\text{plx}}^* \quad (2.1.b)$$

$$M_{\text{ply},N} = 2\chi(1-\chi) M_{\text{ply}}^* \quad (2.2.b)$$

Der Wert für  $M_{plx,N}$  nach Formel (2.1.b) kann bei schiefer Biegung nicht überschritten werden, da er bereits gleich dem Wert des vollplastischen Moments bei einachsiger Biegung um die x-Achse und gleichzeitig wirkender Normalkraft ist (vgl. [3], S.23, Gl.(3.6)).

Hier erhält man für  $\text{tg}\varphi$  die Beziehung:

$$\text{tg}\varphi = \chi \cdot \frac{b}{h-t}, \quad (2.5.b)$$

und damit für den Hilfswert  $\gamma$  den Grenzwert

$$\gamma_{gr} = \frac{\text{tg}\varphi}{b/(h-t)} = \chi, \quad (2.6.b)$$

der zu dem möglichen Maximalwert von  $M_{ply,N}$  führt.

Für  $\gamma \geq \chi$  gelten die Formeln (2.1.a) und (2.2.a),  
für  $\gamma \leq \chi$  gelten die Formeln (2.1.b) und (2.2.b).

Zur Erleichterung der praktischen Berechnung sind diese Beziehungen graphisch in zwei Interaktions-Diagrammen in Bild 2.2 dargestellt.

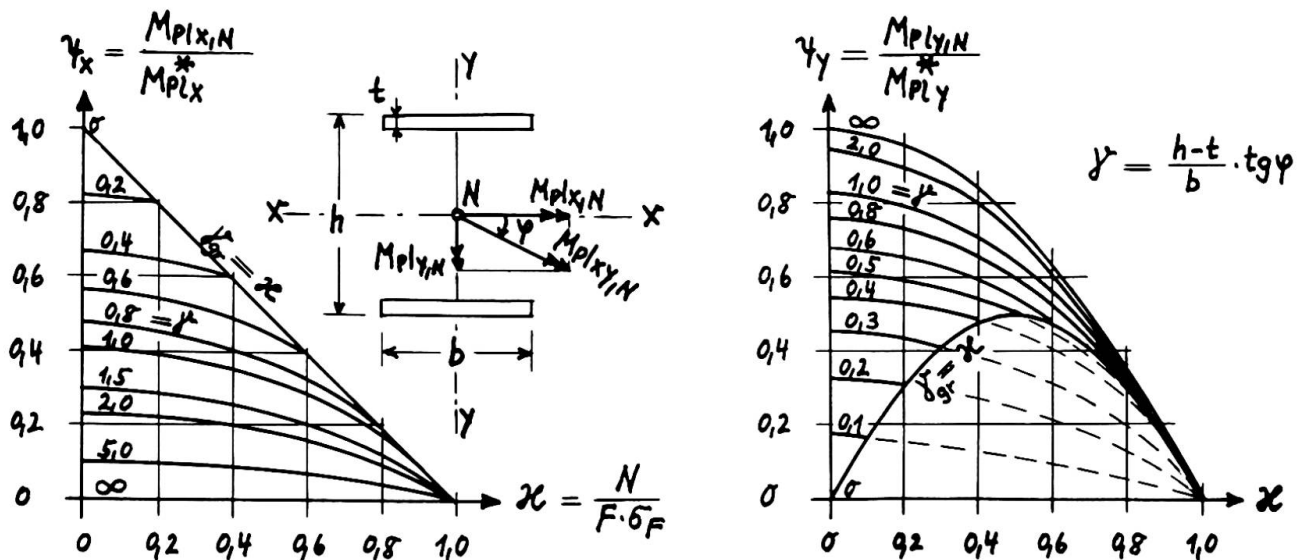


Bild 2.2 : Abminderungsfaktoren für die Komponenten des vollplastischen Moments bei schiefer Biegung und Normalkraft

#### 2.4 Traglast von Geschosstützen bei entgegengesetzt gleich grossen Kopf- und Fussdrehwinkeln um x- und y-Achse

Dieser Beanspruchungsfall ist in Bezug auf die Traglast in der Regel der ungünstigste, da ein einsinniger Krümmungsbauch der Stütze entsteht (s. Bild 2.3, Stütze I).

Die Traglast einer Stütze vom Typ I ist erreicht, wenn drei Fließgelenke entstanden sind. In [3], S. 35, wurde für einachsige Biegung gezeigt, dass das erste Fließgelenk in Stabmitte und die beiden letzten gleichzeitig an Kopf und Fuss entstehen. Dies gilt auch bei zweiachsiger Biegung.

Die Traglast kann aus den Gleichgewichts- und Verformungsbedingungen der deformierten Stütze im Zustand des beginnenden Versagens ermittelt werden. In diesem Zustand hat noch keine Verdrehung in den sich zuletzt bildenden Fließgelenken stattgefunden.



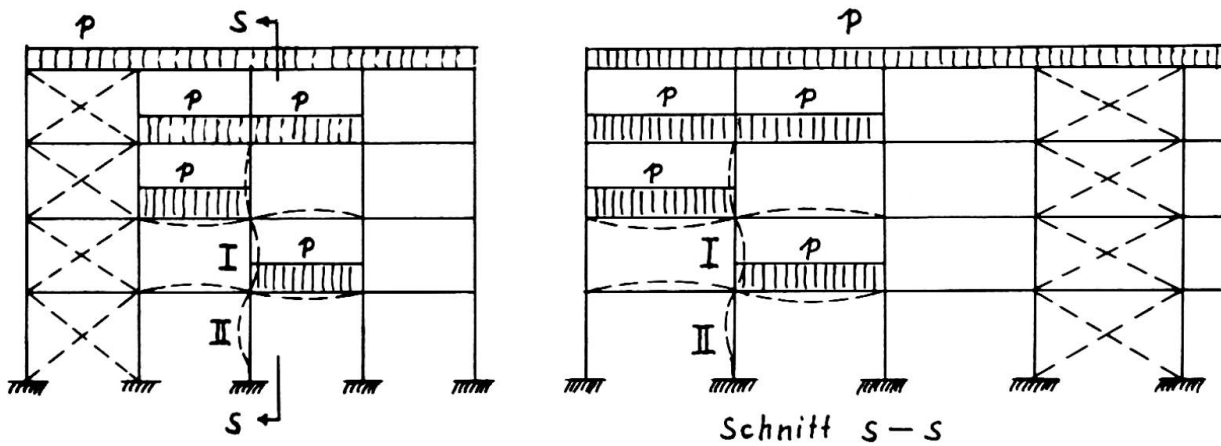


Bild 2.3 : Schachbrettbelastung im Bereich der untersuchten Stützen

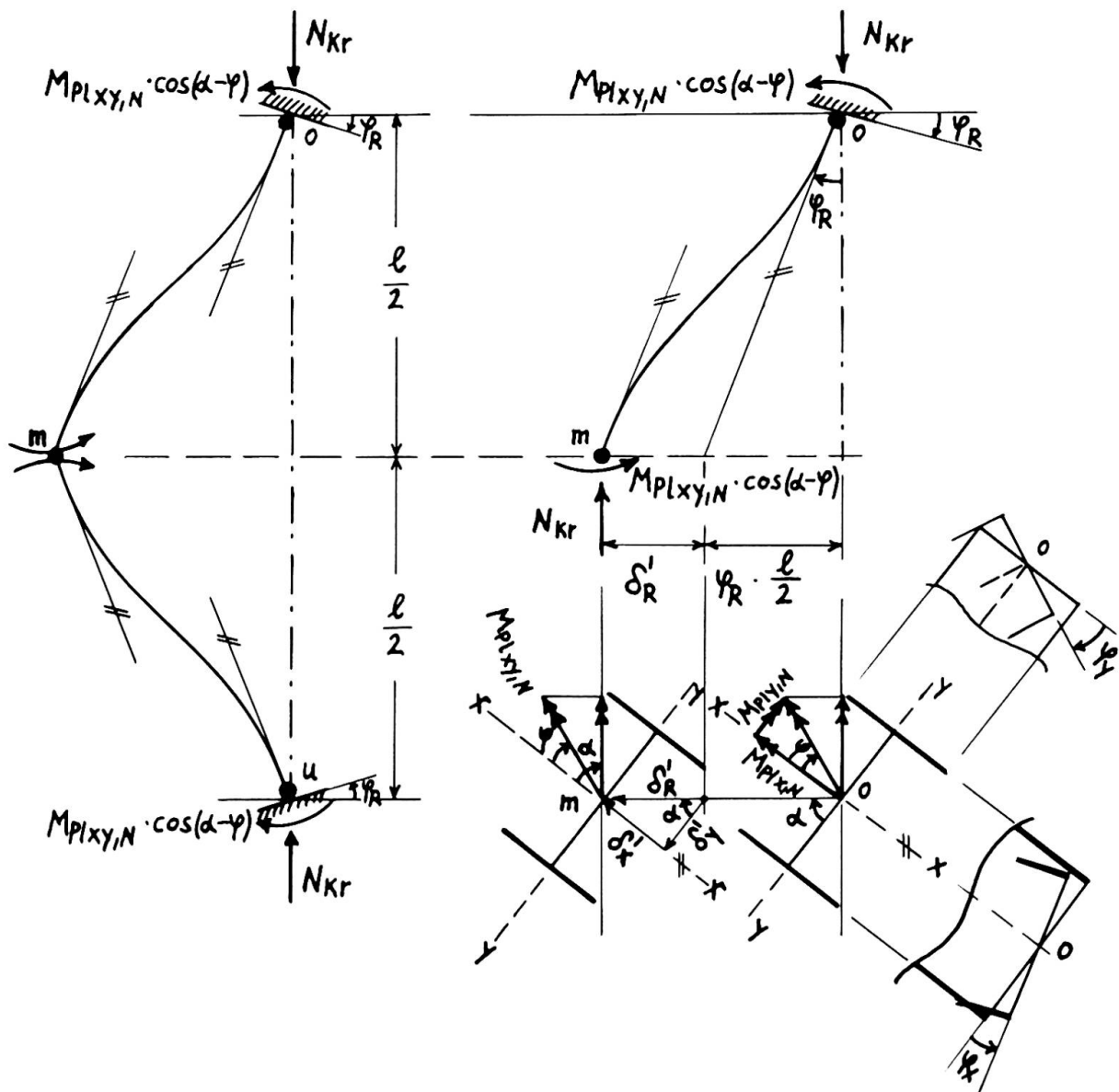


Bild 2.4 : Kräftespiel und Verformungen beim Erreichen der Traglast  
(Kopf- und Fussdrehwinkel gleich gross)

Die Bedingung für das Momentengleichgewicht in der Verformungs-Ebene der oberen Stabhälfte lautet mit den Bezeichnungen von Bild 2.4

$$N_{kr} \cdot (\delta'_R + \varphi_R \cdot \frac{1}{2}) = 2 M_{ply,N} \cdot \cos(\alpha - \varphi) \quad (2.8)$$

Mit der Voraussetzung e) des Abschnittes 2.2 lassen sich die Verformungen in x- und y- Richtung getrennt ermitteln. Man erhält somit nach Theorie II. Ordng.:

$$\delta'_R = \frac{\delta'_y}{\cos \alpha} = \frac{1}{\cos \alpha} \cdot \frac{(1/2)^2}{EI_x} \cdot \psi_x \cdot M_{plx}^* (\alpha'_x - \beta'_x) \quad (2.9.a)$$

mit den Hilfwerten  $\alpha'_x$  und  $\beta'_x$ , die als Funktionen der Stabkennzahl

$$\epsilon_{x(y)} = \frac{1}{2} \sqrt{\frac{N_{kr}}{EI_x}} = \sqrt{\epsilon} \cdot \lambda_x \cdot \sqrt{\frac{\sigma_F}{E}} \quad (2.9.b)$$

aus [8] entnommen werden können. Für praktische Berechnungen ist die Differenz  $(\alpha' - \beta')$  als Funktion von  $\epsilon$  in Bild 2.5 graphisch dargestellt.

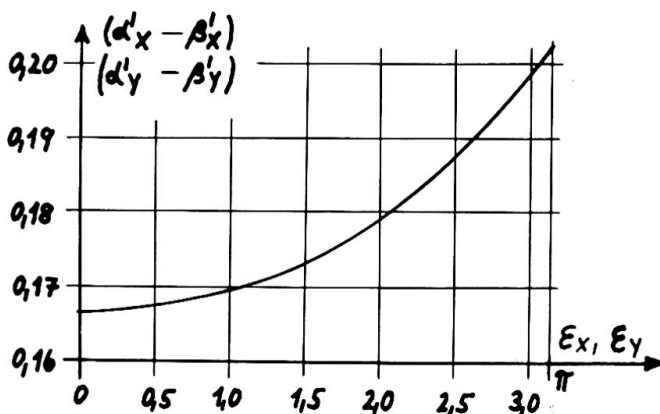


Bild 2.5 : Hilfwerte  $(\alpha' - \beta') = f(\epsilon)$

Für den resultierenden Kopf- bzw. Fussdrehwinkel gilt:

$$\varphi_R = \varphi_x \cdot \cos \alpha + \varphi_y \cdot \sin \alpha = \varphi_x \left( \cos \alpha + \frac{\varphi_y}{\varphi_x} \cdot \sin \alpha \right) \quad (2.10)$$

Und für den Neigungswinkel  $\alpha$  der Verformungsebene gegen die Ebene durch die y-Achse des Querschnitts erhält man entsprechend (2.9.a):

$$\tan \alpha = \frac{\delta'_x}{\delta'_y} = \frac{I_x \cdot \psi_y \cdot M_{ply}^* (\alpha'_y - \beta'_y)}{I_y \cdot \psi_x \cdot M_{plx}^* (\alpha'_x - \beta'_x)}$$

Setzt man  $M_{plx}^* = \alpha_x \cdot W_x \cdot \sigma_F$ ,  $M_{ply}^* = \alpha_y \cdot W_y \cdot \sigma_F$  und beachtet, dass  $\frac{I_x \cdot W_y}{I_y \cdot W_x} = \frac{h}{b}$

ist, so wird daraus

$$\tan \alpha = \frac{\psi_y}{\psi_x} \cdot \frac{\alpha_y}{\alpha_x} \cdot \frac{h}{b} \cdot \frac{\alpha'_y - \beta'_y}{\alpha'_x - \beta'_x} \quad (2.11)$$

worin  $\alpha_x$  und  $\alpha_y$  die "Formfaktoren" für plastische Biegung um x-, bzw. y-Achse des I-Querschnitts bedeuten.

Der Wert  $\tan \varphi$  ist durch (2.5.a) definiert. Mit der Annahme, dass das Verhältniss der vollplastischen Momente um y-Achse und x-Achse zueinander gleich dem Verhältniss der Biegemomente nach Theorie I. Ordnung ist,

ergibt sich die - gegenüber (2.5.a) unabhängige - Beziehung :

$$\operatorname{tg} \varphi = \frac{M_{y, \text{Th.I.O.}}}{M_{x, \text{Th.I.O.}}} = \frac{I_y \cdot \varphi_y}{I_x \cdot \varphi_x}, \quad (\gamma \gg \kappa) \quad (2.12)$$

die nur im Bereich  $(\gamma \gg \kappa)$  gültig ist. Ergibt sich mit (2.12) der Wert  $\gamma < \kappa$ , so ist  $\gamma = \kappa$  zu setzen und für  $\operatorname{tg} \varphi$  Gleichung (2.5.b) zu verwenden.

Setzt man nun (2.9.a) und (2.10) in Gleichung (2.8) ein, so erhält man nach Umformung die gesuchte Traglastbedingung zu:

$$\kappa = \frac{N_{kr}}{F \cdot \sigma_F} = \frac{2 \cdot \psi_x \cdot \alpha_x \cdot (1 + \operatorname{tg} \alpha \cdot \operatorname{tg} \varphi)}{(\alpha'_x - \beta'_x) \frac{\psi_x \alpha_x}{\cos^2 \alpha} \left( \lambda_x \sqrt{\frac{6F}{E}} \right)^2 + (\lambda_x \cdot \varphi_x) \cdot \frac{h}{2i_x} \cdot \left( 1 + \frac{\varphi_y}{\varphi_x} \cdot \operatorname{tg} \alpha \right)} \quad (2.13)$$

Diese Gleichung muss - zusammen mit (2.11) und (2.12) - durch Probieren gelöst werden, da auch auf der rechten Seite der gesuchte Wert  $\kappa$  in den Funktionen für  $\psi_x$ ,  $\alpha'_x$ ,  $\beta'_x$ ,  $\operatorname{tg} \alpha$  und gegebenenfalls auch  $\operatorname{tg} \varphi$  enthalten ist.

Bild 2.6 gibt die graphische Parameter-Darstellung der numerischen Auswertung von (2.13) mit  $\varphi_y/\varphi_x = 1$  und  $\varphi_y/\varphi_x = 0$  (einachsige Biegung) für die Stützenprofile IPB 100 ÷ 300 nach DIN 1025 wieder, wobei für die Verhältnisse der Querschnittswerte folgende Mittelwerte eingesetzt wurden:

$h/i_x = 2,34$ ,  $I_y/I_x = 0,353$ ,  $b/(h-t) = 1,08$ ,  $h/b = 1$ ,  $\alpha_x = 1,13$ ,  $\alpha_y = 1,5$ .

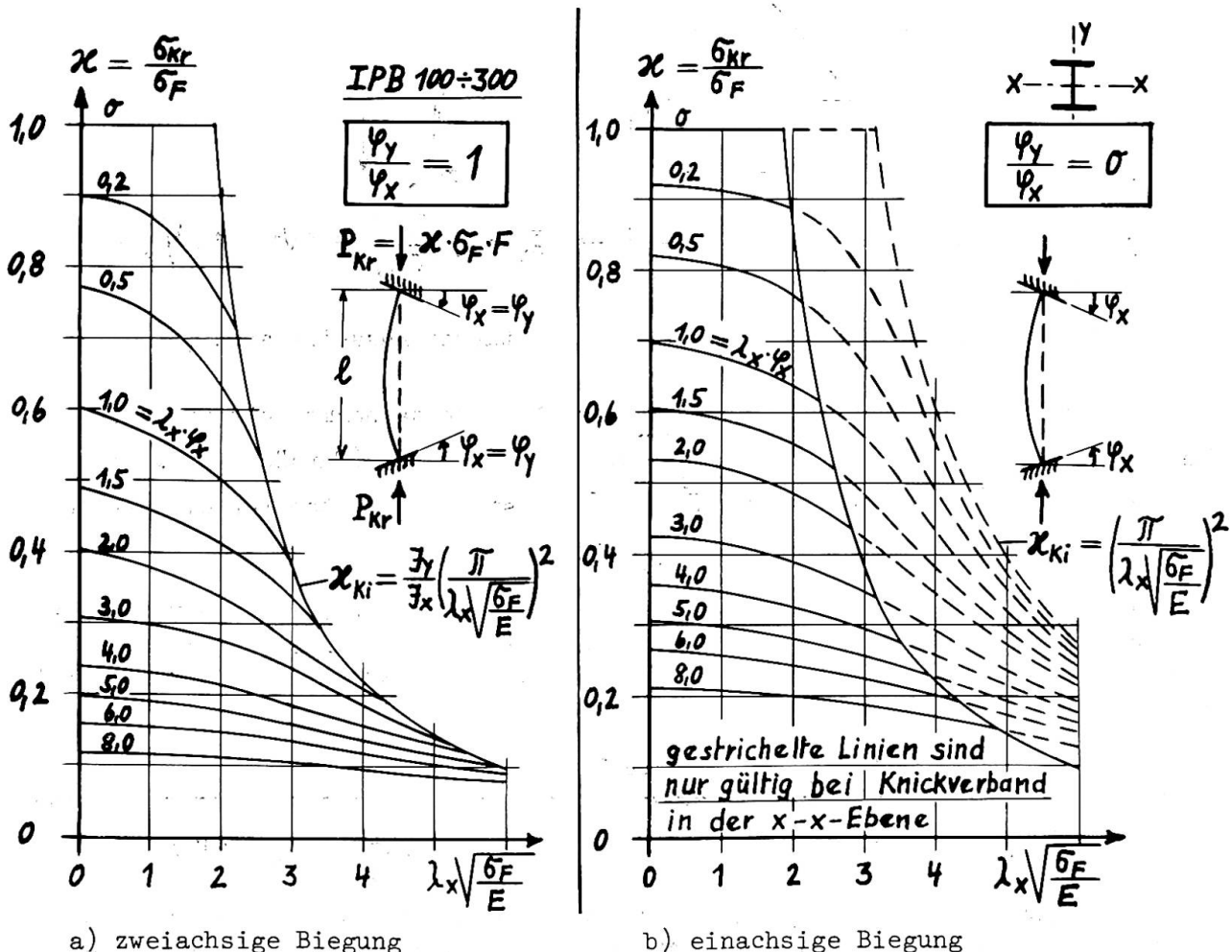


Bild 2.6 : Traglasten eingespannter Stützen mit Kopf- und Fussverdrehung

Die Traglasten für Werte von  $1 > \varphi_y / \varphi_x > 0$  können mit ausreichender Genauigkeit durch lineare Interpolation zwischen den Bildern 2.6.a und 2.6.b ermittelt werden. Der Wert  $\varphi_y / \varphi_x > 1$  wird i.a. nicht auftreten, dann man dann das Stützenprofil um  $90^\circ$  drehen wird.

## 2.5 Traglasten von Geschosstützen mit starrer Füsseinspannung und Verdrehung des Kopfes um x- und y-Achse

Dieser Beanspruchungsfall entspricht der Stütze II in Bild 2.3. Die Traglast ist auch hier erreicht, wenn drei Fließgelenke entstanden sind. In [3], S. 38/39, wurde für einachsige Biegung gezeigt, dass im Bereich der Stabkennzahl  $\bar{E} \leq 0,745 \cdot \pi$  die Traglast durch Vollplastizierung infolge der Normalkraft  $P$  allein bestimmt ist, da hier keine drei Fließgelenke entstehen können. Im Bereich  $0,745 \cdot \pi < \bar{E} \leq 2 \cdot \pi$  bilden sich jedoch drei Fließgelenke in folgender Reihenfolge aus: Das erste Fließgelenk an der Stelle  $x_0$  zwischen Stützenkopf und Stützenmitte, das zweite am Stützenfuss und das letzte am Stützenkopf. Dies gilt auch bei zweiachsiger Biegung. Die Lage des ersten Fließgelenks ist von der Stabkennzahl  $\bar{E}$  abhängig und kann in dem aus [3] entnommenen Diagramm des Bildes 2.7 abgelesen werden.

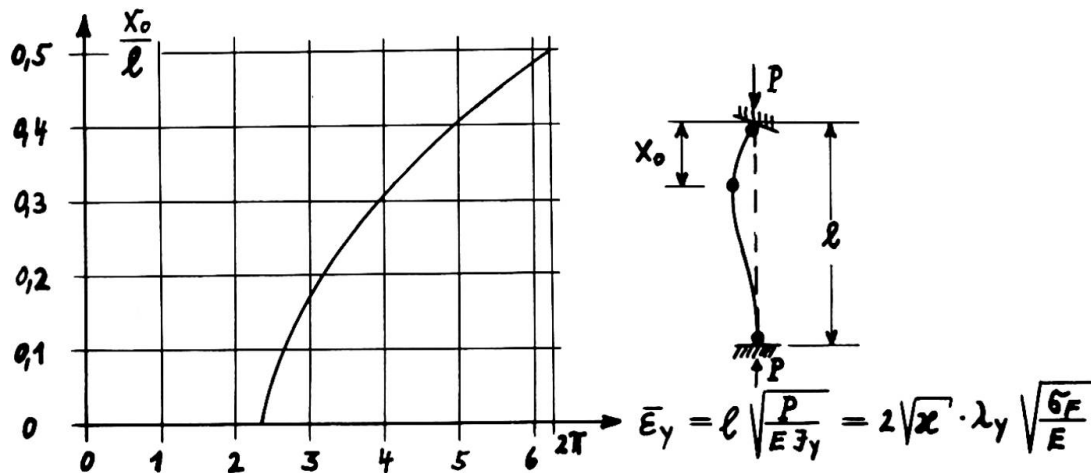


Bild 2.7 : Lage des 1. Fließgelenks bei starrer Füsseinspannung

Dabei wird die ~~die~~ etwas zu ungünstige Näherungsannahme getroffen, dass  $x_0$  bei schiefer Biegung durch  $\bar{E}_y = 1 \sqrt{P/EI_y}$  bestimmt ist. (Tatsächlich wird  $x_0$  zwischen den durch die Kennzahlen  $\bar{E}_x$  und  $\bar{E}_y$  bestimmten Werten für die Stellen der Momenten-Maxima  $M_{x,max}$  und  $M_{y,max}$  liegen.)

Die Traglastermittlung kann analog Abschnitt 2.4 erfolgen. Der Vergleich der Bilder 2.4 und 2.7 zeigt, dass die Traglastbedingung unmittelbar angeschrieben werden kann, indem in Gleichung (2.13) der Wert  $1/2$  durch  $x_0$  ersetzt wird:

$$\chi = \frac{N_{kr}}{F \delta_F} = \frac{2 \cdot \varphi_x \cdot \alpha_x \cdot (1 + \operatorname{tg} \alpha \cdot \operatorname{tg} \varphi)}{(\alpha'_x - \beta'_x) \frac{\varphi_x \alpha_x}{\cos^2 \alpha} \left( \frac{x_0}{1/2} \cdot \lambda_x \sqrt{\frac{6F}{E}} \right)^2 + \left( \frac{x_0}{1/2} \cdot \lambda_x \cdot \varphi_x \right) \frac{h}{2i_x} \left( 1 + \frac{\varphi_y}{\varphi_x} \operatorname{tg} \alpha \right)} \quad (2.14)$$

Für  $\operatorname{tg} \alpha$  und  $\operatorname{tg} \varphi$  gelten wieder die Beziehungen (2.11) und (2.12), für  $x_0$  Bild 2.7. Die Differenzen  $(\alpha'_x - \beta'_x)$  und  $(\alpha'_y - \beta'_y)$  sind als Funktion von

$$\bar{\epsilon}_{x(y)} = \sqrt{\alpha} \cdot \frac{x_0}{1/2} \cdot \lambda_x \sqrt{\frac{6F}{E}} \quad (2.15)$$

aus Bild 2.5 zu entnehmen.

Wie (2.13) so kann auch (2.14) nur durch Probieren gelöst werden. Die Bilder 2.8.a und 2.8.b geben die numerische Auswertung von Gl. (2.14) für  $\varphi_y/\varphi_x = 1$  und  $\varphi_y/\varphi_x = 0$  für die Stützenprofile IPB 100 ÷ 300 wieder. Auch hier kann man für Zwischenwerte von  $\varphi_y/\varphi_x$  linear interpolieren.

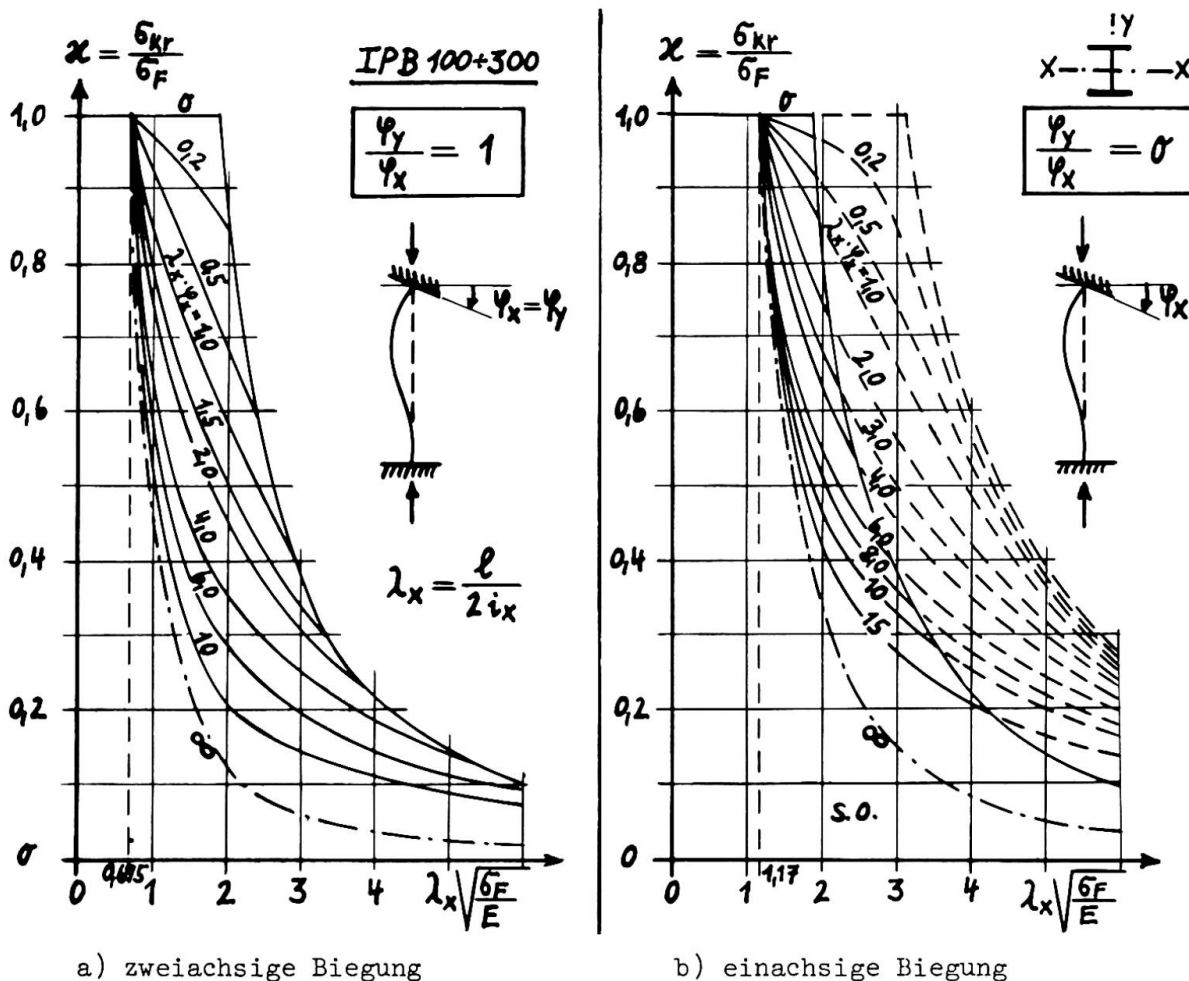


Bild 2.8 : Traglasten eingespannter Stützen bei starrer Füsseinspannung

### 3. Experimentelle Traglast-Ermittlung

#### 3.1. Vorbemerkung

Zur Überprüfung und Ergänzung der in Abschnitt 2 entwickelten Näherungstheorie wurden im "Otto-Graf-Institut" der Universität Stuttgart (TH) vier Traglastversuche durchgeführt. Eine ausführliche Beschreibung dieser Versuche einschliesslich der Auswertung der Messergebnisse wird in [9] gegeben. Es werden daher hier nur die wichtigsten Ergebnisse zusammengestellt.

Die Versuchsstützen erhielten angeschweisste Kopf- und Fussplatten. Beim Traglastversuch wurden Keilplatten mit Neigungen in x- und y-Richtung zwischen

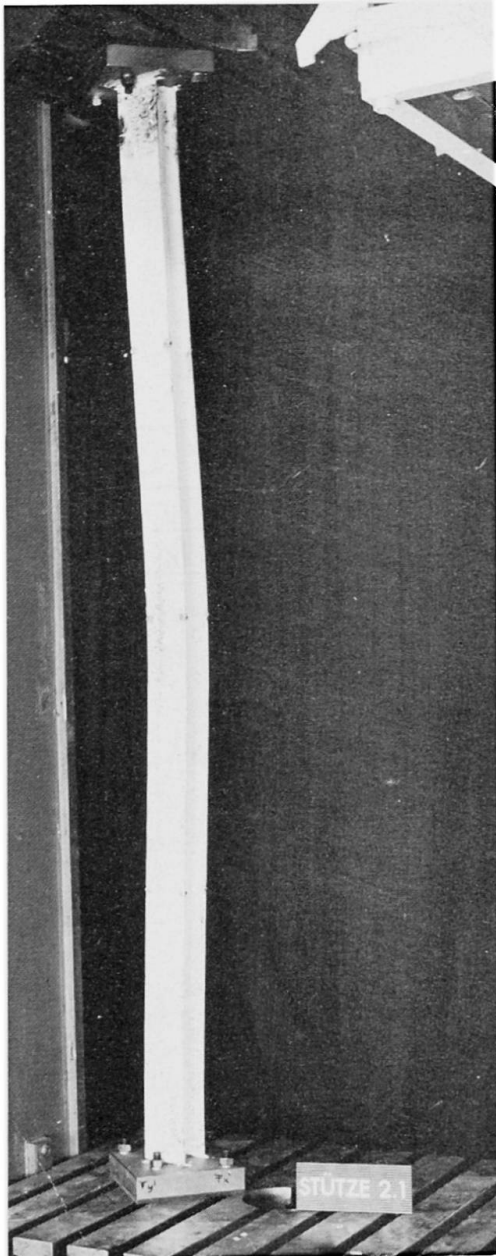


Bild 3.1 : Stütze 2.1 nach dem Traglastversuch

die Kopf- bzw. Fussplatten und die parallel zur Stützenachse geführten Pressen-Querhölzer der Versuchsmaschine gelegt. Durch das Vorspannen von HV-Schrauben, welche die Fuss- und Kopfplatten mit den Pressen-Querhölzern verbinden, wurden die den Keilplatten entsprechenden Neigungen als Enddrehwinkel in die Stützen eingetragen (Bild 3.1). Anschliessend wurde die Axiallast über die Pressen-Querhölzer bis zur Traglast gesteigert.

### 3.2 Einführung von baupraktisch unvermeidbaren Imperfektionen

Es zeigte sich, dass trotz sorgfältiger Werkarbeit die vorgesehenen Stabendverdrehungen nicht genau eingehalten werden konnten. Diese Ungenauigkeiten lagen insbesondere in den Abweichungen vom Rechten Winkel zwischen den angeschweissten Kopf- bzw. Fussplatten und den Stabachsen und sind daher auch bei praktischer Bauausführung zu erwarten. Da ausserdem die Stützen auch gewisse Vorverformungen aufweisen und sicher auch Eigenspannungen aus den Walzvorgängen vorhanden sind, wird vorgeschlagen, bei der Bemessung einen zusätzlichen Enddrehwinkel stellvertretend für den Einfluss aller möglichen Imperfektionen anzunehmen. Gleichzeitig können damit auch die praktisch auftretenden Abweichungen von den Voraussetzungen a) und c) des Abschnittes 2.2 zumindest qualitativ etwas ausgeglichen werden.

In Anlehnung an DIN 4114, Ri. 7.22 wird eine parabelförmige Verkrümmung der Stabachse mit dem Biegepfel

$$u = \frac{i}{20} + \frac{1}{500}$$

in Stabmitte in x- und y-Richtung angesetzt. Die Enddrehwinkel betragen dann:

$$\Delta\varphi = \frac{4u}{l} = 0,1 \cdot \frac{2i}{l} + \frac{1}{125}$$

Mit  $\lambda = 1/2i$  für die eingespannte Stütze wird daraus:

$$\Delta\varphi_{(y)} = \frac{0,1}{\lambda_{(y)}} + 0,008 \quad (3.1)$$

Der erste Anteil kann dabei die Einflüsse von Eigenspannungen und von der Ausbreitung teilplastischer Zonen neben den Fliessgelenken berücksichtigen, die beide tatsächlich mit wachsender Schlankheit abnehmen. Der zweite Anteil ist jedoch konstant und berücksichtigt die Bau- Ungenauigkeiten, die mit einem  $\Delta\varphi_2 = 0,008$ , d.h.  $\Delta\varphi_2 = 0^\circ 27'$  sicher nicht zu gross angesetzt sind.

### 3.3 Zusammenstellung der Versuchsergebnisse und Vergleich mit der Theorie

In der Tabelle 3.1 sind die Versuchsergebnisse den nach Abschnitt 2 ermittelten theoretischen Werten für die Traglast bei Berücksichtigung der tatsäch-



lich gemessenen Enddrehwinkel gegenübergestellt. Die Versuchsergebnisse liegen i.M. um 7,4 % unter den theoretischen Ergebnissen, d.h. auf der "unsicheren Seite".




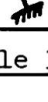
| Ver-<br>such | Sys-<br>tem   | Profil<br>$\sigma_F$ (Mp/cm <sup>2</sup> ) | l<br>(m) | Soll<br>$\varphi_x = \varphi_y$ | vorhanden<br>$\varphi_x$   $\varphi_y$ |        | $P_{kr}^{theor.}$<br>( $\varphi_{vorh.}$ ) | $P_{Exp.}$<br>(Mp) | $\frac{P_{Exp.}}{P_{kr}^{theor.}}$ |
|--------------|---|--|----------|---------------------------------|--|--------|--|--------------------|------------------------------------|
| 1.1          |  | IPB 120                                    | 3,0      | 0,0071                          | 0,0067                                 | 0,0082 | 76,5                                       | 69,2               | 0,904                              |
| 1.2          |  | 2,43                                       | 6,0      | 0,0071                          | 0,0097                                 | 0,0124 | 50,4                                       | 44,4               | 0,880                              |
| 2.1          |  | IPB 120                                    | 3,0      | 0,0142                          | 0,0169                                 | 0,0126 | 61,8                                       | 62,2               | 1,050                              |
| 2.2          |  | 2,48                                       | 6,0      | 0,0142                          | 0,0236                                 | 0,0160 | 36,9                                       | 33,7               | 0,915                              |

Tabelle 3.1 : Vergleich der Traglasten nach Theorie (mit  $\varphi_{vorh.}$ ) und Experiment

Führt man jedoch den Winkel  $\Delta\varphi$  nach Gleichung (3.1) ein, so erhält man die Werte nach Tabelle 3.2. Die theoretischen Ergebnisse liegen nun i.M. um 8 % über den Versuchsergebnissen.

| Ver-<br>such | $\Delta\varphi_x$ | $\Delta\varphi_y$ | $P_{kr}^{theor.}$<br>(Mp) | $P_{Exp.}$<br>(Mp) | $\frac{P_{Exp.}}{P_{kr}^{theor.}}$ | $P_F$<br>(Mp) |
|--------------|-------------------|-------------------|---------------------------|--------------------|------------------------------------|---------------|
| 1.1          | 0,0114            | 0,0100            | 64,0                      | 69,2               | 1,081                              | 0             |
| 1.2          | 0,0097            | 0,0090            | 43,5                      | 44,4               | 1,021                              | 21,0          |
| 2.1          | 0,0114            | 0,0100            | 51,0                      | 62,2               | 1,219                              | 0             |
| 2.2          | 0,0097            | 0,0090            | 33,7                      | 33,7               | 1,000                              | 24,5          |

Tabelle 3.2 : Vergleich der Traglasten nach Theorie (mit  $\varphi_{soll} + \Delta\varphi$ ) und Experiment

Es sei noch auf die letzte Spalte von Tabelle 3.2 hingewiesen, in welcher diejenigen Werte von  $P$  eingetragen sind, die bei Vorhandensein der gemessenen Enddrehwinkel den Fließbeginn in den am ungünstigsten beanspruchten Querschnitten erzeugen. Man erkennt, dass z.B. nach einer "elastischen Berechnung" die Stützen 1.1 und 2.1 überhaupt nicht mehr belastet werden dürften, obwohl gerade sie wegen ihrer geringen Schlankheit die grössten Traglasten aufweisen!

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## ZUSAMMENFASSUNG

Im vorliegenden Aufsatz wird eine Näherungslösung nach der Plastizitätstheorie zur Ermittlung der Traglasten von eingespannten Geschosstützen bei zweiachsiger Biegung entwickelt. Für einige praktisch auftretende Randbedingungen werden die Ergebnisse in Kurventafeln dargestellt. Traglastversuche haben gezeigt, dass die entwickelten Traglastformeln bei Berücksichtigung einer zusätzlichen Annahme für mögliche Imperfektionen nach Gleichung (3.1) zu für die Praxis ausreichend genauen und "sicheren" Ergebnissen führen.

## SUMMARY

In this paper an approximate solution by plastic design method for the calculation of the ultimate strength of biaxially loaded restrained columns is developed.

For some practical boundary conditions the results are given in interaction-diagrams. Ultimate load tests have shown, that the developed ultimate strength formulas lead to a design which is sufficient and conservative for practical purposes, if additional possible imperfections (equation 3.1) are taken into account.

## RÉSUMÉ

L'exposé développe une solution approximative selon la théorie de plasticité pour la détermination de la charge de rupture de colonnes encastrées soumises à des flexions biaxiales. Les résultats sont présentés sous forme de graphiques pour quelques conditions limites qu'on trouve dans la pratique. On a démontré par des essais de rupture que les formules développées conduisent à des résultats suffisamment exacts et sûrs, à condition de respecter une supposition supplémentaire pour de possibles imperfections selon l'équation (3.1).

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### IIIa

#### Tests on Hinged Connections for Non-Sway Continuous Frames

Essai de noeuds articulés pour ossatures contreventées

Versuche an gelenkigen Knoten für verstrebt Skelette

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#### 1. INTRODUCTION.

Most of multi-story frames built at present have either a rigid central concrete core, or a diagonal bracing to resist wind forces, so that these structures may be designed as non-sway structures. They usually have rigid connections between beams and columns.

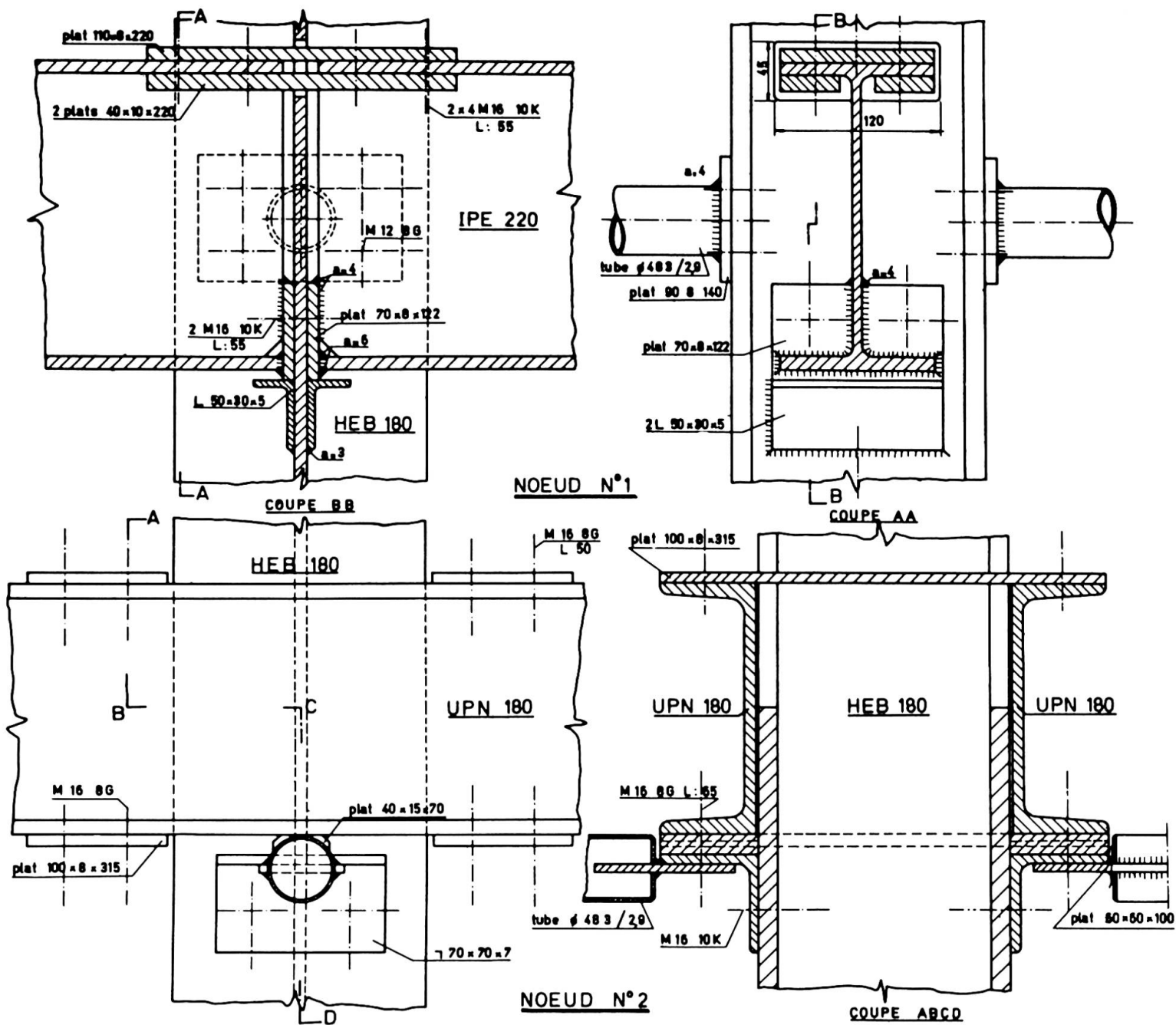
Research conducted in the United States, in Great Britain, and elsewhere have made possible the plastic analysis of such structures on a practical basis. In particular, the Lehigh team has developed a method solving the problem of verifying the rotational capacity of joints, and analysing the buckling of columns, by means of "column deflection curves", obtained theoretically for current shapes.

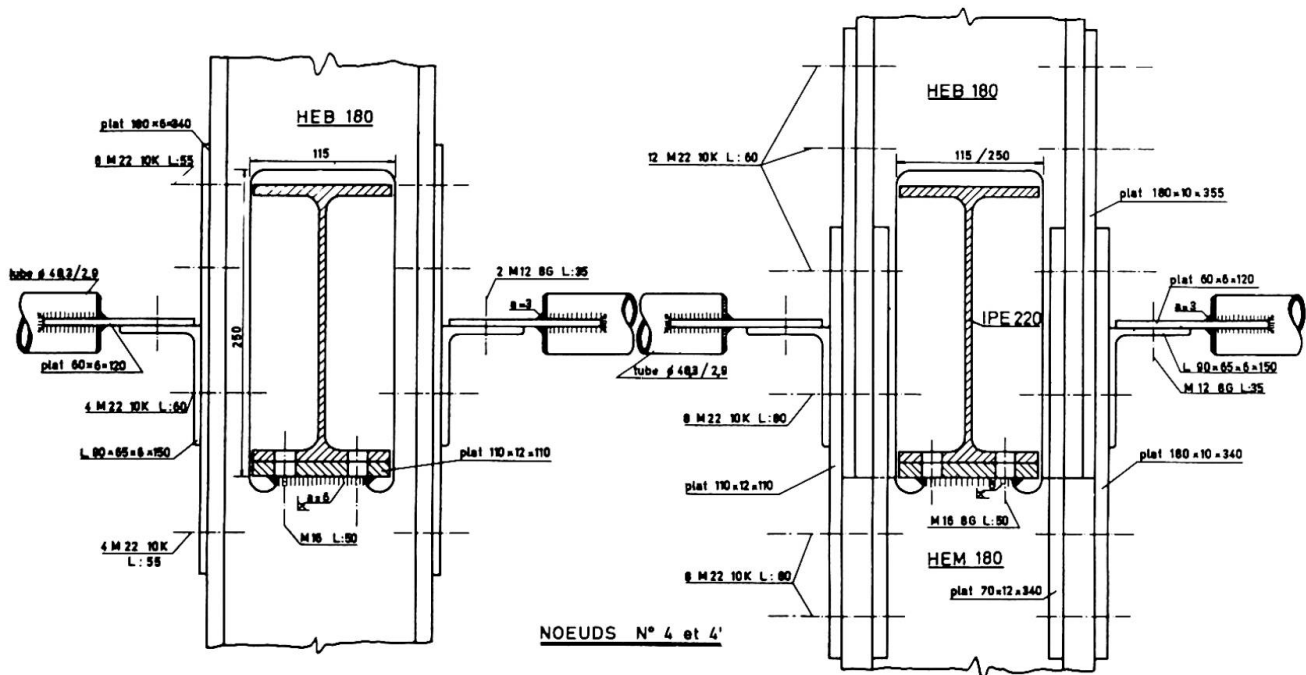
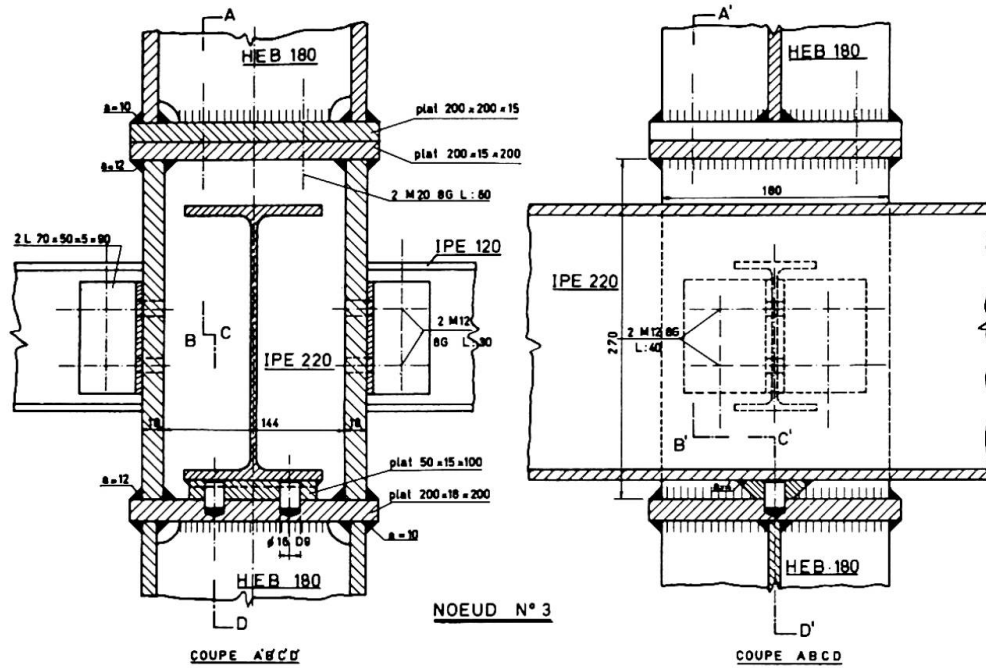
A simplification of this type of structure can be obtained by hinging continuous beams on continuous columns. The work of the designer is greatly reduced: beams are treated as continuous beams, either in plastic or elastic design; and columns become axially loaded, without bending. Such structures are also interesting from an economical point of view as substantial savings can be made on the columns, relatively to rigid-joint design. Of course, this advantage is partly compensated by an increase of the size of the beams. Two students working on different structures at Liege University have shown that the point of equilibrium between the two conceptions lies around 7 stories; the hinged solution shows better under this figure. When the number of stories increases, the bending effect in columns of rigid-joint structures become less and less significant against axial loading and this last effect governs the design, as in the hinged solution, so that the savings made on beams make the rigid solution more economical.

Of course, a prior requirement for the hinged-joints design is that these hinges may be effectively fabricated. Another requirement is that their cost must not off-set the savings made on the columns.

#### 2. DESCRIPTION OF THE CONNECTIONS.

In order to check these two points, a research sponsored by the CECA (Commission Européenne du Charbon et de l'Acier) was undertaken by SERCOM (Station d'Essais et de Recherches de la Construction Métallique) in the laboratories of Liege University. Four types of joints were designed (Fig. 1 - 2 - 3 - 4) and one sample of each tested.





N° 1 was developed from a scheme suggested by Romanian searchers working at Liège. The beam is cut at the joint and the two parts are placed on both sides of the web of the column, resting on small shoes. These are welded or bolted on the web of the column, and theoretically, they serve only during the assembly phase, for positioning the beams. On each half-beam, a small steel plate is welded on the lower flange and the bottom part of the web. They are joined together through the column by two high-strength bolts which insure transmission of the shear forces to the column. Compression efforts in the lower flange are transmitted directly by contact, while tensile forces in the upper flanges are transmitted through coverplates going through a hole purposely made in the web of the column. It is important to note that the plates on the webs of the beams must be as small as possible in height and the bolts as near as possible to the lower flange, in order to obtain a good rotational capacity of the beam. The design may be completed by shear stiffeners if needed, but they were not necessary in the tested model.

In N° 2 design, the beams are made of two U shaped profiles which pass on each side of the column. Each is supported by a small console, bolted to the flanges of the column. A small rocking skid is welded under the lower flange, to provide hinging. A bolt avoids translations. This system is quite simple, but the double-U beams are generally heavier than an equivalent I-beam, and they must be braced together against torsional effects proper to U-sections.

In type 3 design, the column is interrupted at joint level and provided with a hollow box, the walls of which must be able to resist the vertical forces coming from above. The beam goes uninterrupted through the box, hinged on a rocking skid and secured against translation by pins. The box is welded on top of the column section below, and the bottom of the above column section is bolted on top of the box. Of course, columns must not have a joint at each level, and they might come from workshop in lengths involving three or four boxes, in all-welded execution. It can be noticed here that, as the column buckles centrically, the orientation of the column does not matter, so it can be placed with its weak axis of inertia in the plane of the frame. In this way, the walls of the box are in the same plane as the flanges of the column, and the horizontal plates of the box may be relatively thin. If the column were placed with its strong axis in the plane of the frame, the walls and flanges would be orthogonal to each other and the horizontal plates would have to be very thick to provide a good transmission of forces. Anyway, troubles would occur at the corners of the flanges. This design, though quite simple in its principle, involves some disagreements which grow with the size of the column: milling of thick plates, much welding, etc... and the erection of a large structure with these joints could lead to some difficulties because of the necessity of running the beams through the boxes.

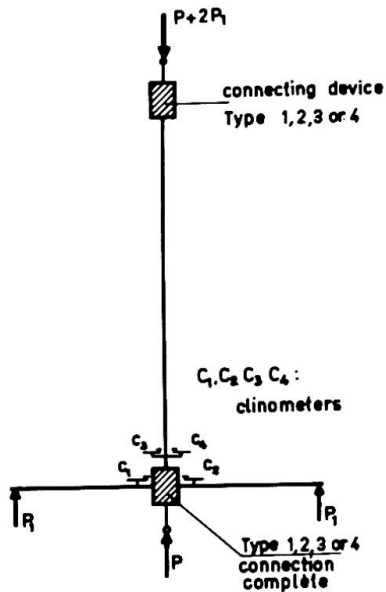
Type 4 is in some way a digest of types 1 and 3: a large hole is cut in the web of the column and the beam passes through it. The flanges are reinforced by cover plates to compensate for the hole. The beam rests directly on the edge of the web which is locally reinforced. The small tongue of web so formed constitutes the hinge. As in type 3, the beam-column connection can easily be combined with a joint in the column.



Each of the above connections is completed by connections between the column and the secondary beams. This does not lead to any difficulty.

### 3. TESTING LAYOUT.

The testing layout was arranged according to the scheme described at fig. 5 : (Specimen is turned upside down from normal position):



a column section supports two connections; the one at the bottom is complete, with main and secondary beam; the one at the top has only the connecting device and the beams are omitted.

The loading is composed of :

- vertical loading on the column, to simulate the effect of the higher stories ;
- vertical loading on the end of the main beam, to produce a negative moment in the beam at the right of the connection.

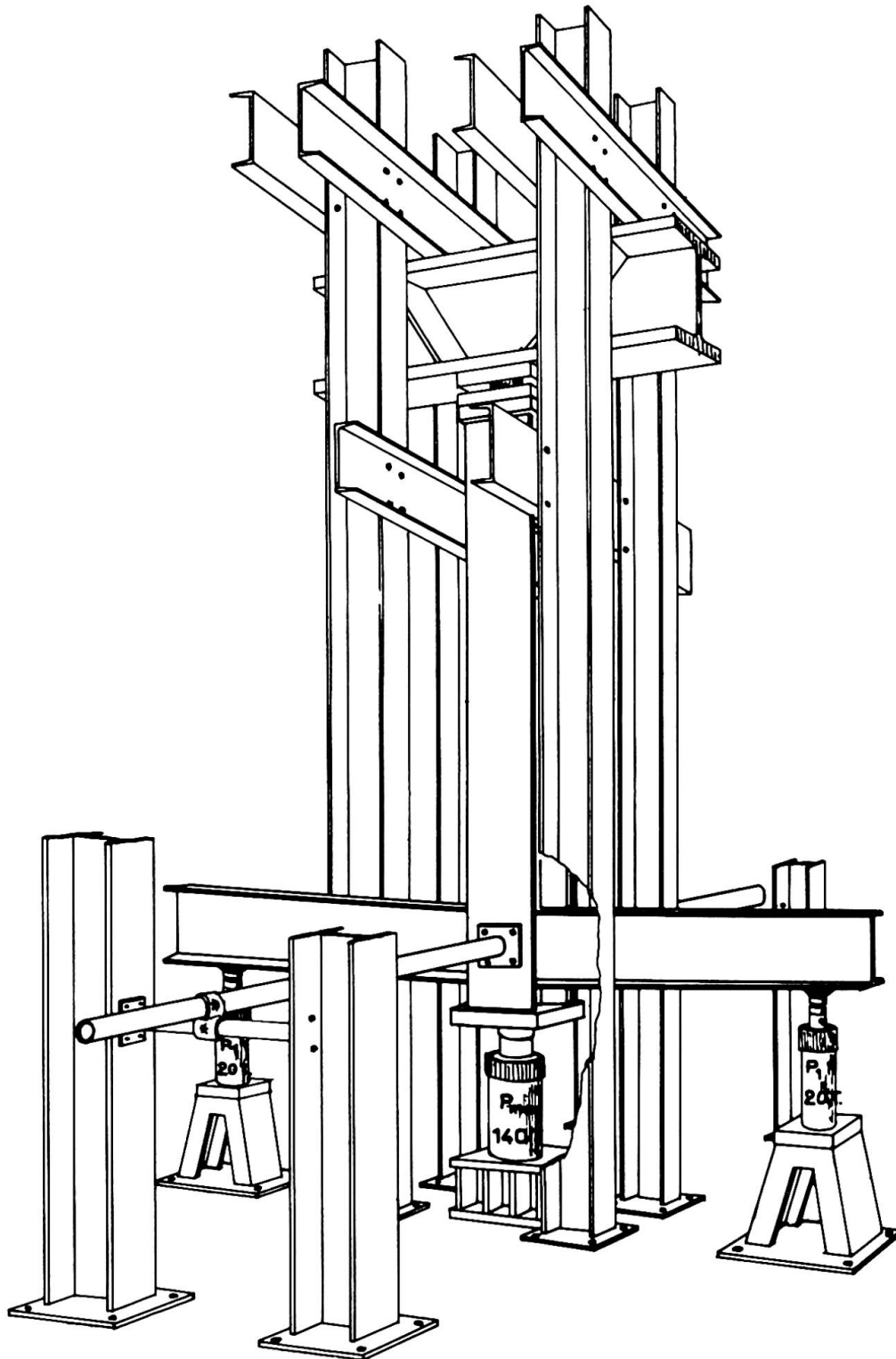
The column section is hinged at its two ends, with hinges placed as near as possible to the connection levels, in order to respect the buckling length.

The maximum load that could be applied with the testing equipment was 160 tons (metric), so it was decided to make the tests at a 6/10 scale.

The profile of the column was HEB 180, and for the beam: IPE 220 (and UPN180 for type 2). The distance between two levels was 2,10 m. The specimen so obtained represents a current column in a building of 8 x 4 m module, supporting loads of 750 kg/m<sup>2</sup>.

There is little to say about the testing apparatus :

The specimens are placed in a frame structure bolted to the concrete slab equipping the laboratory, and loads are applied by means of hydraulic jacks, placed under the column for the column load, and under the ends of the beam. Loads are controlled by strain-gages load cells. The apparatus is shown at fig. 6.



Testing for each specimen was conducted in three phases :

- In phase 1, a small load is applied to the column and two equal forces are applied to the beam at different distances from the column. In this way, the rotational capacity of the "hinge" can be tested.
- In phase 2, the loads on the beam, acting symmetrically, are increased until the full plastic moment is developed in the beam. A small load is applied on the column.
- In phase 3, the column loading is increased up to the collapse of the column or the maximum loading, whichever occurs.

During phase 1, measurement is made of the rotations of the beam and the column sections near the connection, by means of clinometers (see fig. 5).

During phases 2 and 3, only loads and the plastic rotation in the beam are measured.

#### 4. EXPERIMENTAL RESULTS.

##### 4.1. Phase 1 - Control of hinging action.

The table below gives the mean value of the rotations of the beam and the column during the phase 1 tests on the four types of connections.

The rotation was obtained by placing the beam jacks at 0.7 and 1.0 meter apart from the center of the joint.

For reasons of clarity, the values of the angular rotations  $\phi_c$  and  $\phi_b$  of the column and the beam, respectively, are given in decimal division of the degree .

The reference value is obtained by applying some load on the column (usually one ton) to get rid of errors due to the initial self-positioning of the different devices.

|               |               | Type 1   |          | Type 2   |          | Type 3   |          | Type 4   |          |
|---------------|---------------|----------|----------|----------|----------|----------|----------|----------|----------|
| $F_c$<br>Tons | $F_b$<br>Tons | $\phi_b$ | $\phi_c$ | $\phi_b$ | $\phi_c$ | $\phi_b$ | $\phi_c$ | $\phi_b$ | $\phi_c$ |
| 1.0           | 0             |          |          | 0        | 0        | 0        |          | 0        | 0        |
| 15.0          | 0             | 0        | 0        | 0.033    | 0.036    | 0.028    | less     | 0.06     | 0.06     |
| 15.0          | 0.5           | 0.13     | 0.015    | 0.46     | 0.038    | 1.79     | than     | 0.54     | 0.06     |
| 15.0          | 1.0           | 0.36     | 0.018    | 0.98     | 0.051    | 3.00     | 0.01     | 2.50     | 0.02     |
| 15.0          | 2.0           | 0.62     | 0.056    | 2.26     | 0.085    | ***      |          | ▼        |          |
| 15.0          | 3.0           | 0.89     | 0.086    |          |          |          |          |          |          |
| 15.0          | 4.0           | 1.45     | 0.120    |          |          |          |          |          |          |
| 15.0          | 5.0           | * 2.60   | 0.206    |          |          |          |          |          |          |
| 15.0          | 0             | * 1.45   | 0.016    | 0.28     | 0.037    |          |          |          |          |
|               |               | **       |          |          |          |          |          |          |          |

\* When this value was reached, web of beam was abutting against web of column.

\*\* Actually,  $F_c$  for this tests was not maintained constant, but gradually increased from 15 tons ( $F_b = 0$ ) to 22 Tons ( $F_b = 5$ ) and back to 15 tons.

\*\*\* The freedom of rotation was such that no state of equilibrium could be obtained beyond 0.5 T. The 3.00 deg. value was reached before 1.0 T was acting as  $F_b$ .

▼ Test was stopped at this point because farthest jack was out of stroke.

As can be seen from above results, all four types of connections behave satisfactorily, and have a good rotational ability. As could be predicted, type one is the stiffest of the four.

The rotation of the beam occurs without inducing significant rotation in the column, excepted for the "stiff" type one. But even for the latter, the rotation of the column does not exceed ten percent of that of the beam.

Furthermore, some part of the column's rotation may be a result of the increasing of the load on the column, as the whole specimen is hinged at its two ends.

The lower hinge<sup>is</sup> constituted by the jacks themselves, and for kinematical reasons its center of rotation is the center of the lower face of the corresponding bearing plate.

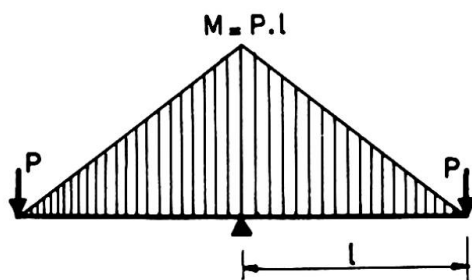
So, it may be concluded that the four proposed types can be considered as real "hinged" connections. The relative rotation of more than 2 degrees between beam and column is far beyond service values.

#### 4.2. Testing of resistance.

##### 4.2.1. Phase 2 - Moment transmission capacity.

The steel of the IPE 220 beams, theoretically of A 37 grade, has its yield-point at  $28 \text{ kg/mm}^2$ , which leads to a theoretical plastic moment of 8.400 kgm. For the UPN 180, these values were  $30 \text{ kg/mm}^2$  and 5.125 kgm, respectively, giving 10.250 kgm for the tested double beam.

The beams were submitted to the moment distribution of fig. 7, obtained by placing the two jacks at one meter from the column.



This distance was chosen in order to respect the shear-moment relationship existing at the support of a uniformly loaded continuous beam. A 15 T load acted on the column.

Lateral buckling of the beam was prevented by appropriate guiding devices or local reinforcement of the tips.

The whole specimens were coated with whitewash to allow visualization of the development of plastic yielding.

The behaviour of the four specimens was as follows :

Type 1 : At 9 Tm, a gliding in the joint of the flanges, and yielding of both upper flanges occurred, thus forming a plastic hinge.  
The relative rotation between the two halves of the beam was 4.3 deg.

Type 2 : At 9 tm, some yielding appeared in the webs, near the support, combined with some bending of the consoles.

Yielding developed regularly when load was increased, until it appeared on the flanges at 11 Tm. The formation of the plastic hinges continued until the test was stopped at 12.0 Tm. The relative rotation of the two halves was 5.7 deg.

Type 3 : Plastic hinge began to form at 9 Tm and processed while loads was increased up to 11 Tm, where the beam collapsed by buckling of the compressed flange. Rotation was 7.8 deg.

Type 4 : At 9.0 Tm,  $45^\circ$  shear yield-lines appeared in the web of the beam, at the support.

At 9.45 Tm, some yielding began in the web of the column under the beam.

At 10.9 Tm, the stretched flange of the beam began to yield while the compressed flange collapsed by local buckling on both sides of support. Total relative rotation was 6.6 deg.

It is clear from above results that the four connections are perfectly able to perform the transmission of the full plastic moment of the beam. None showed premature failure or instability in the beam, the column or the binding parts before reaching the plastic moment.

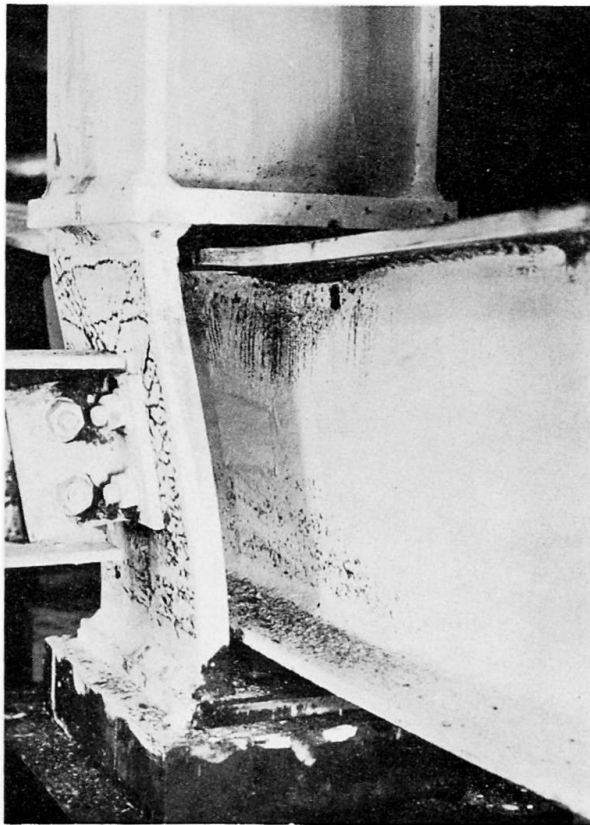
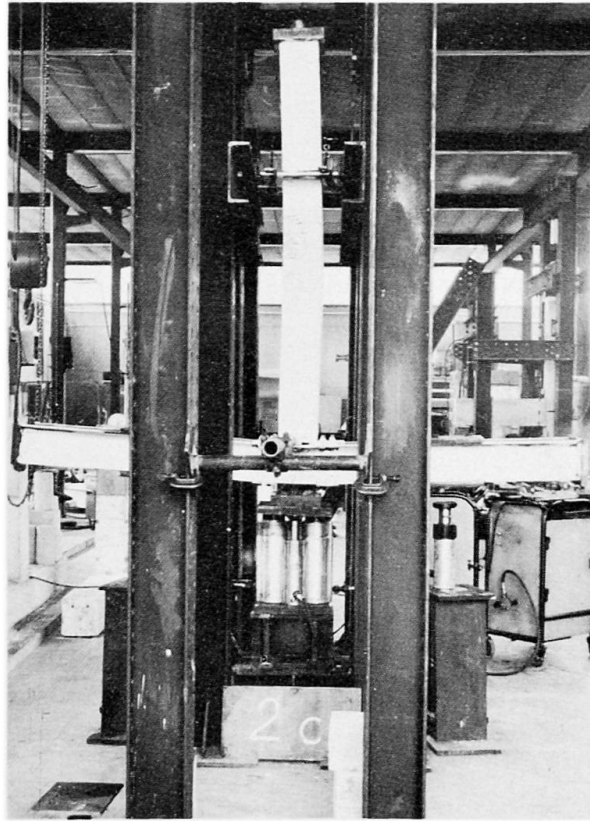
#### 4.2.2. Phase 3 - Vertical load transmission capacity.

For this test, the load acting on the column was increased as high as possible, while a load of 10 Tons was maintained in the two beam-jacks.

The four specimens behave as follows :

Type 1 : The column buckled in the weak plane under a load of 130 T.  
No special phenomenon occurred in the hole in the web.

Type 2 : The column buckled in the weak plane under a load of 158 T.  
Fig. 8 gives a general view of the testing apparatus, with buckling column of type 2 specimen.



Type 3 : The upper box, with no primary nor secondary beam, began to show signs of yielding in the walls at 95 T.

The upper box collapsed by buckling of the walls at 117 T.

That box was then removed and the load increased again. The test was interrupted at 156 T, when the lower box, in turn, collapsed by local buckling (see fig. 9). That difference in the resistance of the two boxes is due to the fact that the lower box is reinforced locally by the connecting parts for the secondary beams, and braced by those beams, while the upper box is not.

Type 4 : Load was increased up to 160 T without exhausting the resistance of the specimen.

We do not intend here to make a complete discussion of the buckling of the column, as this was only a secondary aspect of the research. It will suffice to observe that, excepted for type 3, the collapse of the column, when achieved, obviously proceeded from the overall conditions of testing and not from local weakenings due to the connections. In case of type 3, it can be seen that the boxes are weak points of the structure. The walls of the box should be reinforced in order to prevent buckling, either by thickening the walls or by welding stiffeners thereon.

## 5. CONCLUSIONS.

From the above results, we may conclude that at least three of the four types of tested connections completely fulfill the required strength conditions : they are able to transmit the full plastic moment, they have a sufficient hinging action and they do not involve early local failure or collapse.

The fourth (type 3), though satisfactory as far as hinging and bending behaviour are concerned, should be improved with respect to its behaviour under vertical loading. One improvement could be the use of T-shaped walls, instead of plates, the webs being placed vertically and outside, thus serving accessorially as binding part with the secondary beam.

Up to now, we do not have enough information to make a numerical estimation of the cost of a plastically designed "hinged" structure, and compare it with the cost of the same structure with rigid connections. Such a study would be rather intricate as, to be complete, it should include not only the cost of steel and labour to manufacture the connections, but also a comparison of the ease or difficulty of assembly (local and global) in each conception and a prevision of the troubles that could appear in one and not in the other.

However, if as a first approximation, we limit the comparison to the connections themselves, it can be expected that the hinged connections will not be more expensive than rigid ones, excepted for type 3 (which had also the less interesting behaviour).

Type 2 and 4 which are quite simple, could even reveal cheaper.

There is thus reasonable matter to hope that the "hinged" solution could lead to actual savings.



The prior requirement for the application of this solution, that is feasibility is then certainly met, and it can be expected that the second, that is economy, will be, too.

#### ACKNOWLEDGMENTS.

The authors thank the personal of the Laboratory of Strength of Materials and especially Mr. J. HAINAUT, Engineer-technician, for the considerable help they gave in performing the tests.

#### RÉSUMÉ

Cet article présente quelques essais effectués à l'Université de Liège sur des noeuds articulés destinés à des ossatures, du type "à noeuds fixés", conçues avec poutres et colonnes continues articulées entre elles à leurs points de jonction.

Quatre types de noeuds sont décrits, ainsi que les résultats d'essais sur la capacité de rotation des articulations, la résistance à la flexion, et la résistance aux charges verticales.

La discussion des résultats montre que le comportement des noeuds est très satisfaisant et l'article se termine par quelques considérations d'ordre économique.

#### SUMMARY

This paper presents some tests made at Liege University on hinged connections between continuous beams and columns of accordingly designed non-sway frames.

Four types of connections are described, so as the results of tests made on them, investigating rotational ability, bending moment transmission, and vertical load transmission.

A discussion of the results shows that the connections behave satisfactorily, and paper ends with some economical considerations.

#### ZUSAMMENFASSUNG

Dieser Beitrag beschreibt einige Versuche der Universität Lüttich über gelenkige, unverschiebbliche Balken und Stützen, die gelenkig verbunden sind. Vier Knoten werden beschrieben, ebenso die Versuchsergebnisse über die Drehfähigkeit der Gelenke, die Biegefestigkeit sowie die Tragfähigkeit gegen lotrechte Lasten. Die Ergebnisse über das Verhalten der Knoten sind sehr zufriedenstellend. Betrachtungen über die Wirtschaftlichkeit beschliessen den Bericht.

### **Inelastic Behaviour of Reinforced Concrete Shear Wall-Frame**

Comportement inélastique de structures en béton armé composées de murs et de portiques

Unelastisches Verhalten der Stahlbeton-Scheibenrahmen

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#### INTRODUCTION

This paper presents some results of a computer study of the behavioural characteristics of a plane reinforced concrete frame braced laterally by a shear wall. The method of analysis employed traces the load-deflection behaviour of the structure until failure occurs either by instability or by a collapse mechanism. The members are assumed to be elastic-perfectly plastic.

The behaviour of a twenty storey two bay reinforced concrete structure is taken as the basis for the discussion. The properties of the structure were adjusted to study the effects of variations in the wall stiffness, axial shortening of the wall and columns, and the secondary or  $P-\Delta$  moments due to lateral deflections.

#### METHOD OF ANALYSIS

Many first order elastic solutions exist for the case of a frame coupled with a shear wall subjected only to lateral loads. In addition, a number of elastic-plastic solutions for unbraced metal frames have been described in the literature. To date, however, the inelastic action of coupled shear wall-frame structures has not been studied extensively.

The analysis on which these results are based provides a second order elastic-plastic solution to the coupled shear wall-frame system <sup>(1)</sup>. An iterative procedure is used to solve slope-deflection equations modified to consider axial load effects and the finite shear wall width. As the loads are incremented and plastic hinges are detected in the structure, adjustments are made to the appropriate slope-deflection equations. Axial shortening of the columns and walls is considered although creep deflections have been ignored. Failure may be due to instability or the formation of a collapse mechanism. The structure is assumed to be braced against local and out-of-plane buckling. It is possible to consider any rectangular configuration of beams, columns and walls in a single plane.

For reinforced concrete members an elastic-perfectly plastic moment-curvature relationship has been derived for the girder, column and wall sections. This relationship considers the section geometry, material properties and the effects of axial loads. Deformations due to shear or inclined cracking have not been considered.

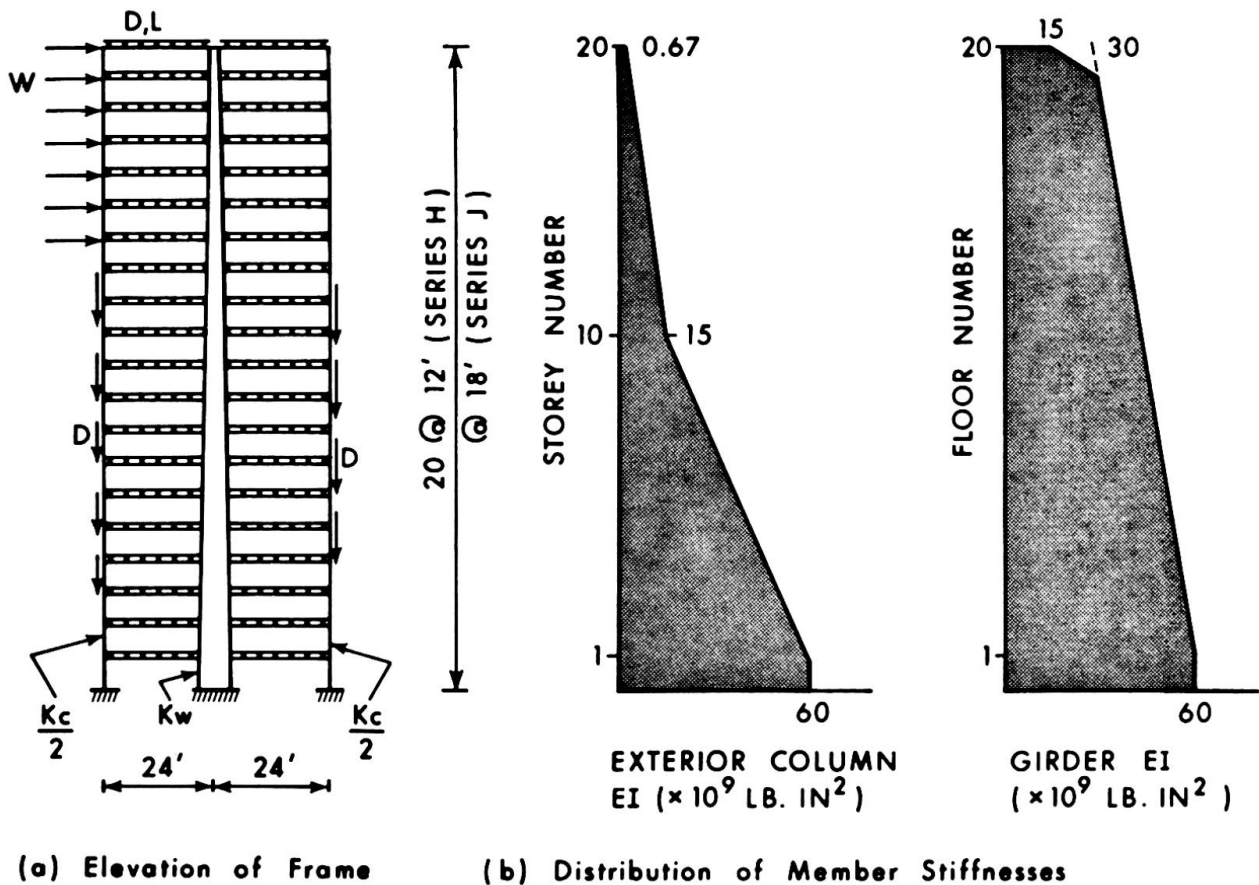


Figure 1. DETAILS OF FRAMES

STRUCTURE AND LOADING

The behaviour of two series of reinforced concrete frames will be discussed in this paper. The frames will be referred to by means of a letter denoting the frame series and a number denoting the ratio,  $K_w/K_c$ , of the EI of the shear wall to the sum of the EI values of the columns in each storey. Details of the frame geometry and the distribution of member stiffnesses are shown in Fig. 1.

The series H and J frames had a 12 foot and an 18 foot storey to storey height, respectively. In each case they consisted of square, symmetrically reinforced tied columns with a total longitudinal reinforcement ratio of 0.04 and rectangular beams reinforced in tension only with  $\rho_f/f'_c = 0.18$ . In all cases the yield strength of the reinforcement was taken as 60,000 psi and the concrete strength was assumed to be 4,000 psi.

To facilitate studies of the effects of variables, all the frames discussed in this paper had the same columns and beams. The structure H1 was designed by the ultimate strength procedures in the ACI Building Code assuming material understrength factors,  $\phi$ , equal to 1.0 for all members. The resulting member stiffnesses are plotted in Figures 1(b) and 1(c). The series J frames had the same member sizes as the series H frames.

The columns varied in size from 8.5 inches square in the top storey to 22 inches square in the bottom storey. The girders varied from 10 inches wide by 22 inches deep at the roof to 14 by 30 inches at the first floor.

In frames H1 and J1, designed as unbraced frames, the "shear walls" were solid tied column sections with 4 percent longitudinal reinforcement. These walls varied from 9.5 inches square in the top storey to 26 inches square in the bottom storey. To augment the shear wall stiffness in the other frames the moment of inertia and plastic moment capacity of the wall were increased by the appropriate value of  $K_w/K_c$ . The width of the wall in the plane of the frame was kept constant to eliminate the effects of wall-width from the basic study. Similarly, to minimize the effects on hinge formation of the relative axial shortening of the wall and columns, the wall area was held constant as  $K_w/K_c$  was varied.

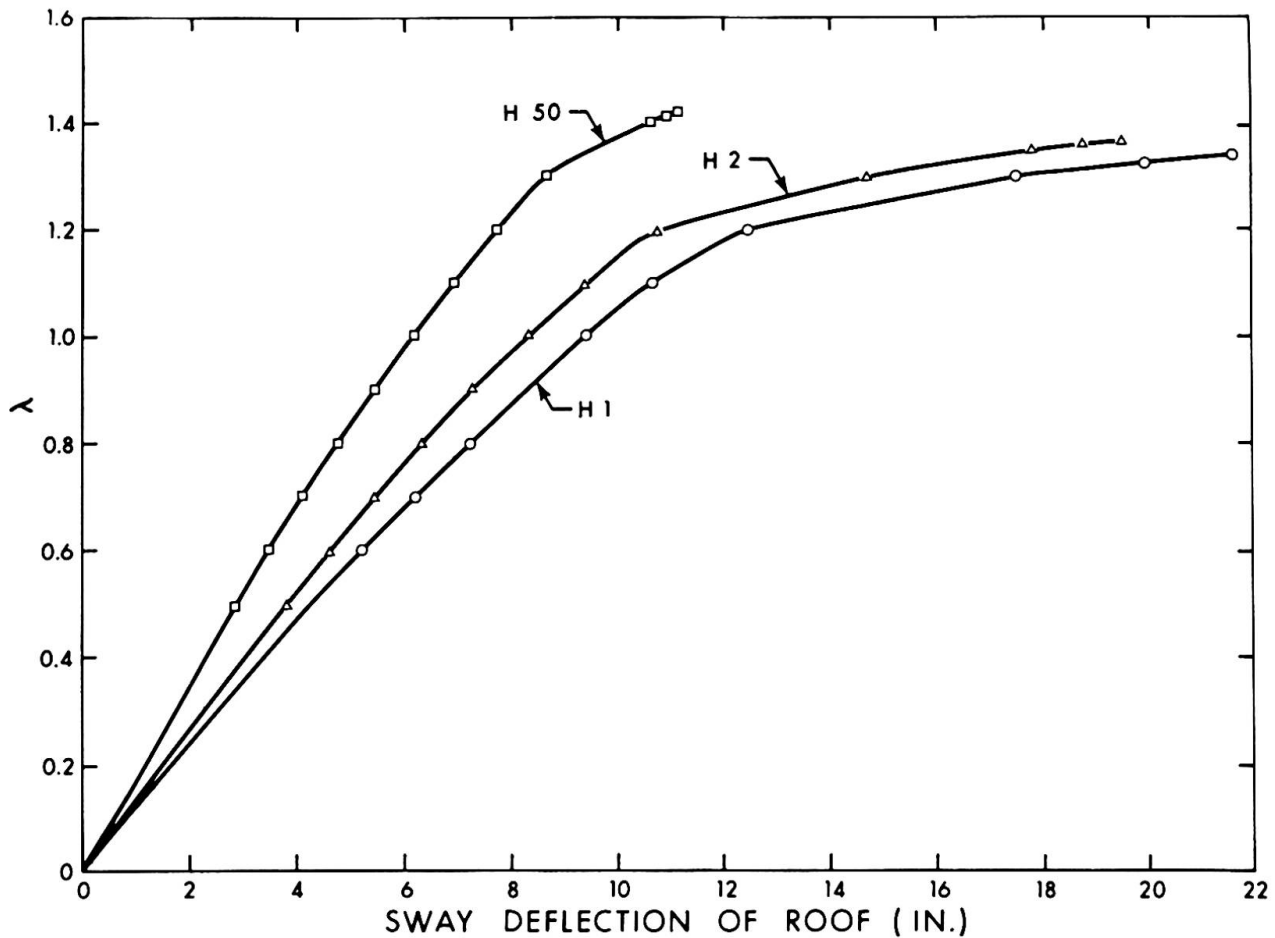


Figure 2. EFFECT OF WALL STIFFNESS ON SWAY DEFLECTION OF TOP OF FRAME

In all cases the loading was applied statically and was proportionally increased until failure occurred. In this paper results will be given in terms of the load factor  $\lambda$  in the expression  $\lambda(D + L + W)$  where  $D$ ,  $L$  and  $W$  represent reasonable working load values of the dead, live and wind loads for structures of the type considered.

#### EFFECTS OF VARIATION OF WALL STIFFNESS ON LOAD DEFLECTION BEHAVIOUR

Second order elastic-plastic analyses were carried out on Series H and J frames with relative wall stiffness values,  $K_w/K_c$ , of 1, 2, 6, 12, 20, and 50. Typical load-deformation plots from these analyses appear in Figure 2. Figure 3 shows bending moment diagrams for the walls in frames H1 and H50 at  $\lambda = 1.00$ , prior to the formation of any plastic hinges in the structure.

It is apparent that, although the wall and columns of Frame H56' possess a total lateral stiffness of 25.5 times that in H1, the overall frame stiffness does not increase in this proportion. This can be explained by the difference in behaviour between a portal frame and a cantilever wall. Inspection of the wall bending moment diagrams in Figure 3 indicates that the stiffening function of the wall is diminished as the structural action reverts to cantilever behaviour at the base of the wall, as indicated by a gradual shift of the initial point of contraflexure up the wall as the wall stiffness increases. Similar behaviour was noted in the Series J frames.

In considering the effect of wall stiffness on the portion of the total lateral load carried by the wall it was also evident that the loads carried by the wall did not increase in direct proportion to the increase in the relative stiffness of the wall.

The implication of this is that, except for structures with extremely stiff walls, the frame members may be underdesigned if the wall is assumed to carry the entire lateral load.

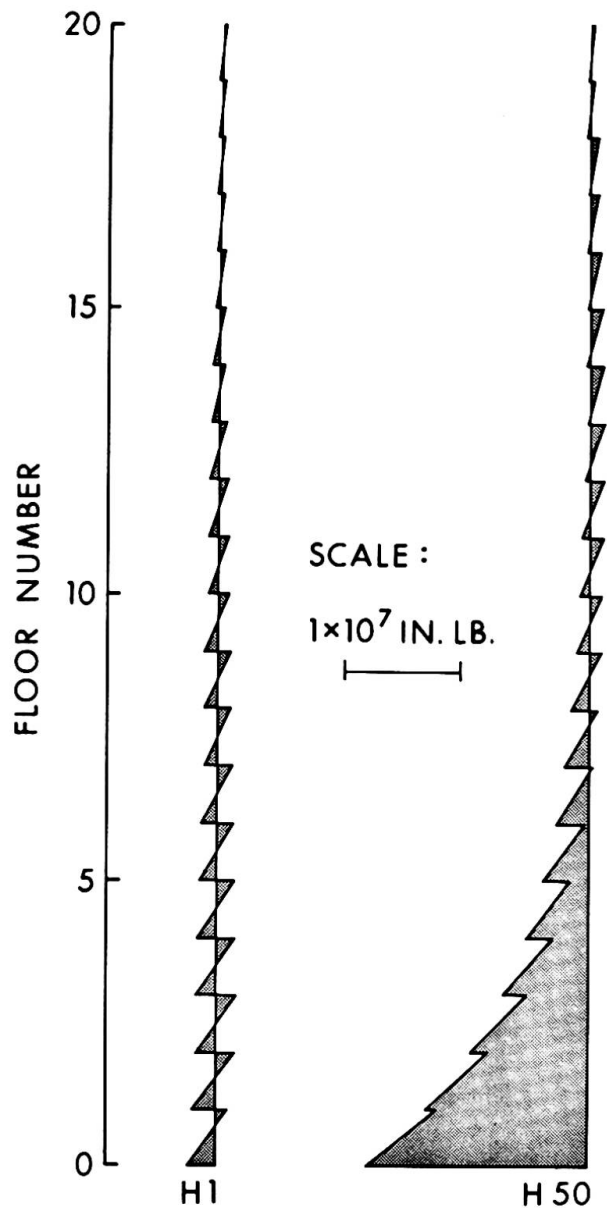


Figure 3. BENDING MOMENTS IN THE WALLS IN FRAMES H1 AND H50 AT WORKING LOADS

EFFECTS OF COLUMN AXIAL SHORTENING

Frame H1 was used as the basis for a study of the effects of relative axial shortening of the columns and wall in a frame. The load-deflection plots from three analyses of this frame are shown in Figure 4.

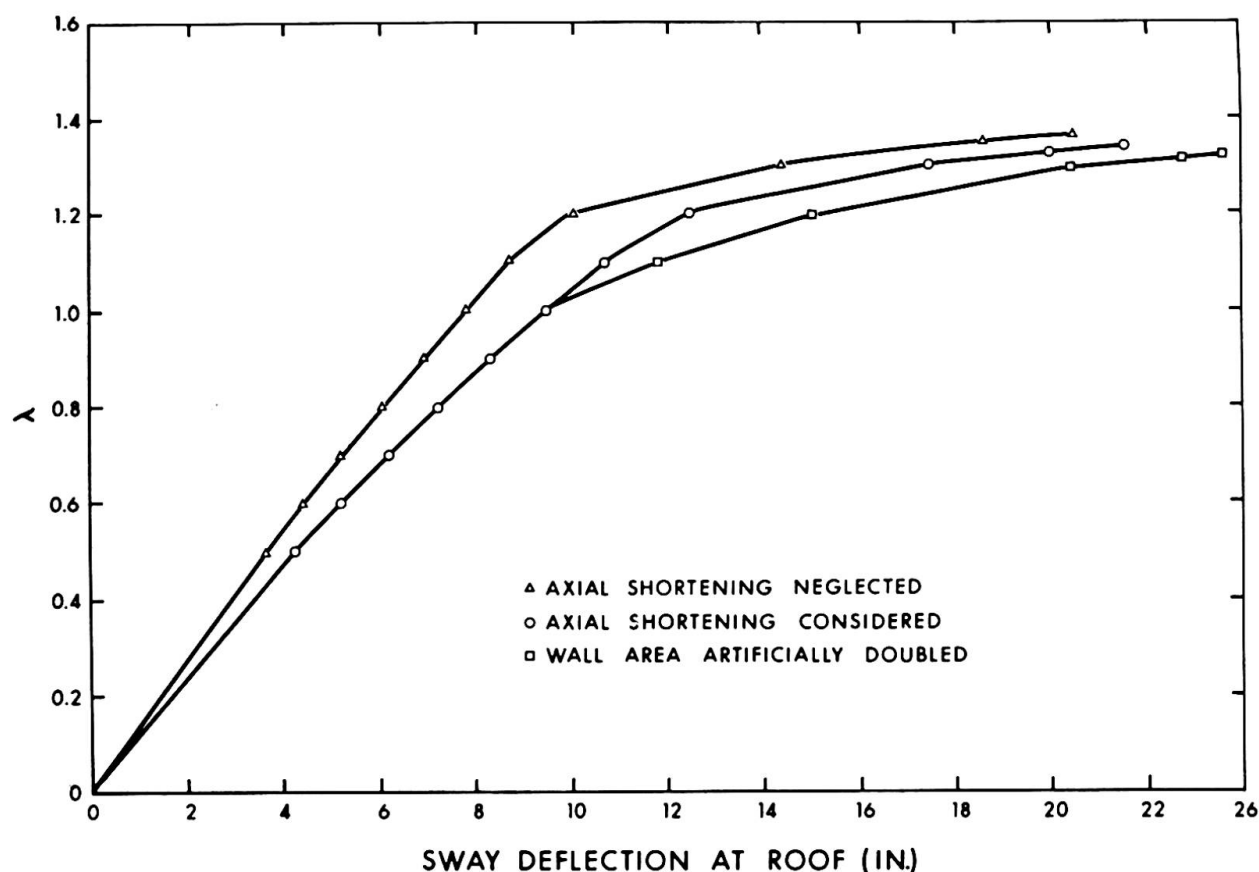


Figure 4. EFFECTS OF AXIAL SHORTENING IN FRAME H1

In this particular case the lateral deflection of the top storey at working loads was underestimated by 18 percent and the failure load was overestimated by 2 percent when the axial shortening of the members was neglected.

When the wall area was doubled without changing its EI or plastic moment capacity there was no change in the stiffness of the structure at low loads. However, the reduction in the axial shortening of the wall resulted in greater relative column to wall deflections and caused premature hinges in the girders near the top of the structure. This reduced the stiffness of the structure and led to earlier instability.



This effect was more pronounced when the ratio of shear wall stiffness to column stiffness was greater, especially if the shear wall section remained constant over the height of the building. These results have not been included here since in most practical designs the thickness of the core walls would be varied in accordance with the axial loads in the core. However, in the case of buildings with prismatic core walls as might be the case if the core was slipformed, for example, the relative axial shortening of the walls and columns should be considered.

#### TRANSITION FROM SWAY INSTABILITY TO BRACED FRAME INSTABILITY

In conjunction with the second order elastic-plastic analyses, first order elastic analyses were performed on the Series H and J frames. The resulting bending moment values were compared to observe the significance of the secondary ( $P-\Delta$ ) moments in the various frames. This effect was expressed in terms of a moment magnifier,  $F$ , equal to the second order analysis moment at any point divided by the corresponding moment from the first order analysis.

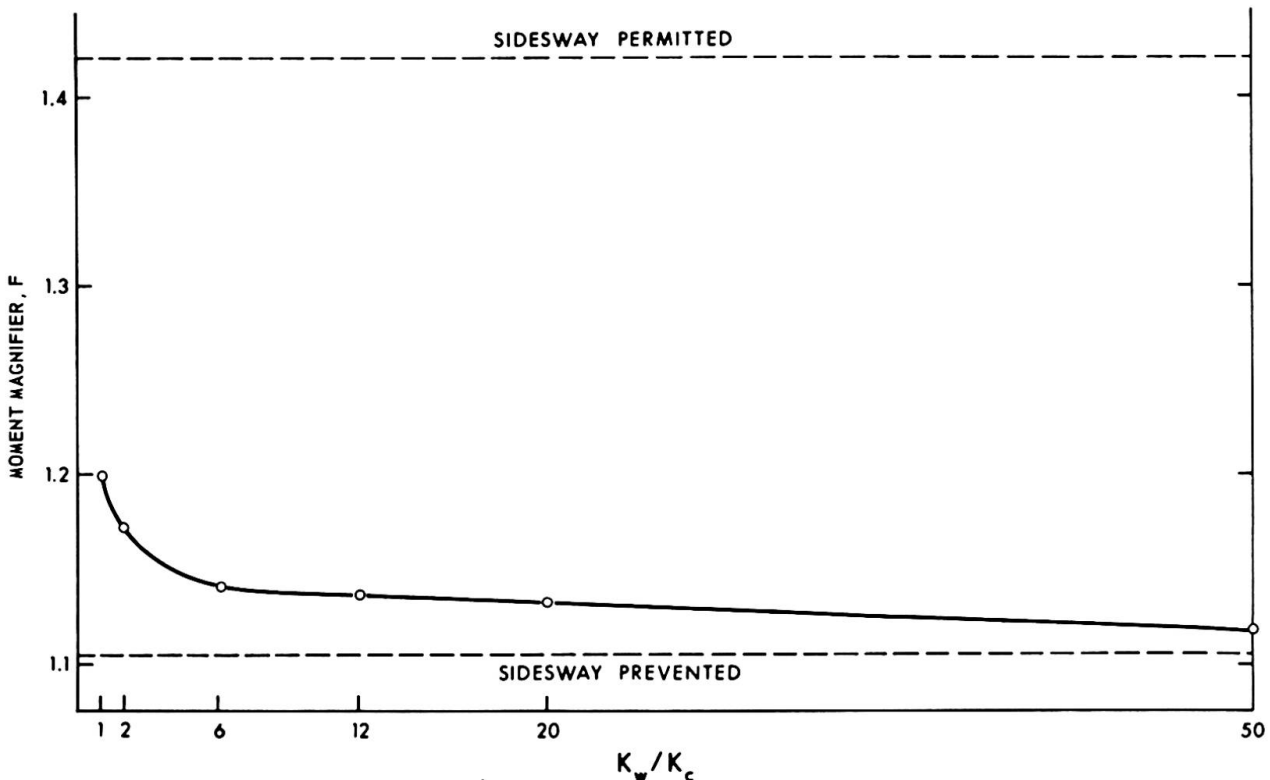


Figure 5. EFFECT OF RELATIVE WALL STIFFNESS ON MOMENT MAGNIFIER

The values of the moment magnifier,  $F$ , at working loads ( $\lambda = 1.00$ ) in the leeward column of the ninth storey of Series J frames are plotted as a function of  $K_w/K_c$  in Figure 5. It should be noted that at  $\lambda = 1.00$ , no hinges had formed in any of the structures considered. The two horizontal dashed lines appearing on this graph represent the values of  $F$  derived using the traditional moment magnifier relationship <sup>(2)</sup> given by Equation 1. The critical load,  $P_e$ , is based on a nomographic evaluation of effective length <sup>(2, 3)</sup>.

$$F = \frac{1}{1 - \frac{P}{P_e}} \quad \dots \dots \dots (1)$$

The  $F$  values derived from this analysis never approached the values computed using Equation 1 assuming the frames are free to sway. Part of this discrepancy is caused by the fact that the values of the effective lengths used were derived assuming a typical interior column in an infinitely large, rectangular structure. In addition, the effective lengths were derived assuming only axial loads in the columns, while the frames considered here had both wind and uniformly distributed gravity loads.

On the other hand, however, for values of  $K_w/K_c$  greater than about 6, the moment magnifier values computed in this study did approach the  $F$  values computed using Equation 1 assuming a frame braced against sidesway. Similar effects were noted for the columns in other stories of the H and J frames.

The values of the moment magnifiers presented in Figure 5 suggest that a safe approximate design procedure for multi-storey frames would be:

- (1) Analyze forces and moments using a conventional first order elastic analysis.
- (2) Amplify the column moments, and where necessary the girder moments, using a moment magnifier given by Equation 1. The effective length for braced columns could be used in computing  $P_e$  if  $K_w/K_c$  is greater than 6, and that for unbraced columns if  $K_w/K_c$  is less than 6.
- (3) Design all sections to have a plastic moment capacity equal to or greater than the moments computed in Step 2.

NOTATION

- $F$  = Moment Magnifier
- $f'_c$  = Compressive strength of the concrete
- $f_y$  = Yield strength of the reinforcement
- $K_c$  = Sum of  $EI/h$  values for all columns in any storey
- $K_w$  =  $EI/h$  of shear wall in any storey
- $P$  = Axial load on column
- $P_e$  = Euler column buckling load

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SUMMARY

An elastic-plastic analysis for reinforced concrete structures consisting of a coupled frame and shear wall has been derived and applied to several examples. The results of this analysis suggest that relative axial shortening of walls and columns may lead to a premature instability failure of the structure. In addition, the studies suggest that a relatively low shear wall stiffness is required to change the behaviour from that of an unbraced frame to that of a braced frame with respect to instability.

RÉSUMÉ

L'analyse plastique-élastique pour des structures de béton armé composées d'un cadre et d'un mur accouplés a été dérivée et a été appliquée à plusieurs exemples. Les résultats de cette analyse suggèrent que le raccourcissement axial relatif des murs et des colonnes peut conduire à un affaiblissement de la structure dû à une instabilité prématurée. En addition, les études montrent qu'un mur d'assez petite rigidité suffit pour changer les propriétés de stabilité d'un portique seul en celles d'un portique renforcé d'un mur bien rigide.

## ZUSAMMENFASSUNG

Eine elasto-plastische Analyse für Stahlbetonhochhäuser bestehend aus einer Zusammenfassung von Rahmen und Schubwand ist präsentiert durch verschiedene Beispiele. Die Resultate dieser Analyse regen an, dass eine verhältnismässige Verkürzung der Wände und Stützen zu einem vorzeitigen Zusammenbruch des Bauwerks führen mögen. Des weiteren schlagen die Studien vor, dass eine verhältnismässig niedrige Schubwand-Steifigkeit erforderlich ist, um eine Veränderung des Verhaltens, mit Hinsicht auf die Unstabilität, zwischen einem unverankerten und verankerten Rahmen zu erzielen.

### IIIa

#### **Approximate Inelastic Analysis of Shear Wall-Frame Structures**

Analyse inélastique approximée pour des structures composées de portiques et de murs

Angenäherte unelastische Berechnung von Scheiben-Rahmentragwerken

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#### INTRODUCTION

Plastic design methods are available for structures in which sway displacements are completely prevented and for those which consist entirely of moment resisting frames <sup>(1)</sup>. Both methods are based on assumptions which make the design of tall structures feasible even using manual computation procedures.

Commonly, however, multi-story structures are neither completely braced nor unbraced but consist of frames coupled to flexural shear walls <sup>(2)</sup>. The shear walls have greater stiffnesses than do the frames and thus tend to dominate the behavior of the structure.

Under lateral loads the deflected shapes of the free frame and shear wall are shown in FIGS. 1 (a) and (b). Since the deformations of the two elements must be compatible, the final deflected shape of the structure will be that shown in FIG. 1 (c). In the top stories the shear wall exerts large shears on the frame. These shears are accounted for in present elastic design procedures which consider the interaction between the frame and shear wall <sup>(3)</sup>.

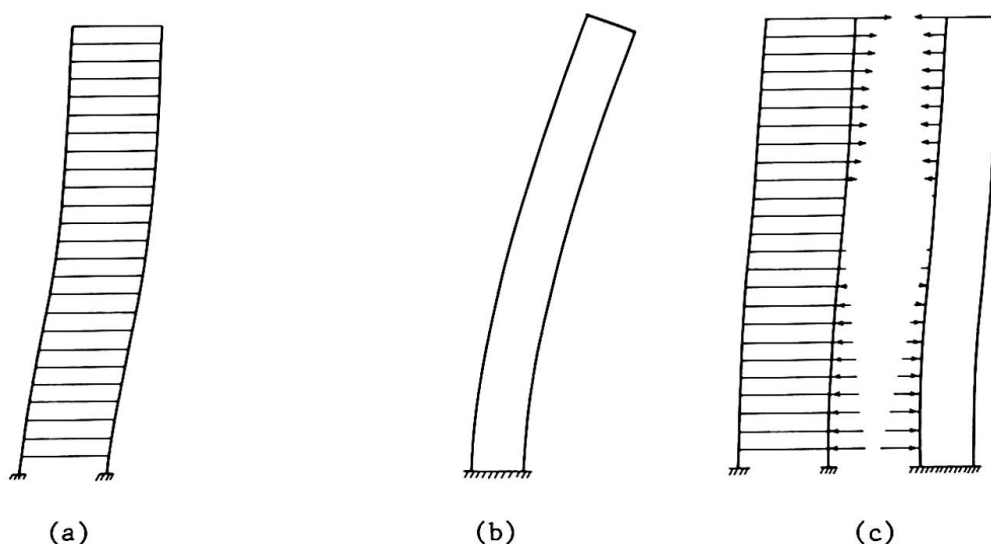


FIG. 1. DEFLECTED SHAPES

In the inelastic range, the frame-shear wall interaction may force plastic hinges to form in the frame early in the loading history, thus reducing the stiffness for additional load increments. The vertical loads on the structure acting through the lateral displacements produce "secondary moments" known as  $P-\Delta$  moments. The  $P-\Delta$  effect combined with the inelastic action of the structure may cause significant reductions in load-carrying capacity.

#### METHOD OF ANALYSIS

To reduce the analysis of the structure to manageable terms the actual structure is replaced by the model shown in FIG. 2. The shear walls and frames of the actual structure have been replaced by the systems shown. These are designed to have equivalent lateral stiffnesses and strengths <sup>(4)</sup>.

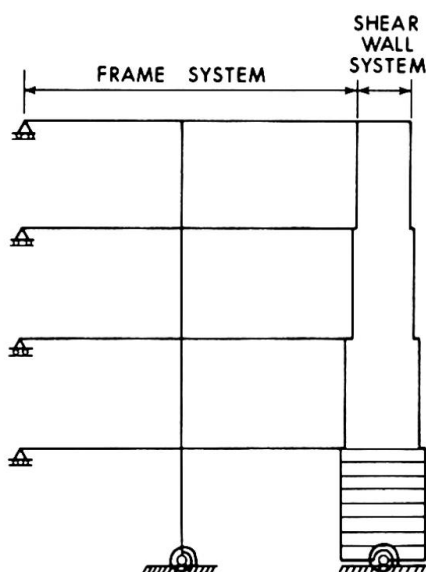


FIG. 2. ANALYTICAL MODEL

This procedure implies that the structures considered are reasonably symmetrical and do not exhibit significant torsional deformations. The lumping procedures used to form the analytical model are similar to those used for the elastic analysis of frame-shear wall structures <sup>(3)</sup>

To analyze the model for a given set of lateral loads, the loads are first applied to the shear wall and its free deflection is computed. The frame is then forced into a compatible set of deformations and the shears developed by the frame are computed. These are applied to the wall as corrective forces and a new deflected shape computed. The process is continued until the total shears developed are in equilibrium with the applied lateral loads <sup>(3)</sup>. To obtain the complete load-deformation relationship for the structure the lateral loads are increased and the above process is repeated.

At each step in the process the inelastic action of the frame and the shear wall is accounted for by using the inelastic moment-curvature ( $M-\theta$ ) relationships in the computation of deflections and the resulting forces <sup>(4)</sup>. An elastic perfectly plastic  $M-\theta$  relationship is used for the frame members with the plastic moment capacity of the columns reduced to account for axial loads. For the shear wall a bilinear  $M-\theta$  relationship is assumed.

The  $P-\Delta$  effect is also included at each stage of the process. The secondary moments in each story are computed from a knowledge of the deflected shape and vertical loads. The corresponding shears are then added at each floor level and the additional deflections computed. The process is continued until the deflected shapes converge.

#### FOURTEEN-STORY BUILDING

The first structure considered is a fourteen-story building, rectangular in plan, with nineteen bays of 11 feet 6 inches in the long direction and three bays of 20 feet 0 inches in the short direction. The building had been analyzed previously for a load of 20 psf. applied perpendicular to the long side of the building <sup>(3)</sup>. The results are presented only to check the validity of the analytical model shown in FIG. 2.

The properties of the original structure are given in REF. 3. The analytical model is shown in FIG. 3, the members have been lumped to form the



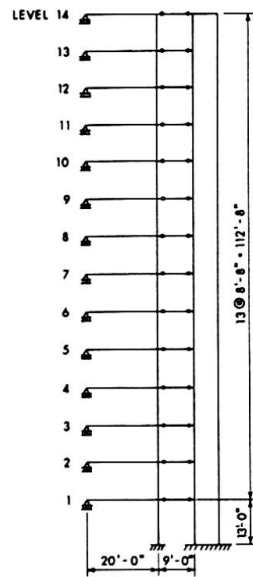


FIG. 3. FOURTEEN-STORY BUILDING

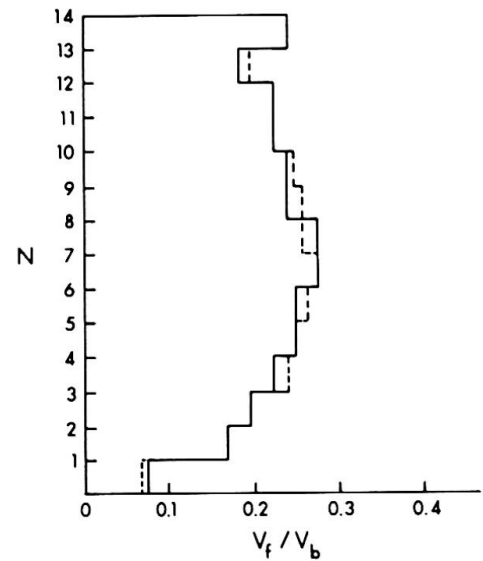


FIG. 4. SHEAR DISTRIBUTION

equivalent systems <sup>(4)</sup>. In FIG. 4 the story number,  $N$ , is plotted versus the proportion of the total base shear carried by the frame,  $V_f/V_b$ . The solid lines indicate the shears obtained using the model shown in FIG. 2, the dashed lines represent the results obtained previously <sup>(3)</sup>. The agreement is satisfactory. At this stage of loading the structure is elastic and the  $P-\Delta$  effect has little influence <sup>(4)</sup>.

In FIG. 4, the frame shear,  $V_f$ , is relatively constant in the top portion of the structure. The applied shear, however, increases linearly (approximately) from the top of the structure. Thus the top stories of the frame must carry shears in excess of those applied on the story due to the pull exerted by the shear wall. To study the influence of the wall stiffness on the shear distribution several additional analyses were performed. The structure was changed for each analysis by reducing the stiffness of the shear wall

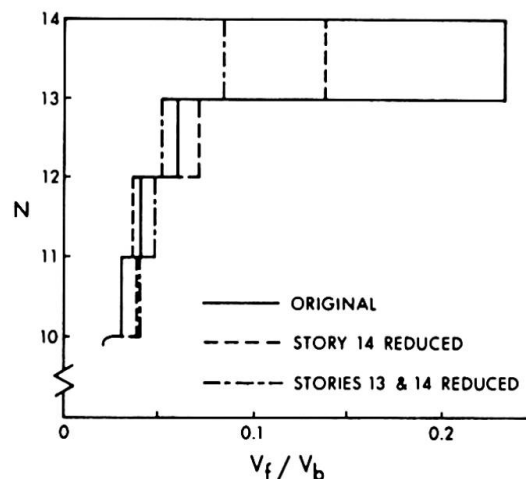


FIG. 5. VARIATION IN SHEAR DISTRIBUTION

to one-hundredth of the original value in the top stories. The results are summarized in FIG. 5 which plots  $N$  versus  $V_f/V_b$ . The results of the analysis of the original structure are shown as the solid lines. The dashed lines represent the values obtained when the top story stiffness is reduced to one-hundredth of the original value and the broken lines represent the results when the stiffnesses of the top two stories are reduced. As the stiffness of the wall is reduced the shears carried by the more flexible stories are also reduced, however, the shears carried by the other stories may be increased. The action of the lower portion of the structure is unchanged.

#### TWENTY-FOUR STORY BUILDING

The second example considered is a twenty-four story, three bay steel frame. The frame had been designed using both the allowable stress and plastic strength

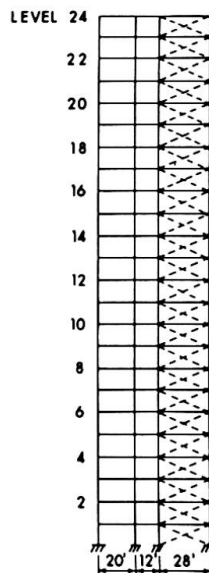


FIG. 6. TWENTY-FOUR STORY STRUCTURE

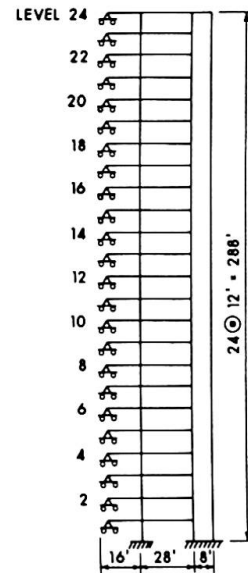


FIG. 7. LUMPED STRUCTURE

techniques, under the assumption that it was completely braced <sup>(1)</sup>. The original frame is shown in FIG. 6 and the analytical model in FIG. 7. The member properties and the vertical loads acting at each floor level are given in REF. 1; the structure was lumped according to methods used in REFS. 3 and 4 and the properties of the analytical model are given in REF. 4. No attempt was made to obtain a flexural shear wall corresponding to the truss shown in FIG. 6, instead several analyses were performed with varying shear wall stiffnesses. The ratio of the wall stiffness to the column stiffness,  $K_w/K_c$ , was held constant in each story. The plastic strength of the wall was chosen to bear a reasonable relationship to the stiffness; this strength/stiffness ratio was

maintained for each story. The shear wall was assumed to have a constant width of 8 feet 0 inches.

The model was subjected to vertical loads at each floor level and to concentrated lateral loads. The vertical loads were held constant for the analysis while the lateral loads increased monotonically. The lateral load at the roof level was one-half those at the other levels.

FIG. 8 shows graphs of the lateral force at the top of the frame,  $H$ , versus the top level column rotation,  $\rho$ . The frame has a ratio of wall stiffness to column stiffness of 50. The upper curve has been obtained from an analysis which neglects the  $P-\Delta$  effect. The first hinge in the frame is detected at point 'a'. The shear wall yields first at the base as shown by point 'b' on the graph. The structure is essentially, a

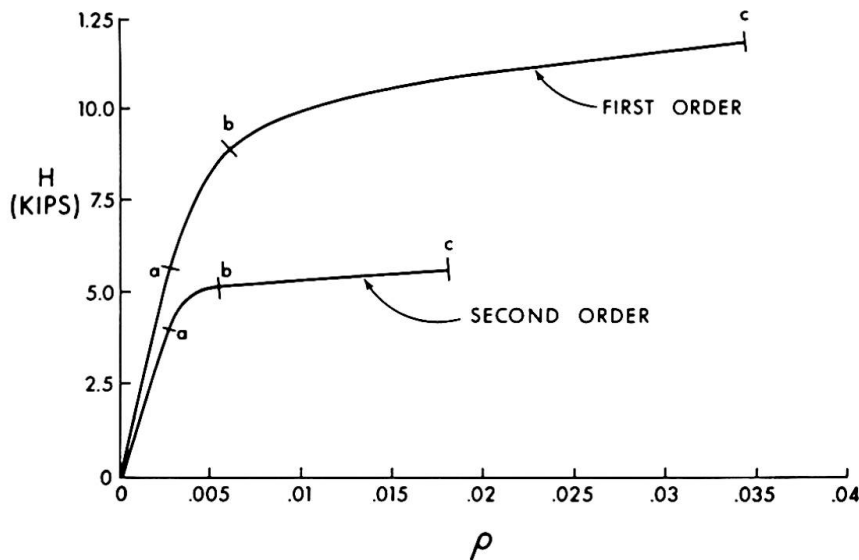


FIG. 8. LOAD-DEFLECTION CURVE

'weak beam-strong column' type and at point 'c' hinges have formed at the ends of all the beams. The only column hinge detected between points 'b' and 'c' occurs at the top of the column in the 24th story. Since a bilinear moment-curvature relationship has been assumed for the wall it will continue to accept increasing load. To demonstrate the  $P-\Delta$  effect, an analysis represented by the lower curve in FIG. 8 was performed. In this case, the structure was analyzed with reduced plastic moment capacities for the columns. The reduced capacities did not influence the results as the structure failed due to instability without hinges forming in the columns. At point 'a' on the lower curve, the first hinge in the structure was

detected. Up to point 'b' the rate of decrease of stiffness is moderate. Beyond point 'b' the deflection of the structure increases rapidly up to point 'c'. At this load level, the wall becomes inelastic. For the next increment of lateral load, the deformations become so large that the system does not converge. The load corresponding to 'c' has been taken as the ultimate load carrying capacity of the structure. In FIG. 8 the difference in load carrying capacity predicted by the two analyses is primarily due to the  $P-\Delta$  effect, since only one hinge forms in the columns.

FIG. 9 consists of several plots showing the deflected shape of the structure as the lateral load is incremented. The curves are obtained from the second order analysis corresponding to the lower curve. In FIG. 9 the

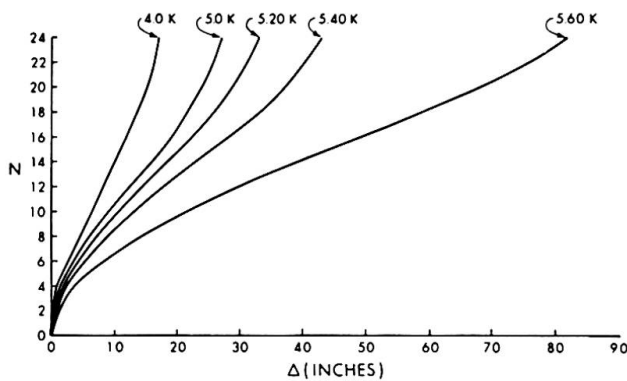


FIG. 9. DEFLECTED SHAPES

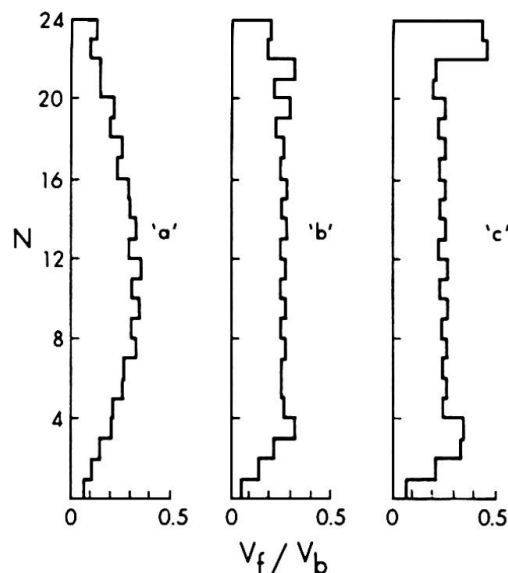


FIG. 10. SHEAR DISTRIBUTION

deflected shapes for lateral loads of 5.20 and 5.60 kips correspond to points 'b' and 'c' on FIG. 8. These two curves emphasize the rapid increase in deflection which occurs as the wall enters the inelastic range.

The shear distribution between the wall and the frame is of interest in this study.. FIG. 10 plots the story,  $N$ , versus the ratio  $V_f/V_b$  for three stages in the loading history. The stages correspond to points 'a', 'b' and 'c' of FIG. 8. The base shear at each stage includes the appropriate component of the  $P-\Delta$  effect. At the elastic limit (stage 'a') large shears act near mid-height of the frame. As the frame yields (between 'a' and 'b') the shears are redistributed and near the ultimate load (stage 'c') are largest near the top and bottom. Relative to the applied story shear,

large shears occur in the top stories at all stages and are accentuated by yielding in the frame.

The effect of varying the wall stiffness was also studied. FIG. 11 is a plot of the top level lateral force,  $H$ , versus the top level lateral deflection,  $\Delta$ . In all cases, the  $P-\Delta$  effect was considered and the reduced plastic moment capacities used for the columns. The curves are

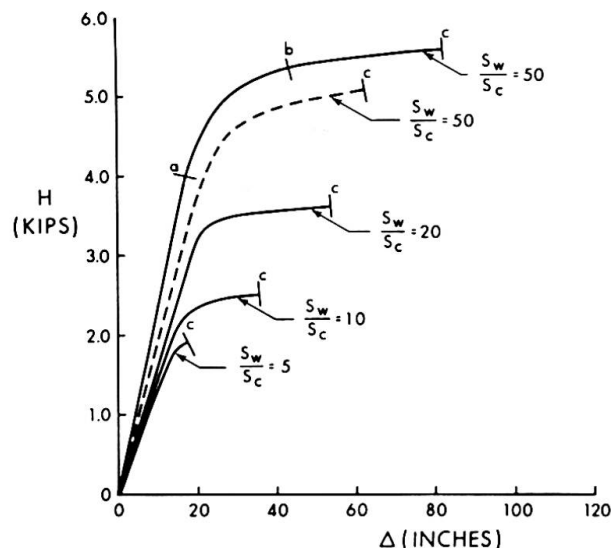


FIG. 11. LOAD-DEFLECTION CURVES

plotted for ratios of  $K_w/K_c$  varying from 5 to 50. The load carrying capacity of the structure decreases with a reduction in the shear wall stiffness. This is primarily due to the increased severity of the  $P-\Delta$  effect.

The structure having  $K_w/K_c = 50$  was reanalyzed assuming zero wall width. The result is shown as the dashed curve. In this case, the analysis (assuming zero wall width) yields conservative results, apparently since it neglects the extra restraining moment on the wall. This moment is the result of the shear at the wall end of the beam acting through half the wall width.

It can be observed from FIG. 11 that the difference in behavior due to the variation in wall to column stiffness is considerable. In all cases, the analysis did not converge beyond point 'c'. The loads corresponding to points 'c' have been taken as the ultimate load carrying capacities of the structures. Due to the procedure used in the analysis, the unloading branch of the load-deflection curve can not be obtained.

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### SUMMARY

A method has been presented for the approximate inelastic analysis of frame-shear wall structures. The method accounts for the wall-frame interaction and the  $P-\Delta$  effect. The results presented illustrate the shear distributions obtained and the reduction in load-carrying capacity due to the secondary effects.

### RÉSUMÉ

Une méthode a été présentée pour l'analyse inélastique approximée d'une forme de structures composées de murs et de câdres. La méthode tient compte de l'action réciproque du mur et du câdre, et de l'effet du  $P-\Delta$ . Les résultats présentés servent à démontrer les distributions de forces et les rapetissements de la charge limite qui résulte des effets secondaires.

### ZUSAMMENFASSUNG

Für die angenäherte unelastische Berechnung von Scheiben-Rahmentragwerken wird ein Verfahren vorgestellt. Diese Methode zieht das Zusammenwirken der Scheibenrahmen und des  $P-\Delta$ -Effekts in Betracht. Die Ergebnisse zeigen die Schubverteilung sowie die Traglastverminderung aus sekundärem Einfluss.

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### IIIa

#### Non Linear Plastic Analysis of High Strength Steel Plane and Space Frameworks

Analyse plastique non-linéaire de système de portiques dans le plan et dans l'espace  
en aciers de haute résistance

Nichtlineare, plastische Analyse ebener und räumlicher Stahl-Rahmentragwerke hoher  
Festigkeit

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#### 1\_Introduction.

The plastic analysis of framed structures requires the determination of the collapse mechanism under the action of proportional loads. Although the collapse mechanism is simple in concept, it depends on too many factors. In rigid plastic theory the collapse mechanism can be obtained by static and kinematic theorems<sup>(1)</sup> or following the successive formation of plastic hinges until the failure of the structure. Whenever a plastic moment is attained at any cross section, a plastic hinge forms at this section, and it can undergo rotation of any magnitude as long as the bending moment stays constant at the fully plastic value. However there are some discrepancies between the assumptions of rigid plastic theory and the actual behavior of the structure. The plastic hinges develop along a plastified zone, and the strain hardening assures that the plastic hinges will extend over increasing lengths of the member even before the extensive ductility is exceeded<sup>(2)</sup>. The structure being loaded beyond the elastic limit of its material, the moment curvature diagrams are not linear and the deformations and also the effect of the deformations upon the equilibrium equations are more accentuated than the linear elastic analysis. The fully plastic moment is subject to variation by the slenderness ratio of the member<sup>(2)(3)</sup> by the rotational angle change<sup>(3)</sup> and also by the member axial and shear forces.<sup>(4)</sup>

Computer programs have been developed for plastic analysis. The program proposed by Wang<sup>(4)</sup> will trace definitely the location and the sequence of formation of all plastic hinges until collapse, yields the cumulative load factor and the deflections and moments at all nodal points at the time of formation of each plastic hinge.

Wang's program has been modified by Harrison<sup>(5)</sup> in order to include the finite deformation effects. Rubinstein and Karagozyan<sup>(6)</sup> have given a solution for minimum weight design.

Intensive experiments have been evolved to show the agreement between the theory and the actual behavior, primarily in two centers: the Cambridge University<sup>(7)</sup>, England, and Lehigh University<sup>(8)</sup>, U.S.A.

In the present paper an attempt has been made to solve the space or plane framework structure accounting for the finite deformation effects, the reduction of plastic moments due to axial member forces, the change in flexural stiffness caused by member axial forces and the influence of shear forces to the deflections<sup>(9)</sup>. But the effect of strain hardening<sup>(10)</sup> and the reduction of plastic moment due to member shear forces are neglected. Also the spread of plastic zone and the residual stresses due to live loads<sup>(11)</sup> are ignored.

The computer program gives as results the collapse mode, that is, whether the collapse occurred by a plastic collapse mechanism or by the instability of whole structure or by a member instability. With an out-of-core Cholesky routine a big structure with more than 2000 unknowns may be handled without any increase in the capacity of the computer. The required computer time is much higher than the non-linear analysis of the same structure, since a non-linear analysis is performed at the formation of each new hinge.

Numerical examples have been given in order to compare the results obtained with those already worked out experimentally or theoretically and one more to illustrate the behavior of the space structures.

## 2. Non-Linear Analysis of Framed Space Structure.

An iteration procedure<sup>(12)</sup> is applied to framed space or plane structure to determine its deformed configuration. The basic idea in this procedure is to perform a standard linear analysis under the action of a given set of external loads and then calculate the member end forces using the deformed geometry. If the member end forces at a joint are not in equilibrium with the given external loads, the out-of-balance forces are applied on to the deformed geometry to yield another set of deformations and forces. If the new forces do not satisfy the joint equilibrium, the linear analysis continues with the latest geometry and with the latest out-of-balance forces. This procedure is repeated until equilibrium is reached at every joint.

The stiffness method has been used as a standard linear analysis procedure. The member center line is chosen as the y-axis while the two principal inertia axes of the section constitute the x and z axes of a cartesian co-ordinate system. These axes are called the "member axes" and are referred to a general stationary XYZ cartesian co-ordinate system (Figure 1). The joint deformations obtained from the linear analysis are relative to the generalized XYZ co-ordinate axes. In evaluating the member end forces, it is extremely convenient to work with the member end

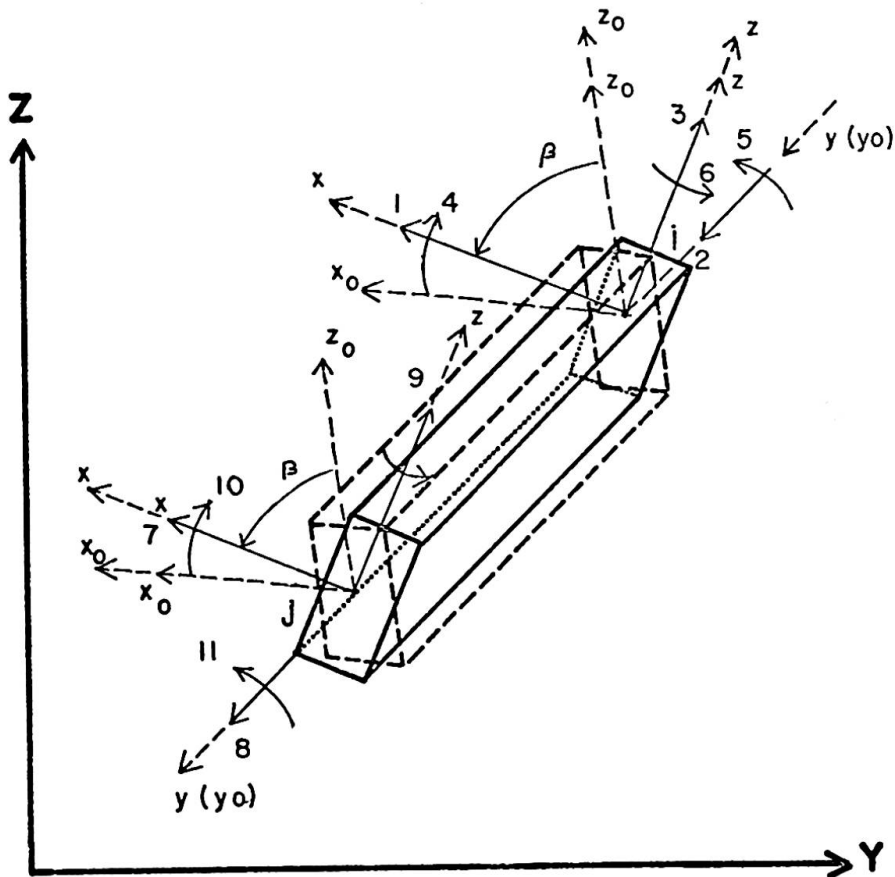


Figure 1. Co-ordinate Axes.

deformations relative to the deformed member axes which are obtained from

$$\{\delta\}_{xyz} = [T] \{\delta\}_{XYZ}$$

where,

$\{\delta\}_{xyz}$  = the column vector of member end deformations relative to the deformed member axes,

$\{\delta\}_{XYZ}$  = the column vector of generalized XYZ co-ordinates

$[T]$  = the orthogonal transformation matrix involving the direction cosines of the deformed member axes

The member forces relative to the deformed member axes, (Figure 2) may be written as follows

$$F_2 = -F_8 = (L_0 - L')AE/L_0$$

$$F_4 = (4EI_x/L'(1+\phi_x))\theta'_4 S_{1x} + (2EI_x/L'(1+\phi_x))\theta'_{10} S_{2x}$$

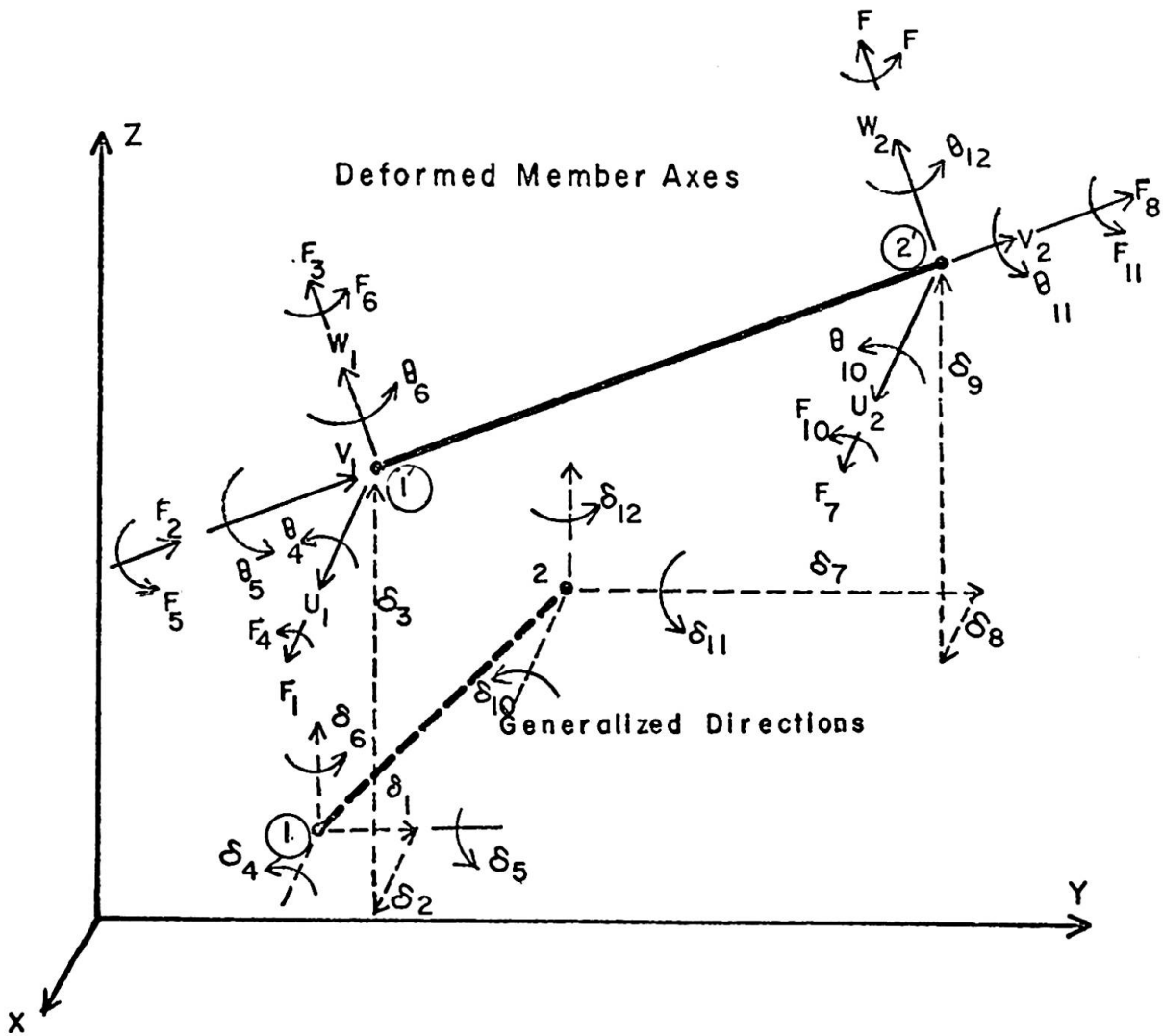


Figure 2. A Beam-Column Member in Space

$$F_{10} = (4EI_x/L'(1+\phi_x))\theta'_{10}S_{1x} + (2EI_x/L'(1+\phi'_x))\theta'_{12}S_{2x}$$

$$F_6 = (4EI_z/L'(1+\phi_z))\theta'_{12}S_{1z} + (2EI_z/L'(1+\phi'_z))\theta'_{10}S_{2z}$$

$$F_{12} = (4EI_z/L'(1+\phi_z))\theta'_{12}S_{1z} + (2EI_z/L'(1+\phi'_z))\theta'_{10}S_{2z}$$

$$F_5 = -F_{11} = (GJ/L')(\theta_5 - \theta_{11})$$

$$F_7 = -F_1 = (F_6 + F_{12})/L'$$

$$F_3 = -F_9 = (F_4 + F_{10})/L'$$

where

$$L_0 = \left[ (X_2 - X_1)^2 + (Y_2 - Y_1)^2 + (Z_2 - Z_1)^2 \right]^{1/2}$$

$$L' = \left[ (X'_2 - X'_1)^2 + (Y'_2 - Y'_1)^2 + (Z'_2 - Z'_1)^2 \right]^{1/2}$$

$$\theta'_4 = \theta_4 + \theta_w : \quad \theta'_{10} = \theta_{10} + \theta_w$$

$$\theta'_6 = \theta_6 + \theta_u : \quad \theta'_{12} = \theta_{12} + \theta'_u$$

$$\theta_u = \text{Arcsin} \left( \frac{u_2 - u_1}{L_0} \right)$$

$$\theta_w = \text{Arcsin} \left( \frac{w_1 - w_2}{L_0} \right)$$

In the above expressions,  $u_1$ ,  $u_2$ ,  $w_1$  and  $w_2$  are the translations and  $\theta_4$ ,  $\theta_{10}$ ,  $\theta_6$ ,  $\theta_{12}$ ,  $\theta_5$  and  $\theta_{11}$  are the rotations of the member ends relative to the deformed member axes as obtained from the linear analysis.  $S_{1x}$ ,  $S_{2x}$ ,  $S_{1z}$ ,  $S_{2z}$ , are the correction factors to include the influence of the axial force on the member flexural stiffness coefficient and  $\phi_x$ ,  $\phi_z$  are the correction factors to include the influence of member shear forces on to the displacements.

### 3. Plastic Analysis of Framed Structures.

To determine the collapse mechanism, a non-linear analysis as mentioned above is performed after each successive hinge formation. The rotation of all previously formed hinges is checked, and if the rotation of one of the previous hinges decreases, this hinge is locked again. The collapse may occur with the formation of a new hinge or within the non-linear cycles. In the former case, the collapse is caused by a plastic mechanism, and in the latter case it is caused either by a member instability or by the instability of the whole structure.

The member instability and the effect of the member shear forces are taken into account by introducing proper factors in the member flexural stiffness coefficients. At every step the value of the member plastic moment is modified, depending on the member axial force. For I beams both cases<sup>(4)</sup> are considered separately, that is, whether the neutral axis lies in the web or in the flange.

No allowance for strain-hardening is made. Also the spread of plastic zone, reduction of plastic moment due to member shear forces

and the residual stresses due to live loads are ignored.

Structures having members with variable moments of inertia can also be solved.

#### 4 - Computer Programming.<sup>(13)</sup>

The data values fed in computer are respectively the characteristic of the structure such as: the Young modulus  $E$ , the Poisson ratio  $\mu$ , the co-ordinates of the joints referred to XYZ generalized co-ordinate axes, the two end joints of each member, moments of inertia in two principal inertia axes, polar moment of inertia, area of the section, the web area and depth if it is an I section, plastic moments in two principal inertia axes, redundant joints information, joint and member loads if any. All the other operations are performed automatically in computer.

The computer gives as output the displacements and rotations at every joint and the member end reactions of all the members for first linear analysis, then the same information for non-linear analysis. This pattern is repeated after formation of each new hinge until the collapse of the structure. The collapse occurs either by the singularity of structure stiffness matrix or by the large joint deformations. The load factors for each step and the cumulative load factor are also pointed out.

#### 5 - Examples of Analysis

The dimensions and member characteristics of the first two examples are selected from previous studies in order to compare the results. An example of space frame is also given. The parameters NL and NC show respectively whether the reduction of plastic moment due to member axial forces and the stability correction factors are taken into account or not. These parameters may have the value equal either to zero or one which means respectively that the corresponding correction factors are included or not in the analysis. QP is the cumulative load factor.

##### 5.1. Portal Frame.

The dimensions and member characteristics are given in Figure 3. The successive hinge formation and their location, cumulative load factors, the horizontal displacement at joint B, ( $\Delta_1$ ), and H, ( $\Delta_3$ ), and the vertical displacement at joint E, ( $\Delta_2$ ), are also given in the tables for linear and non-linear analysis.

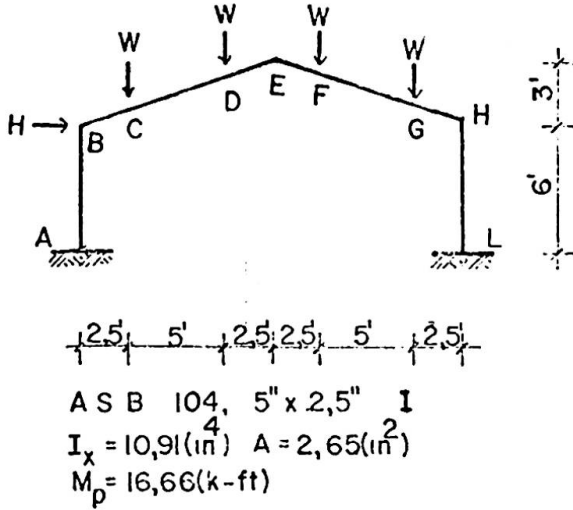


Figure 3

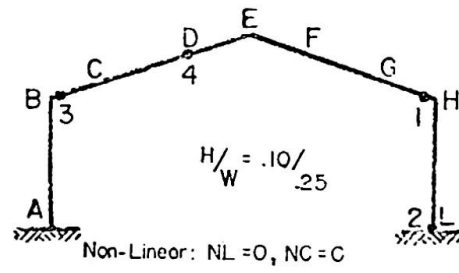


Figure 4

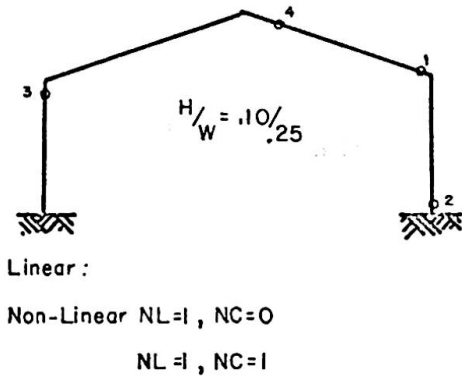


Figure 5

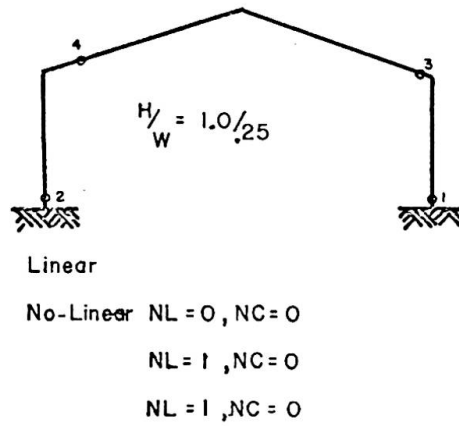


Figure 6

Table I  $H/W = .10/.25$

|                                    |            | LINEAR<br>ANALYSIS | NON-LINEAR ANALYSIS |              |              |
|------------------------------------|------------|--------------------|---------------------|--------------|--------------|
|                                    |            |                    | NL=0<br>NC=0        | NL=1<br>NC=0 | NL=1<br>NC=1 |
| DEFORMATION PLASTIC HINGE<br>ORDER | 1          | 14.051             | 13.85               | 13.428       | 13.40        |
|                                    | 2          | 14.555             | 14.38               | 13.937       | 13.89        |
|                                    | 3          | 16.161             | 15.90               | 15.717       | 15.66        |
|                                    | 4          | 18.330             | 18.02               | 17.703       | 17.69        |
| DEFORMATION<br>(in)                | $\Delta_1$ | 0.172              | 0.178               | 0.220        | 0.220        |
|                                    | $\Delta_2$ | 3.253              | 3.272               | 3.264        | 3.324        |
|                                    | $\Delta_3$ | 2.097              | 1.996               | 2.034        | 2.065        |

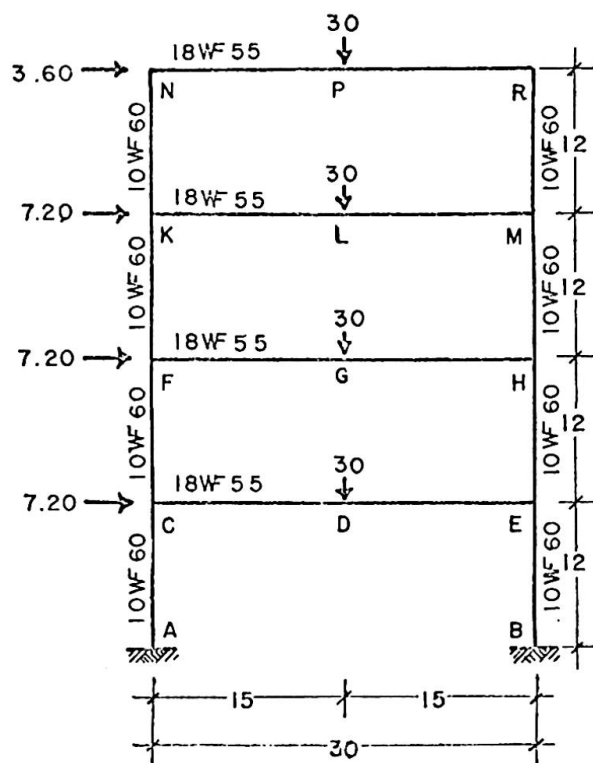


|                        |            | LINEAR<br>ANALYSIS | NON-LINEAR ANALYSIS |              |              |
|------------------------|------------|--------------------|---------------------|--------------|--------------|
|                        |            |                    | NL=0<br>NC=0        | NL=1<br>NC=0 | NL=1<br>NC=1 |
| PLASTIC HINGE<br>ORDER | 1          | 6.627              | 6.559               | 6.386        | 6.367        |
|                        | 2          | 8.666              | 8.562               | 8.474        | 8.463        |
|                        | 3          | 9.003              | 8.911               | 8.724        | 8.729        |
|                        | 4          | 10.286             | 10.077              | 9.920        | 9.922        |
| DEFORMATION<br>(in)    | $\Delta_1$ | 4.127              | 4.141               | 4.162        | 4.224        |
|                        | $\Delta_2$ | 2.363              | 2.555               | 2.579        | 2.617        |
|                        | $\Delta_3$ | 5.521              | 5.461               | 5.507        | 5.586        |

Table II  $H/W = 1./ .25$ 

### 5.2, Four Storey Frame.

The dimensions and member characteristics are given in Figure 7. The successive hinge formations and their location, cumulative load factors, the horizontal displacement at joint C( $\Delta_1$ ), N( $\Delta_3$ ), R( $\Delta_5$ ), the vertical displacement at joint D( $\Delta_2$ ) and P( $\Delta_4$ ) are also given in the tables for linear and non-linear analysis.

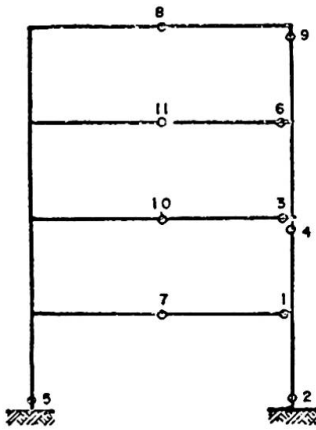


|        | $I_x$ (in <sup>4</sup> ) | $I_z$ (in <sup>4</sup> ) | $J$ (in <sup>4</sup> ) |
|--------|--------------------------|--------------------------|------------------------|
| 10WF60 | 343.0                    | 116.5                    | 2.15                   |
| 18WF55 | 888.9                    | 42.0                     | 2.65                   |
| 18WF60 | 984.0                    | 47.1                     | 2.94                   |

|        | $A$ (in <sup>2</sup> ) | $M_{px}$ (k.ft) | $M_{pz}$ (k.ft) |
|--------|------------------------|-----------------|-----------------|
| 10WF60 | 17.60                  | 213.73          | 99.68           |
| 18WF55 | 16.19                  | 317.69          | 54.52           |
| 18WF60 | 17.64                  | 349.10          | 60.94           |

Figure 7



Linear.

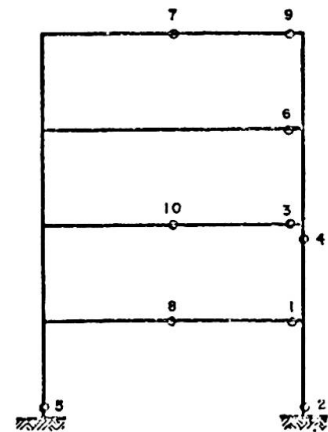
Figure 8

| PLASTIC<br>HINGE<br>ORDER | LINEAR<br>ANALYSIS | NON-LINEAR ANALYSIS |              |              |
|---------------------------|--------------------|---------------------|--------------|--------------|
|                           |                    | NL=1<br>NC=0        | NL=0<br>NC=0 | NL=1<br>NC=1 |
| 1                         | 1.739              | 1.739               | 1.739        | 1.739        |
| 2                         | 1.903              | 1.759               | 1.906        | 1.769        |
| 3                         | 1.916              | 1.851               | 1.914        | 1.812        |
| 4                         | 1.991              | 1.941               | 1.996        | 1.891        |
| 5                         | 2.147              | 2.059               | 2.139        | 1.975        |
| 6                         | 2.148              | 2.123               | 2.146        | 2.038        |
| 7                         | 2.158              | 2.135               | 2.151        | 2.127        |
| 8                         | 2.162              | 2.141               | 2.154        | 2.133        |
| 9                         | 2.189              | 2.158               | 2.177        | 2.138        |
| 10                        | 2.210              | 2.160               | 2.190        | 2.148        |
| 11                        | 2.230              | 2.161               |              | 2.143        |
| 12                        |                    | 2.186               |              |              |

Table III

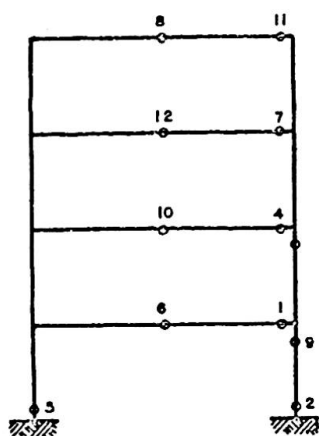
| PLASTIC<br>HINGE<br>ORDER | NON-LINEAR ANALYSIS (NL=0, NC=0) |            |            |            |            |
|---------------------------|----------------------------------|------------|------------|------------|------------|
|                           | $\Delta_1$                       | $\Delta_2$ | $\Delta_3$ | $\Delta_4$ | $\Delta_5$ |
| 1                         | 0.899                            | 0.731      | 2.889      | 1.023      | 2.867      |
| 2                         | 1.088                            | 0.922      | 3.396      | 1.113      | 3.371      |
| 3                         | 1.103                            | 0.939      | 3.427      | 1.107      | 3.402      |
| 4                         | 1.249                            | 1.047      | 3.889      | 1.042      | 3.862      |
| 5                         | 1.522                            | 1.273      | 4.721      | 1.228      | 4.685      |
| 6                         | 1.557                            | 1.287      | 4.781      | 1.229      | 4.762      |
| 7                         | 1.588                            | 1.300      | 4.862      | 1.229      | 4.832      |
| 8                         | 1.604                            | 1.306      | 4.899      | 1.234      | 4.869      |
| 9                         | 2.608                            | 2.595      | 6.824      | 1.546      | 6.793      |
| 10                        | 3.136                            | 3.271      | 8.001      | 1.691      | 7.964      |

Table IV



Non-Linear: NL=0, NC=0.

Figure 9



Non-Linear NL=1, NC=0.

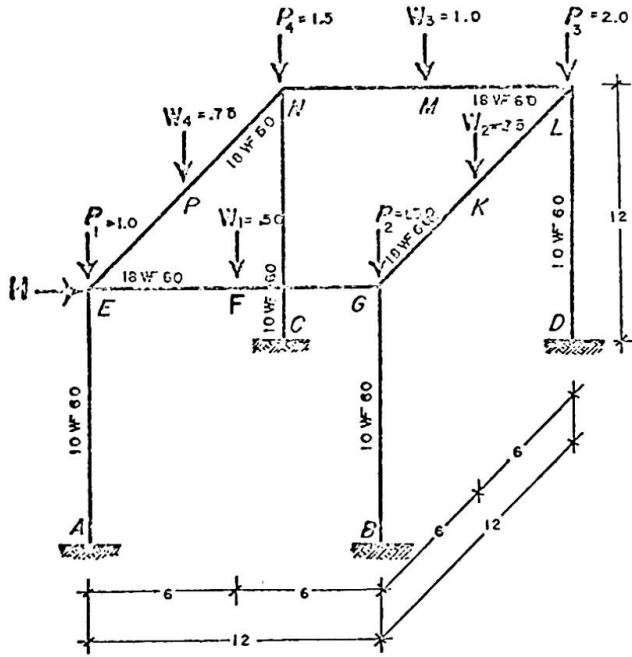
Figure 10

| PLASTIC<br>HINGE<br>ORDER | LINEAR ANALYSIS |            |            |            |            |
|---------------------------|-----------------|------------|------------|------------|------------|
|                           | $\Delta_1$      | $\Delta_2$ | $\Delta_3$ | $\Delta_4$ | $\Delta_5$ |
| 1                         | 0.898           | 0.730      | 2.885      | 1.017      | 2.868      |
| 2                         | 1.083           | 0.921      | 3.383      | 1.114      | 3.364      |
| 3                         | 1.103           | 0.938      | 3.429      | 1.121      | 3.410      |
| 4                         | 1.253           | 1.063      | 3.890      | 1.169      | 3.880      |
| 5                         | 1.524           | 1.288      | 4.735      | 1.254      | 4.713      |
| 6                         | 1.530           | 1.291      | 4.746      | 1.255      | 4.724      |
| 7                         | 1.582           | 1.312      | 4.867      | 1.261      | 4.846      |
| 8                         | 1.681           | 1.448      | 5.065      | 1.264      | 5.044      |
| 9                         | 2.311           | 2.314      | 6.328      | 1.360      | 6.306      |
| 10                        | 2.806           | 2.992      | 7.563      | 1.803      | 7.541      |
| 11                        | 4.150           | 4.731      | 11.344     | 2.720      | 11.322     |

Table V

### 5-3. Space Frame.

The dimensions and member characteristics are given in Figure 10. The successive hinge formation and their location, cumulative load factors, the horizontal displacement at joints E( $\Delta_1$ ), G( $\Delta_3$ ) and vertical displacement at joint F( $\Delta_2$ ) are also given in the tables for non-linear analysis.



Same steel section characteristics as Four Storey Frame

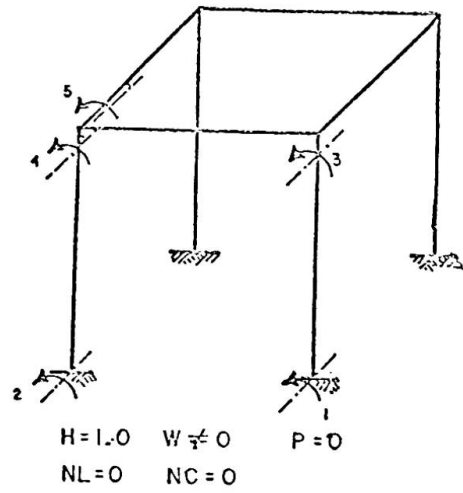
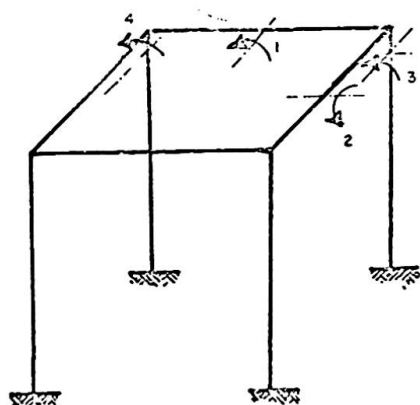


Figure 12

Figure 11

|                     |   | NL = 0  |            |            | NC = 0     |         |            | NL = 1     |            |         | NC = 0     |            |            |
|---------------------|---|---------|------------|------------|------------|---------|------------|------------|------------|---------|------------|------------|------------|
|                     |   | QP      | $\Delta_1$ | $\Delta_2$ | $\Delta_3$ | QP      | $\Delta_1$ | $\Delta_2$ | $\Delta_3$ | QP      | $\Delta_1$ | $\Delta_2$ | $\Delta_3$ |
| PLASTIC HINGE ORDER | 1 | 67.8013 | -0.0051    | 0.9448     | -0.0639    | 67.8184 | -0.0051    | 0.9450     | -0.0639    | 67.8184 | -0.0051    | 0.9450     | -0.0639    |
|                     | 2 | 71.9553 | -0.0071    | 1.0379     | -0.0682    | 70.1642 | -0.0062    | 0.9976     | -0.0663    | 70.1642 | -0.0062    | 0.9976     | -0.0663    |
|                     | 3 | 72.0123 | -0.0099    | 1.0407     | -0.0645    | 71.5020 | -0.0081    | 1.0367     | -0.0679    | 71.5020 | -0.0081    | 1.0367     | -0.0679    |
|                     | 4 | 76.4655 | -0.0137    | 1.4552     | -0.0931    | 76.0266 | -0.0129    | 1.4596     | -0.0970    | 76.0266 | -0.0129    | 1.4596     | -0.0970    |
|                     | 5 | 90.3714 | -0.0170    | 5.4564     | -0.2097    |         |            |            |            |         |            |            |            |

Table VI



$H = .10 \quad W \neq 0 \quad P = 0$

$NL = 0 \quad , \quad NC = 0$

$NL = 1 \quad , \quad NC = 0$

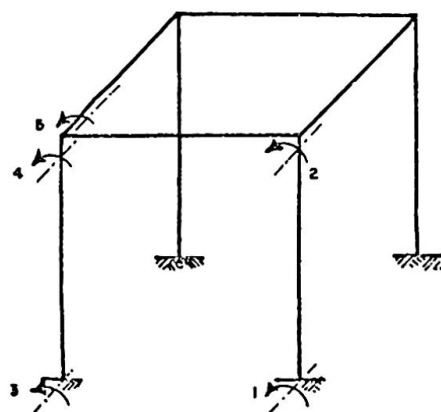
Figure 13

|                  |            | PLASTIC HINGE ORDER |          |          |          |
|------------------|------------|---------------------|----------|----------|----------|
|                  |            | 1                   | 2        | 3        | 4        |
| $NL = 0, NC = 0$ | QP         | 146.243             | 171.4713 | 186.4638 | 187.3258 |
|                  | $\Delta_1$ | .00051              | -0.0058  | -0.0066  | -0.0066  |
|                  | $\Delta_2$ | 0.0111              | 0.0130   | 0.0140   | 0.0416   |
|                  | $\Delta_3$ | -0.2569             | -0.5581  | -0.7379  | -0.7792  |
| $NL = 1, NC = 0$ | QP         | 146.2433            | 171.4620 | 178.6744 | 179.2672 |
|                  | $\Delta_1$ | -0.0051             | -0.0058  | -0.0062  | -0.0063  |
|                  | $\Delta_2$ | 0.0111              | 0.0130   | 0.0135   | 0.0325   |
|                  | $\Delta_3$ | -0.2569             | -0.5580  | -0.6444  | -0.6727  |
| $NL = 1, NC = 0$ | QP         | 146.243             | 179.603  | 180.296  |          |
|                  | $\Delta_1$ | -0.0051             | +0.0087  | +0.0084  |          |
|                  | $\Delta_2$ | 0.0111              | -0.0040  | -0.0069  |          |
|                  | $\Delta_3$ | -0.2569             | -0.7373  | -0.7719  |          |

Table VII

|                     |   | $NL = 0$ |            | $NC = 0$   |            |
|---------------------|---|----------|------------|------------|------------|
|                     |   | Qp       | $\Delta_1$ | $\Delta_2$ | $\Delta_3$ |
| PLASTIC HINGE ORDER | 1 | 67.695   | -0.0098    | 0.9475     | -0.0876    |
|                     | 2 | 71.840   | -0.0120    | 1.0370     | -0.0956    |
|                     | 3 | 72.040   | -0.0139    | 1.0451     | -0.0898    |
|                     | 4 | 76.385   | -0.0189    | 1.3656     | -0.1199    |
|                     | 5 | 88.249   | -0.0246    | 5.4655     | -0.2455    |

Table VIII



$H = 1.0 \quad W \neq 0 \quad P = 0$

$NL = 1 \quad NC = 0$

Figure 14

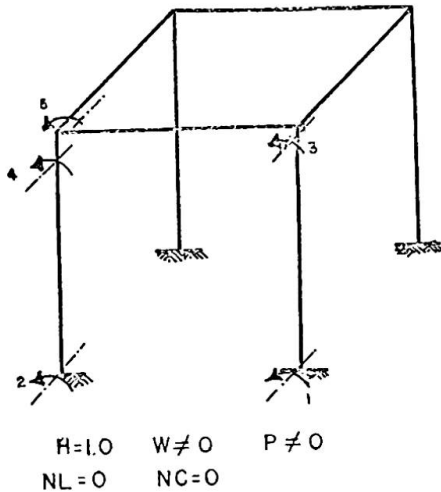


Figure 15

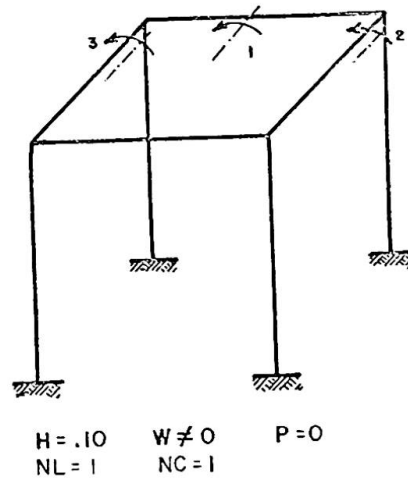


Figure 16

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#### SUMMARY

In the present paper an attempt has been made to solve the space or plane framework structures accounting for the finite deformation effects, the reduction of plastic moments due to axial member forces, the change in flexural stiffness caused by member axial forces and the influence of shear forces to the deflection. But the effect of strain hardening and the reduction of plastic moment due to member shear forces are neglected. Also the spread of the plastic zone and the residual stresses due to live loads are ignored.

#### RÉSUMÉ

Cette étude essaie de résoudre les systèmes de portiques plans ou dans l'espace en tenant compte des effets des déformations finies, de la réduction des moments plastiques et de la variation de rigidité à la flexion dues aux efforts axiaux et de l'influence des efforts de cisaillement sur la déformation. On a négligé cependant l'effet du durcissement ainsi que la réduction du moment plastique due aux efforts de cisaillement. De même on ne tient pas compte de l'extension de la zone plastique ni des tensions résiduelles dues à la charge de service.

#### ZUSAMMENFASSUNG

In diesem Beitrag ist der Versuch unternommen worden, ebene und räumliche Rahmentragwerke mit Berücksichtigung der Wirkung endlicher Verformungen, der Abminderung der plastischen Momente unter Achsiallasten, des Wechsels der Biegesteifigkeit aufgrund der Stabachsialkräfte sowie des Einflusses der Querkräfte auf die Durchbiegungen zu lösen. Hingegen sind die Wirkung der Verfestigung und die Abminderung des plastischen Moments infolge Stabquerkräfte vernachlässigt worden. Ebenso sind die Ausbreitung der plastischen Zone und die Eigenspannungen infolge Verkehrslast unberücksichtigt.