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## Minimal entropy for uniform lattices in product of hyperbolic planes

Louis Merlin

**Abstract.** Let M be a quotient of  $\mathbb{H}^2 \times \cdots \times \mathbb{H}^2$  (product of hyperbolic planes) by a uniform lattice of  $(PSL_2(\mathbb{R}))^n$ . We prove that, among metrics of M of prescribed volume, the sum of hyperbolic metrics has minimal volume entropy.

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#### 1. Introduction

Let (X, g) be a compact Riemannian n-manifold and  $\widetilde{X}$  be the universal Riemannian cover of X. The volume entropy is defined as

$$h(g) = \lim_{R \to \infty} \frac{1}{R} \log(\text{Vol}(B(x, R)))$$

where B(x, R) is the ball of radius R in  $\widetilde{X}$  centered at any point  $x \in \widetilde{X}$ . The limit exists and is independent of the choice of x (see [16, p. 568]).

In this paper, we are interested in the following problem.

**Question 1.** Let M be a compact locally symmetric space of noncompact type with locally symmetric metric  $g_0$ . Let g be any other metric on M such that  $Vol(M, g_0) = Vol(M, g)$ . Do we have

$$h(g) \geqslant h(g_0)$$
?

M. Gromov was the first to conjecture such a result in [10]. He was only interested in the real hyperbolic case. But the question still makes sense for a general symmetric space of noncompact type.

In the case where  $\widetilde{M}$  is reducible, there exist a unique locally symmetric metric of minimal entropy among locally symmetric metrics of prescribed volume, which are obtained by scaling the metric in the factors [6, Chapter 2]. This metric is called "the" locally symmetric metric and is denoted by  $g_0$ .

In this work, we give a positive answer to Question 1 in the case of compact quotients of products of n hyperbolic planes, that is  $M = \Gamma \setminus (\mathbb{H}^2)^n$  where  $\Gamma$  is a uniform lattice in  $(PSL_2(\mathbb{R}))^n$ . More precisely our main result is the following:

**Theorem 2** (Main theorem). Assume that  $(M, g_0)$  is a compact quotient of the product of n hyperbolic planes. Then, for any other metric g on M,

$$h^{2n}(g) \operatorname{Vol}(M, g) \ge h^{2n}(g_0) \operatorname{Vol}(M, g_0).$$

Let us remark that the above inequality is sharp and no assumption is made on the metric g.

In the fundamental paper [2], G. Besson, G. Courtois and S. Gallot dealt with the case where M is a locally symmetric space of rank one ( $g_0$  is negatively curved) and obtained a similar statement than the main theorem for such spaces. The same result was obtained before (see [1]) in any rank but for a metric g in the conformal class of the locally symmetric metric  $g_0$  (supposed to be irreducible). In the case where dim  $M \ge 3$ , the method is based on the barycenter map and the inequality in Theorem 2 appears as an inequality of calibration (to be described below). In the case where dim M = 2, already proved by Katok (see [12]), one can still ask if the inequality can be seen as an inequality of calibration. Besson, Courtois and Gallot showed that it is indeed true and gave another proof of the conjecture for hyperbolic surfaces.

The barycenter method was improved by Connell and Farb in [6] and, working factor by factor, they also gave a positive answer to Question 1 in the case where M is locally a product of rank one symmetric spaces with no factor  $\mathbb{H}^2$ .

In both of those papers, the authors pointed out that the case of products of hyperbolic surfaces still remained unknown.

Note also that there is an answer to question 1 in the same setting as [6] (products of rank 1 symmetric spaces without  $\mathbb{H}^2$ -factors) in [3] using an interesting different point of view. The inequality between volumes and entropies appears as a corollary of a general work on representations of fundamental groups of compact manifolds into Lie groups of noncompact types.

We now describe the content of this paper. To prove our main result, we use the general outline introduced in [2]. It consists of an application of a method of calibration. To make this method efficient, we embed the universal cover  $\mathbb{H}^2 \times \cdots \times \mathbb{H}^2$  in the unit sphere of L<sup>2</sup>-functions on the Furstenberg boundary  $\mathbb{T}^n = \mathbb{S}^1 \times \cdots \times \mathbb{S}^1$  by products of Poisson kernels. The aim is to show that this embedding has minimal volume. In order to detect this minimality property, one may use a differential 2n-form taking its extremal values over orthonormal frames in tangent frames of the embedding. The method is briefly recalled in Sections 2.1 and 2.2.

The hardest part is to find the calibrating form. Apart from the barycenter map, which is not efficient in the 2-dimensional case, Besson, Courtois and Gallot

developed an alternative idea. In Chapter 3 of [1], following Gromov [9], there is a general process to build suitable differential forms using bounded cocycles. The choice of the appropriate cocycle in  $\mathbb{H}^2$  is then discussed in [2] Chapter 6. We generalize this approach for the compact quotients of  $(\mathbb{H}^2)^n$  using the bounded 2n-cocycle on  $\mathbb{T}^n$  that M. Bucher exploits in [4] (for n=2). We describe this bounded cocycle in paragraph 3.1 and we check that the derived differential form has the required properties afterwards. The calibrating inequality is finally obtained in paragraph 3.4.

The last section is devoted to applications. We obtain a (non optimal) estimate for the minimal volume (to be defined in Section 4) of a compact quotient  $\Gamma \setminus (\mathbb{H}^2)^n$ .

**Corollary 3.** Let  $M = \Gamma \setminus (\mathbb{H}^2)^n$  be a compact quotient of  $(\mathbb{H}^2)^n$ . Then

$$\operatorname{MinVol}(M) \geqslant \left(\frac{\sqrt{n}}{2n-1}\right)^{2n} \operatorname{Vol}(g_0).$$

The most spectacular application is that we are able to give an optimal bound for degrees of maps  $f: Y^{2n} \to \Gamma \backslash (\mathbb{H}^2)^n$  from any Riemannian 2n-manifold. Precisely,

**Corollary 4.** Let Y be a smooth manifold of dimension 2n endowed with a Riemannian metric g and let f be a continuous map

$$f:(Y,g)\longrightarrow (M,g_0).$$

Then

$$h(g)^{2n} \operatorname{Vol}(Y, g) \ge |\deg f| h(g_0)^{2n} \operatorname{Vol}(M, g_0).$$

We strongly believe that the equality is achieved if and only if f is homotopic to a Riemannian covering map but our approach is not relevant to investigate the equality case.

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#### 2. Calibration method

**2.1. The spherical volume.** In this section, M is a quotient of  $(\mathbb{H}^2)^n$  by a uniform torsion-free lattice  $\Gamma = \pi_1(M)$  and then  $\widetilde{M}$  is the Riemannian product  $(\mathbb{H}^2)^n$  with the usual metric of curvature -1 in each factors (called  $g_0$  in both of the manifolds M and  $\widetilde{M}$ ). Remark that  $g_0$  is the best locally symmetric metric in the sense of [6, Chapter 2], that is the metric with minimal entropy among all locally symmetric metrics of same volume. As above, g is any other metric on M.

Let us start with a few notations. We choose once and for all a basepoint  $o \in \mathbb{H}^2$ , for instance o = 0 in the Poincaré disk model (sitting inside the complex plane). We will denote by the same letter o the basepoint in  $(\mathbb{H}^2)^n$ . There will be no ambiguity resulting from that convention. The basepoint is used to compute the Buseman functions and to identify the boundary at infinity  $\partial_{\infty}\mathbb{H}^2$  with the circle  $\mathbb{S}^1$  (see below).

In what follows,  $\partial_F(\widetilde{M})$  will denote the Furstenberg boundary of  $\widetilde{M}$ : the space of Weyl chambers at infinity in  $\widetilde{M}$  emanating from the same point (see [7] or [11] for further discussions). There will be no conceptual difficulties coming from a general theory of Furstenberg boundary: we just use the fact that  $\partial_F((\mathbb{H}^2)^n)$  is identified to the n-dimensional torus  $\mathbb{T}^n = (\mathbb{S}^1)^n$ , by the above choice of a basepoint. The Furstenberg boundary is better adapted to the case of higher rank symmetric spaces and it is one of the key points in [6]. The Furstenberg boundary and the visual boundary are the same in the rank one case and that's why the distinction does not appear in [2].

The Furstenberg boundary turns out to be a probability space in the following way. The circle  $\mathbb{S}^1 = \mathbb{R}/2\pi\mathbb{Z}$  is endowed with the Lebesgue probability measure  $d\theta$  (normalized in such a way that  $d\theta(\mathbb{S}^1) = 1$ ). The n-torus is the product (in the sense of probability spaces) of n such circles. The spaces of  $L^2$  functions on  $\mathbb{T}^n$  is defined with respect to this measure.

The Poisson kernel  $p_o$  of the disk is defined by:

$$p_o(x,\theta) = e^{-\mathcal{B}_o(x,\theta)},$$

where  $\mathcal{B}_o(x, \theta)$  is the Buseman function. A classical computation gives the explicit expression in the Poincaré disk

$$p_o(x,\theta) = \frac{1 - |x|^2}{|x - e^{2i\pi\theta}|^2}$$

for any  $x \in B(0, 1)$  and  $\theta \in \mathbb{S}^1$ .

The definition of the spherical volume in [2] extends to  $(\mathbb{H}^2)^n$  in the following way. We consider two representations of  $\Gamma$ . The first one in  $\mathrm{Isom}(\widetilde{M},g_0)$  is the holonomy representation of  $\Gamma$ . The second one is the representation in the unit sphere of  $\mathrm{L}^2(\partial_F \widetilde{M})$ , the Hilbert space of  $\mathrm{L}^2$ -functions on the Furstenberg boundary with real values. We denote this unit sphere by  $\mathcal{S}^\infty$  or  $\mathcal{S}^\infty(\partial_F \widetilde{M})$  if the universal cover needs to be specified. More precisely, it is a unitary representation restricted to  $\mathcal{S}^\infty$ . It is defined by

$$(\gamma f)(\theta) = f(\gamma^{-1}(\theta)) \sqrt{p_0(\gamma o_1, \theta^1)} \cdots \sqrt{p_0(\gamma o_n, \theta^n)}$$

where o is the basepoint of  $(\mathbb{H}^2)^n$ ,  $\gamma o = (\gamma o_1, \dots, \gamma o_n) \in (\mathbb{H}^2)^n$  and  $\theta = (\theta^1, \dots, \theta^n) \in \mathbb{T}^n$ . This is the change of variables formula (for  $L^2$  functions).

Indeed the Jacobian of an isometry acting on the Furstenberg boundary is given by the product of Poisson kernels.

Then, as in [2], we introduce the family  $\mathcal{N}$  of Lipschitz immersions

$$\Phi: \widetilde{M} \longrightarrow L^2(\partial_F \widetilde{M})$$

which are  $\Gamma$ -equivariant, that is satisfying the following equation

$$\Phi(\gamma x) = \gamma \Phi(x)$$

for all  $\gamma \in \Gamma$  and all  $x \in \widetilde{M}$ . We also require that

$$\forall x \in \left(\mathbb{H}^2\right)^n, \quad \|\Phi(x)\|_{L^2} = 1,$$

that is  $\Phi(x) \in \mathcal{S}^{\infty}$  and that, for every  $x \in \widetilde{M}$ ,  $\Phi(x)$  is positive almost everywhere. We can also consider those immersions as functions of two variables  $\Phi: (x, \theta) \mapsto \Phi(x)(\theta)$ . The product of square roots of Poisson kernels

$$\Phi_0 := \frac{\left(\mathbb{H}^2\right)^n \longrightarrow \mathcal{S}^{\infty}}{(x^1, \dots, x^n) \longmapsto \sqrt{p_o(x^1, \cdot)} \times \dots \times \sqrt{p_o(x^n, \cdot)}}$$

is an example of such an immersion (see Lemma 6 below). Moreover it is an embedding. We will think of  $(\mathbb{H}^2)^n$  as embedded in  $\mathcal{S}^{\infty}$  by the product of Poisson kernels. The spherical volume is then defined by

$$\mathrm{SphereVol}(M) = \inf_{\Phi \in \mathcal{N}} \{ \mathrm{Vol}(\Phi) \}$$

where

$$Vol(\Phi) = \int_{M} \sqrt{\left| \det_{g_0}(g_{\Phi}(x)) \right|} dv_{g_0}(x),$$

where  $g_{\Phi}$  denotes the almost everywhere defined pull-back of the usual Hilbertian metric on  $L^2$  by the Lipschitz immersion  $\Phi$  and  $\det_g(g_{\Phi})$  is computed in any g-orthonormal basis. The integral on M means that we integrate on a fundamental domain in  $(\mathbb{H}^2)^n$  for the  $\Gamma$ -action and the equivariance relation satisfied by  $\Phi$  shows that this does not depend on the fundamental domain.

The spherical volume is a transitional object. We use it to make a link between entropies and volumes. We want to prove the following inequalities.

$$\left(\frac{h(g_0)^2}{8n}\right)^n \text{Vol}(M, g_0) = \text{SphereVol}(M) \leqslant \left(\frac{h(g)^2}{8n}\right)^n \text{Vol}(M, g).$$

First we recall the second inequality.

**Proposition 5** ([2] Chapter 3). We have

SphereVol
$$(M) \le \left(\frac{h(g)^2}{8n}\right)^n \text{Vol}(M, g).$$

*Proof.* We refer to Chapter 3 of [2] for the same proof in the rank one case. There are only very few modifications to make in our setting. Let's first reintroduce a family of immersions which satisfy the conditions above. For a real parameter c > h(g), we consider:

$$\Psi_c(x,\theta) = \left( \int_{\tilde{M}} e^{-cd(x,y)} p_0(y^1,\theta^1) \cdots p_0(y^n,\theta^n) dv_g(y) \right)^{1/2}.$$

The condition on c ensures that the integral converges. Indeed for uniform lattices volume entropy and critical exponent are the same. Then we define an element of  $\mathcal{N}$  by

$$\Phi_c(x,\theta) = \frac{\Psi_c(x,\theta)}{\left(\int_{\mathbb{T}^n} \Psi_c^2(x,\theta) d\theta\right)^{1/2}}.$$

We just have replaced the boundary sphere by the Furstenberg boundary. We can now perform the very same computation as [2] (p. 742 for a proof of the Lipschitz regularity and p. 746 for the volume computation). We get the required estimate for the spherical volume.

It remains to check now that if M is a compact quotient of  $(\mathbb{H}^2)^n$ , we have

SphereVol
$$(M) = \left(\frac{h(g_0)^2}{8n}\right)^n \text{Vol}(M, g_0).$$

In fact, we can find an immersion  $\Phi_0$  of  $\mathcal N$  which has precisely the needed volume.

**Lemma 6.** Let M be a compact quotient of  $(\mathbb{H}^2)^n$ . Let  $\Phi_0: (\mathbb{H}^2)^n \to L^2(\mathbb{T}^n)$  be defined by

$$\Phi_0(x^1, \dots, x^n, \theta^1, \dots, \theta^n) = \prod_{i=1}^n \sqrt{\frac{1 - |x^i|^2}{|x^i - e^{2i\pi\theta^i}|^2}}.$$

Then

(1)  $\Phi_0$  is a smooth embedding, it belongs to  $\mathcal N$  and

$$\operatorname{Vol}(\Phi_0) = \left(\frac{h(g_0)^2}{8n}\right)^n \operatorname{Vol}(g_0) = \left(\frac{1}{8}\right)^n \operatorname{Vol}(g_0).$$

(2) The tangent space at the basepoint  $\mathbb{1} \in \mathcal{S}^{\infty}$  of the image of  $\Phi_0$ ,  $T_{\mathbb{1}}\Phi_0\left(\left(\mathbb{H}^2\right)^n\right)$  is generated by the 2n functions

$$f_i: \mathbb{T}^n \longrightarrow \mathbb{R}$$
  
 $\theta = (\theta^1, \dots, \theta^n) \longmapsto \sqrt{2} \cos \theta^i$ 

$$f_{i+1}: \mathbb{T}^n \longrightarrow \mathbb{R}$$
  
 $\theta = (\theta^1, \dots, \theta^n) \longmapsto \sqrt{2} \sin \theta^i$ 

for 
$$i = 1, ..., n$$
.

*Proof.* It is enough to handle the same situation with only one factor  $\mathbb{H}^2$ , the volume and the description of the tangent space will be easily deduced from the 2-dimensional case. The family of measures  $(\nu_z)_{z\in\mathbb{H}^2}$  on  $\mathbb{S}^1$  which are in the Lebesgue class and satisfy

$$\frac{dv_z}{d\theta} = \frac{1 - |z|^2}{\left|z - e^{2i\pi\theta}\right|^2}$$

are in fact the so-called Patterson–Sullivan measures of the hyperbolic plane which were constructed in [17]. We refer to this original paper for the equivariance relation (note that this family of measures is even  $SL_2(\mathbb{R})$ -equivariant).

Then it is enough to show that  $\Phi_0$  is an immersion at the basepoint o,  $SL_2(\mathbb{R})$  acting (transitively on  $\mathbb{H}^2$ ) by diffeomorphisms. The differential of  $\Phi_0$  is easy to compute and we get the basis we claimed for the tangent.

This shows in particular the point 2 of the above Lemma which shall be used later on. As the 2 functions cos and sin are a free family in  $L^2(\mathbb{S}^1)$ , we obtain that  $\Phi_0$  is an immersion at o.

Finally the volume of  $\Phi_0$  has been computed in [2, p. 744].

This Lemma 6 shows in particular that

SphereVol
$$(M) \le \left(\frac{h(g_0)^2}{8n}\right)^n \text{Vol}(M, g_0).$$

The purpose of Section 3 is to prove that this inequality is sharp, providing the required equality.

**2.2.** Calibration theory. In order to show that the Spherical Volume is achieved by the map  $\Phi_0$ , we use a classical method of calibration, following [2] chapter 4. Let us make a brief review on how we implement this method.

Let  $\Omega$  be a differential 2n-form which is  $\Gamma$ -invariant.

**Definition 7.** (1) The comass of  $\Omega$  is the quantity

$$comass(\Omega) = sup |\Omega_{\varphi}(f_1, \ldots, f_{2n})|,$$

where the supremum is taken over all functions  $\varphi \in \mathcal{S}^{\infty}$  and every orthonormal family  $(f_1, \ldots, f_{2n})$  where each  $f_i$  belongs to  $T_{\varphi}\mathcal{S}^{\infty}$ .

- (2) One says that the differential form  $\Omega$  calibrates some immersion  $\Phi_0 \in \mathcal{N}$  if
  - (a) The form  $\Omega$  is closed,

- (b) its comass is finite and nonzero and
- (c) when we restrict  $\Omega$  to orthonormal families, it is maximal on the tangent space  $T\Phi_0((\mathbb{H}^2)^n)$ , that is,

$$\frac{\left|\Omega_{\Phi_0(x)}(d_x\Phi_0(u_1),\ldots,d_x\Phi_0(u_{2n}))\right|}{\|d_x\Phi_0(u_1)\wedge\cdots\wedge d_x\Phi_0(u_{2n})\|} = \text{comass}(\Omega)$$

for every  $x \in (\mathbb{H}^2)^n$  and every orthonormal family  $(u_1, \dots, u_{2n})$ .

Here is the way we shall exploit a calibrating differential form. The following proposition follows readily from Stokes theorem. Here, we emphasize the fact that we use in a decisive way the compactness hypothesis for M (see [18]).

**Proposition 8** ([2] Proposition 4.3, p. 748). Assume there exists a differential 2n-form which calibrates an immersion  $\Phi_0 \in \mathcal{N}$ . Then

SphereVol
$$(M)$$
 = Vol $(\Phi_0)$ .

From now on it remains to find such a calibrating form for the Poisson kernel.

- 3. A calibrating form for  $(\mathbb{H}^2)^n$
- **3.1. Definition of the form.** We will denote by e the Euler class of the circle,

$$\begin{cases} e(\theta_0, \theta_1, \theta_2) = 1 & \text{if the points are cyclically ordered on } \mathbb{S}^1. \\ e(\theta_0, \theta_1, \theta_2) = -1 & \text{if not.} \end{cases}$$

Then we consider the application  $C: (\mathbb{T}^n)^{2n+1} \to \mathbb{R}$  given by the following formula,

$$C(\theta_0, \dots, \theta_{2n}) = \frac{1}{(2n+1)!} \sum_{\sigma \in \mathfrak{S}_{2n+1}} \operatorname{sign}(\sigma) \prod_{i=1}^n e\left(\theta_{\sigma(2i-2)}^i, \theta_{\sigma(2i-1)}^i, \theta_{\sigma(2i)}^i\right).$$

For example if n = 1 then C = e, the Euler class and if n = 2, this is the cocycle used in [4]. This map C could be seen as the alternation of the cup product of n Euler classes. In particular C is alternate, that is,

$$C(\theta_{\sigma(0)},\ldots,\theta_{\sigma(2n)}) = \operatorname{sign}(\sigma)C(\theta_0,\ldots,\theta_{2n}).$$

Then the following formula defines a differential 2n-form on  $S^{\infty}$ :

$$\Omega_{\varphi}(f_1,\ldots,f_{2n}) = \int_{(\mathbb{T}^n)^{2n+1}} C(\theta_0,\ldots,\theta_{2n}) \varphi^2(\theta_0) \varphi f(\theta_1) \cdots \varphi f(\theta_{2n}) d\theta_0 \cdots d\theta_{2n}.$$

We conclude this paragraph by stating some properties of C that we shall use later on.

**Proposition 9.** Let G be the group  $\left(\operatorname{Diff}^+(\mathbb{S}^1)\right)^n$  embedded diagonally in  $\operatorname{Diff}^+(\mathbb{T}^n)$ . The map C is G-invariant, that is

$$\forall g \in G, \ C(g\theta_0, \dots, g\theta_{2n}) = C(\theta_0, \dots, \theta_{2n}).$$

*Proof.* The group  $\mathrm{Diff}^+(\mathbb{S}^1)$  preserves the cyclic order on  $\mathbb{S}^1$  then, for  $\gamma \in \mathrm{Diff}^+(\mathbb{S}^1)$ ,

$$e(\gamma \theta_0, \gamma \theta_1, \gamma \theta_2) = e(\theta_0, \theta_1, \theta_2).$$

Taking  $g = (\gamma^1, \dots, \gamma^n) \in G$ , one has

$$C(g\theta_0, \dots, g\theta_{2n}) = \frac{1}{(2n+1)!} \sum_{\sigma \in \mathfrak{S}_{2n+1}} \operatorname{sign}(\sigma) \prod_{i=1}^n e(\gamma^i \theta^i_{\sigma(2i-2)}, \gamma^i \theta^i_{\sigma(2i-1)}, \gamma^i \theta^i_{\sigma(2i)})$$

$$= \frac{1}{(2n+1)!} \sum_{\sigma \in \mathfrak{S}_{2n+1}} \operatorname{sign}(\sigma) \prod_{i=1}^n e(\theta^i_{\sigma(2i-2)}, \theta^i_{\sigma(2i-1)}, \theta^i_{\sigma(2i)})$$

$$= C(\theta_0, \dots, \theta_{2n}).$$

**Proposition 10.** The map C is closed as a combinatorial cochain, that is

$$\sum_{i=0}^{2n+1} (-1)^i C(\theta_0, \dots, \hat{\theta_i}, \dots, \theta_{2n+1}) = 0.$$

*Proof.* It is classical that alternating cup products of cocycles leads to a cocycle.  $\Box$ 

**3.2.** An invariance relation satisfied by  $\Omega$ . Let us show now that the form  $\Omega$  is invariant under the action of the group  $G = \left(\operatorname{Diff}^+(\mathbb{S}^1)\right)^n$ . This group contains  $\left(\operatorname{PSL}_2(\mathbb{R})\right)^n$  and extends its action on  $\operatorname{L}^2(\mathbb{T}^n)$  by the change of variables formula,

$$(gf)(\theta) = \sqrt{\operatorname{Jac} g^{-1}(\theta)} f \circ g^{-1}(\theta).$$

The action being unitary, we let act G on the unit sphere  $S^{\infty}$  by restriction and on the tangent space of this sphere. Then we have, for  $g \in G$ ,

$$(g^*\Omega)_{\varphi}(f_1, \dots, f_{2n})$$

$$= \Omega_{g\varphi}(gf_1, \dots, gf_{2n})$$

$$= \int C(\theta_0, \dots, \theta_{2n})(g\varphi)^2(\theta_0) \prod_{i=1}^{2n} (g\varphi)(gf_i)(\theta_i)d\theta_i$$

$$= \int C(\theta_0, \dots, \theta_{2n}) \operatorname{Jac} g^{-1}(\theta_0) \varphi^2(\theta_0) \prod_{i=1}^{2n} \operatorname{Jac} g^{-1}(\theta_i) \varphi f_i(\theta_i)d\theta_i.$$

$$= \int_{(\mathbb{T}^n)^{2n+1}} C(\theta_0, \dots, \theta_{2n}) \operatorname{Jac} g^{-1}(\theta_0) \varphi^2(\theta_0) \prod_{i=1}^{2n} \operatorname{Jac} g^{-1}(\theta_i) \varphi f_i(\theta_i)d\theta_i.$$

We now perform the change of variables formula  $\theta'_i = g^{-1}(\theta_i)$ . We get

$$(g^*\Omega)_{\varphi}(f_1,\ldots,f_{2n}) = \int_{(\mathbb{T}^n)^{2n+1}} C(g\theta_0,\ldots,g\theta_{2n})\varphi^2(\theta_0)\varphi f(\theta_1)\cdots\varphi f(\theta_{2n})d\theta_0\cdots d\theta_{2n}.$$

The conclusion now follows from proposition 9.

**3.3.** Closure of  $\Omega$ . In order to use the method of calibration, we have to deal with a closed form. This is the aim of this paragraph.

**Proposition 11.** *The differential* 2n*-form*  $\Omega$  *is closed.* 

*Proof.* To differentiate  $\Omega$ , it is easier to have an expression on a space of measures instead of the unit L<sup>2</sup>-sphere. Let us begin by a quick review on the structure of the space of measures we will deal with.

Let  $\mathcal{M}$  be the Banach vector space dual to  $\mathcal{C}^0(\mathbb{T}^n)$ , the Banach space of continuous functions on  $\mathbb{T}^n$ . The space  $\mathcal{M}$  is also the space of Radon measures on  $\mathbb{T}^n$ . We consider the affine space

$$\mathcal{M}_1 = \{ \mu \in \mathcal{M} | \mu(\mathbb{T}^n) = 1 \}.$$

We think of this affine space as an infinite dimensional manifold shaped on a Banach space. The tangent space in each point is the vector space of zero-mass measures.

The differential form  $\Omega$  comes from a form on  $\mathcal{M}_1$  pulled-back by the smooth map

$$\begin{array}{cccc} \mathcal{A}: & \mathcal{S}^{\infty} & \longrightarrow & \mathcal{M}_1 \\ & \varphi & \longmapsto & B \mapsto \int_B \varphi^2(\theta) d\theta. \end{array}$$

The image of a function  $\varphi$  is the measure with density  $\varphi^2$  with respect to the Lebesgue measure. Let us define a differential 2n-form  $\Omega'$  on  $\mathcal{M}_1$ ,

$$\Omega'_{\mu}(\alpha_1,\ldots,\alpha_{2n}) = \int_{(\mathbb{T}^n)^{2n+1}} C(\theta_0,\ldots,\theta_{2n}) d\mu(\theta_0) d\alpha_1(\theta_1) \cdots d\alpha_{2n}(\theta_{2n}).$$

Clearly

$$\Omega = 2^{2n} \mathcal{A}^* \Omega'$$

Then it is enough to show that  $\Omega'$  is closed. But now,  $\Omega'$  is a linear map with respect to  $\mu$ . Then, we have (see [14, p. 84] for the differential formula of a form on a Banach manifold)

$$d\Omega'_{\mu}(\alpha_0,\ldots,\alpha_{2n}) = \sum_{i=0}^{2n} (-1)^i \partial_{\mu} \Omega_{\mu}(\alpha_0,\ldots,\hat{\alpha_i},\ldots,\alpha_{2n}) \cdot \alpha_i.$$

By linearity this expression is also

$$d\Omega'_{\mu}(\alpha_0,\ldots,\alpha_{2n}) = \sum_{i=0}^{2n} (-1)^i \Omega_{\alpha_i}(\alpha_0,\ldots,\hat{\alpha_i},\ldots,\alpha_{2n}).$$

With skew-symmetry, this is again

$$d\Omega'_{\mu}(\alpha_0,\ldots,\alpha_{2n})=(2n+1)\int\limits_{(\mathbb{T}^n)^{2n+1}}C(\theta_0,\ldots,\theta_{2n})d\alpha_0(\theta_0)\cdots d\alpha_{2n}(\theta_{2n}).$$

Each measure has a vanishing total mass. Let us show that the above expression is in fact

$$d\Omega'_{\mu}(\alpha_0, \dots, \alpha_{2n})$$

$$= -(2n+1) \int_{(\mathbb{T}^n)^{2n+2}} \partial C(\theta_0, \dots, \theta_{2n+1}) d\alpha_0(\theta_0) \cdots d\alpha_{2n}(\theta_{2n}) d\mu(\theta_{2n+1}).$$

Let us recall the definition of the combinatorial boundary of a cochain,

$$\partial C(\theta_0, \dots, \theta_{2n+1}) = \sum_{i=0}^{2n+1} (-1)^i C(\theta_0, \dots, \hat{\theta_i}, \dots, \theta_{2n+1}).$$

First we have,

$$\int_{(\mathbb{T}^n)^{2n+1}} C(\theta_0, \dots, \theta_{2n}) d\alpha_0(\theta_0) \cdots d\alpha_{2n}(\theta_{2n})$$

$$= \int_{(\mathbb{T}^n)^{2n+2}} C(\theta_0, \dots, \theta_{2n}) d\alpha_0(\theta_0) \cdots d\alpha_{2n}(\theta_{2n}) d\mu(\theta_{2n+1})$$

because  $\mu(\mathbb{T}^n) = 1$ . We recognize the opposite of the last term in the expression of  $\partial C$  (corresponding to the index i = 2n + 1). We now prove that the other terms in the expression of  $\partial C$  vanish. Each of these remaining terms are of the form

$$\int_{(\mathbb{T}^n)^{2n+2}} C(\theta_0, \dots, \hat{\theta_i}, \dots, \theta_{2n+1}) d\alpha_0(\theta_0) \cdots d\alpha_{2n}(\theta_{2n}) d\mu(\theta_{2n+1})$$

with  $i \neq 2n + 1$ . Integrating with respect to the variable  $\theta_i$  which is not involved in the cocycle, make appear a multiplicative term, the total mass of one of a tangent measure, supposed to be zero.

So finally the closure of C as a combinatorial cocycle (see Proposition 10) proves the result.

**3.4. The calibrating inequality.** Let us first remark that we only have to establish the inequality at the basepoint  $\varphi = 1$ . Indeed one can show exactly as in paragraph 3.3 that

$$\int_{(\mathbb{T}^n)^{2n+1}} C(g\theta_0, \dots, g\theta_{2n}) \left( \varphi^2(\theta_0) - 1 \right) \varphi f(\theta_1) \cdots \varphi f(\theta_{2n}) d\theta_0 \cdots d\theta_{2n} = 0.$$

Replacing the functions  $f_i \in T_{\varphi}S^{\infty}$  by the functions  $\varphi f_i \in T_{\mathbb{1}}S^{\infty}$ , we can make the assumption  $\varphi = \mathbb{1}$ .

Besson, Courtois and Gallot studied the 2-dimensional case in [2, Chapter 6]. They used the Euler class to build a differential form

$$\omega_{\varphi}(f_1, f_2) = \int e(\theta_0, \theta_1, \theta_2) \varphi^2(\theta_0) \varphi f_1(\theta_1) \varphi f_2(\theta_2) d\theta_0 d\theta_1 d\theta_2.$$

$$(\mathbb{S}^1)^3$$

Here is what they proved:

**Proposition 12** ([2] Chapter 6). (1) One may use the following alternative expression for  $\omega$ ,

 $\omega_{\varphi}(f_1, f_2) = 2 \int_{\mathbb{S}^1} F_1 dF_2,$ 

where  $F_1$  and  $F_2$  are the primitives with vanishing integrals for  $\varphi f_1$  and  $\varphi f_2$ .

- (2) The comass of  $\omega$  equals  $\frac{1}{\pi}$ .
- (3) Moreover  $\omega$  is a calibrating form for the Poisson kernel, that is, at the basepoint  $\mathbb{1}$ ,  $\omega$  is maximal over orthonormal families  $(f_1, f_2)$  if

$$f_1(\theta) = \sqrt{2}\cos\theta$$
 and  $f_2(\theta) = \sqrt{2}\sin\theta$ .

Back to the 2n-dimensional situation, we first show that the differential form  $\Omega$  is nonzero, evaluating it on  $T_1\Phi_0((\mathbb{H}^2)^n)$ . Remember the family of functions given by

$$f_i: \mathbb{T}^n \longrightarrow \mathbb{R}$$
  
 $\theta = (\theta^1, \dots, \theta^n) \longmapsto \sqrt{2} \cos \theta^i$ 

and

$$f_{i+1}: \quad \mathbb{T}^n \longrightarrow \mathbb{R}$$
  
 $\theta = (\theta^1, \dots, \theta^n) \longmapsto \sqrt{2} \sin \theta^i$ 

for i = 1, ..., n, is an orthonormal basis of  $T_1 \Phi_0 \left( \left( \mathbb{H}^2 \right)^n \right)$ .

**Lemma 13.** We have the relation

$$\Omega_{\mathbb{1}}(f_1, f_2, \dots, f_{2n}) = \frac{2^n}{\pi^n(2n)!}.$$

*Proof.* Let us look for permutations  $\sigma \in \mathfrak{S}_{2n+1}$  for which the corresponding term

$$2^{n} \operatorname{sign}(\sigma) \int_{(\mathbb{T}^{n})^{2n+1}} \prod_{i=1}^{n} \left( e(\theta_{\sigma(2i-2)}^{i}, \theta_{\sigma(2i-1)}^{i}, \theta_{\sigma(2i)}^{i}) \cos \theta_{2i-1}^{i} \sin \theta_{2i-2}^{i} \right) d\theta_{0} \cdots d\theta_{2n}$$

is nonzero. In order to get such a permutation, the variables  $\theta^i_{2i-1}$  and  $\theta^i_{2i}$  which are involved in the expression

$$\cos\theta_1^1\sin\theta_2^1\cdots\cos\theta_{2n-1}^n\sin\theta_{2n}^n$$

have to appear also in the expression

$$\prod_{i=1}^{n} e(\theta_{\sigma(2i-2)}^{i}, \theta_{\sigma(2i-1)}^{i}, \theta_{\sigma(2i)}^{i}).$$

If not we integrate with respect to one of the variables  $\theta_{2i-1}^i$  or  $\theta_{2i}^i$  missing in the term of the cocycle and we get a multiplicative vanishing term which is the integral of one of the functions  $f_i$ . Hence, we need that, for each i,

$$\{\theta_{2i-1}, \theta_{2i}\} \subset \{\theta_{\sigma(2i-2)}, \theta_{\sigma(2i-1)}, \theta_{\sigma(2i)}\}.$$

Let us now compute the number of suitable permutations. The first image  $\sigma(0)$  could be any of the 2n+1 elements. Let us say  $\sigma(0)$  falls in the  $i^{th}$  Euler class,  $\sigma(0) \in \{2i-2, 2i-1, 2i\}$  (e.g  $\sigma(0) = 2i-2$ , other cases are similar). From the condition above, it remains only two possibilities for  $\sigma(2i-1)$  and  $\sigma(2i)$ , namely,

$$\sigma(2i-1) = \sigma(2i-1) \text{ and } \sigma(2i) = \sigma(2i)$$
 or 
$$\sigma(2i-1) = \sigma(2i) \text{ and } \sigma(2i) = \sigma(2i-1).$$

Once we fill the  $i^{th}$  Euler class, the adjacent one(s) already have one element imposed (remember  $\theta_{2i}$  appears in both the  $i^{th}$  Euler class and the  $(i+1)^{th}$  Euler class). Hence we have again two possibilities for the two remaining arguments and inductively for each Euler class.

Finally we find

$$2^n(2n+1)$$

suitable permutations.

We now play with the skew-symmetry relation to show that, for each suitable permutation  $\sigma$ , the corresponding term

$$2^{n} \operatorname{sign}(\sigma) \int_{(\mathbb{T}^{n})^{2n+1}} \prod_{i=1}^{n} \left( e(\theta_{\sigma(2i-2)}^{i}, \theta_{\sigma(2i-1)}^{i}, \theta_{\sigma(2i)}^{i}) \cos \theta_{2i-1}^{i} \sin \theta_{2i-2}^{i} \right) d\theta_{0} \cdots d\theta_{2n}$$

equals  $\frac{1}{\pi^n}$ . From now on, we assume that  $\sigma$  is some suitable permutation characterized above.

The variable  $\theta_0$  appears in one or two Euler classes, let us say for example that

$$\sigma(0) = 2i$$

for some i < n (other cases are simpler). Then the variable  $\theta_0$  appears in both the  $i^{\text{th}}$  and the  $(i+1)^{\text{th}}$  Euler class. We compute the term

$$T_{\sigma} := \operatorname{sign}(\sigma) \int_{(\mathbb{T}^n)^{2n+1}} \prod_{i=1}^n \left( e(\theta^i_{\sigma(2i-2)}, \theta^i_{\sigma(2i-1)}, \theta^i_{\sigma(2i)}) \cos \theta^i_{2i-1} \sin \theta^i_{2i-2} \right) d\theta_0 \cdots d\theta_{2n}$$

by first performing the change of variables

$$\theta_{\sigma(2i-2)} = \theta_1', \ \theta_{\sigma(2i-1)} = \theta_2', \ \theta_{\sigma(2i+1)} = \theta_3', \ \theta_{\sigma(2i+2)} = \theta_4' \ \text{and} \ \theta_k = \theta_k',$$

for  $k \neq 2i-2, 2i-1, 2i+1, 2i+2$ . Since the Jacobian of this change of variable is 1, we do not change the value of  $T_{\sigma}$ . Remember we took  $\sigma$  such that

$$\{\sigma(2i-2), \sigma(2i-1)\} = \{2i-2, 2i-1\}$$
$$\{\sigma(2i+1), \sigma(2i+2)\} = \{2i+1, 2i+2\}.$$

and

So we can assume that  $\theta_0$  appears in the first two Euler classes.

Now the disjoint support cycles of the permutation  $\sigma$  are all contained in sets of the form

$$\{2i-2,2i-1,2i\}$$
.

Hence, when one reorders the variables in each Euler class such that  $\theta_{\sigma(2i-1)}$  sits in the  $(2i-1)^{th}$  place and  $\theta_{\sigma(2i)}$  sits in the  $(2i)^{th}$  place, the sign by which we changed  $T_{\sigma}$  is precisely sign $(\sigma)$ .

Therefore, because the first variables in each Euler class don't play any role, each term  $T_{\sigma}$  equals  $T_{id}$ . The computation of  $T_{id}$  is easy because the situation appears now as a product and one can use Lemma 12. Indeed,

$$T_{id} = 2^{n} \prod_{i=1}^{n} \int_{\left(\mathbb{S}^{1}\right)^{3}} e(\theta_{2i-2}^{i}, \theta_{2i-1}^{i}, \theta_{2i}^{i}) \cos \theta_{2i-1}^{i} \sin_{2i}^{i} d\theta_{2i-2}^{i} d\theta_{2i-1}^{i} d\theta_{2i}^{i}$$

$$= \prod_{i=1}^{n} \text{comass}(\omega)$$

$$= \frac{1}{\pi^{n}}.$$

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We now proceed to the calibrating inequality. We introduce the (2n-1)-cochain,

$$D(\theta_1,\ldots,\theta_{2n})=\int_{\mathbb{T}^n}C(\theta_0,\ldots,\theta_{2n})d\theta_0.$$

The reasoning involves the Fourier coefficient of D. A function  $f \in T_1 \mathcal{S}^{\infty}$  is written as

$$f(\theta^1, \dots, \theta^n) = \sum_{k=(k^1, \dots, k^n) \in I} a_k \cos(k^1 \theta^1 + \dots + k^n \theta^n) + b_k \sin(k^1 \theta^1 + \dots + k^n \theta^n),$$

where  $\theta = (\theta^1, \dots, \theta^n) \in \mathbb{T}^n$  and  $k \in I$ , the subset of  $\mathbb{Z}^n$  given by

$$I = \mathbb{N} \setminus \{0\} \times \mathbb{Z}^{n-1} \cup \{0\} \times \mathbb{N} \setminus \{0\} \times \mathbb{Z}^{n-2} \cup \cdots \cup \{0, \dots, 0\} \times \mathbb{N} \setminus \{0\}.$$

The convergence of the sum has to be understood for the  $L^2$  topology.

We denote by  $\gamma: \mathbb{S}^1 \to \mathbb{R}$  a function which can be either  $\sqrt{2} \cos$  or  $\sqrt{2} \sin$ . For some  $K = (k^1, \dots, k^n) \in I$  we denote by  $\gamma_K : \mathbb{T}^n \to \mathbb{R}$  a function which can be either

or 
$$\theta = (\theta^1, \dots, \theta^n) \longmapsto \sqrt{2} \cos(k^1 \theta^1 + \dots + k^n \theta^n)$$
$$\theta = (\theta^1, \dots, \theta^n) \longmapsto \sqrt{2} \sin(k^1 \theta^1 + \dots + k^n \theta^n).$$

**Definition 14** (Fourier transform and Fourier coefficients). Let F be a map from  $(\mathbb{T}^n)^{2n}$  to  $\mathbb{R}$ . The Fourier transform of F is the map

$$\hat{F}: I^{2n} \longrightarrow \mathbb{R}^{2^{2n}} 
(K_1, \dots, K_{2n}) \longmapsto \int_{(\mathbb{T}^n)^{2n}} D(\theta_1, \dots, \theta_{2n} \gamma_{K_1}(\theta_1) \cdots \gamma_{K_{2n}}(\theta_{2n}) d\theta_1 \cdots d\theta_{2n}.$$

We call  $\hat{F}(K_1, \ldots, K_{2n})$  a Fourier coefficient. The  $2^{2n}$  coordinates of a Fourier coefficient correspond to the possible choices of functions  $\gamma$ .

**Remark.** Fourier coefficients of the cochain D contain values of  $\Omega$ . In particular

$$\hat{D} \begin{pmatrix} 1 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 1 \end{pmatrix}$$

contains the value of  $\Omega$  on the orthonormal tangent of the image of the Poisson kernel. That is why we investigate the combinatorial properties of  $\hat{D}$ .

Here is a characterization of the nonzero Fourier coefficients of D.

**Lemma 15.** (1) The Fourier coefficient  $\hat{D}(K_1, ..., K_{2n})$  is nonzero if and only if there exist some nonzero integers  $k^1, ..., k^n$  such that

$$(K_1, \dots, K_{2n}) = \begin{pmatrix} k^1 & k^1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & k^2 & k^2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & & \cdots & k^n & k^n \end{pmatrix}$$

up to permutation of lines and rows. Moreover if  $(K_1, \ldots, K_{2n})$  is as above, the nonzero coordinates of  $\hat{D}(K_1, \ldots, K_{2n})$  (among the  $2^{2n}$  ones) is constructed by taking

$$\gamma_{K_{2i-1}}(\theta) = \sqrt{2}\cos(k^i\theta^1)$$
 and  $\gamma_{K_{2i}} = \sqrt{2}\sin(k^i\theta^n)$ 

for all i and up to permutations of the functions.

(2) A nonzero coordinate of some Fourier coefficient, that is,

$$2^n \int_{(\mathbb{T}^n)^{2n+1}} C(\theta_0, \dots, \theta_{2n}) \left( \prod_{i=1}^n \cos(k^i \theta_{2i-1}^i) \sin(k^i \theta_{2i}^i) \right) d\theta_0 \cdots d\theta_{2n}$$

equals

$$\frac{2^n}{(2n)!\pi^n \prod_{i=1}^n k^i}.$$

In particular, any nonzero value is smaller than the value of  $\Omega$  on the tangent of the image of the Poisson kernel.

*Proof.* Take some functions  $\gamma_{K_1}, \ldots, \gamma_{K_{2n}}$ . One may use the addition formulas for the trigonometric functions  $\gamma_{K_i}$ . Hence  $\hat{D}(K_1, \ldots, K_{2n})$  is a sum of terms of the form

$$\int_{\left(\mathbb{S}^{1}\right)^{2n^{2}}} \prod_{i=1}^{n} e\left(\theta_{\sigma(2i-2)}^{i}, \theta_{\sigma(2i-1)}^{i}, \theta_{\sigma(2i)}^{i}\right) \prod_{j=1}^{2n} \prod_{l=1}^{n} \gamma\left(k_{j}^{l} \theta_{j}^{l}\right) d\theta_{j}^{l}$$

(if for some integer  $k_j^l = 0$ , we set  $\gamma(k_j^l \theta_j^l) = 1$ ). We show that if  $(K_1, \ldots, K_{2n})$  is not as in the statement of the Lemma, every such term vanishes. In order to do that, we will use several times the arguments below.

**Argument 1**: If there is some variable  $\theta_j^l \in \mathbb{S}^1$  which is involved in some function  $\gamma$  and which is not involved in the term of the cocycle, that is

$$\theta_j^l \notin \bigcup_{i=1}^n \left\{ \theta_{\sigma(2i-2)}^i, \theta_{\sigma(2i-1)}^i, \theta_{\sigma(2i)}^i \right\},$$

then we integrate with respect to this variable  $\theta_j^l$  and we get zero as a multiplicative term because the integral of  $\theta_j^l \mapsto \gamma(k_j^l \theta_j^l)$  vanishes.

Argument 2: One can also show exactly as in paragraph 3.3 that

$$\int_{\left(\mathbb{S}^{1}\right)^{3}} e(\theta_{0}, \theta_{1}, \theta_{2}) \gamma(k_{0}\theta_{0}) \gamma(k_{1}\theta_{1}) \gamma(k_{2}\theta_{2}) d\theta_{0} d\theta_{1} d\theta_{2} = 0.$$

Indeed the Euler class e is combinatorially closed.

**Argument 3**: An expression of the form

$$\int_{\left(\mathbb{S}^{1}\right)^{3}} e(\theta_{0}, \theta_{1}, \theta_{2}) \gamma(\theta_{0}) d\theta_{0} d\theta_{1} d\theta_{2}$$

$$\left(\mathbb{S}^{1}\right)^{3}$$

must vanish. Indeed for a fixed  $\theta_0$ ,

$$\int_{\left(\mathbb{S}^{1}\right)^{2}} e(\theta_{0}, \theta_{1}, \theta_{2}) d\theta_{1} d\theta_{2} = 0.$$

In each term of the cocycle there is 3n variables involved. Then we cannot have more than 3n nonzero integers (otherwise we use argument 1 above). We cannot have also more than 3 nonzero integers in each row. Indeed,

- If there is 4 or more, there is at least one variable involved in the functions and not in the term of the cocycle. We use argument 1.
- If there is 3, there is again 2 possibilities. Either the variables involved in the functions and in the cocycle are not the same and we use argument 1; either they are the same and after we integrate with respect to this 3 variable, we use argument 2.

Moreover we cannot have more than 2 nonzero integers in each line. Indeed there is at most one repetition of the variables in the different Euler classes. In fact there is exactly two nonzero integers in each line. If there is only one, this means that there is only one of three variables in some Euler class matching with a variable in the functions. We integrate with respect to this three variables and we use argument 3.

Hence there is exactly 2n nonzero integers in the  $2n^2$  coordinates of a nonzero index  $(K_1, \ldots, K_{2n}) \in I^{2n}$  and exactly two nonzero integers in each line. So there is exactly one nonzero integer in each row.

So far we can assume that

$$(K_1, \dots, K_{2n}) = \begin{pmatrix} k^1 & k^2 & 0 & 0 & \cdots & 0 \\ 0 & 0 & k^3 & k^4 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & k^{2n-1} & k^{2n} \end{pmatrix}$$

for 2n nonzero integers  $k^1, k^2, \dots, k^{2n}$ .

Indeed, up to sign, the values of  $\hat{D}(K_1, \ldots, K_{2n})$  are left unchanged when we permute the  $K_i$ 's. One can also reorder the lines by performing some change of variables of the form

$$\theta_i^{'\sigma(l)} = \theta_i^l$$

which only changes the sign. From now on the situation appears completely as a product. One can check that the permutations  $\sigma \in \mathfrak{S}_{2n+1}$  giving a nonzero contribution are exactly the ones we characterized in Lemma 13. Each term gives the same value. A generic coordinate of  $\hat{D}(K_1, \ldots, K_{2n})$  can be written as

$$\frac{2^{n}}{(2n)!} \prod_{i=1}^{n} \int e(\theta_{2i-2}^{i}, \theta_{2i-1}^{i}, \theta_{2i}^{i}) \gamma(k^{2i-1}\theta_{2i-1}^{i}) \gamma(k^{2i}\theta_{2i}^{i}) d\theta_{2i-2}^{i} d\theta_{2i-1}^{i} d\theta_{2i}^{i}.$$

We can now conclude with the assertion 1 of Lemma 12. Indeed we must choose the integers  $k^1, k^2, \ldots, k^{2n}$  and the functions  $\gamma_{K_1}, \gamma_{K_2}, \ldots, \gamma_{K_{2n}}$  such that, for all index  $i, \gamma_{K_{2i}}$  and the primitive of  $\gamma_{K_{2i-1}}$  are not L<sup>2</sup>-orthogonal.

We can also perform the exact computation of the nonzero values thanks to the same assertion 1 of Lemma 12. Indeed for each index i,

$$2 \int_{(\mathbb{S}^{1})^{3}} e(\theta_{2i-2}^{i}, \theta_{2i-1}^{i}, \theta_{2i}^{i}) \cos(k^{i}\theta_{2i-1}^{i}) \sin(k^{i}\theta_{2i}^{i}) d\theta_{2i-2}^{i} d\theta_{2i-1}^{i} d\theta_{2i}^{i}$$

$$= 4 \int_{\mathbb{S}^{1}} \frac{1}{k^{i}} \sin^{2}(k^{i}\theta^{i}) d\theta^{i} = \frac{1}{k^{i}\pi}.$$

We finally deduce the calibrating inequality. Take 2n functions  $f_1, \ldots, f_{2n}$  with integrals zero, the family  $(f_1, \ldots, f_{2n})$  being orthonormal. For each function  $f_i$ , we write

$$f_i(\theta) = \sum_{K=(k^1,\dots,k^n)\in I} a_{K,i} \cos(k^1\theta^1 + \dots + k^n\theta^n) + b_{K,i} \sin(k^1\theta^1 + \dots + k^n\theta^n).$$

and we denote by  $c_{K,i}$  some Fourier coefficient of  $f_i$  which can be either  $a_{K,i}$  or  $b_{K,i}$ . Beside, let us set the following convention in order to design the coordinates of some Fourier coefficient. We take  $C = (c_{K_1,1}, \ldots, c_{K_{2n},2n}) \in \prod_{i=1}^{2n} \{a_{K_i,i}, b_{K_i,i}\}$  and denote by  $\hat{D}(K_1, \ldots, K_{2n})^C$  the coordinate of  $\hat{D}(K_1, \ldots, K_{2n})$  corresponding to

$$\begin{cases} \gamma_{K_i}(\theta) = \cos(k_i^1 \theta^1 + \dots + k_i^n \theta^n) & \text{if } c_{K_i,i} = a_{K_i,i}. \\ \gamma_{K_i}(\theta) = \sin(k_i^1 \theta^1 + \dots + k_i^n \theta^n) & \text{if } c_{K_i,i} = b_{K_i,i}. \end{cases}$$

Hence

$$\Omega_{1}(f_{1},...,f_{2n}) = \sum_{\substack{K_{1},...,K_{2n} \\ C \in \prod_{i=1}^{2n} \{a_{K_{i},i},b_{K_{i},i}\}}} \hat{D}(K_{1},...,K_{2n})^{C} c_{K_{1},1} \cdots c_{K_{2n},2n}.$$

We already isolated the vanishing Fourier coefficients. Let  $B = (e_1, \ldots, e_n)$  be a basis of  $\mathbb{R}^n$ . For  $\rho \in \mathfrak{S}_n$ , we denote by  $Q(\rho)$  the  $n \times n$  matrix in B of the linear map sending  $e_i$  to  $e_{\rho(i)}$ . We have

$$\Omega_{1}(f_{1},...,f_{2n}) = \sum \hat{D} \left( Q(\rho) \cdot \begin{pmatrix} k^{1} & k^{1} & 0 & 0 & \cdots & 0 \\ 0 & 0 & k^{2} & k^{2} & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & k^{n} & k^{n} \end{pmatrix} \right) \prod_{i=1}^{n} c_{k^{\rho(i)},2i-1} c'_{k^{\rho(i)},2i}.$$

The sum is taken over all possible choices of nonzero integers  $k^1, \ldots, k^n$ , all permutations  $\rho \in \mathfrak{S}_n$  and over all possibilities of  $c_{k^{\rho(i)},2i-1}$  and  $c'_{k^{\rho(i)},2i}$  such that, for all i,

$$c_{k^{\rho(i)},2i-1} = a_{k^{\rho(i)},2i-1}$$
 and  $c'_{k^{\rho(i)},2i} = b_{k^{\rho(i)},2i}$   
 $c_{k^{\rho(i)},2i-1} = b_{k^{\rho(i)},2i-1}$  and  $c'_{k^{\rho(i)},2i} = a_{k^{\rho(i)},2i}$ .

We now have

or

$$\left|\Omega_{\varphi}(f_{1},\ldots,f_{2n})\right| \leq \sum \frac{2^{n}}{(2n)!\pi^{n} \prod_{i=1}^{n} k^{i}} \prod_{i=1}^{n} \left| c_{k^{\rho(i)},2i-1} c'_{k^{\rho(i)},2i} \right|$$

$$\leq \sum \frac{2^{n}}{(2n)!\pi^{n}} \prod_{i=1}^{n} \left| c_{k^{\rho(i)},2i-1} c'_{k^{\rho(i)},2i} \right|.$$

It is a standard fact that, using repetitively the Cauchy-Schwartz inequality, one gets

$$\sum_{\alpha \in A} \prod_{\beta=1}^{N} x_{\alpha,\beta} \leqslant \prod_{\beta=1}^{N} \sqrt{\sum_{\alpha \in A} x_{\alpha,\beta}^{2}},$$

for some countable set A, some integer N and some non-negative numbers  $x_{\alpha,\beta}$ . Here we obtain

$$|\Omega_{\mathbb{I}}(f_{1},\ldots,f_{2n})| \leq \frac{2^{n}}{(2n)!\pi^{n}} \prod_{i=1}^{n} \sqrt{\sum |c_{k^{\rho(i)},2i-1}|} \prod_{i=1}^{n} \sqrt{\sum |c'_{k^{\rho(i)},2i}|}$$

$$\leq \frac{2^{n}}{(2n)!\pi^{n}} \prod_{i=1}^{2n} ||f_{i}||_{L^{2}}$$

$$= \frac{2^{n}}{(2n)!\pi^{n}}.$$

This inequality is an equality when  $(f_1, \ldots, f_{2n})$  generates the tangent to the image of the Poisson kernel. The proof of the main theorem is then complete.

### 4. Applications

We finally look for some consequences, suggested in the last chapter of [2].

It is possible to extend the main result to the case where g lives on another differentiable manifold related to M by a map of non-zero degree. The result we obtain is an optimal "degree theorem" as in the article [5] who misses the case we investigate. There is also a similar result in [15] but with a nonoptimal constant and with an additional hypothesis on the Ricci curvature of g.

We denote again  $M = \Gamma \setminus (\mathbb{H}^2)^n$  a compact quotient of  $(\mathbb{H}^2)^n$  and  $g_0$  the sum of hyperbolic metrics in the different factors  $\mathbb{H}^2$ .

**Corollary 4.** Let Y be a differentiable manifold of dimension 2n endowed with a Riemannian metric g and let f be a continuous map

$$f:(Y,g)\longrightarrow (M,g_0)$$

Then

$$h(g)^{2n} \operatorname{Vol}(Y, g) \ge |deg f| h(g_0)^{2n} \operatorname{Vol}(M, g_0)$$

*Proof.* Observe that the inequality is trivial if  $\deg(f) = 0$ . So let us assume that  $\deg(f)$  is non-zero. First, one can regularize the map f in a homotopic map, still denoted f, which is  $\mathcal{C}^1$ . We call  $\tilde{f}$  the map induced by f from  $\tilde{Y}$  to  $\tilde{M}$ . Let us introduce the invariant appropriated to this new situation

$$SphereVol(f) = \inf Vol((U, \Phi^*(can)))$$

where  $\Phi$  are Lipschitz continuous equivariant immersions from  $\tilde{Y}$  to  $L^2(\mathbb{T}^n)$ . As before, one example is given by the product of Poisson kernels,

$$\Phi_0(y,\theta) = \prod_{i=1}^n \sqrt{p_0(\tilde{f}(y)^i,\theta^i)},$$

where the  $\tilde{f}(y)^i$ 's are the coordinates in the factors  $\mathbb{H}^2$  and the  $\theta^i$ 's are the coordinate in  $\mathbb{T}^n$ . We also consider

$$\Phi_c(y,\theta) = \left(\frac{\int_{\widetilde{Y}} e^{-cd(y,z)} \Phi_0^2(z,\theta) dv_g(z)}{\int_{\mathbb{T}^n} e^{-cd(y,z)} \Phi_0^2(z,\theta) d\theta}\right)^{1/2}.$$

where d is the g-distance in  $\widetilde{Y}$ . The two arguments above (page 111 for the first and Section 3 for the second) give in this context

- (1) SphereVol  $\leq \left(\frac{h(g)^2}{8n}\right)^n \text{Vol}(Y, g)$  using the computation of Vol $(\Phi_c)$
- (2) The image of  $\Phi_0$  is still calibrated because f is surjective and then SphereVol = Vol( $\Phi_0$ ). Moreover

$$Vol(\Phi_0) = |\deg f| \left(\frac{h(g_0)^2}{8n}\right)^n Vol(X, g_0).$$

We also obtain an estimate for the minimal volume. Let X be a compact manifold. The minimal volume is defined as

$$MinVol = \inf \{ Vol(g), |K(g)| \le 1 \}$$

(see [9]).

**Corollary 3.** Let  $M = \Gamma \setminus (\mathbb{H}^2)^n$  be a compact quotient of  $(\mathbb{H}^2)^n$ . Then

$$\operatorname{MinVol}(M) \geqslant \left(\frac{\sqrt{n}}{2n-1}\right)^{2n} \operatorname{Vol}(g_0).$$

In particular, we reprove in a quantitative way a general theorem of [13] stating that MinVol is nonzero. However the inequality is probably not sharp.

*Proof.* We still follow chapter 9 of [2]. Take a metric g on M with  $|K(g)| \le 1$ . We deduce an equality on the Ricci curvature

$$Ric(g) \ge -(2n-1)g$$
.

We then apply Bishop's inequality ([8] p. 144) comparing volumes of balls for g and volumes of balls in the hyperbolic 2n-space  $\mathbb{H}^{2n}$ . Taking the logarithm and making the radius go to infinity, we have

$$h(g) \leq 2n - 1$$
.

We conclude introducing this inequality in

$$\operatorname{Vol}(g) \geqslant \left(\frac{\sqrt{n}}{h(g)}\right)^{2n} \operatorname{Vol}(g_0).$$

Here is a last consequence in dimension 4. P. Suarez-Serrato in [19] classified the 4-dimensional Thurston geometries admitting a metric of minimal normalized volume entropy. The only missing case were the case of quotients of  $\mathbb{H}^2 \times \mathbb{H}^2$ . In dimension 4, there exist 19 geometries admitting a compact quotient (see the list and references in [19] p. 366). P. Suarez-Serrato was able to decide among the 18 geometries (all but  $\mathbb{H}^2 \times \mathbb{H}^2$ ) which ones admit a metric of volume 1 with minimal volume entropy (theorem A). Hence we obtain

**Corollary 16.** The 4-dimensional Thurston geometries admitting a metric with minimal normalized volume entropy are only those of "hyperbolic type"

$$\mathbb{H}^4_{\mathbb{R}}, \mathbb{H}^2_{\mathbb{C}} \ and \ \mathbb{H}^2_{\mathbb{R}} \times \mathbb{H}^2_{\mathbb{R}}.$$

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